PHYS 410 Homework 1

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Problem 1 - Hybrid Algorithm

(Statement of problem goes here.)
lalalalla this is example text.

```
%% Problem 1 - Hybrid algorithm

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% A hybrid algorithm that uses bisection and Newton's method
% to locate a root within a given interval [xmin, xmax].
%
% Arguments:
%  f:      Function whose root is sought (takes one argument).
%  dfdx:   Derivative function (takes one argument).
%  xmin:   Initial bracket minimum.
%  xmax:   Initial bracket maximum.
%  tol1:   Relative convergence criterion for bisection.
%  tol2:   Relative convergence criterion for Newton iteration.
% Returns:
%  x:      Estimate of root.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
function x = hybrid(f, dfdx, xmin, xmax, tol1, tol2)
    % Bisection:
    converged = false;
    fmin = f(xmin);
    while not(converged)
        xmid = (xmin + xmax)/2;
        fmid = f(xmid);
        if fmid == 0
            break
        elseif fmid*fmin < 0
            xmax = xmid;
        else
            xmin = xmid;
            fmin = fmid;
        end
        if (xmax - xmin)/abs(xmid) < tol1
            converged = true;
        end
    end
    bisection_result = xmid;

    % Newton's method:
    converged = false;
    x = bisection_result;
    xprev = bisection_result;
    while not(converged)
        x = xprev - f(xprev)/dfdx(xprev);
```

```
        if abs((x - xprev)/xprev) < tol2
            converged = true;
        end
        xprev = x;
    end

    disp(x)
end
```

Problem 2

(Statement of problem goes here.)
lalalalla this is example text.

```
%% Problem 2 - D-dimensional Newton iteration

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Newton's method for a d-dimensional space.
%
% Arguments:
%  f:   Function which implements the nonlinear system of
%       equations. Function is of the form f(x) where x is a
%       length-d vector, and which returns length-d column
%       vector.
%  jac: Function which is of the form jac(x) where x is a
%       length-d vector, and which returns the d x d matrix of
%       Jacobian matrix elements for the nonlinear system defined
%       by f.
%  x0:  Initial estimate for iteration (length-d column vector).
%  tol: Convergence criterion: routine returns when relative
%       magnitude of update from iteration to iteration is
%       <= tol.
% Returns:
%  x:   Estimate of root (length-d column vector).
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
function x = newtond(f, jac, x0, tol)
    x = x0;
    res = f(x0);
    dx = jac(x0)\res;
    while rms(dx) > tol
        res = f(x);
        dx = jac(x)\res;
        x = x - dx;
    end
end
```

Appendix A - Testing Code

(Statement of problem goes here.)
lalalalla this is example text.

The Jacobian matrix is

$$\begin{bmatrix} 2x & 4y^3 & 6z^5 \\ -yz^2\sin\left(xyz^2\right)-1 & -xz^2\sin\left(xyz^2\right)-1 & -2xyz\sin\left(xyz^2\right)-1 \\ -2x-2y+2z & -2x+2z & 2x+2y+3z^2-2z \end{bmatrix}$$

