.MODEL SMALL .DATA

PA EQU 0D800H PB EQU 0D801H PC EQU 0D802H CW EQU 0D803H

CLEAR DB 0E0H,0D0H,0B0H,70H

;Ports PA7-PA4 ;GF 1110 ;FF 1101 ;SF 1011 ;TF 0111

.CODE

MOV AX,@DATA MOV DS,AX

MOV DX,CW

MOV AL,82H ;port B is Input

OUT DX,AL

LEA SI,CLEAR

MOV AL,0F0H ;clear SR flip flop PA4-PA7

MOV DX,PA OUT DX,AL

NOREQ:

CALL REQUEST ;read input from Elevator Key

JZ NOREQ

SHR AL,01H ;1110 ground

JNC GF

SHR AL,01H ;1101 first

JNC FF

SHR AL,01H ;1011 second

JNC SF

JMP TF ;0111 third

GF:

CALL DELAY

CALL RESET ;stays at Ground floor

JMP EXIT

FF:

MOV CX,03H ;initialize counter to 3

CALL MOVEUP

PUSH AX ;store ax = 1111 0011, al = 3

CALL DELAY

INC SI ;si points to FF = 1101

CALL RESET ;stay at that floor

MOV CX,03H ;initialize counter to 3 again to move down

POP AX

CALL MOVEDOWN

JMP EXIT

SF:

MOV CX,06H

CALL MOVEUP

PUSH AX

CALL DELAY

ADD SI,02

CALL RESET

MOV CX,06H

POP AX

CALL MOVEDOWN

JMP EXIT

TF:

MOV CX,09H

CALL MOVEUP

PUSH AX

CALL DELAY

ADD SI,03H

CALL RESET

MOV CX,09H

CALL MOVEDOWN

POP AX

JMP EXIT

EXIT:

MOV AH,4CH

INT 21H

```
REQUEST PROC NEAR
     MOV DX,PB
                      ;read from Port B
     IN AL, DX
     AND AL,0FH
     CMP AL,0FH
     RET
REQUEST ENDP
RESET PROC NEAR
                      ;out SI to port A
     MOV DX,PA
     MOV AL,[SI]
     OUT DX,AL
     RET
RESET ENDP
MOVEUP PROC NEAR
                      ;out AL to port A
     MOV DX,PA
     MOV AL,0F0H
     L1:
           OUT DX,AL
           CALL DELAY
           INC AL
     LOOP L1
     OUT DX,AL
     RET
MOVEUP ENDP
MOVEDOWN PROC NEAR ;out AL to port A
     MOV DX,PA
     L2:
           OUT DX,AL
           CALL DELAY
           DEC AL
     LOOP L2
     OUT DX,AL
     RET
MOVEDOWN ENDP
DELAY PROC NEAR
     PUSH SI
     PUSH DI
```

```
MOV SI,0FFFFH
Outer:

MOV DI,0FFFFH
Inner:

DEC DI
JNZ Inner
DEC SI
JNZ Outer

POP DI
POP SI
RET
DELAY ENDP
```

END