TechPart Vision: Final Project Report

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1. Introduction

1.1 Project Overviews

The project "TechPart Vision" aims to develop a robust image classification model to accurately classify and identify various personal computer(PC) parts. Utilizing the EfficientNet architecture and transfer learning techniques, this project leverages pre-trained models to enhance classification accuracy and efficiency.

1.2 Objectives

- To build a high-accuracy image classification model for PC parts.
- To aid in activities such as invemtory management, online shopping and technical support.

2. Project Initialization and Planning Phase

2.1 Define Problem Statement

The primary challenge addressed by this project is the automatic and accurate identification of personal computer parts from images, which is essential for inventory management, online marketplaces, and technical support.

2.2 Project Proposal (Proposed Solution)

The proposed solution involves using EfficientNet for transfer learning to develop a classification model that can identify different PC parts. The model will be trained on a labelled dataset of PC part images and will undergo several optimizations to achieve high accuracy.

2.3 Initial Project Planning

- Identify and collect a diverse dataset of PC part images.
- Data preprocessing to bring it up to standard
- Choosing the appropriate model for high accuracy and efficiency
- Evaluation/validation followed by deployment

3. Data Collection and Preprocessing Phase

3.1 Data Collection Plan and Raw Data Sources Identified

Dataset was collected from Kaggle, whose raw data was scraped from google images.

3.2 Data Quality Report

- Dataset had issues such as missing values and inconsistent image sizes.
- Solutions such as resizing images, and reducing the number to match the least represented group were implemented.

3.3 Data Preprocessing

- Resizing and normalizing images for consistent input to the model.
- Augmenting the dataset with transformations such as rotations, flips, and brightness adjustments to enhance model robustness.
- Splitting the dataset into training, validation, and test sets.

4. Model Development Phase

4.1 Model Selection Report

Initial Model: Custom CNN

Structure:

- Layers: Convolutional, MaxPooling, Dropout, Flatten, Dense
- Activation: ReLU (convolutional and dense), Softmax (final dense)
- Optimizer: Adam
- Loss Function: Categorical cross-entropy
- Training: 10 epochs, batch size 32, verbose 1

Performance:

• Result: Underfitting; low accuracy

Transition to EfficientNetV2B1

Rationale:

- Selected for its efficiency and performance, suitable for deployment with limited resources
- Utilizes pre-trained ImageNet weights for transfer learning
- Enhanced accuracy with fewer training samples

Custom Layers Added:

- GlobalAveragePooling for dimension reduction
- BatchNormalization for training stability
- Dense layer with ReLU and regularization to prevent overfitting
- Dropout layer for further overfitting reduction
- Softmax activation in output layer for classification into 14 categories

Performance:

- Significant improvement in training and validation accuracy and loss
- Outperformed VGG19

Comparison with VGG19

Structure:

- VGG19 without top classification layer (include_top=False)
- Added: GlobalAveragePooling2D, two Dense layers (1024 units with ReLU, final layer with softmax)

Performance:

• Initial improvements but validation accuracy plateaued, indicating overfitting

Transition Justification:

• EfficientNetV2B1 showed better training and validation accuracy, justifying its selection over VGG19.

4.2. Initial Model Training Code, Model Validation and Evaluation Report

```
from tensorflow.keras.applications import VGG19
from tensorflow.keras.models import Model
from tensorflow.keras.layers import Dense, GlobalAveragePooling2D
from tensorflow.keras.optimizers import Adam
base_model = VGG19(weights='imagenet', include_top=False, input_shape=(224, 224, 3))

x = base_model.output
x = GlobalAveragePooling2D()(x)
x = Dense(1024, activation='relu')(x)
predictions = Dense(len(train_gen.class_indices), activation='softmax')(x)

model = Model(inputs=base_model.input, outputs=predictions)

for layer in base_model.layers:
    layer.trainable = False

model.compile(optimizer=Adam(learning_rate=0.001),
    loss='categorical_crossentropy',
    metrics=['accuracy'])

model.summary()
```

