

# Hill climbing with distributed restarts: an alternative to random-restart hill climbing

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While looking for alternatives to the hill climbing algorithm, we initially chose to implement hill climbing with random restarts (sometimes referred to as shotgun hill climbing). Classic random-restart hill climbing is built on top of the original hill climbing algorithm but does so iteratively with an initial condition  $x_0$  being chosen at random. In the case of the knapsack problem, the best solution  $x_m$  is kept until a future repetition potentially finds a better solution  $x_m$  than the previous best and replaces it.

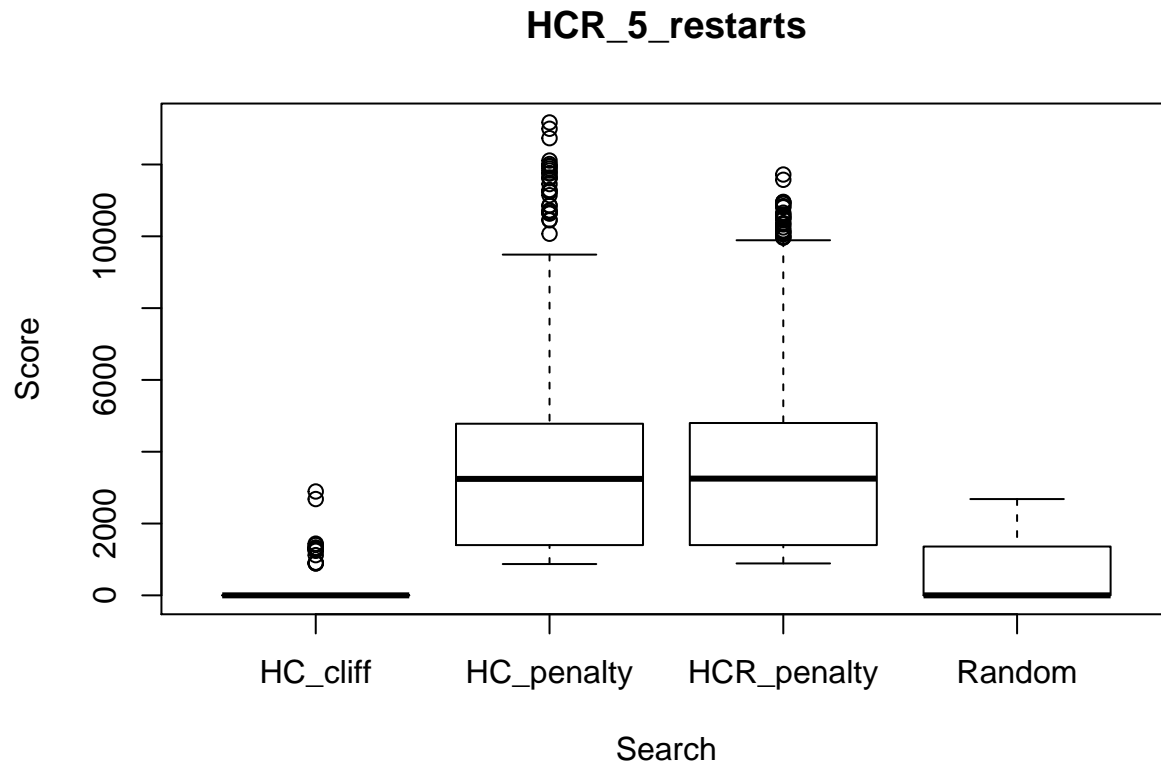
Our approach differs from random-restart hill climbing in that the initial condition is not random. Instead, the initial condition is calculated by taking the max number of tries and dividing it by the number of restarts that we are going to execute. The goal of this variant on hill climber is to place our bets on spending the time to explore the space rather than optimizing from an initial condition, and we can hoped to accomplish this without using a random condition. Ideally, this would yield results that were better than classic hill climbing.

```
data_30_runs_HC <- read.csv("~/EC-AI/simple-search/data/data_30_runs_HC.txt", sep="")
data_30_runs_HC$Non_negative_score = ifelse(data_30_runs_HC$Score<0, 0, data_30_runs_HC$Score)
data_30_runs_HCR_5 <- read.csv("~/EC-AI/simple-search/data/data_30_runs_HCR_5.txt", sep="")
data_30_runs_HCR_5$Non_negative_score = ifelse(data_30_runs_HCR_5$Score<0, 0, data_30_runs_HCR_5$Score)
data_30_runs_HCR_15 <- read.csv("~/EC-AI/simple-search/data/data_30_runs_HCR_15.txt", sep="")
data_30_runs_HCR_15$Non_negative_score = ifelse(data_30_runs_HCR_15$Score<0, 0, data_30_runs_HCR_15$Score)
data_30_runs_5_restarts <- read.csv("../data/data_30_runs_5_restarts.txt", sep="")
data_30_runs_5_restarts$Non_negative_score = ifelse(data_30_runs_5_restarts$Score<0, 0, data_30_runs_5_restarts$Score)
data_30_runs_15_restarts <- read.csv("../data/data_30_runs_15_restarts.txt", sep="")
data_30_runs_15_restarts$Non_negative_score = ifelse(data_30_runs_15_restarts$Score<0, 0, data_30_runs_15_restarts$Score)
```

