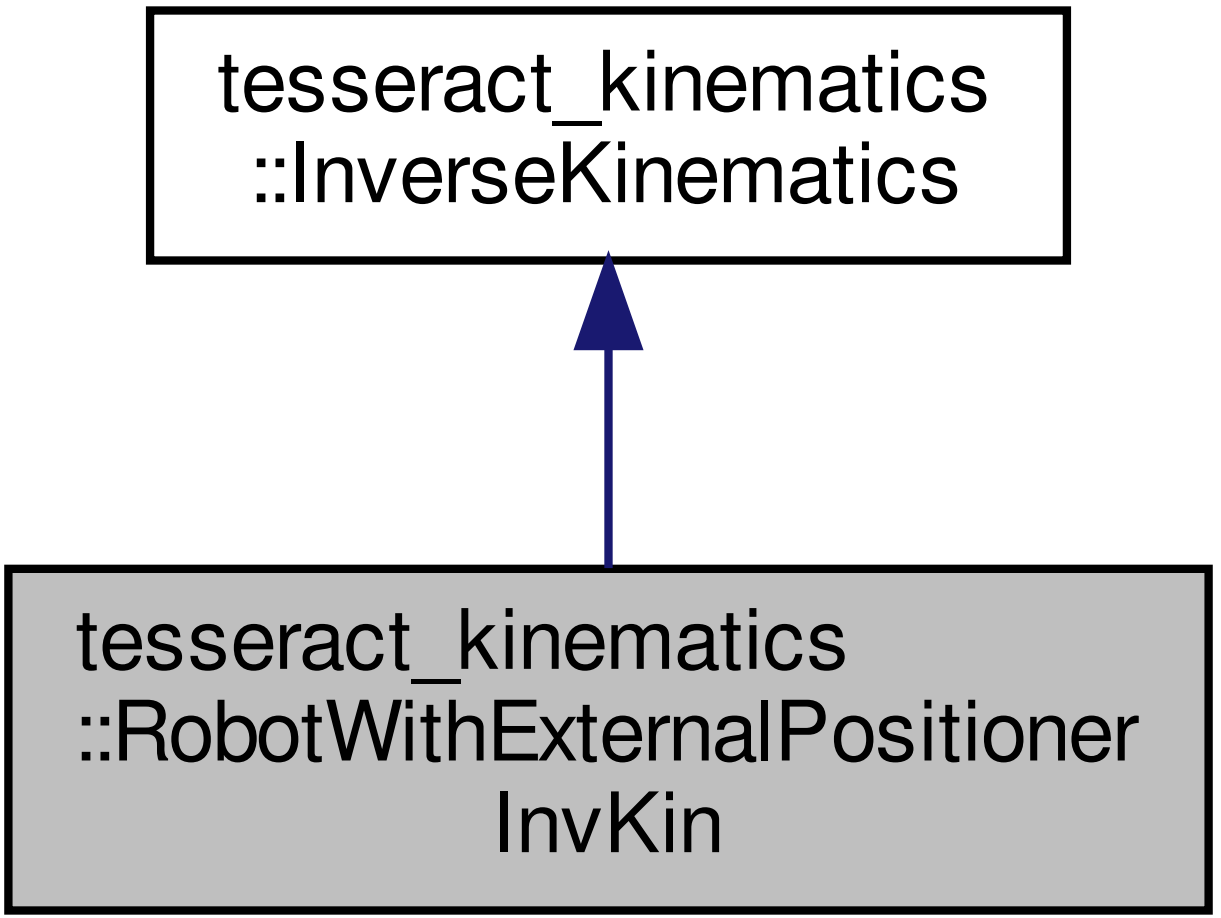
tesseract_kinematics
::InverseKinematics
tesseract_kinematics
::RobotWithExternalPositioner
InvKin