5. Model Optimization and Tuning Phase

5.1 Tuning Documentation

CNN Sequential model:

Convolutional Layers: Number of Filters: 32; Kernel Size: 3 (first layer), 2 (second

layer); Activation Function: ReLU; Padding: Same

Pooling Layers: Pooling Size: 2

Regularization: Dropout Rate: 0.5

Dense Layers: Units: 128; Kernel Initializer: HeNormal

Output Layer: Units: 14

Training Parameters: Batch Size: 32; Number of Epochs: 10

EfficientnetV2B1:

Base Model

 Base Model: EfficientNetV2B1 (pretrained on ImageNet, used as a feature extractor)

Pooling

• Pooling: Max (global max pooling applied to the output of the base model)

Batch Normalization

• Axis: -1

Momentum: 0.99Epsilon: 0.001

Dense Layer

• Units: 256

Regularization

Kernel Regularization: 12(0.016)Activity Regularization: 11(0.006)

• Bias Regularization: 11(0.006)

Activation

• Activation Function: ReLU

Dropout

• Rate: 0.4

Output Layer

• Units: 14 (softmax activation for multi-class classification)

Optimizer

Optimizer: AdamaxLearning Rate: 0.001

Callbacks

- ReduceLROnPlateau:
 - o Monitor: "val_loss"
 - Factor: 0.4Patience: 2Min LR: 0.0
- EarlyStopping:
 - o Monitor: "val_loss"
 - o Patience: 2
 - o Restore Best Weights: True

Training Parameters

• Number of Epochs: 5

VGG19:

Base Model

- Base Model: VGG19 (pretrained on ImageNet, used as a feature extractor)
- Input Shape: (224, 224, 3)

Pooling

• Pooling: Global Average Pooling

Dense Layers

• Units: 1024

• Activation Function: ReLU

Output Layer

- Units: len(train gen.class indices)
- Activation Function: Softmax

Optimizer

Optimizer: AdamLearning Rate: 0.001

Loss Function

• Loss Function: Categorical Crossentropy

Metrics

Metrics: Accuracy

Freezing Layers

• Freezing Layers: Initially freeze all base model layers

5.2 Final Model Selection Justification

The comparison between VGG19 and EfficientNetV2B1 shows that EfficientNetV2B1 outperforms VGG19 in several key areas. EfficientNetV2B1 achieves higher training accuracy more quickly and maintains a relatively stable validation accuracy around 0.75, while VGG19's validation accuracy fluctuates and remains generally lower. Both models exhibit a significant decrease in training loss, but EfficientNetV2B1 starts with a higher value and decreases more sharply initially. Additionally, EfficientNetV2B1's validation loss shows a more consistent decrease, whereas VGG19's validation loss fluctuates after the initial decrease. Overall, EfficientNetV2B1 demonstrates better performance with higher and more stable validation accuracy and a consistent decrease in validation loss, indicating quicker and more reliable improvements compared to VGG19.

6. Results

This project was able to classify various PC parts such as keyboards, monitors, cables, RAM, HDD etc, and identify them with significant accuracy.



From website:



7. Advantages & Disadvantages

Advantages

- Significant accuracy in classifying PC parts.
- Efficient and fast training with EfficientNet.
- Transfer learning reduces the need for a large dataset.

Disadvantages

- Requires significant computational resources.
- Performance is dependent on the limited dataset.

8. Conclusion

The project successfully implemented EfficientNet for classifying PC parts with high accuracy. The model's performance demonstrated the effectiveness of transfer learning for image classification tasks.

9. Future Scope

- Extending the model to classify more types of PC parts.
- Integrating the model into real-time inventory or e-commerce systems.
- Exploring other advanced architectures and techniques for further improvement.

