

tesseract_common/include
/tesseract_common/manipulator_info.h

```
graph TD; A["tesseract_common/include  
/tesseract_common/manipulator_info.h"] --> B["tesseract_common/macros.h"]; A --> C["vector"]; A --> D["Eigen/Geometry"]; A --> E["boost/serialization  
/base_object.hpp"];
```

tesseract_common/macros.h

vector

Eigen/Geometry

boost/serialization
/base_object.hpp