### Mathematical Logic

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### **Outline**

Introduction

First-order logic

# **Short History of Logic**

- Logic is the study of reasoning.
- The first recorded use of logic was by Aristotle (384–322 BC).
- Aristotle explored the concept of arguing from premises to conclusions. He calls logic conclusions syllogisms.

### Syllogism

A syllogism is a statement in which certain things [the premises] are asserted, and something else [the conclusion] necessarily follows from what is asserted. By the last sentence, I mean that the premises result in the conclusion, and by that, I mean that no additional premise is required to make the conclusion unavoidable.

Example: If all humans are mortal, and Socrates is a human, then Socrates is mortal.



### **Propositional Logic**

Boole (1815–1864) introduced propositional logic in the 19th century.



### **Applications of Logic**

- Electronic circuit design
- Logic programming (e.g. Prolog)
- Expert systems (form of AI)
- Databases (e.g. SQL using first-order logic)
- Formal verification of software

## Language of first-order logic

A language  $\mathscr{L}$  of first-order logic consists of the following components:

- Variable symbols:  $x_1, x_2, \dots$
- For each  $n \in \mathbb{N}$ , a set of n-ary function symbols:  $f_0, f_1, \ldots$  The 0-ary function symbols are called constant symbols.
- For each  $n \in \mathbb{N}$ , a set of n-ary predicate symbols:  $p_0, p_1, \ldots$  The 0-ary predicate symbols are the constants  $\top$  (for **true**) and  $\bot$  (for **false**).
- special symbols:  $\neg$  (negation),  $\land$  (conjunction),  $\lor$  (disjunction),  $\rightarrow$  (implication),  $\leftrightarrow$  (equivalence),  $\forall$  (universal quantification),  $\exists$  (existential quantification), and parentheses.

#### **Terms**

The set of terms of  $\mathscr L$  is defined inductively as follows:

- Each variable is a term.
- If  $t_1, \ldots, t_n$  are terms and f is an n-ary function symbol, then if  $f(t_1, \ldots, t_n)$  is a term.

#### Variables in terms

We define a function var: Terms  $\rightarrow$  Variables that maps each term to the set of variables occurring in it. The function is defined as follows:

- $var(x) = \{x\}$  for each variable x.
- $var(f(t_1, \ldots, t_n)) = var(t_1) \cup \ldots \cup var(t_n)$ .

#### **Formulas**

The set of formulas of  $\mathcal L$  is defined inductively as follows:

- If  $t_1, \ldots, t_n$  are terms and p is an n-ary predicate symbol, then if  $p(t_1, \ldots, t_n)$  is a formula.
- If  $\varphi$  is a formula, then if  $\neg \varphi$  is a formula.
- If  $\varphi_1$  and  $\varphi_2$  are formulas, then if  $\varphi_1 \wedge \varphi_2$ ,  $\varphi_1 \vee \varphi_2$ ,  $\varphi_1 \to \varphi_2$ , and  $\varphi_1 \leftrightarrow \varphi_2$  are formulas.
- If  $\varphi$  is a formula and x is a variable, then if  $\forall x. \varphi$  and  $\exists x. \varphi$  are formulas.

An example of a formula is  $\forall x. \exists y. p(x,y) \rightarrow \neg q(y)$ .



### Interpretations

An interpretation  $\mathcal M$  of  $\mathscr L$  consists of the following components:

- A non-empty set D called the domain of  $\mathcal{M}$ .
- For each n-ary function symbol f of  $\mathscr{L}$ , a function  $f^{\mathcal{M}}: D^n \to D$ .
- For each n-ary predicate symbol p of  $\mathcal{L}$ , a relation  $p^{\mathcal{M}} \subseteq D^n$ .

