# CL 305 TRANSPORT PHENOMENA

## **VECTORS AND TENSORS**

## **INSTRUCTOR**

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# VECTOR MULTIPLICATION

**Vector**: Quantity with a definite magnitude and direction

Magnitude of a vector,  $\mathbf{v}$ : Represented by either  $|\mathbf{v}|$  or v

#### **Scalar Product or Dot Product:**

Consider two vectors **v** and **w**. Their scalar product (or dot product) is defined as

$$(\mathbf{v} \cdot \mathbf{w}) = |\mathbf{v}||\mathbf{w}|\cos\phi_{\mathbf{v}\mathbf{w}}$$

 $\phi_{\mathbf{v}\mathbf{w}}$  is the angle between the vectors  $\mathbf{v}$  and  $\mathbf{w}$ .

Scalar product of a vector with itself is the square of its magnitude:

$$(\mathbf{v} \cdot \mathbf{v}) = |\mathbf{v}||\mathbf{v}| = |\mathbf{v}|^2 = v^2$$

# VECTOR MULTIPLICATION

Scalar Product or Dot Product: Governing rules are

Commutative:  $(\mathbf{v} \cdot \mathbf{w}) = (\mathbf{w} \cdot \mathbf{v})$ 

Distributive:  $(\mathbf{u} \cdot \{\mathbf{v} + \mathbf{w}\}) = (\mathbf{u} \cdot \mathbf{v}) + (\mathbf{u} \cdot \mathbf{w})$ 

NOT Associative:  $(\mathbf{u} \cdot \mathbf{v})\mathbf{w} \neq \mathbf{u}(\mathbf{v} \cdot \mathbf{w})$ 

# VECTOR MULTIPLICATION

#### **Vector Product or Cross Product:**

Consider two vectors **v** and **w**. Their vector product (or cross product) is defined as

$$[\mathbf{v} \times \mathbf{w}] = (|\mathbf{v}||\mathbf{w}|\sin\phi_{\mathbf{v}\mathbf{w}})\mathbf{n}_{\mathbf{v}\mathbf{w}}$$

 $\phi_{vw}$  is the angle between the vectors  $\mathbf{v}$  and  $\mathbf{w}$ , and  $\mathbf{n}_{vw}$  is a unit vector perpendicular to both  $\mathbf{v}$  and  $\mathbf{w}$  and pointing in a direction given by the right hand rule.

Vector product of a vector with itself is zero:  $[\mathbf{v} \times \mathbf{v}] = 0$ 

NOT Commutative:  $[\mathbf{v} \times \mathbf{w}] = -[\mathbf{w} \times \mathbf{v}]$  (anti-commutative)

Distributive:  $[\mathbf{u} \times \{\mathbf{v} + \mathbf{w}\}] = [\mathbf{u} \times \mathbf{v}] + [\mathbf{u} \times \mathbf{w}]$ 

NOT Associative:  $\left[\mathbf{u} \times \left[\mathbf{v} \times \mathbf{w}\right]\right] \neq \left[\left[\mathbf{u} \times \mathbf{v}\right] \times \mathbf{w}\right]$ 

## VECTOR OPERATIONS IN TERMS OF COMPONENTS

## Kronecker Delta, $\delta_{ij}$ :

$$\delta_{ij} = +1$$
 if  $i = j$ 

$$\delta_{ij} = 0$$
 if  $i \neq j$ 

## Permutation Symbol, $\varepsilon_{ijk}$ :

$$\varepsilon_{ijk} = \frac{1}{2}(i-j)(j-k)(k-i)$$

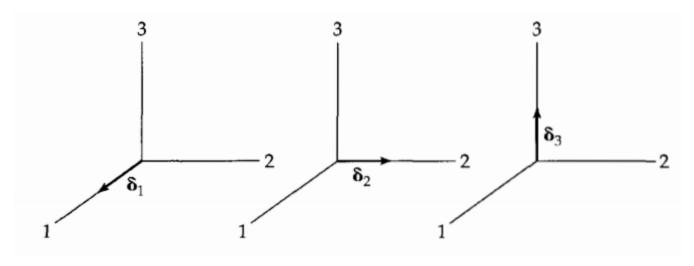
$$\varepsilon_{ijk} = +1$$
 if  $ijk = 123, 231$  or 312

$$\varepsilon_{ijk} = -1$$
 if  $ijk = 321, 132$  or 213

$$\varepsilon_{ijk} = 0$$
 if any two indices are alike

# UNIT VECTORS

Let  $\delta_1$ ,  $\delta_2$ , and  $\delta_3$  be the unit vectors along the 1, 2 and 3 axis respectively.



Taken from Transport Phenomena by Bird, Stewart, Lightfoot.

$$\left(\boldsymbol{\delta}_{i}\cdot\boldsymbol{\delta}_{j}\right)=\delta_{ij}$$

$$\left[\boldsymbol{\delta}_{i} \times \boldsymbol{\delta}_{j}\right] = \sum_{k=1}^{3} \varepsilon_{ijk} \boldsymbol{\delta}_{k}$$

## VECTOR IN TERMS OF COMPONENTS

$$\mathbf{v} = \boldsymbol{\delta}_1 v_1 + \boldsymbol{\delta}_2 v_2 + \boldsymbol{\delta}_3 v_3 = \sum_{i=1}^3 \boldsymbol{\delta}_i v_i$$

 $v_1, v_2, v_3$  are the projections of the vector  $\mathbf{v}$  on the 1, 2 and 3 axis respectively. These are called the components of the vector  $\mathbf{v}$ .