Figure 1: Calculated Jacobian matrix for the provided system of equations.

```
%% Test script for Problem 1 and Problem 2

close all; clear; clc;

format long;

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Test Script - Problem 1
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Example polynomial function given in problem 1 of Homework 1
% document.
%
% Arguments:
%  x:  Polynomial independent variable
% Returns:
%  example_f_out:  Function evaluated at x
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
function example_f_out = example_f(x)
    example_f_out = 512*x^10 - 5120*x^9 + 21760*x^8 - 51200*x^7 + ...
    72800*x^6 - 64064*x^5 + 34320*x^4 - 10560*x^3 + 1650*x^2 - 100*x + 1;
end

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Derivative of example polynomial function given in problem 1 of
% Homework 1 document.
%
% Arguments:
%  x:  Polynomial independent variable
% Returns:
%  example_dfdx_out:  Derivative evaluated at x
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
function example_dfdx_out = example_dfdx(x)
    example_dfdx_out = 20*(-5 + 165*x - 1584*x^2 + 6864*x^3 - 16016*x^4 ...
    + 21840*x^5 - 17920*x^6 + 8704*x^7 - 2304*x^8 + 256*x^9);
end

% Root finding
roots = ones([1,10]);

BS_tol = 1.0e-2;
NM_tol = 1.0e-12;

roots(1) = hybrid(@example_f, @example_dfdx, 0.0, 0.04, BS_tol, NM_tol);
roots(2) = hybrid(@example_f, @example_dfdx, 0.05, 0.15, BS_tol, NM_tol);
```

```matlab
roots(3) = hybrid(@example_f, @example_dfdx, 0.23, 0.35, BS_tol, NM_tol);
roots(4) = hybrid(@example_f, @example_dfdx, 0.47, 0.6, BS_tol, NM_tol);
roots(5) = hybrid(@example_f, @example_dfdx, 0.77, 0.9, BS_tol, NM_tol);
roots(6) = hybrid(@example_f, @example_dfdx, 1.11, 1.22, BS_tol, NM_tol);
roots(7) = hybrid(@example_f, @example_dfdx, 1.65, 1.75, BS_tol, NM_tol);
roots(8) = hybrid(@example_f, @example_dfdx, 1.86, 1.90, BS_tol, NM_tol);
roots(9) = hybrid(@example_f, @example_dfdx, 1.4, 1.5, BS_tol, NM_tol);
roots(10) = hybrid(@example_f, @example_dfdx, 1.98, 2.0, BS_tol, NM_tol);

% Plotting
xvec = linspace(0,2,10000);

fig = figure;
plot(xvec, arrayfun(@example_f, xvec), 'LineWidth', 1);
for i = 1:length(roots)
    xline(roots(i), 'LineWidth', 1);
end
yline(0, 'LineWidth', 1);
grid on

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Test Script - Problem 2
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Example nonlinear system given in problem 2 of Homework 1
% document.
%
% Arguments:
%  x:  Vector of length 3. x, y, z independent variables in the
%      system.
% Returns:
%  example_sys_out:  Column ector of length 3. f1, f2, f3
%      outputs of each function in the system.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
function example_sys_out = example_sys(x)
    example_sys_out = zeros(3,1);
    example_sys_out(1) = x(1)^2 + x(2)^4 + x(3)^6 - 2;
    example_sys_out(2) = cos(x(1)*x(2)*x(3)^2) - x(1) - x(2) - x(3);
    example_sys_out(3) = x(2)^2 + x(3)^3 - (x(1) + x(2) - x(3))^2;
end

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Jacobian matrix of example nonlinear system given in problem 2
% of Homework 1 document.
%
% Arguments:
%  x:  Vector of length 3. x, y, z independent variables in the
%      System.
% Returns:
%  example_jac_out:  3x3 matrix. Entries of the Jacobian matrix
%      for f1(x,y,z), f2(x,y,z), f3(x,y,z).
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
function example_jac_out = example_jac(x)
    example_jac_out(1,1) = 2*x(1);
    example_jac_out(1,2) = 4*x(2)^3;
    example_jac_out(1,3) = 6*x(3)^5;
    example_jac_out(2,1) = -x(2)*x(3)^2*sin(x(1)*x(2)*x(3)^2) - 1;
```

```
    example_jac_out(2,2) = -x(1)*x(3)^2*sin(x(1)*x(2)*x(3)^2) - 1;
    example_jac_out(2,3) = -2*x(1)*x(2)*x(3)*sin(x(1)*x(2)*x(3)^2) - 1;
    example_jac_out(3,1) = -2*x(1)-2*x(2)+2*x(3);
    example_jac_out(3,2) = -2*x(1)+2*x(3);
    example_jac_out(3,3) = 2*x(1)+2*x(2)+3*x(3)^2-2*x(3);
end

% Root finding
initial_guess = [-1.0; 0.75; 1.50];
NM_3D_tol = 1.0e-6;

roots = newtond(@example_sys, @example_jac, initial_guess, NM_3D_tol)

disp(example_sys(roots));
```