### Interpretations of Terms

Let  $\mathcal M$  be an interpretation for our first-order language. An assignment  $\sigma$  of values to variables, i.e.,  $\sigma:Variables \to D$ . The value of a term t under  $\sigma$  is denoted by  $t^{\mathcal M}[\sigma]$  and defined as

- If t = x for a variable x, then  $t^{\mathcal{M}}[\sigma] = \sigma(x)$ .
- If  $t = f(t_1, \dots, t_n)$ , then  $t^{\mathcal{M}}[\sigma] = f^{\mathcal{M}}(t_1^{\mathcal{M}}[\sigma], \dots, t_n^{\mathcal{M}}[\sigma])$ .

follows:

# Validity of Formulas under Interpretations

We say an assignment  $\sigma$  satisfies a formula  $\varphi$  under an interpretation  $\mathcal{M}$ , denoted by  $\mathcal{M}, \sigma \models \varphi$ , iff the following conditions hold:

- $\varphi = p(t_1, \dots, t_n)$ , then if  $(t_1^{\mathcal{M}}[\sigma], \dots, t_n^{\mathcal{M}}[\sigma]) \in p^{\mathcal{M}}$ .
- $\varphi = \neg \psi$ , then if  $\mathcal{M}, \sigma \not\models \psi$ .
- $\varphi = \psi_1 \vee \psi_2$ , then if  $\mathcal{M}, \sigma \models \psi_1$  or  $\mathcal{M}, \sigma \models \psi_2$ .
- $\varphi = \psi_1 \wedge \psi_2$ , then if  $\mathcal{M}, \sigma \models \psi_1$  and  $\mathcal{M}, \sigma \models \psi_2$ .
- $\varphi = \psi_1 \to \psi_2$ , then if  $\mathcal{M}, \sigma \models \psi_1$  implies  $\mathcal{M}, \sigma \models \psi_2$ .
- $\varphi = \psi_1 \leftrightarrow \psi_2$ , then if  $\mathcal{M}, \sigma \models \psi_1$  if and only if  $\mathcal{M}, \sigma \models \psi_2$ .
- $\varphi = \forall x. \psi$ , then if  $\mathcal{M}, \sigma[x \mapsto d] \models \psi$  for all  $d \in D$ .
- $\varphi = \exists x. \psi$ , then if  $\mathcal{M}, \sigma[x \mapsto d] \models \psi$  for some  $d \in D$ .

A formula  $\varphi$  is satisfiable if there exists an interpretation  $\mathcal{M}$  and an assignment  $\sigma$  such that  $\mathcal{M}, \sigma \models \varphi$ .



#### Models

An interpretation  $\mathcal{M}$  is a model of a formula  $\varphi$ , denoted by  $\mathcal{M} \models \varphi$ , if for all assignments  $\sigma$ ,  $\mathcal{M}$ ,  $\sigma \models \varphi$ .

A formula is satisfiable if it has a model, i.e., if there exists an interpretation  $\mathcal M$  such that  $\mathcal M \models \varphi$ .

## Validity

A formula  $\varphi$  is valid if for all interpretations  $\mathcal{M}$  and all assignments  $\sigma$ ,  $\mathcal{M}, \sigma \models \varphi$ .

We write  $\models \varphi$  to denote that  $\varphi$  is valid.

### Free Variables in Fomulas

The set of free variables of a formula  $\varphi$ , denoted by  $FV(\varphi)$ , is defined inductively as follows:

- $FV(p(t_1,\ldots,t_n)) = var(t_1) \cup \ldots \cup var(t_n)$ .
- $FV(\neg \psi) = FV(\psi)$ .
- $FV(\psi_1 \wedge \psi_2) = FV(\psi_1) \cup FV(\psi_2)$ .
- $FV(\psi_1 \vee \psi_2) = FV(\psi_1) \cup FV(\psi_2)$ .
- $FV(\psi_1 \rightarrow \psi_2) = FV(\psi_1) \cup FV(\psi_2)$ .
- $FV(\forall x.\psi) = FV(\psi) \setminus \{x\}.$
- $FV(\exists x.\psi) = FV(\psi) \setminus \{x\}.$



### **Term Substitution**

Let  $\varphi$  be a formula, x a variable, and t a term. The formula  $\varphi[t/x]$  is obtained by replacing all occurrences of x in  $\varphi$  by t. The substitution is defined inductively as follows:

- $(p(t_1,\ldots,t_n))[t/x] = p(t_1[t/x],\ldots,t_n[t/x]).$
- $\bullet \ (\psi_1 \wedge \psi_2)[t/x] = \psi_1[t.x] \wedge \psi_2[t/x].$
- $(\psi_1 \vee \psi_2)[t/x] = \psi_1[t/x] \vee \psi_2[t/x]$ .
- $(\psi_1 \to \psi_2)[t/x] = \psi_1[t/x] \to \psi_2[t/x]$ .
- $(\forall y.\psi)[t/x] = \forall y.\psi[t/x] \text{ if } x \in FV(t).$
- $(\exists y.\psi)[t/x] = \exists y.\psi[t/x] \text{ if } x \in FV(t).$
- $(\forall x.\psi)[t/x] = \forall x.\psi.$
- $\bullet (\exists x.\psi)[t/x] = \exists x.\psi.$

So,  $\varphi[t/x]$  represents the formular obtained by substituting every **free** occurrence of the variable x in  $\varphi$  by the term t.