## Results

For the summaries I am using data sets with only penalty scores because those are what I want to compare.  
##Comparison of the Searches 5 restarts

```
plot(main = "HCR_5_restarts", data_30_runs_5_restarts$Non_negative_score ~ data_30_runs_5_restarts$Search,
      xlab="Search", ylab="Score")
```



```
#Hill-Climber_penalty
summary(data_30_runs_HC$Non_negative_score)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
##      872   1400   3244   4145   4780   13170
```

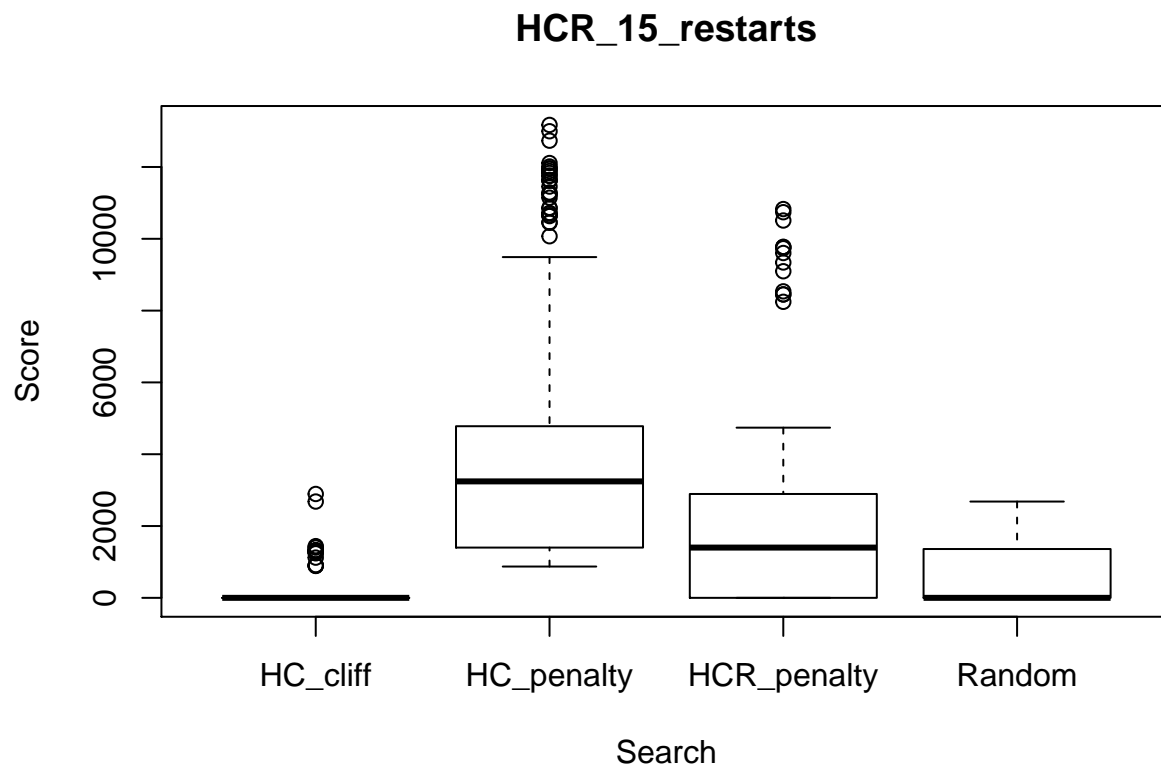
```
#Hill-Climber-5-restarts_penalty
summary(data_30_runs_HCR_5$Non_negative_score)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
##      889   1400   3252   3993   4790   11720
```

From the plot and summaries, we can see that (HC\_penalty) is returning better results than (HCR\_penalty). However what is interesting is that (HCR\_penalty) returns a higher Median, 4th Qu, and 3rd Qu. than (HC\_penalty) even though it is by a small amount, it's still larger.

