Path Planning for Dynamic Graphs using A* on GPU

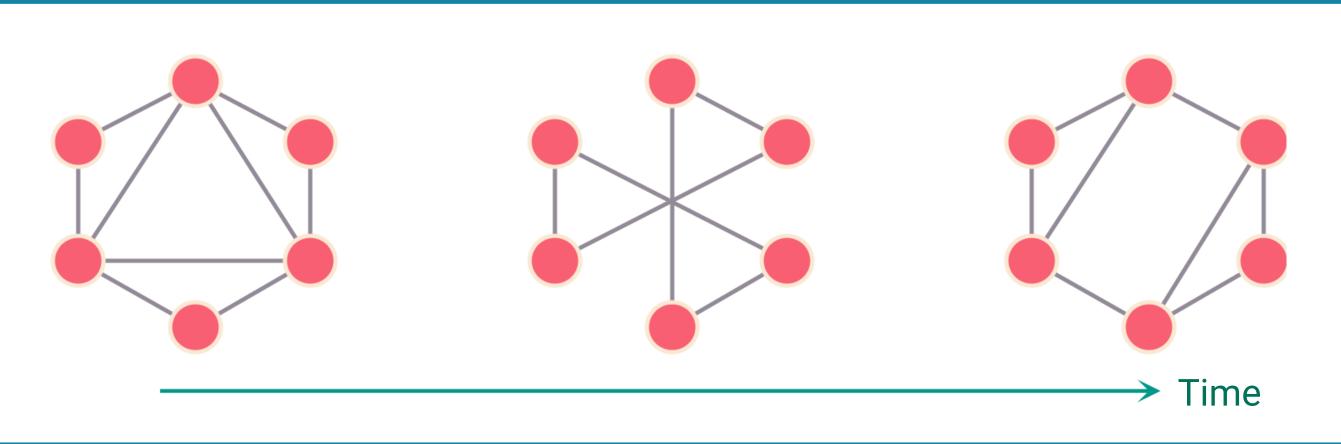
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Abstract

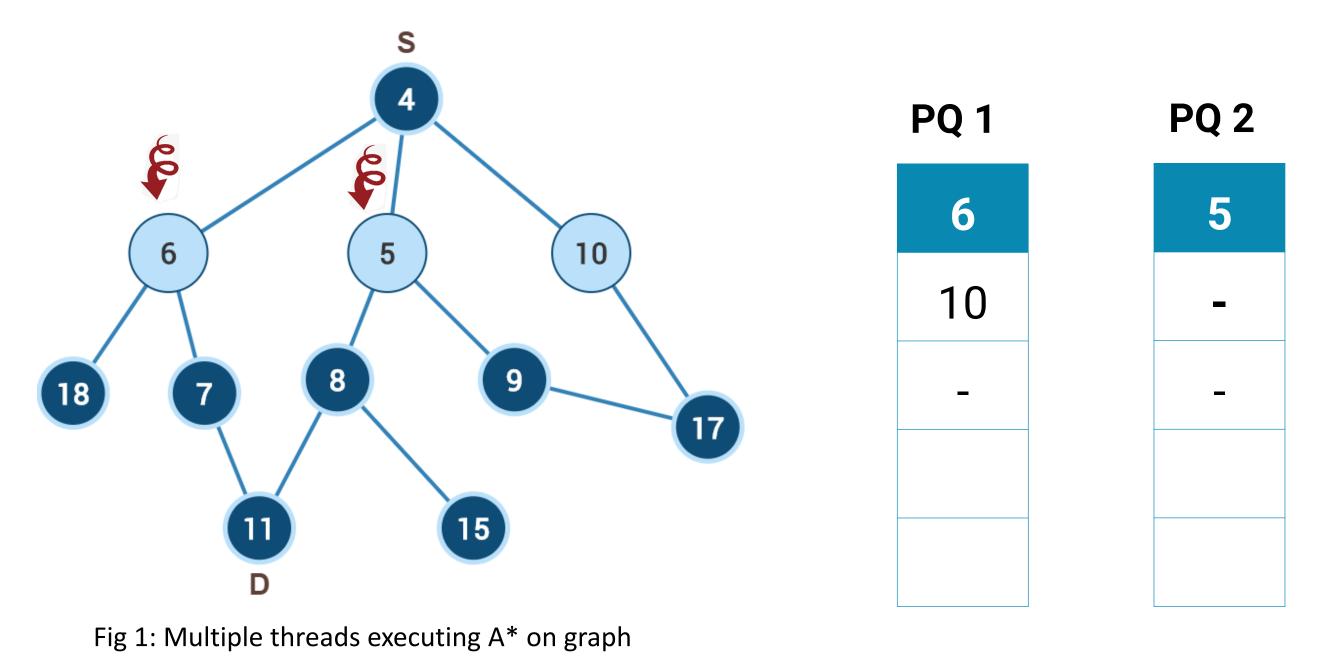
- A* is one of the widely used path planning algorithms applied in a diverse set of problems in robotics and video games.
- Here we present A* for dynamic graphs (dynamic A*) on GP-GPUs which achieves 5x-8x speedup than existing methods on the SNAP dataset [2].
- Our implementation is freely available on GitHub¹.

