

tesseract_kinematics
/include/tesseract_kinematics
/kdl/kdl_inv_kin_chain_lma
_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_inv_kin_chain_lma  
_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

A diagram showing the relationship between three files. At the top is a grey box containing the header file path: `tesseract_kinematics/include/tesseract_kinematics/kdl/kdl_inv_kin_chain_lma_factory.h`. Below it are two white boxes. The left box contains the source file path: `tesseract_environment/src/core/manipulator_manager.cpp`. The right box contains the source file path: `tesseract_kinematics/test/kdl_kinematics_unit.cpp`. Two blue arrows point from the bottom of each white box to the bottom of the grey box, indicating that both source files include the header file.

tesseract_environment
/src/core/manipulator
_manager.cpp

tesseract_kinematics
/test/kdl_kinematics
_unit.cpp