#### Calculus

A calculus is a mechanism to prove formulas by applying rules.

A rule of a calculus has the form  $\frac{\varphi_1,\ldots,\varphi_n}{\psi}$ , where  $\varphi_1,\ldots,\varphi_n$  are premises and  $\psi$  is the conclusion. The rule states that if  $\varphi_1,\ldots,\varphi_n$  are derivable, then  $\psi$  is derivable.

We denote that a formula can be proved by a calculus by  $\vdash \varphi$ .

We can also denote that a formula  $\varphi$  is derivable from a set of formulas (premises)  $\Gamma$  by  $\Gamma \vdash \varphi$ .

### Calculus of Natural Deduction

- inspired by the way humans reason
- goal is to prove a conclusion from a set of premises
- In a natural deduction proof the formula occurring at the root of the tree is called the conclusion, while the formulas at the leaves of the tree are its assumptions.
- In a natural deduction proof the assumptions can be of two kinds: canceled and uncanceled.
- When one starts building ones proof tree all assumptions are uncanceled, but in certain inferences one is allowed to cancel certain assumptions.

### Rules of Calculus of Natural Deduction

$$\frac{A \cap B}{A \wedge B} \wedge I$$

$$\frac{A \wedge B}{A} \wedge E_1$$

$$\frac{A \wedge B}{B} \wedge E_2$$

$$\frac{A \wedge B}{B} \vee I$$

$$\frac{A \vee B}{C} \wedge B \vdash C \vee E$$

$$\frac{A \vdash B}{A \rightarrow B} \rightarrow I$$

$$\frac{A \wedge B}{B} \rightarrow E$$

### Rules of the Calculus of Natural Deduction

$$\frac{A \vdash B \quad A \vdash \neg B}{\neg A} \neg I \qquad \qquad \frac{A \quad \neg A}{\bot} \neg E$$

$$\frac{\bot}{A} \bot I \qquad \qquad \frac{A}{\neg \neg A} \neg \neg I \ (\neg \neg E \ \text{analogously})$$

$$\underbrace{A[u/x] \text{ (for a variable } u \notin FV(A))}_{\forall x.A} \forall I \qquad \underbrace{\frac{\forall x.A}{A(t) \text{ for a term } t}} \forall E$$

$$\frac{\forall x.A}{A(t) \text{ for a term } t} \, \forall E$$

$$\underbrace{\frac{A[u/x] \text{ (for a variable } u \notin FV(A))}{\forall x.A}}_{\forall X.A} \forall I \qquad \underbrace{\frac{\forall x.A}{A(t) \text{ for a term } t}}_{\forall E}$$

$$\frac{\forall x.A}{A(t) \text{ for a term } t} \forall E$$

### Rules of the Calculus of Natural Deduction

$$\frac{A[t/x] \text{ (for a term } t)}{\exists x.A} \; \exists I$$
 
$$\frac{\exists x.A \quad A(u) \vdash B \text{ where } u \text{ is a variable not in } B}{B} \; \exists E$$

Example: I know that there is a Norwegian logician. I was able to infer from 'Skolem was Scandinavian and Logician'. Hence, from 'there exists a Norwegian logician', I can infer 'there exists a Scandinavian logician'.



### Example Proof via the Calculus of Natural Deduction

We want to show:  $((p \land q) \rightarrow q) \rightarrow r \vdash (p \land q) \rightarrow r$ 

$$\frac{\frac{[p \wedge q]^1}{q} \wedge E}{\frac{(p \wedge q) \to q}{r} \to I} \xrightarrow{((p \wedge q) \to q) \to r} \to E$$

### Sequent Calculus

- In sequent calculus, we have sequences Γ ⊢ Δ, where Γ and Δ are sets of formulas.
- The interpretation is that if all formulas in  $\Gamma$  are true, then at least one formula in  $\Delta$  is true.
- Proofs in sequent calculus are performed backwards: We start from the conclusion and apply rules to derive the premises.

