

# Classifying Polarized Satellite Images of Iceberg and Ship

A Combination of  
Transfer Learning with  
Traditional Approaches

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MCM (Data Analytics)  
Module - CA640

Dublin City University

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# Outline

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Introduction

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Previous Work

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Implications

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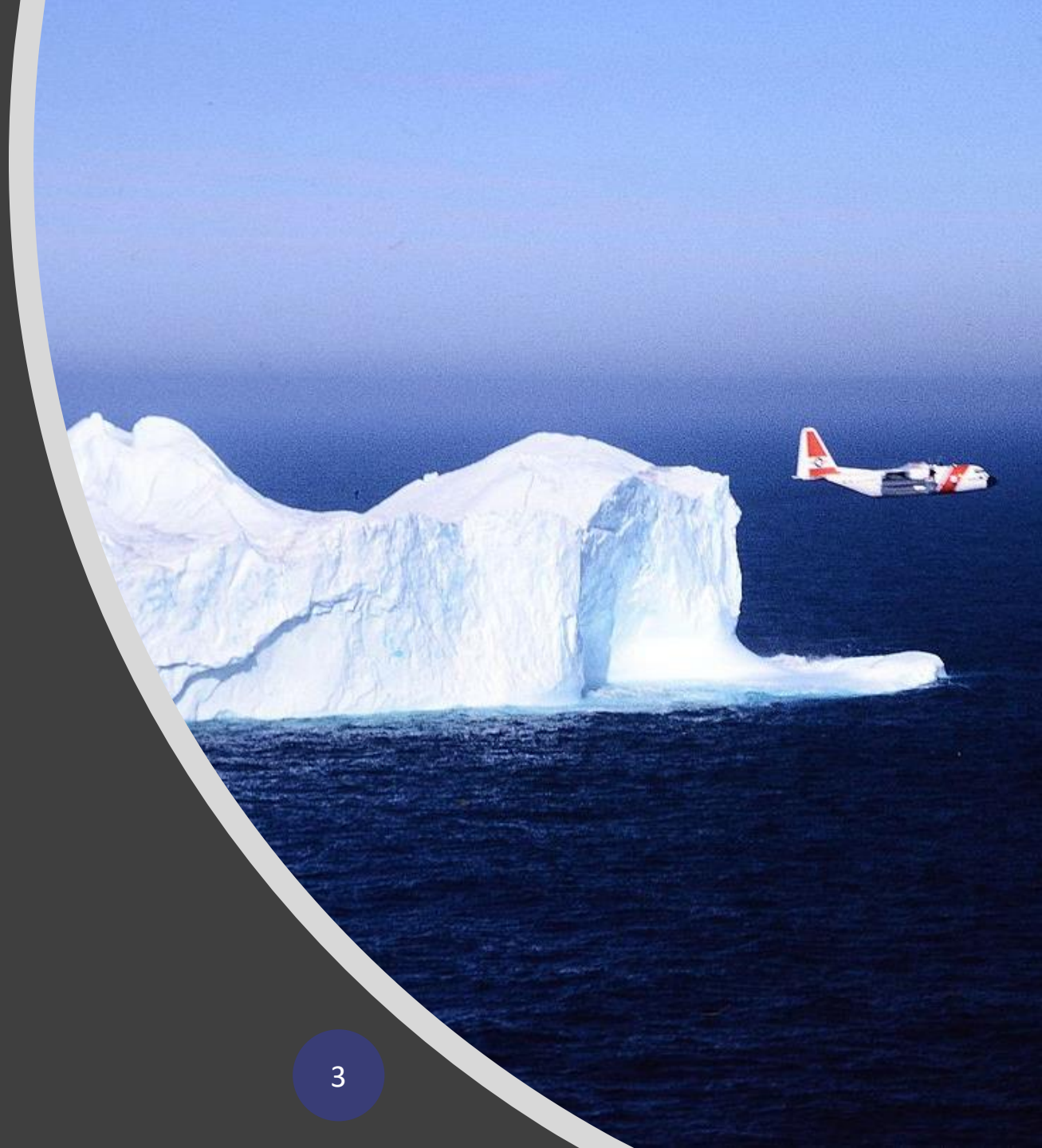
Conclusion