10. Appendix

4.1 Source Code

```
import pandas as pd
import numpy as np
from numpy import random
import os
from sklearn.metrics import confusion_matrix, classification_report
from sklearn.model_selection import train_test_split
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.layers import Dense, Activation, Dropout, Conv2D, MaxPooling2D, BatchNormalization
from tensorflow.keras.optimizers import Adam, Adamax
from tensorflow.keras.metrics import categorical crossentropy
from tensorflow.keras import regularizers
from tensorflow.keras.models import Model
from tensorflow.keras import backend as K
import albumentations as A
from sklearn.metrics import f1_score
import cv2
```

Loading Image set into colab from google.colab import drive drive.mount('/content/drive') Mounted at /content/drive !unzip /content/drive/MyDrive/archive.zip

```
directory="/content/pc_parts"

labels = os.listdir(directory)
labels
```

```
def read_data(folder):
    data, label, paths = [], [], []
    for 1 in labels:
        path = f"{folder}/{1}/"
        folder_data = os.listdir(path)
```

```
for l in labels:
    path = f"{folder}/{l}/"
    folder_data = os.listdir(path)
    for image_path in folder_data:
        img = cv2.imread(path + image_path)
        data.append(img)
        label.append(l)
        paths.append(os.path.join(directory, l, image_path))

return data, label, paths
```

```
import cv2
import matplotlib.pyplot as plt

def edge_detection(image):
    gray_image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)
    edges = cv2.Canny(gray_image, 100, 200)
    return edges

image_path = 'path_to_image.jpg'
image = cv2.imread(image_path)
edges = edge_detection(image)
```

```
all_data, all_labels, all_paths = read_data(directory)

df = pd.DataFrame({
    'image':all_data,
    'path': all_paths,
    'label': all_labels
})
```

```
train_df, dummy_df=train_test_split(df, train_size=.8, random_state=123, shuffle=True, stratify=df['label'])
    valid_df, test_df=train_test_split(dummy_df, train_size=.5, random_state=123, shuffle=True, stratify=dummy_df['label'])
print("Train dataset : ",len(train_df),"Test dataset : ",len(test_df),"Validation dataset : ",len(valid_df))
train_balance=train_df['label'].value_counts()
print('Train dataset value count: \n',train_df['label'].value_counts())
Train dataset : 2623 Test dataset : 328 Validation dataset : 328
Train dataset value count:
 label
cables
                      238
speakers
                      237
keyboard
headset
hdd
                      210
monitor
                      205
motherboard
microphone
mouse
webcam
gpu
                     114
Name: count, dtype: int64
```

```
import plotly.express as px

px.histogram(train_df, x='label', barmode='group')
```

