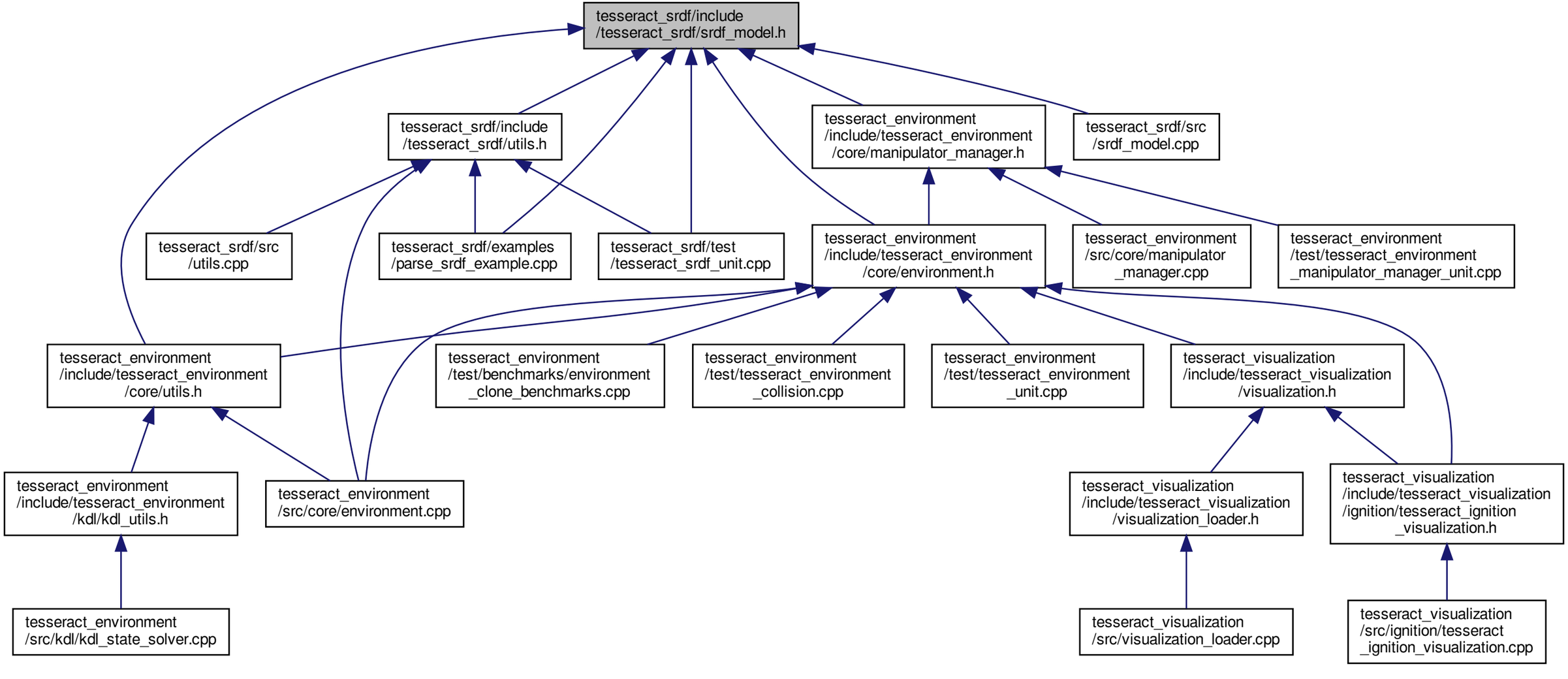
tesseract_srdf/include /tesseract_srdf/srdf_model.h
tesseract_srdf/include /tesseract_srdf/utils.h
tesseract_environment /include/tesseract_environment /core/manipulator_manager.h
tesseract_srdf/src /srdf_model.cpp
tesseract_srdf/src /utils.cpp
tesseract_srdf/examples /parse_srdf_example.cpp
tesseract_srdf/test /tesseract_srdf_unit.cpp
tesseract_environment /include/tesseract_environment /core/environment.h
tesseract_environment /src/core/manipulator _manager.cpp
tesseract_environment /test/tesseract_environment _manipulator_manager_unit.cpp
tesseract_environment /include/tesseract_environment /core/utils.h
tesseract_environment /test/benchmarks/environment _clone_benchmarks.cpp
tesseract_environment /test/tesseract_environment _collision.cpp
tesseract_environment /test/tesseract_environment _unit.cpp
tesseract_visualization /include/tesseract_visualization /visualization.h
tesseract_environment /include/tesseract_environment /kdl/kdl_utils.h
tesseract_environment /src/core/environment.cpp
tesseract_visualization /include/tesseract_visualization /visualization_loader.h
tesseract_visualization /include/tesseract_visualization /ignition/tesseract_ignition _visualization.h
tesseract_environment /src/kdl/kdl_state_solver.cpp
tesseract_visualization /src/visualization_loader.cpp
tesseract_visualization /src/ignition/tesseract _ignition_visualization.cpp