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Appendix

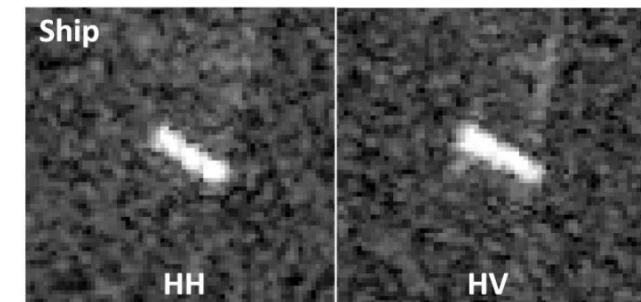
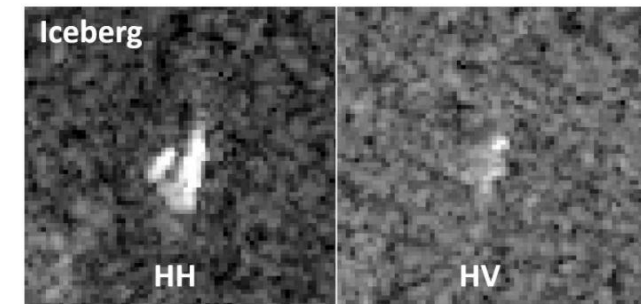
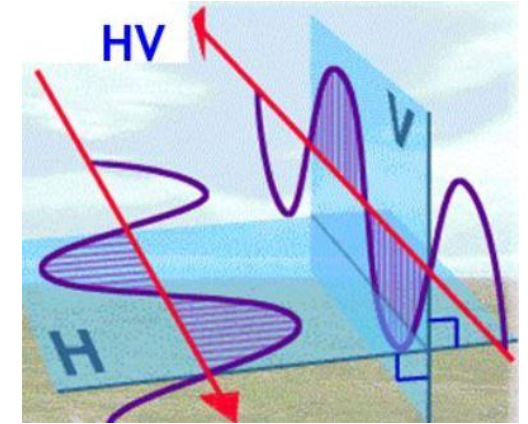
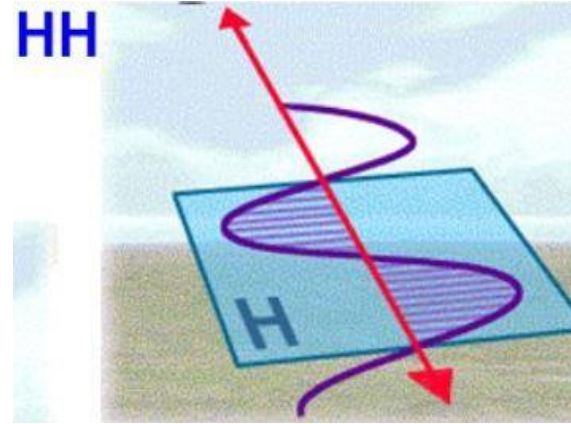
# Introduction

- Drifting icebergs
- Titanic and Hans Hedtoft disaster
- International Ice Patrol and Greenland Ice Service
- Synthetic Aperture Radar(SAR)
- Integration of data analytics
- Reduce the risk, cost and carbon footprint



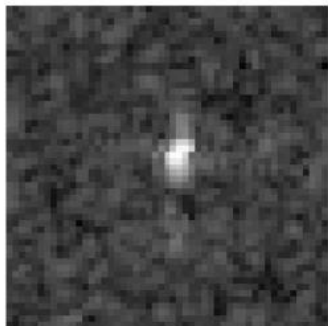
# Data

- C-band dual-polarization images
- Two channels:
  - HH (transmit and receive horizontally)
  - HV (transmit horizontally and receive vertically)
- Can See through cloud, fog, rain and even darkness.