# Sequent Calculus Rules

$$\overline{\Gamma, \varphi \Rightarrow \varphi, \Delta}$$
 Taut

$$\frac{\Box}{\Gamma, \bot \Rightarrow \Delta} \bot \Rightarrow$$

$$\frac{\Gamma\Rightarrow\Delta}{\varphi,\Gamma\Rightarrow\Delta}$$
 Weakening left

$$\frac{\varphi,\varphi,\Gamma\Rightarrow\Delta}{\varphi,\Gamma\Rightarrow\Delta}$$
 Contraction left

$$\frac{\Gamma, \varphi, \psi, \Pi \Rightarrow \Delta}{\Gamma, \psi, \varphi, \Pi \Rightarrow \Delta}$$
 Exchange left

$$\frac{\Gamma\Rightarrow\Delta,\varphi\quad\varphi,\Pi\Rightarrow\Lambda}{\Gamma,\Pi\Rightarrow\Delta,\Lambda}\operatorname{Cut}$$

$$T \Rightarrow \Delta, T \Rightarrow T$$

$$\frac{\Gamma\Rightarrow\Delta}{\Gamma\Rightarrow\Delta,\varphi}$$
 Weakening right

$$\frac{\Gamma\Rightarrow\Delta,\varphi,\varphi}{\Gamma\Rightarrow\Delta,\varphi}$$
 Contraction right

$$\frac{\Gamma\Rightarrow\Delta,\varphi,\psi,\Lambda}{\Gamma\Rightarrow\Delta,\psi,\varphi,\Lambda}$$
 Exchange right

## Sequent Calculus Rules

$$\frac{\Gamma, \bot \Rightarrow \Delta}{\Gamma, \bot \Rightarrow \Delta} \bot \Rightarrow$$

$$\frac{\Gamma \Rightarrow \Delta, \varphi}{\Gamma, \neg \varphi \Rightarrow \Delta} \neg \Rightarrow$$

$$\frac{\Gamma, \varphi \Rightarrow \Delta}{\Gamma, \varphi \lor \psi \Rightarrow \Delta} \lor \Rightarrow$$

$$\frac{\Gamma, \varphi, \psi \Rightarrow \Delta}{\Gamma, \varphi \land \psi \Rightarrow \Delta} \land \Rightarrow$$

$$\frac{\Gamma\Rightarrow\Delta,\varphi\quad\psi,\Pi\Rightarrow\Lambda}{\varphi\rightarrow\psi,\Gamma,\Pi\Rightarrow\Delta,\Lambda}\rightarrow\Rightarrow$$

$$\frac{\Box}{\Gamma \Rightarrow \Delta . \top} \Rightarrow \top$$

$$\frac{\Gamma, \varphi \Rightarrow \Delta}{\Gamma \Rightarrow \Delta, \neg \varphi} \Rightarrow \neg$$

$$\frac{\Gamma \Rightarrow \Delta, \varphi, \psi}{\Gamma \Rightarrow \Delta, \varphi \vee \psi} \Rightarrow \vee$$

$$\frac{\Gamma\Rightarrow\Delta,\varphi\quad\Gamma\Rightarrow\Delta,\psi}{\Gamma\Rightarrow\Delta,\varphi\wedge\psi}\Rightarrow\wedge$$

$$\frac{\Gamma, \varphi \Rightarrow \Delta, \psi}{\Gamma \Rightarrow \Delta, \varphi \rightarrow \psi} \Rightarrow \rightarrow$$

## Sequent Calculus Rules

$$\frac{\Gamma, \varphi[t/x] \Rightarrow \Delta}{\Gamma, \forall x. \varphi(x) \Rightarrow \Delta} \, \forall \Rightarrow$$

$$\frac{\Gamma, \varphi[y/x] \Rightarrow \Delta}{\Gamma \ \exists x \ \varphi(x) \Rightarrow \Delta} \ \exists \Rightarrow$$

$$\frac{\Gamma \Rightarrow \Delta, \varphi[y/x]}{\Gamma \Rightarrow \Delta, \forall x. \varphi(x)} \Rightarrow \forall$$

$$\frac{\Gamma \Rightarrow \Delta, \exists x. \varphi(x), \varphi[t/x]}{\Gamma \Rightarrow \Delta, \exists x. \varphi(x)} \Rightarrow \exists$$

In the quantifier rules, t is a term, and y is a 'fresh' variable, i.e., a variable that does not occur in  $\Gamma$ ,  $\Delta$ , or  $\varphi$ .

