

# GAVIN C. MARTIN

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## EXPERIENCE

### Amazon - Project Kuiper

#### Software Development Engineer II, Constellation Operations

📅 May 2022 – Present

📍 Remote (Irvine, CA)

- Designing and developing mission operations tooling for planning, execution, and automation use cases for the Kuiper satellite constellation
- Building and maintaining hardware-in-the-loop test frameworks for functional and system-level satellite testing
- Developed automated test + mission ops reporting pipelines and dashboards using a variety of AWS services

Python Jupyter Lambda SNS Glue Athena QuickSight

### NASA Jet Propulsion Laboratory

#### Software Systems Engineer, Europa Clipper

📅 Jan 2020 – Apr 2022

📍 Pasadena, CA

- Led the Activity Planning Software development team (10 engineers)
- Designed and implemented models of spacecraft subsystems and instruments for use in planning software
- Architected integrated uplink software and processes to satisfy operational needs for a range of science and engineering stakeholders

Java GraphQL Dagger JUnit Guava Gradle

#### Software Systems Engineering Intern, AMMOS (contracted via Raytheon)

📅 Apr 2019 – Dec 2019

📍 Remote (Austin, TX)

- Collaborated in designing a multi-mission framework for spacecraft activity planning and mission simulation
- Developed a generic discrete event engine for simulating activity plans and predicting resource usage

Java SPICE Toolkit

#### Mission Planning Intern, Europa Clipper

📅 May 2018 – Aug 2018

📍 Pasadena, CA

- Optimized legacy mission modeling and simulation software for speed, scalability, and reliability
- Automated simulation, mission plan analysis, and data delivery workflows

Python Pandas Docker Jenkins MATLAB

### Texas Spacecraft Laboratory

#### Project Manager, Seeker Vision

📅 Oct 2017 – May 2018

📍 Austin, TX

- Designed computer vision system for NASA JSC's Seeker-1 CubeSat mission
- Directed 15+ student development team through successful NASA reviews and flight software delivery
- Trained neural networks to intelligently detect, recognize, and localize nearby vehicles in space

Python TensorFlow OpenCV NumPy Unreal Engine

## EDUCATION

### B.S., Aerospace Engineering

#### The University of Texas at Austin

📅 Aug 2015 – Dec 2019

Engineering Honors Program

Concentration: Space Flight

GPA: 3.81

## SKILLS

### Languages

Java Python Go Bash

### Technologies

AWS Docker Git Linux  
GraphQL Jenkins Jupyter

### Interpersonal

Public Speaking Proj. Management  
Technical Leadership Mentorship

## PROJECTS

### Seeker Vision

- Developed spacecraft detection and relative bearing estimation system for NASA mission using deep neural networks
- Co-architected ML pipeline for synthetic image generation, CNN training, and evaluation

🔗 <https://bit.ly/seeker-vision>

### ADCS Simulator

- Developed object-oriented simulation engine for spacecraft attitude determination and control systems
- Can be used to demonstrate the viability of a specific suite of sensor, actuator, and controller designs
- Detailed models for dynamics, actuators, sensors, and control algorithms in associated paper

🔗 <https://bit.ly/adcs-simulator>

Mission Manager, ARMADILLO CubeSat

Mar 2017 – Nov 2017 Austin, TX

- Constructed operations infrastructure to support a CubeSat funded by the Air Force Research Lab
- Scaled satellite laboratory from 5 to 50+ student engineers

Python PyQt5 Pandas GPredict

General Electric Aviation

Software Engineering Intern

May 2016 – Aug 2016 San Marcos, TX

- Built custom enterprise resource planning software using Java’s Swing framework
- Automated customer service reporting by integrating custom ERP software with Apache POI

Java Swing Apache POI

HONORS & AWARDS

Professional Awards

- Voyager Award (Individual)**  
NASA JPL 2022  
For implementing a proof of concept ...to resolve MOS issues with gathering ... activity definitions
- Team Award**  
NASA 2022  
For excellence in developing comprehensive models and simulations for ... mission architecture and design decisions
- Discovery Award (Individual)**  
NASA JPL 2021  
For shepherding Europa Clipper adaptation of Merlin planning tool
- Bonus Award (Team)**  
NASA JPL 2020  
For contributions to the successful Europa Clipper ... S/W Peer Review
- Voyager Award (Individual)**  
NASA JPL 2020  
For foundational advancement of Europa Clipper and Aerie Merlin simulation and scheduling concepts
- Above & Beyond Bronze Award (Individual)**  
GE Aviation 2016

Academic Honors

- Graduation with Honors**  
UT Cockrell School of Engineering 2019
- Longhorn Poster Session Audience Favorite Award (1st Place)**  
UT Research Week 2019
- Tejas Scholarship**  
UT Office of the Dean of Students 2017 – 2019
- Uniden Corporation of America Endowed Scholarship**  
UT Cockrell School of Engineering 2015 – 2019
- Class of 2019 Representative**  
UT Aerospace Dept. Advisory Board 2015 – 2019
- National Merit Scholar**  
National Merit Scholarship Corp. 2015

FLIGHT PROJECTS

- Kuiper Protosats 1 & 2**  
launches 2023
- Europa Clipper**  
launches October 2024
- Mars Sample Retrieval Lander**  
launches 2028
- Seeker-1 CubeSat**  
launched April 2019
- ARMADILLO CubeSat**  
launched June 2019

PUBLICATIONS

Conference Proceedings

- C. Schubert, K. Black, D. Fonseca, A. Dhir, J. Deutsch, N. Dhamani, **G. Martin**, and M. Akella, “A pipeline for vision-based on-orbit proximity operations using deep learning and synthetic imagery,” in *2021 IEEE Aerospace Conference*, 2021.
- N. Dhamani, **G. Martin**, C. Schubert, P. Singh, N. Hatten, and M. R. Akella, “Applications of machine learning and monocular vision for autonomous on-orbit proximity operations,” in *AIAA Scitech 2020 Forum*, 2020.
- M. Kumar, A. Rothstein-Dowden, and **G. Martin**, “A higher-order temporal reasoning approach to authoring semantically precise flight rules for spacecraft systems,” in *The 16th International Conference on Space Operations 2020*, 2020.

LANGUAGES

English	<div><div></div><div></div><div></div><div></div><div></div></div>
Spanish	<div><div></div><div></div><div></div><div></div><div></div></div>
Italian	<div><div></div><div></div><div></div><div></div><div></div></div>