# PHYS 410 Project 1

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October 13, 2024

#### Introduction

In this project, the problem of N identical point charges confined to free motion on the surface of a sphere is examined. Via a finite-difference approximation simulation, the dynamic behaviour of point charges each originating from random initial positions on the surface of the sphere is computed. Since like charges repel, if a velocity-dependent retarding force is present for each charge then it follows that all charges will eventually reach a stable equilibrium where the electrostatic potential energy is minimized.

Through examining the potential energy of these equilibrium configurations as well as conducting equivalence class analysis, the equilibrium configurations of the charges are cataloged and their symmetry is characterized. The equilibrium configurations in this problem are described in detail in the Thomson problem.

In order to test the validity of the numerical model constructed for this problem, convergence testing is also applied. This is done by simulating an identical scenario using multiple discretization levels, and analyzing the level-to-level differences. This convergence testing allows us to determine to which order our finite difference approximation is accurate.

Review of Theory

Equations of motion

Electrostatic Potential Energy

Equivalence Classes

# Numerical Approach

Finite Difference Equations

Convergence Testing

# Implementation

## Results

convtest.m output

plotv.m output

survey.m output

Video of sample evolution

## Conclusions

### Appendix A - charges.m Code

```
\% 5.2 - Top-level function for simulation
 2
    3
     % charges: Top-level function for solution of charges-on-a-sphere
     % problem.
    %
     % Input arguments
    % r0: Initial positions (nc x 3 array, where nc is the number of
    % charges)
     % tmax: Maximum simulation time
     % level: Discretization level
     % gamma: Dissipation coefficient
     % epsec: Tolerance for equivalence class analysis
    % Output arguments
17
     % t: Vector of simulation times (length nt row vector)
18
     % r: Positions of charges (nc x 3 x nt array)
     % v: Potential vector (length nt row vector)
     % v_ec: Equivalence class counts (row vector with length determined
     % by equivalence class analysis)
     \(\frac{\partial \partial \par
      function [t, r, v, v_ec] = charges(r0, tmax, level, gamma, epsec)
24
25
              nt = 2^level + 1;
                                                                            % Number of timesteps
26
              dt = tmax / (nt - 1);
                                                                            % Time period between steps
              t = linspace(0, tmax, nt); % Vector of simulation times
28
29
              % Number of charges
30
              nc = height(r0);
31
32
              % Intialize array for locations of charges throughout all timesteps
33
              r = zeros(nc, 3, nt);
              r(:,:,1) = r0; r(:,:,2) = r0; \%  No initial velocity
36
              % Array for storing the potential at each time step
37
              v = zeros(1, nt);
39
              % Compute for all time steps
40
               for n = 1:nt
41
                       % Compute the position of each charge at the current time step
                        for i = 1:nc
43
                               % We already know all positions at the first two time steps
44
                                if n = 1 \mid \mid n = 2
45
                                         continue
                                end
47
48
                                % Compute electrostatic forces on the current charge
                                es_disp = [0 \ 0 \ 0];
                                for j = 1:nc
51
                                         if j == i
52
                                                  continue
53
                                         es_disp = es_disp + (r(j,:,n-1) - r(i,:,n-1)) / ...
55
                                                               norm(r(j,:,n-1) - r(i,:,n-1))^3;
56
```

```
end
57
58
                % Displacement term depending on location of the charge from 1
59
                one_ts_disp = (2 / dt^2) * r(i,:,n-1);
60
                % Displacement term depending on location of the charge from 2
61
                two_ts_disp = (gamma/(2 * dt) - 1/(dt^2)) * r(i,:,n-2);
62
63
                % Combining all computed displacements prior to normalization
                pos_before_norm = (two_ts_disp + one_ts_disp - es_disp) / ...
65
                                     (1 / dt^2 - gamma/(2 * dt));
66
67
                \% Normalize the position
                pos_norm = pos_before_norm / (norm(pos_before_norm));
69
                % Add to r matrix
70
                r(i, :, n) = pos\_norm;
71
            end
72
73
           % Compute potential at the current time step
            for i = 2:nc
                for j = 1:i-1
                     v(n) = v(n) + 1/(norm(r(j,:,n) - r(i,:,n)));
77
78
            end
79
       end
80
81
       % Compute equivalence classes
82
       % Compute dij matrix
84
       dij = zeros(nc);
85
        for i = 1:nc
86
            for j = 1:nc
87
                dij(i, j) = norm(r(j,:,nt) - r(i,:,nt));
88
89
       end
90
       % Sort each row of matrix to be in ascending order
       dij_sorted = sort(dij, 2);
92
93
       % Vector for storing the number of charges in each equivalence class.
94
       % The number of equivalence classes is the number of nonzero entries
95
       v_{ec} = zeros(1, nc);
96
97
       % Array of flags for if each row has been sorted into an equivalence
           class
       rows_in_ec = zeros(1, nc);
99
100
        for i = 1:nc
101
            if rows_in_ec(i) = 1
102
                continue
103
            end
104
            % If not already matched, create a new equivalence class
106
            v_{ec}(i) = v_{ec}(i) + 1;
107
            rows_in_ec(i) = 1;
108
            for j = 1:nc
110
                if j = i \mid \mid rows_i n_ec(j) = 1
111
```

```
continue
112
                   \quad \text{end} \quad
113
                   \% Check if rows are the same
114
                   if \ all (abs(dij\_sorted(j,:) - dij\_sorted(i,:)) < epsec)\\
115
                         v_{ec}(i) = v_{ec}(i) + 1;
116
                         rows_in_ec(j) = 1;
117
                   \quad \text{end} \quad
118
              end
119
         end
120
121
         % Remove zero entries and sort in descending order
122
         v_{ec}(v_{ec} = 0) = [];
123
         v_ec = sort(v_ec, 'descend');
^{124}
126
   end
```

