Gaurav Duggal

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EDUCATION

Virginia Tech, USA, Wireless@VT

2021 – present

• P.h.D. in Electrical Engineering

Indraprastha Institute of Information Technology, Delhi, India

2017 - 2019

Masters (M.Tech.) in Communications and Signal Processing Engineering.

Birla Institute of Technology and Sciences, Hyderabad India

2009 - 2013

■ Bachelor (B.E.) in Electrical and Electronics Engineering.

PROFESSIONAL EXPERIENCE

Research Intern, Samsung Research America, Plano, Texas (SMI-lab) May 2022 – Aug 2022

• Worked on an Ultra WideBand (UWB) Radar-based product and submitted a patent application for an algorithm that optimized the latency-accuracy tradeoff.

Engineer, Qualcomm, India (RF software team)

Jul 2019 – Aug 2021

- Worked on board bring-up of Qualcomm modems.
- Worked on algorithms that managed the RF front end of qualcomm modems and also resource allocation algorithms.

Research Intern, Hertzwell, Singapore

Dec 2018 - Feb 2019

• Developed an end-to-end automotive MIMO radar signal processing including waveform design, ground clutter modelling, automotive target modelling and receiver effects modelling.

Member of Technical Staff, Tonbo Imaging, India

May 2015 – Jun 2016

Developed firmware for a thermal imaging camera system used by Defence Forces across the globe.

Embedded Electronics Engineer, Ducere Technologies, India

Jul 2013 - Apr 2015

• Implemented prototypes of Wearable technology-based design ideas using basic physics and electronics.

Research Intern, Cranfield University, United Kingdom

May 2012 - Jul 2012

 Designed an Inertial Navigation System (INS) for an Unmanned Ground Vehicle using mems-based sensors.

PUBLICATIONS

- [4] G. Duggal, R.M Buehrer, Nishith Tripathi, Jeffrey.H. Reed "Line-of-Sight Probability for Outdoor-to-Indoor UAV-Assisted Emergency Networks", accepted in IEEE International Conference on Communications, 2023
- [3] N. Pandey, G. Duggal, en S. S. Ram, "Database Of Simulated Inverse Synthetic Aperture Radar Images For Short Range Automotive Radar", in **2020 IEEE International Radar Conference** (RadarConf), 2020, bll 238–243. [Paper]
- [2] <u>G. Duggal</u>, S. Vishwakarma, K. V. Mishra, en S. S. Ram, "Doppler-resilient 802.11 ad-based ultrashort range automotive joint radar-communications system", **IEEE Transactions on Aerospace and Electronic Systems**, vol 56, no 5, bll 4035–4048, 2020. [Paper]
- [1] <u>G. Duggal</u>, S. S. Ram, en K. V. Mishra, "Micro-Doppler and micro-range detection via Doppler-resilient 802.11 ad-based vehicle-to-pedestrian radar", in **2019 IEEE Radar Conference** (**RadarConf**), 2019, bll 1–6. [Paper]

COURSEWORK

Multi-Channel Communications (MIMO), Information Theory, Software Defined Radios, Stochastic Signals & Systems, Radar Systems, Reinforcement Learning, Data Structures and Algorithms.

TEACHING Teac

Teaching Assistantship

- TA for the Grad course Radar Systems (ECE 5675) with Prof. Mike J. Ruohoniemi [Fall 2021, Virginia Tech.]
- Wearable Applications, Research, Devices, Interactions (DES 513) with Prof. Aman Parnami at IIIT
 Delhi. [Monsoon 2018](Aug-Dec)
- Probability And Statistics (MTH 201) with Prof. Sanjit Kaul at IIIT Delhi [Winter 2018](Jan-May)

PROJECTS

MIMO-Course - MATLAB simulations, instructor Prof. R. Michael Buehrer

- Simulated, Jakes channel model with known temporal and spatial autocorrelation properties.
- Simulated various transmit and receive side diversity algorithms Maximal Ratio Combining, Eigen-beamforming, Maximal ratio transmission, TX antenna selection.
- Simulated various spatial multiplexing techniques including Alamouti space-time block codes, MMSE, Zeo Forcing, SIC+MMSE.
- Simulated OFDM with cyclic prefix in frequency selective channels and exploited frequency diversity using BCH codes.
 [Fall 2022, Virginia Tech.]

Wireless localization in a Joint-Radar communication system in an urban environment, under Prof. R. Michael Buehrer and Prof. Harpreet Dhillon

- Derived Cramer-Rao bounds for wireless localization using a Joint Radar-Cellular Communication system with the radar doing range/angle measurements in Line of Sight conditions and a ToA system with Non-Line of Sight bias operating in both LoS and NLoS conditions.
- This proposal made it to the North America finals of the Qualcomm Innovation Fellowship, 2022. [Proposal] [Spring 2022, Virginia Tech]

Business Plan on - A High Quality Wireless Video Streaming Module for Drones, under Prof. J.H Reed

 Identified a business opportunity and proposed an idea for a wireless video streaming product for the Cinematography using Drones industry.
 [Proposal] [Spring 2022, Virginia Tech.]

Orthogonal Time Frequency Space waveform simulation, under Prof. J.H. Reed.

• Simulated the OTFS waveform which included going from the Delay-Doppler domain to the Time Frequency domain at the transmitter. This was then passed through a channel and then from Time-Frequency domain back to Delay-Doppler domain. [Code] [Spring 2022, Virginia Tech.]

Micro Doppler Radar using HB100 and RCWL-0516, Independent project

- Implemented a Doppler radar in hardware by amplifying the received baseband signals from an RF front end (HB100) and then using an opamp-based active amplifier circuit with adjustable gain.
- Sampled the amplified signal using an Arduino ADC and used Serial to send this data to the computer.
- The digitally sampled signals were processed using an Short time Fourier Transform (STFT) algorithm with a hamming window in Python code. We can see micro Doppler features of the target ceiling fan blades in the spectrogram output [Code], [Video]

ADS-B Receiver and Antenna Design to Track Aircraft, Dr. SS Ram, Assoc Prof, IIITD

- Designed and Constructed a portable Automatic Dependent Surveillance-Broadcast (ADS-B) radio receiver using a Software Defined Radio and an embedded computer to track commercial aircraft
- Implemented a Matched Filter in the preamble detection stage of the ADSB receiver code.
- Implemented 1 bit error correction for the adsb packet.
- Constructed a phased array antenna based on a paper in the Antennas and Propagation journal, for the system to improve aircraft tracking up to the horizon (400km). [Presentation]

Reinforcement Learning Agent for the Atari game Catch, Dr. Sanjit Kaul, Assoc Prof, IIITD

■ Implemented Policy Gradient based methods (2018 research papers) and compared it with Deep-Q learning to learn the optimal policy for Atari game Catch. [Code]

Qualcomm Innovation Fellowship 2022 - finalist - Joint radar-communication based wireless localisation
 Secured a scholarship amounting to 960 UK pounds per month for 3 months for a research internship at Cranfield University, United Kingdom.
 All India Engineering Entrance Exam - Top 0.4 percent among 1.2 million candidates.
 IIT Joint Entrance Exam - Top 1 percent among 0.5 million candidates.
 Won an Individual Silver medal (among 77 teams from 11 countries) at the 4th International Young Mathematician's Convention (IYMC).
 National Cyber Olympiad 2007 - All India Rank 13

SKILLS Languages: C, C++, Python, Matlab

Deep Learning Libraries : Tensorflow (Basic)

Version Management : Git (fluent)