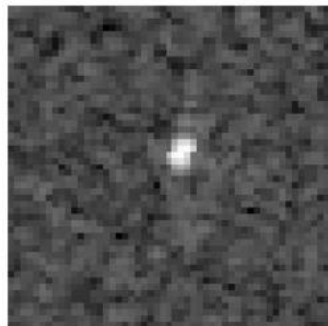


# The Challenge!

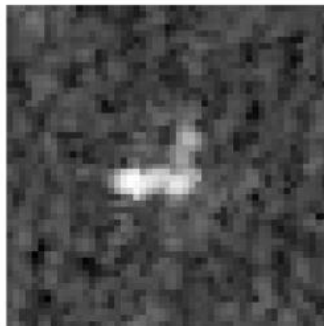
ship\_HH



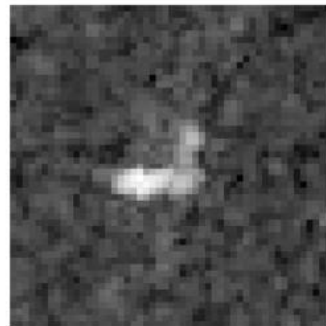
ship\_HV



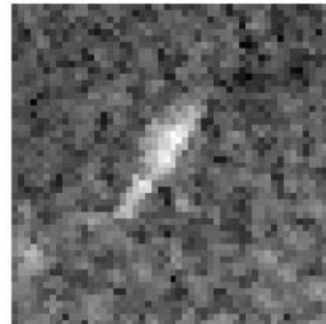
ship\_HH



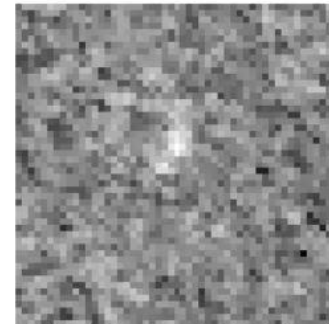
ship\_HV



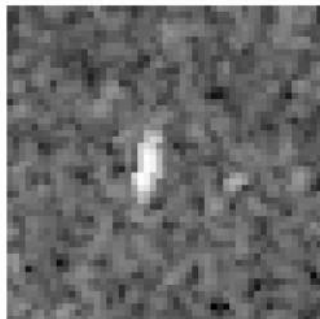
iceberg\_HH



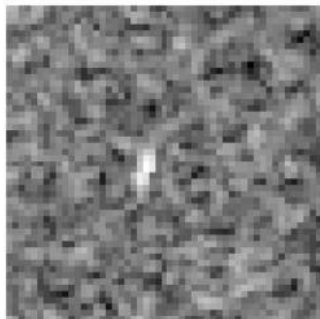
iceberg\_HV



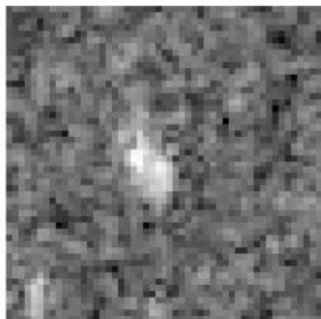
ship\_HH



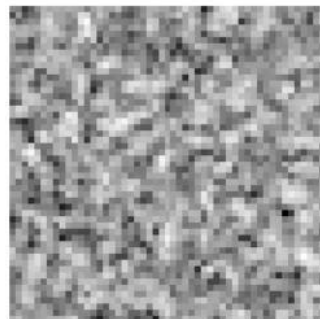
ship\_HV



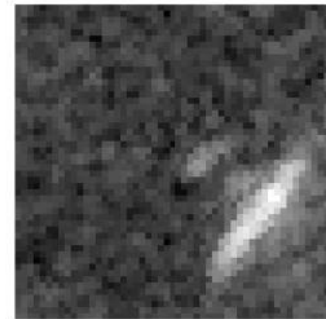
ship\_HH



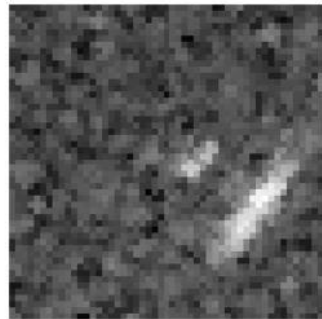
ship\_HV



iceberg\_HH



iceberg\_HV



# Previous work

- Data
  - ENVISAT
  - RADARSAT-2
  - TerraSAR-X
  - Urban Atlas
- Methods
  - Traditional
  - ANN, CNN
- Evaluation
  - Accuracy, F1

# Purpose

## Hypothesis

- Transfer Learning + Traditional Features Improves performance

## Object Detection - noisy images

## Applications

- Atmospheric observation
- Earth remote sensing
- Medical diagnosis
- Surveillance and reconnaissance
- Image de-hazing and 3D reconstruction



