

tesseract_kinematics
/include/tesseract_kinematics
/kdl/kdl_inv_kin_chain_nr
_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_inv_kin_chain_nr  
_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

A diagram showing two source files at the bottom and a header file at the top. Two blue arrows point from the source files to the header file, indicating inclusion relationships. The top box is shaded gray, while the bottom boxes are white.

tesseract_environment
/src/core/manipulator
_manager.cpp

tesseract_kinematics
/test/kdl_kinematics
_unit.cpp