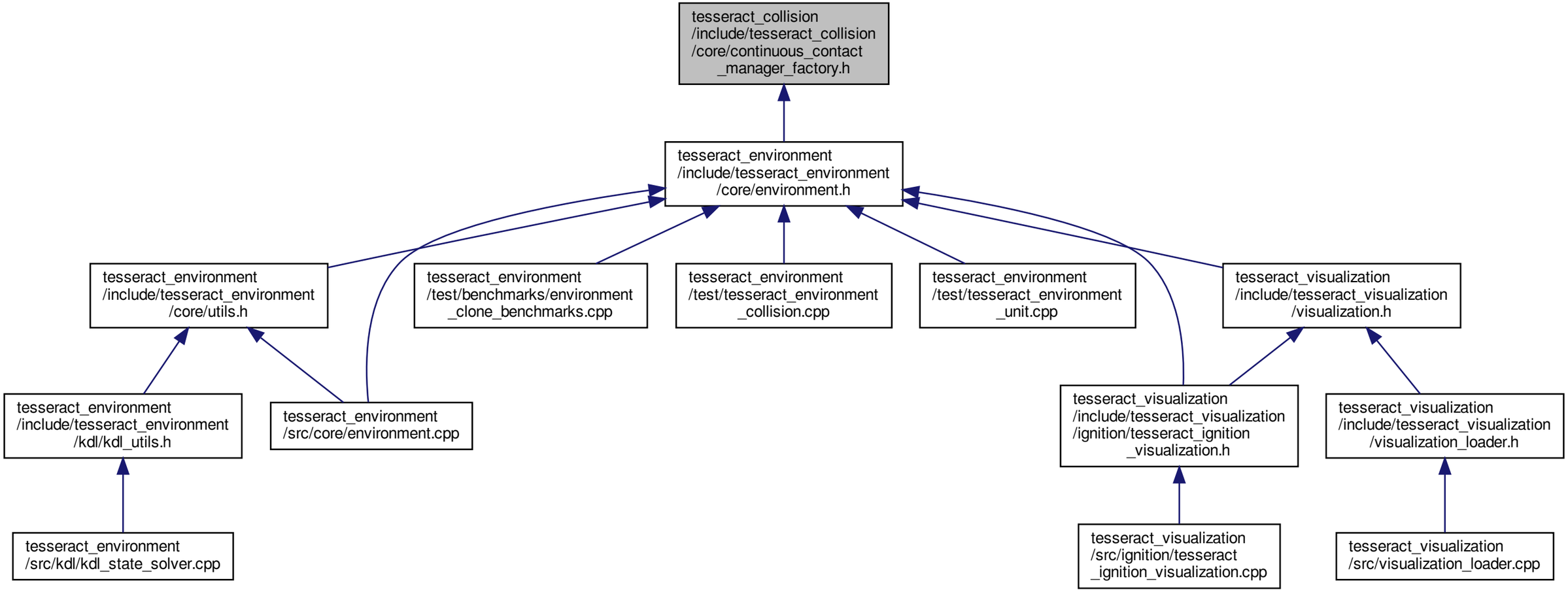
tesseract_collision /include/tesseract_collision /core/continuous_contact _manager_factory.h
tesseract_environment /include/tesseract_environment /core/environment.h
tesseract_environment /include/tesseract_environment /core/utils.h
tesseract_environment /test/benchmarks/environment _clone_benchmarks.cpp
tesseract_environment /test/tesseract_environment _collision.cpp
tesseract_environment /test/tesseract_environment _unit.cpp
tesseract_visualization /include/tesseract_visualization /visualization.h
tesseract_environment /include/tesseract_environment /kdl/kdl_utils.h
tesseract_environment /src/core/environment.cpp
tesseract_visualization /include/tesseract_visualization /ignition/tesseract_ignition _visualization.h
tesseract_visualization /include/tesseract_visualization /visualization_loader.h
tesseract_environment /src/kdl/kdl_state_solver.cpp
tesseract_visualization /src/ignition/tesseract _ignition_visualization.cpp
tesseract_visualization /src/visualization_loader.cpp