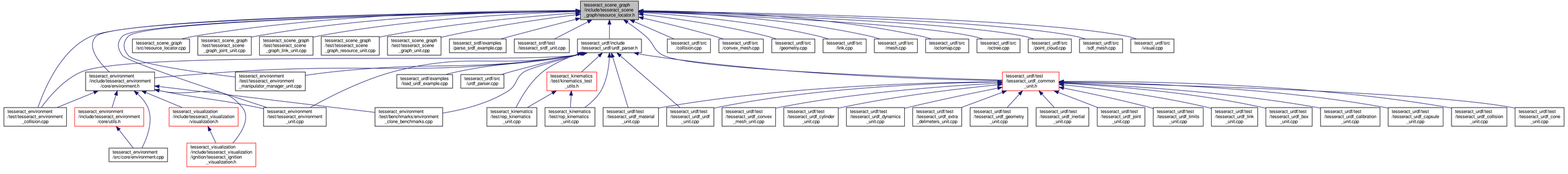
tesseract_scene_graph/include/tesseract_scene_graph/resource_locator.h
tesseract_scene_graph/src/resource_locator.cpp
tesseract_scene_graph/test/tesseract_scene_graph_joint_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_link_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_resource_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_unit.cpp
tesseract_srdf/examples/parse_srdf_example.cpp
tesseract_srdf/test/tesseract_srdf_unit.cpp
tesseract_urdf/include/tesseract_urdf/urdf_parser.h
tesseract_urdf/src/collision.cpp
tesseract_urdf/src/convex_mesh.cpp
tesseract_urdf/src/geometry.cpp
tesseract_urdf/src/link.cpp
tesseract_urdf/src/mesh.cpp
tesseract_urdf/src/octomap.cpp
tesseract_urdf/src/octree.cpp
tesseract_urdf/src/point_cloud.cpp
tesseract_urdf/src/sdf_mesh.cpp
tesseract_urdf/src/visual.cpp
tesseract_environment/include/tesseract_environment/core/environment.h
tesseract_environment/test/tesseract_environment_manipulator_manager_unit.cpp
tesseract_urdf/examples/load_urdf_example.cpp
tesseract_urdf/src/urdf_parser.cpp
tesseract_kinematics/test/kinematics_test_utils.h
tesseract_urdf/test/tesseract_urdf_common_unit.h
tesseract_environment/test/tesseract_environment_collision.cpp
tesseract_environment/include/tesseract_environment/core/utils.h
tesseract_visualization/include/tesseract_visualization/visualization.h
tesseract_environment/test/tesseract_environment_unit.cpp
tesseract_environment/test/benchmarks/environment_clone_benchmarks.cpp
tesseract_kinematics/test/rep_kinematics_unit.cpp
tesseract_kinematics/test/rop_kinematics_unit.cpp
tesseract_urdf/test/tesseract_urdf_material_unit.cpp
tesseract_urdf/test/tesseract_urdf_urdf_unit.cpp
tesseract_urdf/test/tesseract_urdf_convex_mesh_unit.cpp
tesseract_urdf/test/tesseract_urdf_cylinder_unit.cpp
tesseract_urdf/test/tesseract_urdf_dynamics_unit.cpp
tesseract_urdf/test/tesseract_urdf_extra_delimeters_unit.cpp
tesseract_urdf/test/tesseract_urdf_geometry_unit.cpp
tesseract_urdf/test/tesseract_urdf_inertial_unit.cpp
tesseract_urdf/test/tesseract_urdf_joint_unit.cpp
tesseract_urdf/test/tesseract_urdf_limits_unit.cpp
tesseract_urdf/test/tesseract_urdf_link_unit.cpp
tesseract_urdf/test/tesseract_urdf_box_unit.cpp
tesseract_urdf/test/tesseract_urdf_calibration_unit.cpp
tesseract_urdf/test/tesseract_urdf_capsule_unit.cpp
tesseract_urdf/test/tesseract_urdf_collision_unit.cpp
tesseract_urdf/test/tesseract_urdf_cone_unit.cpp
tesseract_environment/src/core/environment.cpp
tesseract_visualization/include/tesseract_visualization/ignition/tesseract_ignition_visualization.h