

Camera::get\_direction

Camera::translate

Camera::get\_rotation  
\_inv\_mat4

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graph LR; A[Camera::get_direction] --> C[Camera::get_rotation<br/>_inv_mat4]; B[Camera::translate] --> C;
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The diagram illustrates a dependency or data flow. On the left, two white rectangular boxes are stacked vertically. The top box contains the text 'Camera::get\_direction' and the bottom box contains 'Camera::translate'. On the right, there is a gray rectangular box containing the text 'Camera::get\_rotation' followed by '\_inv\_mat4' on a new line. Two blue arrows originate from the right side of the left boxes and point towards the left side of the gray box, indicating that both 'get\_direction' and 'translate' methods or functions are associated with or provide data to 'get\_rotation\_inv\_mat4'.