# Data Collected

Statoil/C-CORE on Kaggle

1604 Samples

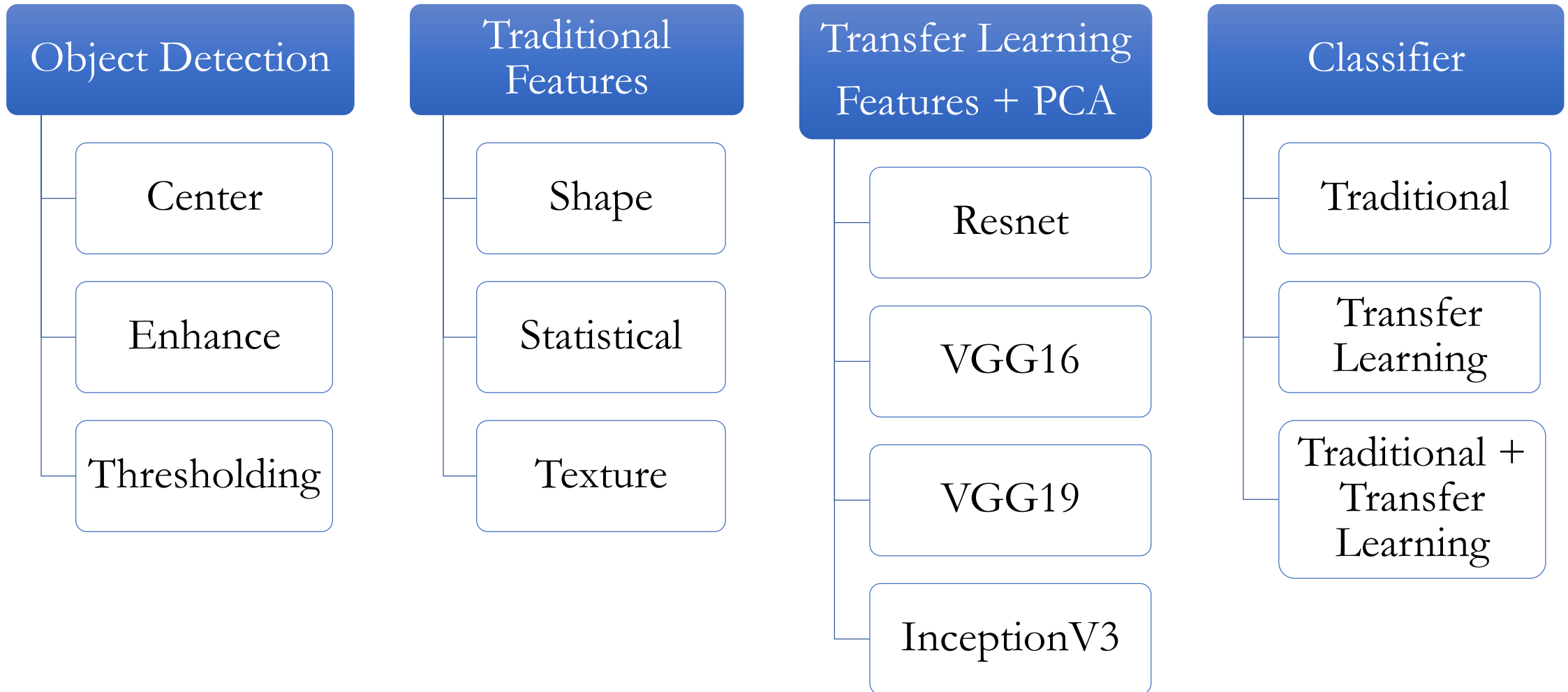
- Iceberg – 753
- Ship - 851
- json

Each Sample

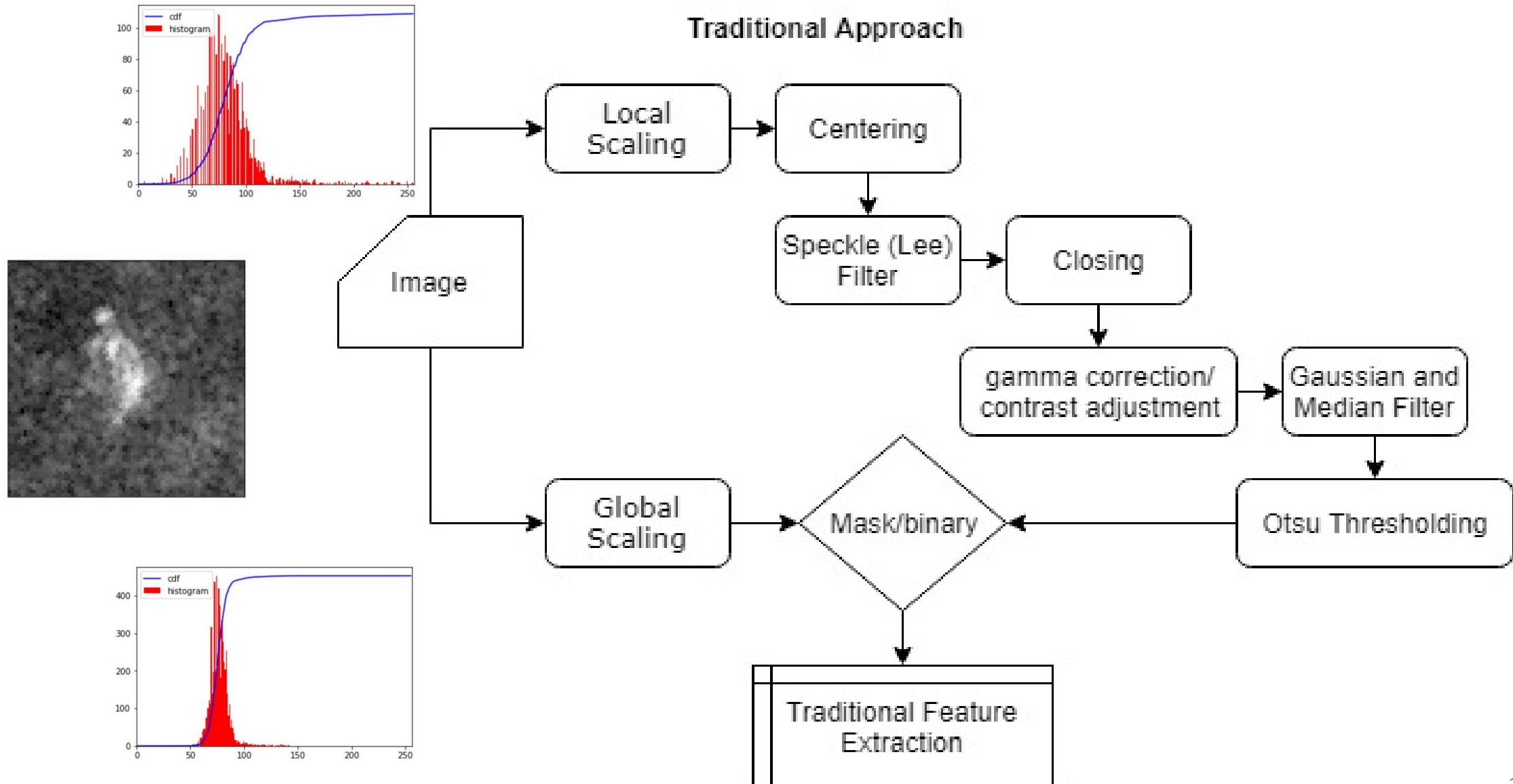
- HH & HV
- 75 X 75 pixels
- decibels (-45, 34)
- hand label