## Comparison of the Searches 15 restarts

```
plot(main = "HCR_15_restarts", data_30_runs_15_restarts$Non_negative_score ~ data_30_runs_15_restarts$Search,
      xlab="Search", ylab="Score")
```



```
#Hill-Climber_penalty
summary(data_30_runs_HC$Non_negative_score)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
##      872   1400   3244   4145   4780   13170
```

```
#Hill-Climber-15-restarts_penalty
summary(data_30_runs_HCR_15$Non_negative_score)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
##         0         0   1400   2001   2893   10830
```

From the plot and summaries, we can see that just like the above plot with 5 restarts (HC\_penalty) is returning better results than (HCR\_penalty). What's very interesting about (HCR\_penalty) this time around is that the 1st Qu. is nonexistent. The mean, median, and upper Qu. are also significantly lower than the standard (HC\_penalty).

Summary: One reason this might be is that in the data for HCR, there is a significant portion of the scores that are returning negative scores. We are removing negative scores from the data set and making the data set smaller in comparison to standard HC.

## Parswise Wilcox test

### 5 restarts

We are just going to look at the 5 restarts data set because it gives us a more significant result that we can compare to HC\_penalty.

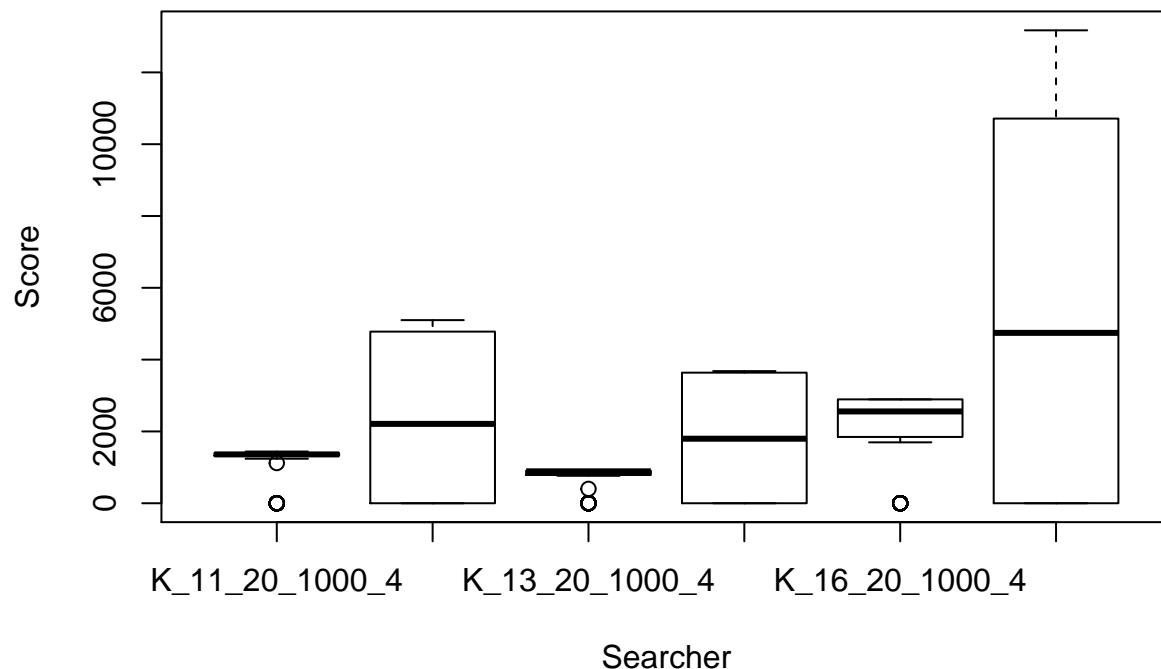
```
pairwise.wilcox.test(data_30_runs_5_restarts$Non_negative_score, data_30_runs_5_restarts$Search_method)

##
## Pairwise comparisons using Wilcoxon rank sum test
##
## data: data_30_runs_5_restarts$Non_negative_score and data_30_runs_5_restarts$Search_method
##
##          HC_cliff HC_penalty HCR_penalty
## HC_penalty < 2e-16 -                -
## HCR_penalty < 2e-16 0.86              -
## Random      6.7e-16 < 2e-16    < 2e-16
##
## P value adjustment method: holm
```

Summary: The test shows us that there is a strong difference with  $p < 2^{-16}$  in all cases except when comparing hcr\_penalty with HC\_penalty. This results with a  $p < 0.86$  that indicates a weak difference between the two search results.