Dynamic Graphs



Static A* Algorithm on GPU [1]

- Find the optimal path from source to destination.
- Sequential in nature, minimum cost nodes are extracted from the priority queue and processed.
- Keep multiple priority queues (PQ) to extract many nodes in parallel to process.



Dynamic A*: Insertion of edges

- Newly added edges can alter the optimal path.
- To find the new optimal path instead of executing A* from scratch, we propagate the change to the affected nodes of the graph.
- Inserted edges are batched and sent to GPU for processing.

Dynamic A*: Deletion of edges

- Deleting only that edge which belongs to the optimal path can create a new optimal path.
- For all such affected nodes recompute the cost and select the neighbour with the least cost.
- Propagate the updated cost to all the affected nodes.

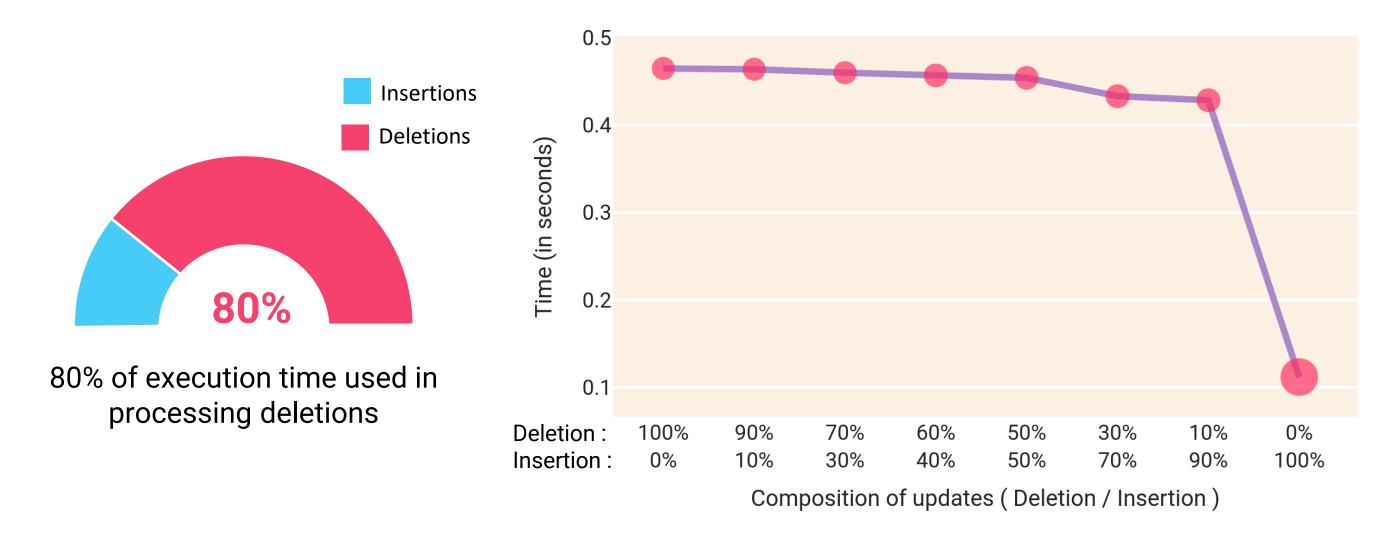


Fig 2: Execution time vs insertion / deletion

Dynamic A*: Insertion + Deletion

- The update contains both insertion and deletion of edges.
- Propagate insertions and deletions of edges separately.
- Performs better than re-executing static A* algorithm after each update.