Data Augmentation

```
import cv2
import numpy as np
```

```
def apply_transform(image):
    # Rotate (random angle between -40 and 40 degrees)
    angle = np.random.uniform(-40, 40)
    rows, cols = image.shape[:2]
    M = cv2.getRotationMatrix2D((cols / 2, rows / 2), angle, 1)
    image = cv2.warpAffine(image, M, (cols, rows))

# Horizontal Flip
    if np.random.rand() < 0.5:
        image = cv2.flip(image, 1)

# Vertical Flip

if np.random.rand() < 0.5:
        image = cv2.flip(image, 0)

# Random Brightness and Contrast
        alpha = 1.0 + np.random.uniform(-0.2, 0.2) # Brightness
        beta = 0.0 + np.random.uniform(-0.2, 0.2) # Contrast
        image = cv2.convertScaleAbs(image, alpha=alpha, beta=beta)

# Random Gamma Correction
    gamma = np.random.uniform(0.8, 1.2)
    image = np.clip((image / 255.0) ** gamma, 0, 1) * 255.0

    return image</pre>
```

```
def apply_augmentation(image_path, label):
    image = cv2.imread(image_path)
    image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
    augmented_image = apply_transform(image=image)
    return augmented_image, label
```

```
augmented_data = []
for index, row in train_df.iterrows():
    image_path = row['path']
    label = row['label']
    augmented_image, augmented_label = apply_augmentation(image_path, label)
    augmented_data.append((augmented_image, augmented_label, image_path))

augmented_df = pd.DataFrame(augmented_data, columns=['object', 'label', 'path'])

merged_df = pd.concat([train_df, augmented_df], ignore_index=True)
```

```
import cv?
import matplotlib.pyplot as plt

def denoise_image(image):
    denoised_image = cv2.fastNlMeansDenoisingColored(image, None, 10, 10, 7, 21)
    return denoised_image

image_path = 'path_to_image.jpg'
image = cv2.imread(image_path)
denoised_image = denoise_image(image)

from collections import Counter

class_counts = Counter(merged_df['label'])
min_class_count = min(class_counts.values())

balanced_data = []
for label, count in class_counts.items():
    class_samples = merged_df[merged_df['label'] == label].sample(min_class_count)
    balanced_data.append(class_samples)

balanced_df = pd.concat(balanced_data)
```

```
balanced_df['label'].value_counts()
label
mouse
         228
keyboard
motherboard
         228
microphone
webcam
         228
         228
cables
ram
gpu
         228
speakers
Name: count, dtype: int64
  gen=ImageDataGenerator()
```

```
CNN Model
    from keras.models import Sequential
    from keras.layers import Dense, Activation, Dropout, Flatten
    from keras.layers import Convolution2D, MaxPooling2D
    import tensorflow as tf
    initializer = tf.keras.initializers.HeNormal()
    model=Sequential()
    model.add(Convolution2D(filters=32, kernel_size=3, padding='same', activation="relu",
                              input_shape=(255, 255, 3)))
    model.add(MaxPooling2D(strides=2, pool_size=2, padding= "valid"))
    model.add(Convolution2D(filters=32, kernel_size=2, padding='same', activation="relu"))
    model.add(MaxPooling2D(strides=2, pool_size=2, padding="valid"))
    model.add(Dropout(0.5))
    model.add(Flatten())
    model.add(Dense(128, activation='relu', kernel_initializer=initializer))
    model.add(Dropout(0.5))
    model.add(Dense(14, activation='softmax'))
    model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'])
```

```
history = model.fit(train_gen, validation_data= val_gen, batch_size= 32, epochs = 10, verbose = 1)
 Epoch 1/10
 100/100 [=
                                          ===] - 18s 106ms/step - loss: 97.1222 - accuracy: 0.0702 - val_loss: 2.6387 - val_accuracy: 0.0823
 Epoch 2/10
 100/100 [==
                                      ======] - 10s 97ms/step - loss: 2.6393 - accuracy: 0.0667 - val_loss: 2.6387 - val_accuracy: 0.0823
 Epoch 3/10
 100/100 [==
                                 =======] - 10s 101ms/step - loss: 2.6402 - accuracy: 0.0674 - val_loss: 2.6388 - val_accuracy: 0.0823
 Fnoch 4/10
 100/100 [==
                                           ==] - 10s 100ms/step - loss: 2.6393 - accuracy: 0.0708 - val loss: 2.6388 - val accuracy: 0.0823
 Epoch 5/10
 100/100 [==
                                      ======] - 9s 90ms/step - loss: 2.6393 - accuracy: 0.0620 - val_loss: 2.6389 - val_accuracy: 0.0823
 Epoch 6/10
 100/100 [==
                                           ==] - 11s 107ms/step - loss: 2.6393 - accuracy: 0.0689 - val_loss: 2.6390 - val_accuracy: 0.0427
 Epoch 7/10
                               100/100 [===
 Fnoch 8/10
                                           ==] - 10s 97ms/step - loss: 2.6394 - accuracy: 0.0636 - val_loss: 2.6389 - val_accuracy: 0.0915
 100/100 [==
 Epoch 9/10
 100/100 [==
                                    :======] - 10s 100ms/step - loss: 2.6393 - accuracy: 0.0711 - val_loss: 2.6390 - val_accuracy: 0.0823
 Epoch 10/10
 100/100 [==
                                           ==] - 10s 99ms/step - loss: 2.6393 - accuracy: 0.0623 - val_loss: 2.6390 - val_accuracy: 0.0823
EfficientNetV2B1 Model Initialisation
    base_model=tf.keras.applications.EfficientNetV2B1(include_top=False, weights="imagenet",input_shape=(255,255,3), pooling='max')
    print('Created EfficientNetV2 B1 model')
 Created EfficientNetV2 B1 model
    x=base model.output
    x=oase_model.eacper
x=BatchNormalization(axis=-1, momentum=0.99, epsilon=0.001)(x)
x = Dense(256, kernel_regularizer = regularizers.l2(l = 0.016),activity_regularizer=regularizers.l1(0.006),
bias_regularizer=regularizers.l1(0.006),activation='relu')(x)
    | blas_regularizer.egularizers.ii(0.000) ,activation='teld')(x)
| var="report(rate=.4, seed=123)(x)
| output=Dense(14, activation='softmax')(x)
| model=Model(inputs=base_model.input, outputs=output)
| model.compile(Adamax(learning_rate=0.001), loss='categorical_crossentropy', metrics=['accuracy'])
                                                                                                                                                    Python
    rlronp=keras.callbacks.ReduceLROnPlateau( monitor="val_loss", factor=0.4, patience=2, verbose=1, mode="auto", min_delta=0.00001, cooldown=0, min_lr=0.0 estop=keras.callbacks.EarlyStopping( monitor="val_loss", min_delta=0, patience=2, verbose=1, mode="auto", baseline=None, restore_best_weights=True)
    callbacks=[rlronp, estop]
    history=model.fit(x=train_gen, epochs=5, verbose=1, callbacks=callbacks, validation_data=val_gen, | validation_steps=None, shuffle=True)
                                      ===] - 94s 423ms/step - loss: 8.3989 - accuracy: 0.5595 - val_loss: 7.3195 - val_accuracy: 0.7043 - lr: 0.0010
 100/100 [=
 100/100 [=
                            =========] - 33s 330ms/step - loss: 6.1665 - accuracy: 0.8233 - val_loss: 5.9759 - val_accuracy: 0.7134 - lr: 0.0010
 Epoch 3/5
 100/100 [=
                                       :==] - 33s 334ms/step - loss: 4.8552 - accuracy: 0.9032 - val_loss: 4.9639 - val_accuracy: 0.7317 - lr: 0.0010
 Epoch 4/5
                                       :==] - 34s 335ms/step - loss: 3.8550 - accuracy: 0.9258 - val_loss: 4.1046 - val_accuracy: 0.7256 - lr: 0.0010
 100/100 [=
                      100/100 [==:
```