### Plot with searcher problems

```
plot(data_30_runs_5_restarts$Non_negative_score ~ data_30_runs_15_restarts$Problem,
      xlab="Searcher", ylab="Score")
```

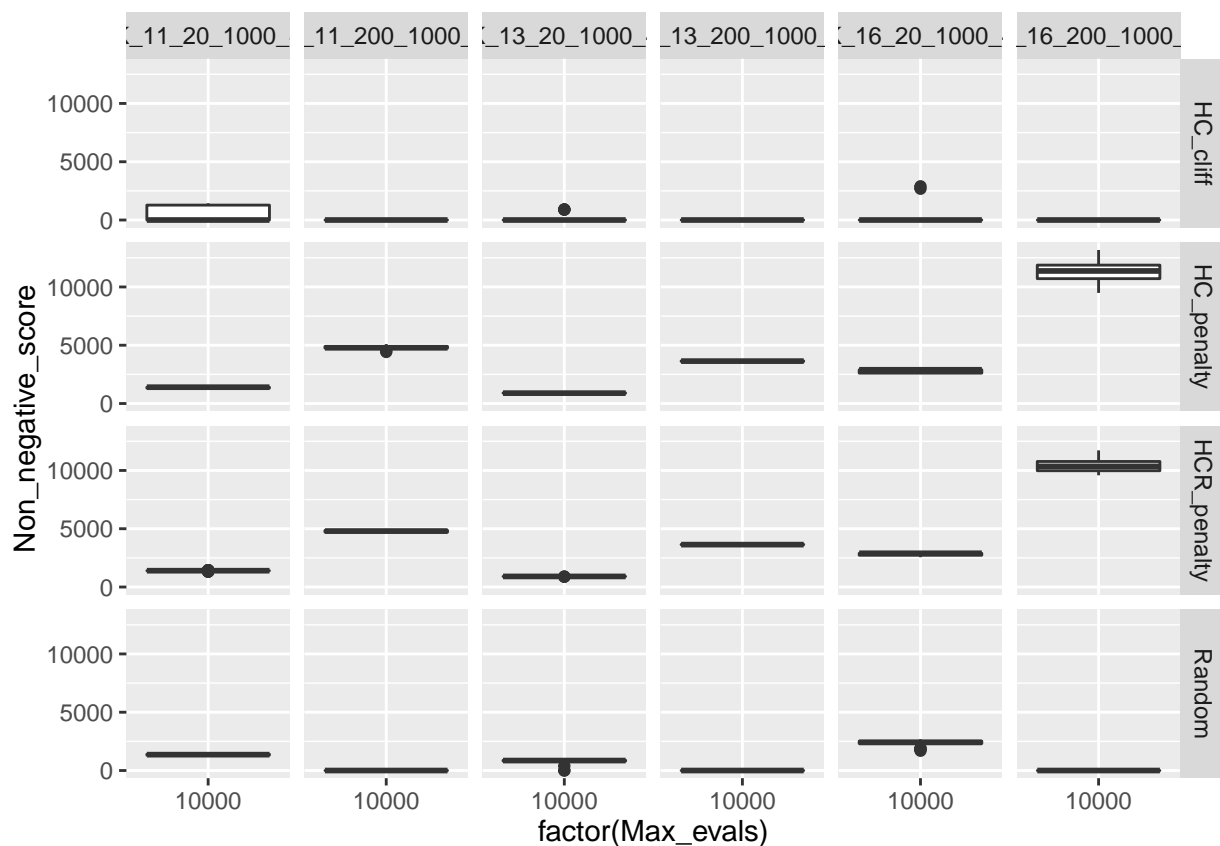


Summary: The Plot shows us that the rightmost plot is achieving the highest values while the rest are indicating more about overall performance. The boxplots that are achieving relatively high values with respectable medians have a reduced difficulty possibly due to the addition of restarts.

