

tesseract_environment
::Command



```
graph BT; A[tesseract_environment::AddAllowedCollisionCommand] --> B[tesseract_environment::Command];
```

A diagram illustrating a class hierarchy. At the bottom is a gray rectangular box containing the text "tesseract_environment::AddAllowedCollisionCommand". A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box above it. The white box contains the text "tesseract_environment::Command".

tesseract_environment
::AddAllowedCollisionCommand