

tesseract_kinematics
/include/tesseract_kinematics
/kdl/kdl_fwd_kin_tree_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_fwd_kin_tree_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

The diagram illustrates the inclusion of the `tesseract_kinematics` header file by two other source files. The header file is located at `tesseract_kinematics/include/tesseract_kinematics/kdl/kdl_fwd_kin_tree_factory.h`. The two source files that include it are `tesseract_environment/src/core/manipulator_manager.cpp` and `tesseract_kinematics/test/kdl_kinematics_unit.cpp`. Arrows point from each source file box to the header file box, indicating the direction of the include relationship.

tesseract_environment
/src/core/manipulator
_manager.cpp

tesseract_kinematics
/test/kdl_kinematics
_unit.cpp