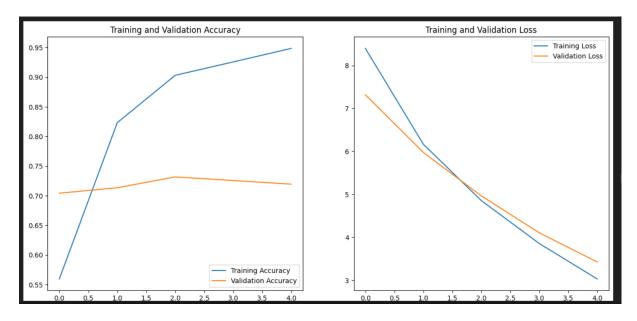
import matplotlib.pyplot as plt

```
acc = history.history['accuracy']
val_acc = history.history['val_accuracy']
loss = history.history['loss']
val_loss = history.history['val_loss']

epochs_range = range(5)

plt.figure(figsize=(15, 15))
plt.subplot(2, 2, 1)
plt.plot(epochs_range, acc, label='Training Accuracy')
plt.plot(epochs_range, val_acc, label='Validation Accuracy')
plt.legend(loc='lower right')
plt.title('Training and Validation Accuracy')

plt.plot(epochs_range, loss, label='Training Loss')
plt.plot(epochs_range, val_loss, label='Validation Loss')
plt.legend(loc='upper right')
plt.title('Training and Validation Loss')
plt.title('Training and Validation Loss')
plt.title('Training and Validation Loss')
plt.title('Training and Validation Loss')
```