Alternatively, the rules can also be stated in the form

$$\frac{\Gamma \Rightarrow \Delta, \varphi}{\Gamma \Rightarrow \Delta, \forall x. \varphi(x)} \Rightarrow \forall$$

Here, it must be guaranteed that x is not free in any formula in  $\Gamma$  or  $\Delta$ . The existential formula can be handled similarly.

# Example Deduction: $\forall x.(P(x) \land Q \Rightarrow \forall x.P(x)$

$$\frac{\overline{P(x),Q\Rightarrow P(x)}}{P(x)\land Q\Rightarrow P(x)} \land \Rightarrow}{\frac{\overline{P(x)\land Q\Rightarrow P(x)}}{\forall x.(P(x\land Q)\Rightarrow P(x))}} \forall \Rightarrow}{\forall x.(P(x)\land Q)\Rightarrow \forall x.P(x)} \Rightarrow \forall$$

Here,  $\forall \Rightarrow$  uses [x/x] as replacement, i.e., just the same free variable is taken.

# Example Deduction: $\forall x.(A \rightarrow B) \Rightarrow A \rightarrow \forall x.B$

Here, the application of  $\Rightarrow \forall$  requires that x is not free in A.



## Example of a Failing Deduction:

$$\exists x. P(x) \land \exists x. Q(x) \Rightarrow \exists x. (P(x) \land Q(x))$$

$$\frac{P(x),Q(y)\Rightarrow P(x)\land Q(x)}{P(x),Q(y)\Rightarrow \exists x.(P(x)\land Q(x))}\Rightarrow \exists}{P(x),\exists x.Q(x)\Rightarrow \exists x.(P(x)\land Q(x))}\exists \Rightarrow} \exists \Rightarrow \frac{\exists x.P(x),\exists x.Q(x)\Rightarrow \exists x.(P(x)\land Q(x))}\exists \Rightarrow}{\exists x.P(x)\land \exists x.Q(x)\Rightarrow \exists x.(P(x)\land Q(x))}\land \Rightarrow}$$

Here, the deduction fails because the variable x is not fresh in the application of  $\exists \Rightarrow$  and therefore the new variable y is introduced. However, then the deduction cannot be completed.

## Soundness and Completeness of Sequent Calculus

- A calculus is sound if all provable formulas are valid, denoted by  $\vdash \varphi \Rightarrow \models \varphi$ .
- A calculus is complete if all valid formulas are provable, denoted by  $\models \varphi \Rightarrow \vdash \varphi$ .

The sequent calculus is sound and complete for first-order logic, i.e.,

- $\bullet \vdash \Gamma \Rightarrow \Delta$ , then  $\models \Gamma \Rightarrow \Delta$ .
- $\bullet \models \Gamma \Rightarrow \Delta$ , then  $\models \Gamma \Rightarrow \Delta$ .

Proof of soundness by induction on the structure of the formulas. Proof of completeness by constructing a Herbrand model.



## Goedel's Incompleteness Theorem

- Goedel's first incompleteness theorem states that in any consistent formal system that is powerful enough to express arithmetic, there are true statements that cannot be proven.
- Goedel's second incompleteness theorem states that in any consistent formal system that is powerful enough to express arithmetic, the system cannot prove its own consistency.

#### Rice's Theorem

- Rice's theorem states that for any non-trivial property of partial functions, i.e., a property that is not true for all partial functions or not true for none, there is no algorithm that can decide whether a given program has that property.
- A property is non-trivial if there are two partial functions that are computable and one has the property and the other does not.

### Halting Problem

The halting problem is the problem of determining, given a program and an input, whether the program will eventually halt when run with that input.

The halting problem is undecidable, i.e., there is no algorithm that can decide whether a given program halts on a given input.

#### Some Conclusions

- There are properties of programs that cannot be decided by an algorithm.
- There are properties of programs that cannot be verified by a formal system.
- It is impossible to generally prove behavioural equivalence of programs.