

Mathematical function

Q1.SIN() - This function helps user to calculate trigonometric sine for all x (being the array elements) ¶

```
In [16]: # sin() function

import numpy as np

array = [0, math.pi / 2, np.pi / 3, np.pi]
print ("Input array : \n", array)

Sin_Values = np.sin(array)
print ("\nSine values : \n", Sin_Values)
```

Input array :
[0, 1.5707963267948966, 1.0471975511965976, 3.141592653589793]

Sine values :
[0.00000000e+00 1.00000000e+00 8.66025404e-01 1.22464680e-16]

we can use np also as well as math also to use pi functions. here pi value is defined in the package as 3.14159

```
In [14]: import numpy as np
import math

array = [0, math.pi / 2, math.pi / 3, math.pi]
print ("Input array : \n", array)

Sin_Values = np.sin(array)
print ("\nSine values : \n", Sin_Values)
```

Input array :
[0, 1.5707963267948966, 1.0471975511965976, 3.141592653589793]

Sine values :
[0.00000000e+00 1.00000000e+00 8.66025404e-01 1.22464680e-16]

Q2. COS() - This mathematical function helps user to calculate trigonometric cosine for all x (being the array elements).

```
In [25]: # Python program explaining
# cos() function

import numpy as np
import math

array = [0, np.pi / 2, np.pi / 3, np.pi]
print ("Input array : \n", array)

cos_Values = np.cos(array)
print ("\nCosine values : \n", cos_Values)
```

Input array :
[0, 1.5707963267948966, 1.0471975511965976, 3.141592653589793]

Cosine values :
[1.000000e+00 6.123234e-17 5.000000e-01 -1.000000e+00]

Q3. TAN() - This mathematical function helps user to calculate trigonometric tangent for all x (being the array elements).

2pi Radians = 360 degrees

$\tan(x) = \sin(x) / \cos(x)$

An array with trigonometric sine of x for all x i.e. array elements

```
In [26]: import numpy as np
import math

in_array = [0, math.pi / 4, 3*np.pi / 2, math.pi/6]
print ("Input array : \n", in_array)

tan_Values = np.tan(in_array)
print ("\nTan values : \n", tan_Values)
```

Input array :
[0, 0.7853981633974483, 4.71238898038469, 0.5235987755982988]

Tan values :
[0.00000000e+00 1.00000000e+00 5.44374645e+15 5.77350269e-01]

Q4. conversion from Radian to degrees

In [27]: *# rad2deg() function*

```
import numpy as np
import math

array = [0, math.pi / 2, np.pi / 3, np.pi]
print ("Radian values : \n", array)

conversion = np.rad2deg(array)
print ("\nDegree values : \n", conversion)
```

Radian values :

[0, 1.5707963267948966, 1.0471975511965976, 3.141592653589793]

Degree values :

[0. 90. 60. 180.]

In [28]: *#2nd method to get radians converted to degrees*
degrees() function

```
import numpy as np
import math

in_array = [0, math.pi / 2, np.pi / 3, np.pi]
print ("Radian values : \n", in_array)

degree_Values = np.degrees(in_array)
print ("\nDegree values : \n", degree_Values)
```

Radian values :

[0, 1.5707963267948966, 1.0471975511965976, 3.141592653589793]

Degree values :

[0. 90. 60. 180.]

Q5. conversion from Degrees to Radian

In [29]: *# degrees() function*

```
import numpy as np
import math

in_array = np.arange(10.) * 90
print ("Degree values : \n", in_array)

radian_Values = np.radians(in_array)
print ("\nRadian values : \n", radian_Values)
```

Degree values :

```
[ 0.  90. 180. 270. 360. 450. 540. 630. 720. 810.]
```

Radian values :

```
[ 0.          1.57079633  3.14159265  4.71238898  6.28318531  7.85398163
 9.42477796 10.99557429 12.56637061 14.13716694]
```

In [30]: *#method2*

degrees() function

```
import numpy as np
import math

in_array = np.arange(10.) * 90
print ("Degree values : \n", in_array)

radian_Values = np.radians(in_array)
print ("\nRadian values : \n", radian_Values)
```

Degree values :

```
[ 0.  90. 180. 270. 360. 450. 540. 630. 720. 810.]
```

Radian values :

```
[ 0.          1.57079633  3.14159265  4.71238898  6.28318531  7.85398163
 9.42477796 10.99557429 12.56637061 14.13716694]
```

Q6. Hyperbolic Functions

This mathematical function helps user to calculate hypotenuse for the right angled triangle, given its side and perpendicular.

In [31]: *# hypot() function*

```
import numpy as np

leg1 = [12, 3, 4, 6]
print ("leg1 array : ", leg1)

leg2 = [5, 4, 3, 8]
print ("leg2 array : ", leg2)

result = np.hypot(leg1, leg2)
print("\nHypotenuse is as follows :")
print(result)
```

```
leg1 array : [12, 3, 4, 6]
leg2 array : [5, 4, 3, 8]
```

```
Hypotenuse is as follows :
[13.  5.  5. 10.]
```