# Proposed Methods

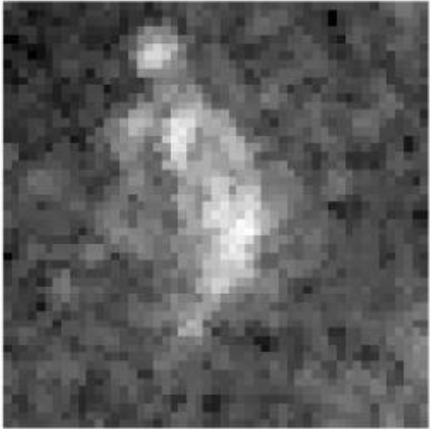


# Object Detection - Overview

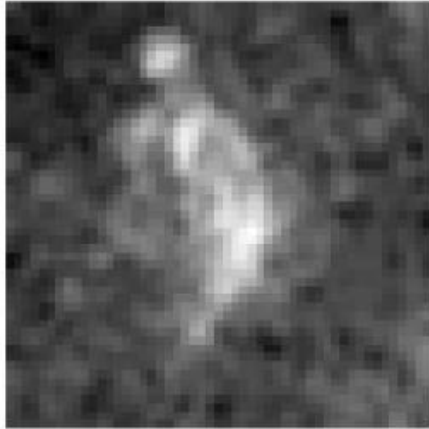


# Object Detection - Sample

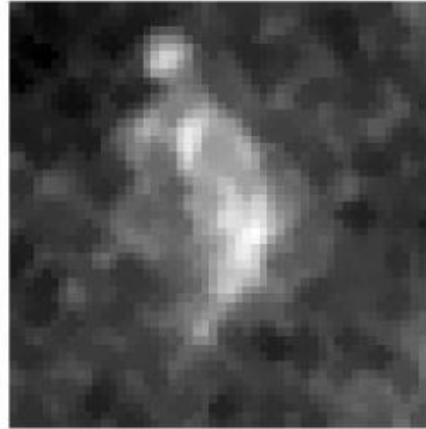
Original Image



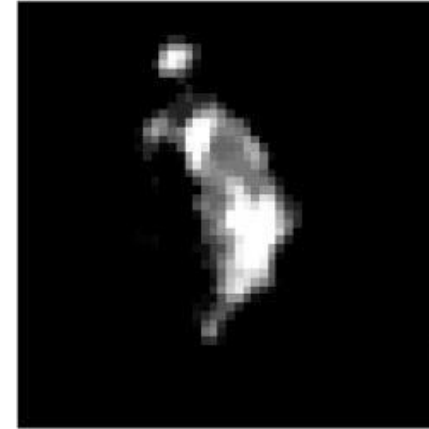
Lee Filtered



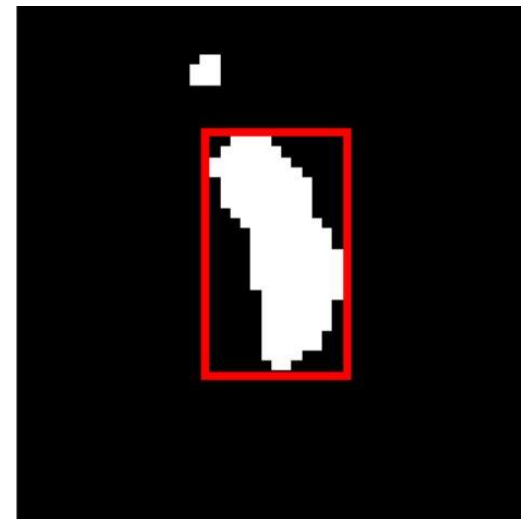
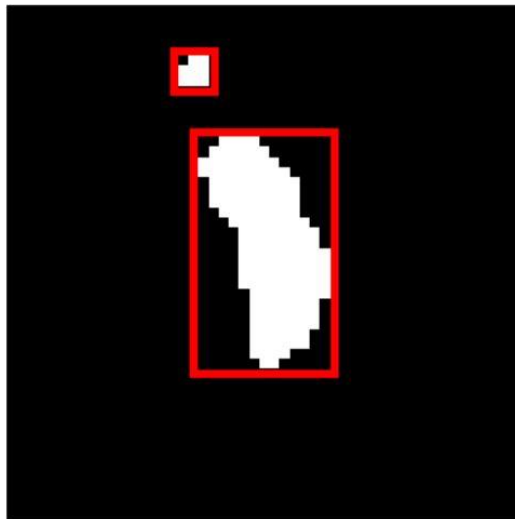
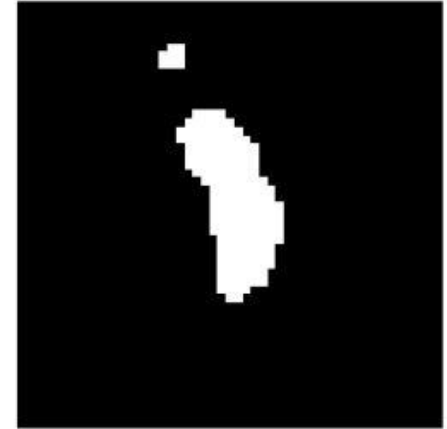
Closing