import seaborn as sns

```
predictor(model,test_gen):
classes=list(test_gen.class_indices.keys())
class_count=len(classes)
preds=model.predict(test_gen, verbose=1)
pred_indices=[]
test_count =len(preds)
for i, p in enumerate (preds):
    pred_index=np.argmax(p)
    pred_indices.append(pred_index)
    true_index= test_gen.labels[i]
    if pred_index != true_index:
        errors +=1
accuracy = (test_count-errors)*100/test_count
ytrue=np.array(test_gen.labels, dtype='int')
ypred=np.array(pred_indices, dtype='int')
msg=f'There were {errors} errors in {test_count} tests for an accuracy of {accuracy:6.2f}'
print (msg)
cm = confusion_matrix(ytrue, ypred )
# plot the confusion matrix
plt.figure(figsize=(20, 20))
sns.heatmap(cm, annot=True, vmin=0, fmt='g', cmap='Blues', cbar=False)
plt.xticks(np.arange(class_count)+.5, classes, rotation=90)
plt.yticks(np.arange(class_count)+.5, classes, rotation=0)
plt.xlabel("Predicted")
plt.ylabel("Actual")
plt.title("Confusion Matrix")
plt.show()
clr = classification_report(ytrue, ypred, target_names=classes, digits= 4) # create classification report
print("Classification Report:\n---
                                                         ----\n", clr)
```

<pre>predictor(model,test_gen) # make predictions on test set</pre>														
11/11 [== There wer	===== e 87 err	 ors in 32	28 tests	===] - 1 for an a	s 86ms/step accuracy of	73 . 48								
		_						on Matrix						
cables -	18	2	0	3	1	0	0	0	0	2	0	3	0	1
case -	3	20	0	1	0	0	0	0	0	4	0	0	0	1
cpu –	0	1	7	0	0	0	0	0	0	5	0	0	1	0
gpu -	1	1	1	8	0	0	0	0	0	4	0	0	0	0
hdd -	0	1	1	1	21	0	0	0	0	2	0	0	0	0
headset -	0	1	0	0	0	18	0	2	1	0	1	0	2	1
keyboard –	1	0	1	0	0	0	21	0	2	0	0	1	0	1
microphone -	0	0	0	1	0	1	2	16	0	0	0	0	0	2
monitor –	0	0	0	0	0	0	1	0	20	1	0	2	1	0
motherboard -	1	1	0	1	0	0	0	0	0	19	0	2	0	0
mouse -	0	0	0	0	0	1	1	0	3	0	15	1	0	0
ram -	1	0	0	0	1	0	0	0	0	0	0	20	0	0
speakers –	0	0	1	0	0	0	0	2	1	0	0	0	26	0
webcam -	1	0	0	2	1	0	0	1	0	0	0	0	0	12
	cables -	case -	- ndɔ	- ndb	- ppq	headset -	keyboard -	microphone -	monitor -	motherboard -	mouse -	ram -	speakers -	webcam -

```
Classification Report:
              precision
                         recall f1-score support
     cables
               0.6923
                         0.6000
                                   0.6429
                                                 30
                         0.6897
                                                29
      case
               0.7407
                                   0.7143
                         0.5000
                                                14
               0.6364
                                   0.5600
        gpu
               0.4706
                                   0.5000
        hdd
               0.8750
                         0.8077
                                   0.8400
    headset
               0.9000
                         0.6923
   keyboard
               0.8400
                         0.7778
                                   0.8077
 microphone
               0.7619
                         0.7273
                                   0.7442
    monitor
               0.7407
                         0.8000
motherboard
                         0.7917
                                   0.6230
      mouse
                                   0.8108
               0.6897
                         0.9091
                                   0.7843
       ram
   speakers
               0.8667
                         0.8667
                                   0.8667
                                                30
               0.6667
                         0.7059
                                  0.6857
     webcam
   accuracy
                                   0.7348
  macro avg
               0.7380
weighted avg
               0.7526
                         0.7348
                                   0.7373
   from tensorflow.keras.preprocessing.image import load_img, img_to_array
```

```
labels
['cables',
 'gpu',
'hdd',
 'headset',
 'keyboard',
 'microphone',
 'monitor',
 'motherboard',
 'mouse',
 'ram',
 'speakers',
 'webcam']
   def get_model_prediction(image_path):
       img = load_img(image_path, target_size=(255, 255))
       x = img_to_array(img)
       x = np.expand_dims(x, axis=0)
       predictions = model.predict(x, verbose=0)
       return labels[predictions.argmax()]
```

