

tesseract_kinematics
/include/tesseract_kinematics
/kdl/kdl_inv_kin_chain_lma
_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_inv_kin_chain_lma  
_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

This diagram illustrates the inclusion relationships between three C++ files. At the top is a header file, `tesseract_kinematics/include/tesseract_kinematics/kdl/kdl_inv_kin_chain_lma_factory.h`, which is shaded gray. Below it are two source files: `tesseract_environment/src/core/manipulator_manager.cpp` on the left and `tesseract_kinematics/test/kdl_kinematics_unit.cpp` on the right. Blue arrows point from each source file to the header file, indicating that both source files include this header.

tesseract_environment
/src/core/manipulator
_manager.cpp

tesseract_kinematics
/test/kdl_kinematics
_unit.cpp