## ggplot

```
library("ggplot2")

ggplot(data_30_runs_5_restarts,
       aes(x=factor(Max_evals), y=Non_negative_score, group=Max_evals)) +
  geom_boxplot() + facet_grid(Search_method ~ Problem)
```



By reading the plot horizontally we can see that HC\_penalty and HCR\_penalty are having much higher values for knapPI\_16\_200\_1000\_4. Reading the plot vertically shows for most knapPI, Random and HC\_cliff searches almost never get past zero except for knapPI\_16\_20\_1000\_4 and knapPI\_11\_200\_1000\_4.

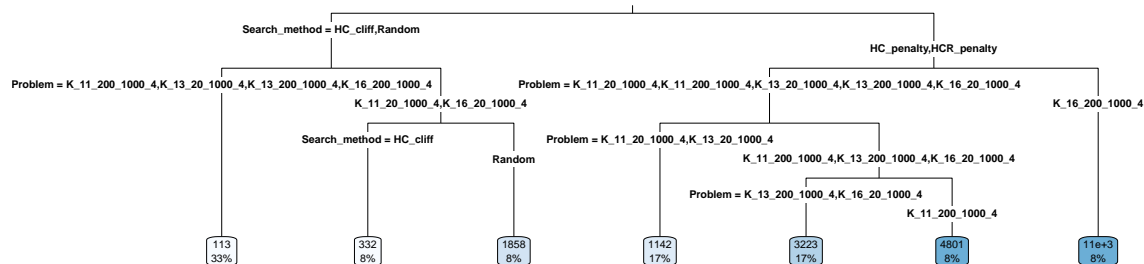
## Recursive partitioning

```
library("rpart")
library("rpart.plot")
```

```
rp <- rpart(Non_negative_score ~ Search_method + Problem + Max_evals, data=data_30_runs_5_restarts)
rp

## n= 720
##
## node), split, n, deviance, yval
##      * denotes terminal node
##
## 1) root 720 6585064000.0  2254.4930
##    2) Search_method=HC_cliff,Random 360  211767200.0  440.2667
##      4) Problem=K_11_200_1000_4,K_13_20_1000_4,K_13_200_1000_4,K_16_200_1000_4 240  20133660.0  11
##      5) Problem=K_11_20_1000_4,K_16_20_1000_4 120  114469900.0  1095.0080
##        10) Search_method=HC_cliff 60  27753570.0  332.2500 *
##        11) Search_method=Random 60  16900290.0  1857.7670 *
##    3) Search_method=HC_penalty,HCR_penalty 360 4003476000.0  4068.7190
##      6) Problem=K_11_20_1000_4,K_11_200_1000_4,K_13_20_1000_4,K_13_200_1000_4,K_16_20_1000_4 300 61
##      12) Problem=K_11_20_1000_4,K_13_20_1000_4 120  7111177.0  1141.6580 *
##      13) Problem=K_11_200_1000_4,K_13_200_1000_4,K_16_20_1000_4 180  122201400.0  3749.0720
##        26) Problem=K_13_200_1000_4,K_16_20_1000_4 120  21661490.0  3222.9420 *
##        27) Problem=K_11_200_1000_4 60  887093.3  4801.3330 *
##    7) Problem=K_16_200_1000_4 60  42579110.0  10881.7800 *
```

```
rpart.plot(rp, type=3, extra=100)
```



This indicates that the searcher is the most important first-order difference in the plot. There is a split between HC\_penalty and HCR\_penalty (on the right) vs. the other two searchers. After that split, though, the problems were the next most important factor along both branches. As predicted, (HC\_penalty), knapPI\_16\_200\_1000\_4 resulted in the highest result.

## Conclusions

Based on our results, Hill Climber penalty with restarts is better but not by much. While standard HC was obtaining a higher values, HCR seemed to be obtaining better scores based off of the higher median, 3rd, and 4th QU in the boxplots.

However based on these results we have concern that there is some aspects of our code that is wrong and not giving the results that we want. On paper, HC with restarts should give us a better score then standard HC. What we think is happening is that the Hill climber is running out of runs well before it actually reaches a value it deems the max. 10000 evaluations with 5 restarts will only give each restart 2000 evaluations where as standart HC will use more.