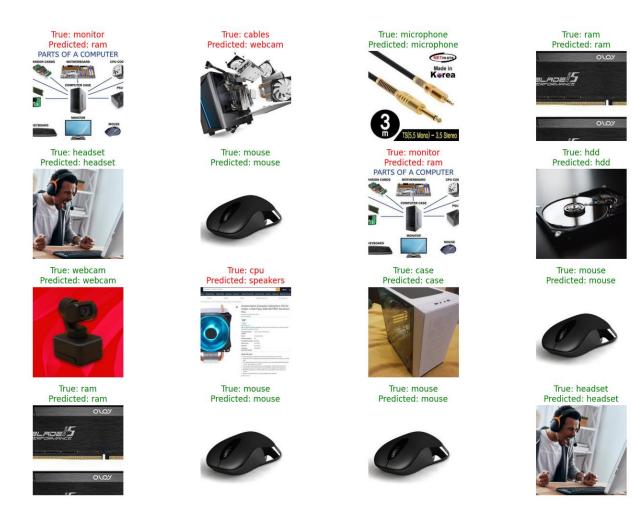
```
fig, axes = plt.subplots(nrows=4, ncols=4, figsize=(15, 10))
random_index = np.random.randint(0, len(test_gen), 16)

for i, ax in enumerate(axes.ravel()):
    img_path = test_df['path'].iloc[random_index[i]]
    ax.imshow( load_img(img_path))
    ax.axis('off')

    if test_df['label'].iloc[random_index[i]] == pred[random_index[i]]:
        color = "green"
    else:
        color = "red"

    ax.set_title(f"True: {test_df['label'].iloc[random_index[i]]}\nPredicted: {pred[random_index[i]]}", color=color)

plt.tight_layout()
plt.show()
```



4.2 Github and Project demo link

Project Demo link:

https://vitapacin-

my.sharepoint.com/:v:/g/personal/kowshik_22bce9556_vitapstudent_ac_in/ Ef3AmwMXiQZNu2fK-iNm1c4BcC77mJ2tRjCON_-

WhX1GKw?nav=eyJyZWZlcnJhbEluZm8iOnsicmVmZXJyYWxBcHAiOi JTdHJlYW1XZWJBcHAiLCJyZWZlcnJhbFZpZXciOiJTaGFyZURpYW xvZy1MaW5rIiwicmVmZXJyYWxBcHBQbGF0Zm9ybSI6IldlYiIsInJlZm VycmFsTW9kZSI6InZpZXcifX0%3D&e=vevLJx

Github:

https://github.com/kowshikdontu/TechPart-Vision