

tesseract\_collision  
/include/tesseract\_collision  
/bullet/tesseract\_compound  
\_compound\_collision\_algorithm.h

```
graph BT; A["tesseract_collision  
/src/bullet/tesseract  
_collision_configuration.cpp"] --> C["tesseract_collision  
/include/tesseract_collision  
/bullet/tesseract_compound  
_compound_collision_algorithm.h"]; B["tesseract_collision  
/src/bullet/tesseract  
_compound_compound_collision  
_algorithm.cpp"] --> C;
```

The diagram illustrates a file dependency structure. At the top is a header file box (shaded gray) containing the path 'tesseract\_collision /include/tesseract\_collision /bullet/tesseract\_compound \_compound\_collision\_algorithm.h'. Below it are two source file boxes. The left box contains 'tesseract\_collision /src/bullet/tesseract \_collision\_configuration.cpp' and the right box contains 'tesseract\_collision /src/bullet/tesseract \_compound\_compound\_collision \_algorithm.cpp'. Blue arrows point from each source file box up to the header file box, indicating that both source files include this header.

tesseract\_collision  
/src/bullet/tesseract  
\_collision\_configuration.cpp

tesseract\_collision  
/src/bullet/tesseract  
\_compound\_compound\_collision  
\_algorithm.cpp