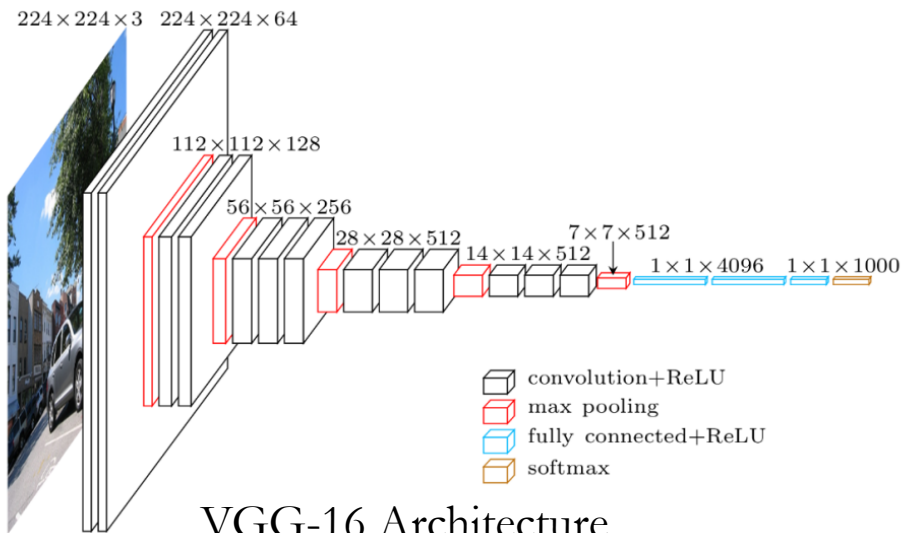


Contrast Adjusted

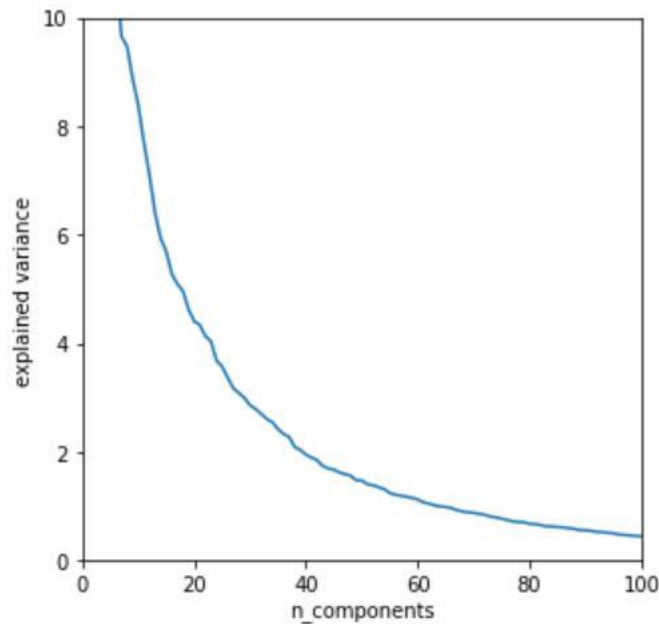


Otsu Threshold





VGG-16 Architecture

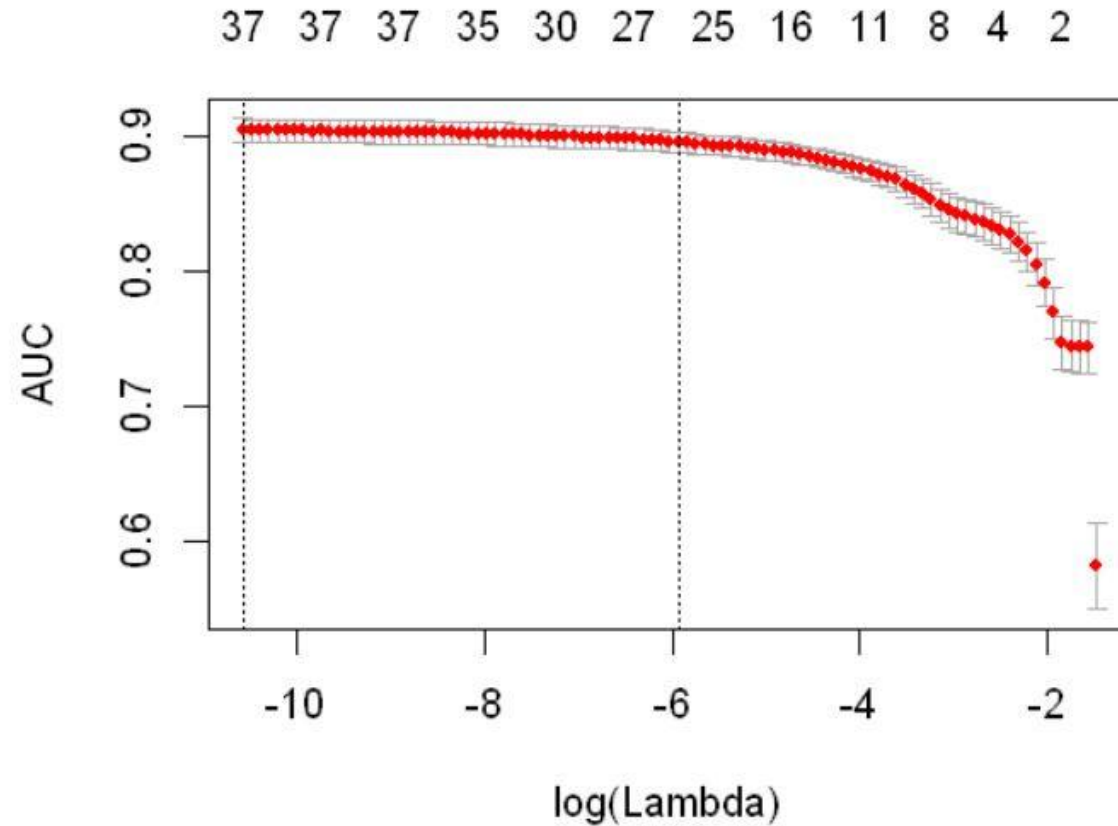