Magnitude of a vector is given by

$$|\mathbf{v}| = v = \sqrt{v_1^2 + v_2^2 + v_3^2} = \sqrt{\sum_i v_i^2}$$

#### **Scalar Product or Dot Product:**

$$(\mathbf{v} \cdot \mathbf{w}) = \left( \left\{ \sum_{i} \mathbf{\delta}_{i} v_{i} \right\} \cdot \left\{ \sum_{j} \mathbf{\delta}_{j} w_{j} \right\} \right) = \sum_{i} \sum_{j} (\mathbf{\delta}_{i} \cdot \mathbf{\delta}_{j}) v_{i} w_{j} = \sum_{i} v_{i} w_{i}$$

## VECTOR IN TERMS OF COMPONENTS

#### **Vector Product or Cross Product:**

$$[\mathbf{v} \times \mathbf{w}] = \left[ \left\{ \sum_{j} \mathbf{\delta}_{j} v_{j} \right\} \times \left\{ \sum_{k} \mathbf{\delta}_{k} w_{k} \right\} \right] = \sum_{i} \sum_{j} \sum_{k} \varepsilon_{ijk} \mathbf{\delta}_{i} v_{j} w_{k} = \begin{vmatrix} \mathbf{\delta}_{1} & \mathbf{\delta}_{2} & \mathbf{\delta}_{3} \\ v_{1} & v_{2} & v_{3} \\ w_{1} & w_{2} & w_{3} \end{vmatrix}$$

### **Dyadic Product of Vectors:**

$$\mathbf{v}\mathbf{w} = \sum_{i} \sum_{j} \mathbf{\delta}_{i} \mathbf{\delta}_{j} v_{i} w_{j}$$

These are tensors of the second order

 $\delta_i \delta_i$  are called **unit dyads** 

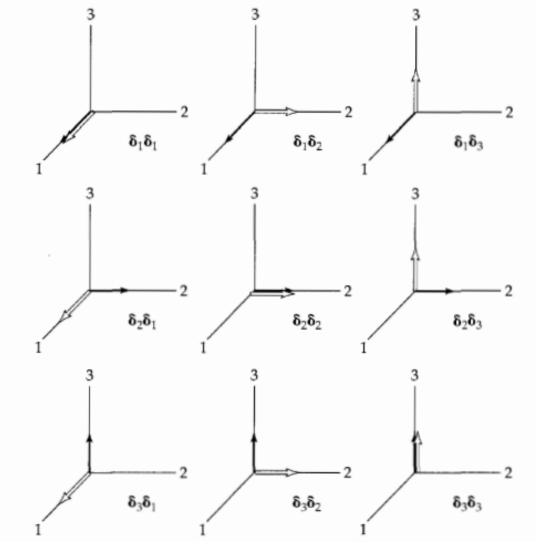
## UNIT DYADS

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Dyadic Product: 
$$\mathbf{v}\mathbf{w} = \sum_{i} \sum_{j} \delta_{i} \delta_{j} v_{i} w_{j}$$

These are tensors of the second order

 $\delta_i \delta_j$  are called **unit dyads** 



Taken from Transport Phenomena by Bird, Stewart, Lightfoot.

# UNIT DYADS: OPERATIONS

$$(\boldsymbol{\delta_i}\boldsymbol{\delta_j}:\boldsymbol{\delta_k}\boldsymbol{\delta_l}) = (\boldsymbol{\delta_j}\cdot\boldsymbol{\delta_k})(\boldsymbol{\delta_i}\cdot\boldsymbol{\delta_l}) = \delta_{jk}\delta_{il}$$

$$[\delta_i \delta_j \cdot \delta_k] = \delta_i (\delta_j \cdot \delta_k) = \delta_i \delta_{jk}$$

$$\left[\delta_i \cdot \delta_j \delta_k\right] = \left(\delta_i \cdot \delta_j\right) \delta_k = \delta_{ij} \delta_k$$

$$\left\{ \boldsymbol{\delta}_{i} \boldsymbol{\delta}_{j} \cdot \boldsymbol{\delta}_{k} \boldsymbol{\delta}_{l} \right\} = \boldsymbol{\delta}_{i} \left( \boldsymbol{\delta}_{j} \cdot \boldsymbol{\delta}_{k} \right) \boldsymbol{\delta}_{l} = \delta_{jk} \boldsymbol{\delta}_{i} \boldsymbol{\delta}_{l}$$

$$\{\delta_i \delta_j \times \delta_k\} = \delta_i [\delta_j \times \delta_k] = \sum_{l=1}^{3} \varepsilon_{jkl} \delta_i \delta_l$$

$$\{\boldsymbol{\delta}_{i} \times \boldsymbol{\delta}_{j} \boldsymbol{\delta}_{k}\} = [\boldsymbol{\delta}_{i} \times \boldsymbol{\delta}_{j}] \boldsymbol{\delta}_{k} = \sum_{l=1}^{3} \varepsilon_{ijl} \boldsymbol{\delta}_{l} \boldsymbol{\delta}_{k}$$