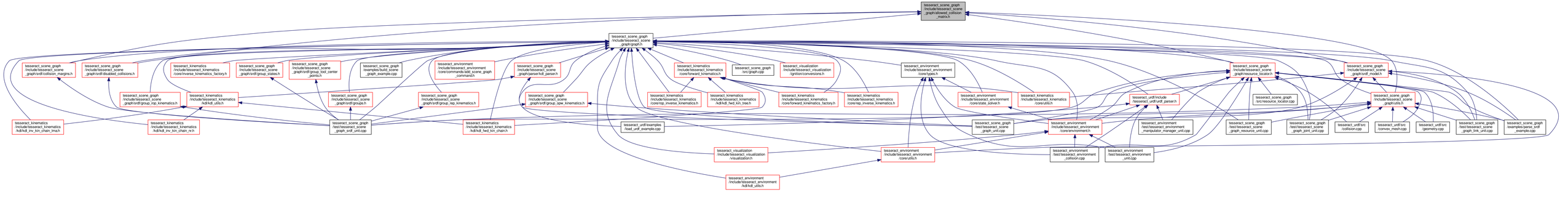
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tesseract_urdf/src /collision.cpp
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tesseract_urdf/src /geometry.cpp
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