# Transfer Learning – PCA

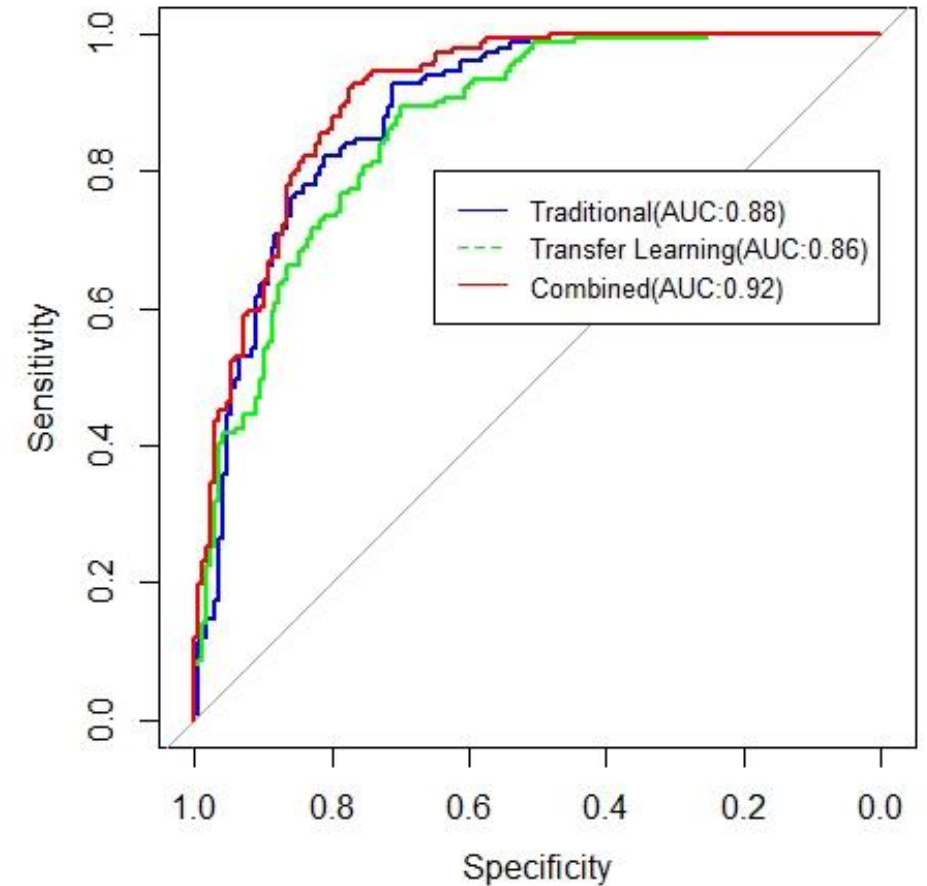
- Architectures
  - Resnet
  - VGG16
  - VGG19
  - InceptionV3
- Embeddings > 25,000
- 50 comp > 97% variance explained