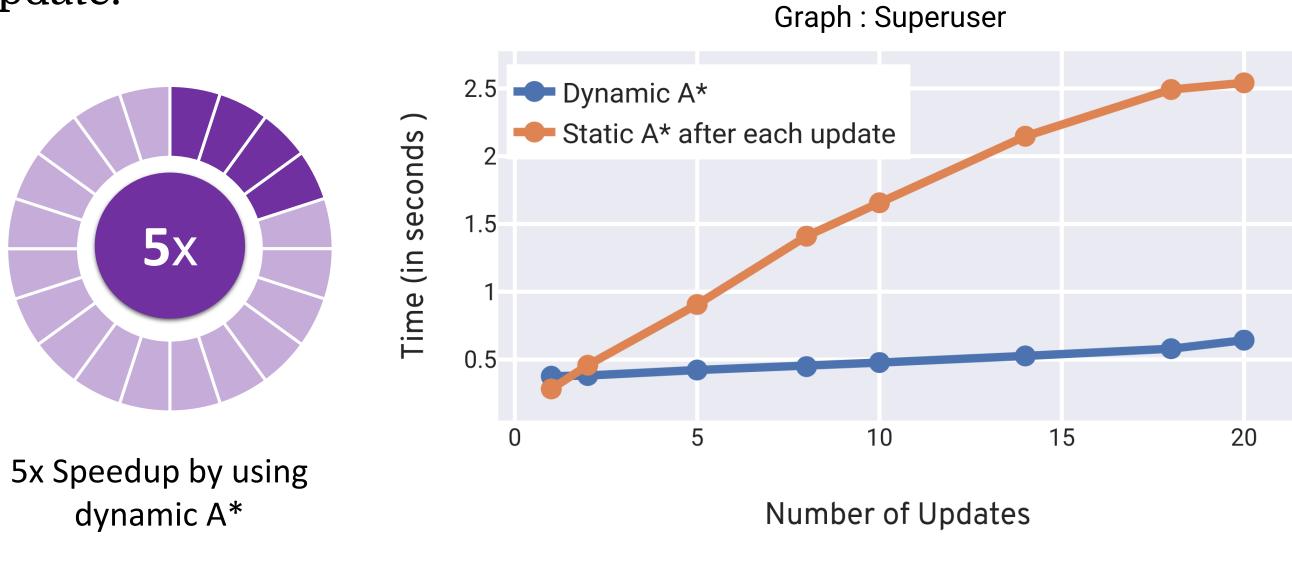


Fig 3: Execution time vs number of updates In the graph

Results

The below table shows execution time (in seconds) and speedup of dynamic A* compared to re-executing static A* every time.

No.	Graph	Edges	Queries	Dynamic A*	Static A*	Speedup
1	Live Journal	34,681,189	10	6.01	33.93	5x
2	Wiki Talk	7,833,140	10	12.24	24.84	2x
3	Ask Ubuntu	964,437	10	0.25	1.31	5x
4	YouTube	2,987,624	10	0.81	5.78	7x
5	Math Overflow	506,550	10	0.09	0.67	7x
6	Live Journal	34,681,189	100	11.41	424.06	37x

Applications

We have applied dynamic A* on energy efficient routing protocol (EERP) and achieved 35x speedup from static A*.



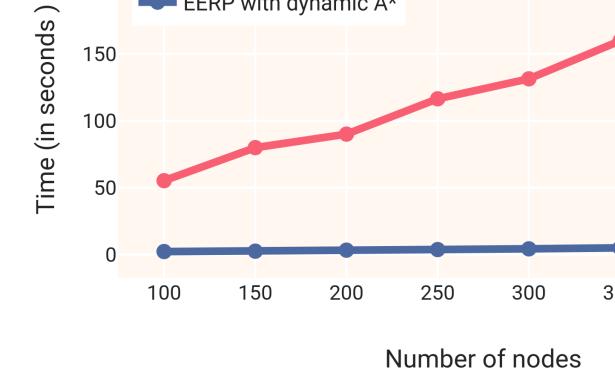


Fig 4: Comparison b/w static A* and dynamic A* on EERP algorithm

Future Work

- In the future, we plan to incorporate the change in heuristic values of nodes as graph changes and how it affects the optimal path.
- We also plan to integrate the proposed algorithm on different applications of A* and analyse the performance improvements.

References

- 1. Yichao Zhou and Jianyang Zeng. "Massively Parallel A* Search on GPU". In: Twenty-Ninth AAAI Conference on Artificial Intelligence (2015).
- 2. Jure Leskovec and Andrej Krevl. SNAP Datasets: Stanford Large Network Dataset Collection. http://snap.stanford.edu/data. June 2014.



