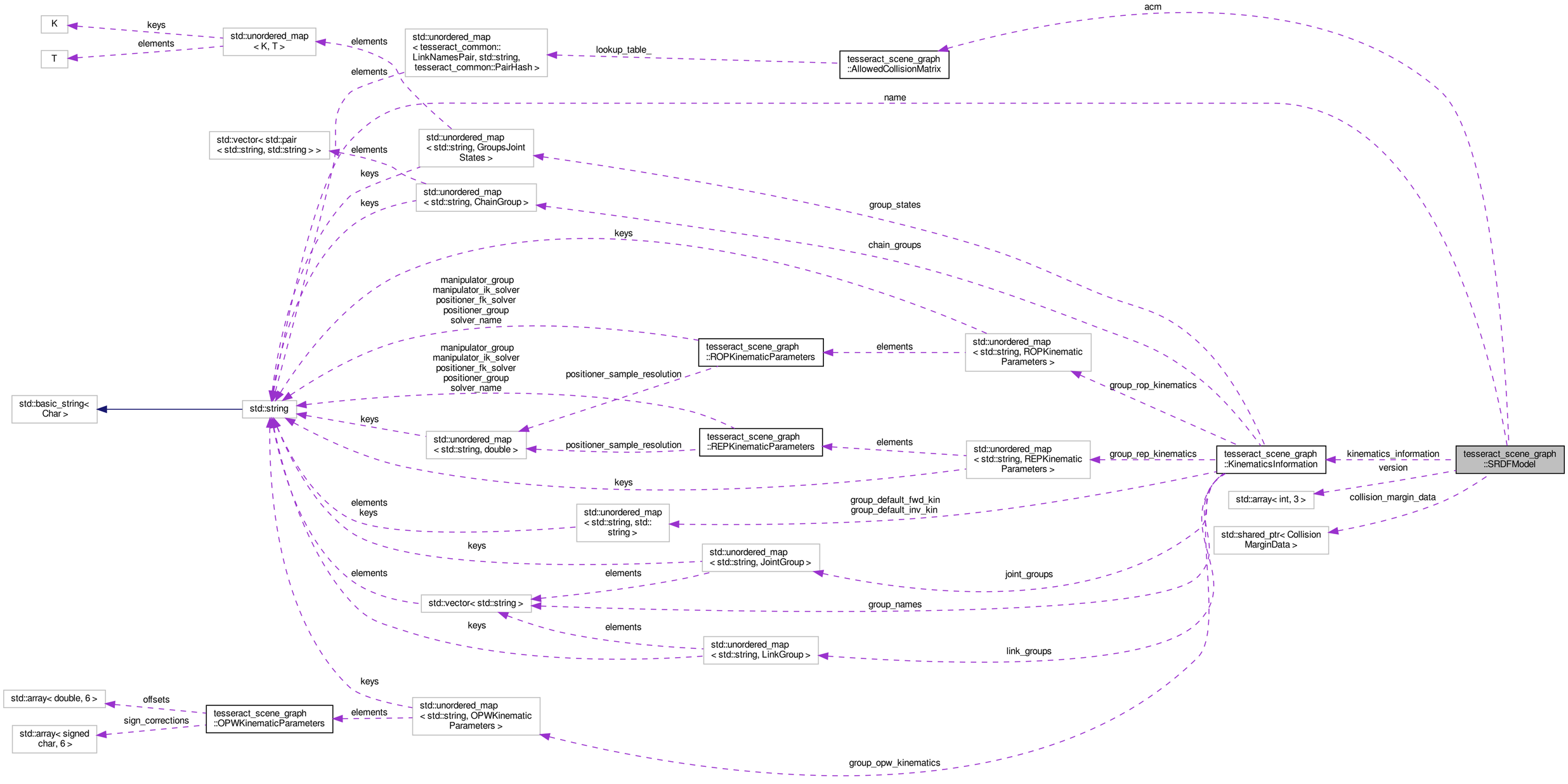
K
T
keys
elements
std::unordered_map
< K, T >
elements
elements
std::unordered_map
< tesseract_common::
LinkNamesPair, std::string,
tesseract_common::PairHash >
lookup_table_
tesseract_scene_graph
::AllowedCollisionMatrix
acm
name
std::vector< std::pair
< std::string, std::string > >
elements
keys
keys
std::unordered_map
< std::string, GroupsJoint
States >
std::unordered_map
< std::string, ChainGroup >
group_states
chain_groups
keys
manipulator_group
manipulator_ik_solver
positioner_fk_solver
positioner_group
solver_name
manipulator_group
manipulator_ik_solver
positioner_fk_solver
positioner_group
solver_name
tesseract_scene_graph
::ROPKinematicParameters
elements
std::unordered_map
< std::string, ROPKinematic
Parameters >
group_rop_kinematics
positioner_sample_resolution
std::basic_string<
Char >
std::string
keys
std::unordered_map
< std::string, double >
positioner_sample_resolution
tesseract_scene_graph
::REPKinematicParameters
elements
std::unordered_map
< std::string, REPKinematic
Parameters >
group_rep_kinematics
tesseract_scene_graph
::KinematicsInformation
kinematics_information
version
tesseract_scene_graph
::SRDFModel
keys
group_default_fwd_kin
group_default_inv_kin
std::array< int, 3 >
collision_margin_data
elements
keys
std::unordered_map
< std::string, std::
string >
std::shared_ptr< Collision
MarginData >
keys
std::unordered_map
< std::string, JointGroup >
elements
joint_groups
elements
std::vector< std::string >
group_names
keys
elements
std::unordered_map
< std::string, LinkGroup >
link_groups
keys
std::array< double, 6 >
offsets
sign_corrections
std::array< signed
char, 6 >
tesseract_scene_graph
::OPWKinematicParameters
elements
std::unordered_map
< std::string, OPWKinematic
Parameters >
group_opw_kinematics