#### Appendix B - convtest.m Code

```
\% 6.1 - 4-level convergence test
2
   close all; clear; clc;
3
  % Simulation parameters as described in project description
  nc = 4;
  tmax = 10;
  gamma = 1;
   epsec = 1.0e-5;
10
  % Initial conditions of charges
   r0 = [[1, 0, 0]; [0, 1, 0]; [0, 0, 1]; (sqrt(3)/3) * [1, 1, 1]];
12
13
  % Run computation at each discretization level
14
   [t10, r10, v10, v_{ec}10] = charges(r0, tmax, 10, gamma, epsec);
   [t11, r11, v11, v_{ec}11] = charges(r0, tmax, 11, gamma, epsec);
   [t12, r12, v12, v-ec12] = charges(r0, tmax, 12, gamma, epsec);
17
   [t13, r13, v13, v-ec13] = charges(r0, tmax, 13, gamma, epsec);
18
  % x coordinate values of charge one at level 10
  x10 = reshape(r10(1,1,:), size(t10));
  x11 = reshape(r11(1,1,:), size(t11));
  x12 = reshape(r12(1,1,:), size(t12));
  x13 = reshape(r13(1,1,:), size(t13));
24
25
  % Calculating the level-to-level differences, taking every second
26
  % value of the larger length array
  dx10 = downsample(x11, 2) - x10;
28
  dx11 = downsample(x12, 2) - x11;
29
   dx12 = downsample(x13, 2) - x12;
  % First plot all curves for rho = 2
32
  fig1 = figure(1);
33
  rho = 2;
34
  hold on
   plot(t10, dx10, 'LineWidth', 2);
   plot(t11, rho*dx11, 'LineWidth', 2);
   {\tt plot}\,(\,{\tt t12}\,,\ {\tt rho\,\hat{}\,} 2\!*\!{\tt dx12}\,,\ {\tt 'LineWidth\,'}\,,\ 2)\,;
   xlabel("Time");
   vlabel("Difference between level");
40
  legend('dx10', 'rho*dx11', 'rho^2*dx12');
   title ("Convergence test: rho = 2");
  ax = gca;
43
  ax.FontSize = 12;
44
45
  % First plot all curves for rho = 4
  fig2 = figure(2);
47
  rho = 4;
48
   hold on
49
   plot(t10, dx10, 'LineWidth', 2);
   plot(t11, rho*dx11, 'LineWidth', 2);
   {\tt plot}\,(\,{\tt t12}\,,\ {\tt rho\,\hat{}\,} 2\!*\!{\tt dx12}\,,\ {\tt 'LineWidth\,'}\,,\ 2)\,;
52
  xlabel("Time");
  ylabel("Difference between level");
  legend('dx10', 'rho*dx11', 'rho^2*dx12');
  title ("Convergence test: rho = 4");
```

```
ax = gca;
ax . FontSize = 12;
```

### Appendix C - plotv.m Code

```
₩ 6.2 - Time evolution of potential for 12-charge calculation
  close all; clear; clc;
  % Simulation parameters
  nc = 12;
  tmax = 10;
  level = 12;
  gamma = 1;
  epsec = 1.0e-5;
10
  % Generate nc random inital locations for charges
12
  r0 = 2*rand(nc,3) - 1;
13
   for i = 1:nc
14
       r0(i,:) = r0(i,:)/(norm(r0(i,:)));
15
16
17
  % Run simulation
18
  [t, r, v, v_{ec}] = charges(r0, tmax, level, gamma, epsec);
20
  % Plot V(t) vs. t
21
  plot(t,v)
22
  xlabel("Time t")
  ylabel ("Total potential energy V(t)")
  title ({" Potential Energy V(t) vs. time t", ...
          "nc = 12, tmax = 10, level = 12, gamma = 1, epsec = 1.0e-5"})
26
  ax = gca;
  ax.FontSize = 12;
```

### Appendix D - survey.m Code

```
\% 6.3 Survey of V(t_max; N) and v_ec(N) for various values of N
   close all; clear; clc;
3
   tmax = 500;
5
   level = 12;
   gamma = 2;
   epsec = 1.0e-3;
   % Creating file to be written to
10
   fid_v = fopen('vsurvey.dat','w');
    fid_ec = fopen('ecsurvey.dat', 'w');
12
13
    for nc = 2:60
14
         r0 = 2*rand(nc,3) - 1;
15
         for i = 1:nc
16
              r0(i,:) = r0(i,:)/(norm(r0(i,:)));
17
18
         [t, r, v, v_ec] = charges(r0, tmax, level, gamma, epsec);
20
         \label{eq:fid_v} \texttt{fprintf}(\texttt{fid_v} \;,\;\; \text{`\%3d \%16.10\,f} \backslash \texttt{n'} \;,\;\; \texttt{nc} \;,\;\; \texttt{v(end)}) \;;
21
         fprintf(fid_ec , '%3d ', nc);
fprintf(fid_ec , '%d ', v_ec);
fprintf(fid_ec , '\n');
22
24
   end
25
26
   fclose(fid_v);
   fclose (fid_ec);
```