# Classifier

- Logistic Regression
  - Regularization(Lasso)
- Train - 80%
  - 10-fold validation
- Test - 20%
- Evaluation - AUC



Features	Count	Train AUC	Test AUC
Traditional	38	0.9	0.88
Resnet	50	0.84	0.76
VGG16	50	0.84	0.79
VGG19	50	0.77	0.72
InceptionNet	50	0.88	0.86
Traditional + Resnet	88	0.92	0.89
Traditional + VGG16	88	0.92	0.89
Traditional + VGG19	88	0.9	0.89
Traditional + InceptionNet	88	0.94	0.92



## Results

# Discussion

- Generalized Object Detection – Noisy Image
- InceptionV3 - better feature representation
- Feature not problem-independent
- Logistic regression with L1 regularization
  - Handles Multicollinearity
  - Feature Selection

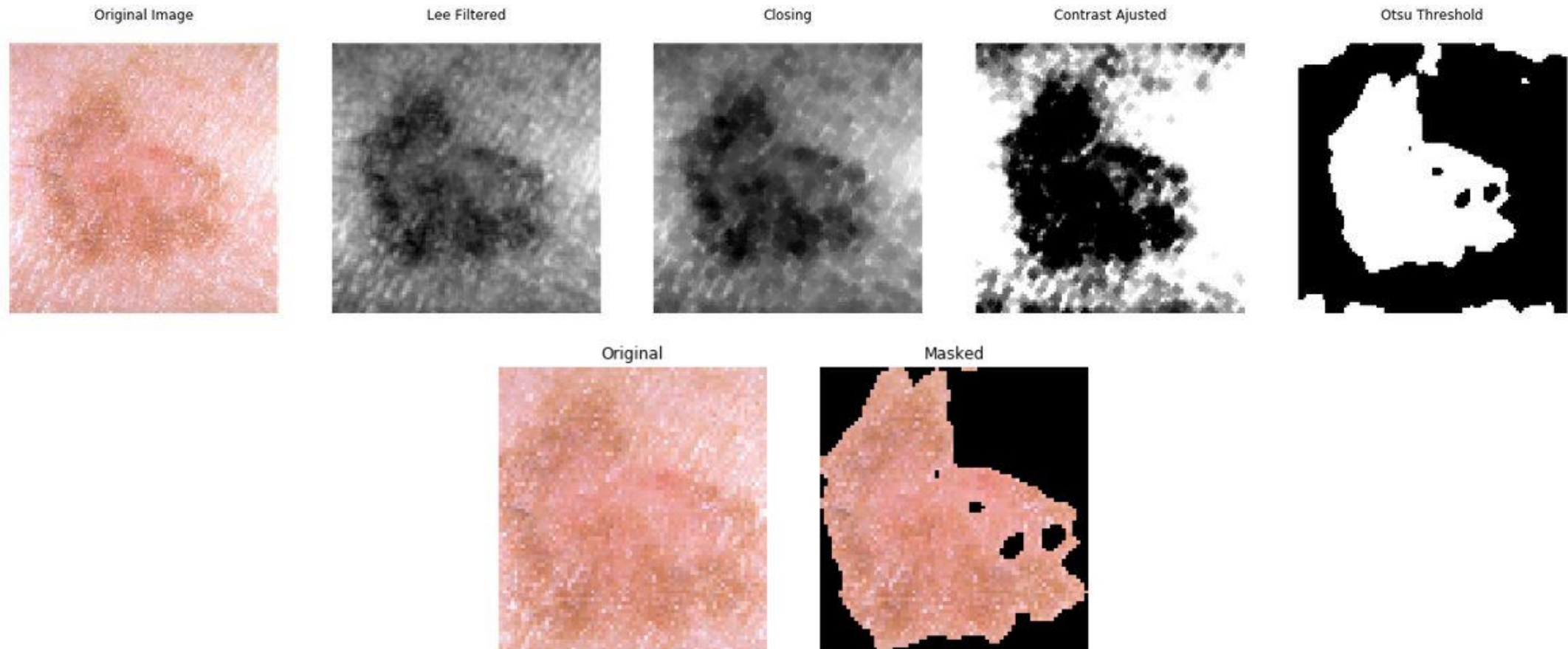


# Limitations

- Traditional Features – Specific to domain
- Identify Right Features
- Transfer Learning
  - Assumption
  - More data to fine-tune network
  - Trial/Error - layers

# Implications

- Object Detection for Medical Imaging



# Conclusion

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Reliable Object Detection

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Traditional methods

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Transfer Learning (InceptionV3)

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Combined - Improve Predictability (AUC – 4%)

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Safe navigation & serve maritime security

# Questions?

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# Thank You