

gratia: An R package for working with generalized additive models

## Gavin L. Simpson<sup>1</sup>

1 Department of Animal and Veterinary Science, Aarhus University, Denmark

# **Summary**

Generalized additive models (GAMs) are an extension of the generalized linear model (GLM) to allow the effects of one or more covariates on the response to be modelled as a smooth function of the covariate. GAMs are increasingly being used in many applied science subjects because the smooth functions of covariates allow for flexible relationships between covariates and the response to be learned from the data through the use of penalized splines. Within the R ecosystem, Simon Wood's mgcv package is widely used to fit GAMs to data as it is a *Recommended* package that ships with R as part of the default desktop installation. Additionally, a growing number of other R packages build upon mgcv, for example as an engine to fit specialised models not handled by mgcv itself, or to make use of the wide range of splines available in mgcv.

The gratia package builds upon mgcv, providing functions that make working with GAMs fitted using mgcv easier. At its core, gratia takes a *tidy* approach providing ggplot2-based replacements for mgcv's base graphics-based plotting capabilities, functions for model diagnostics and exploration of fitted models, as well as a family of functions for drawing samples from the posterior distribution of a fitted GAM. Additional functionality is provided to facilitate the teaching of GAMs.

In this short paper, I briefly introduce GAMs, before providing an overview of the niche filled by gratia. Finally, I provide a brief example of some of the main features of the gratia.

### Generalized additive models

A GAM has the general form

$$y_i \sim \mathcal{D}(\mu_i, \phi)$$
  
 $g(\mu_i) = \mathbf{A}_i \gamma + \sum_{j=1} f_j(x_{ji})$ 

where observations  $y_i$  are assumed to be conditionally distributed  $\mathcal D$  with expectation  $\mathbb E(y_i)=\mu_i$  and dispersion parameter  $\phi$ . The expectation of  $y_i$  is given by a linear predictor of strictly parametric terms, whose model matrix is  $\mathbf A_i$  with parameters  $\gamma$ , plus a sum of smooth functions of covariates  $f_j()$ . g() is a link function mapping values on the linear predictor to the scale of the response.

### Statement of need

mgcv is state-of-the-art R-based software for fitting GAMs are their extensions to data sets on the order of millions of observations. The package is continually maintained and ships with the standard R installation as a *recommended* package. mgcv provides functions for plotting the estimated smooth functions of a model, as well as for producing model diagnostic

DOI: DOIunavailable

#### Software

- Review 🗗
- Repository 🗗
- Archive 🗗

Editor: Pending Editor ♂

Reviewers:

@Pending Reviewers

**Submitted:** N/A **Published:** N/A

#### License

Authors of papers retain copyright and release the work under a Creative Commons Attribution 4.0 International License (CC BY 4.0).



plots. These functions produce plots using base graphics, the original plotting system for R. One of the original motivations driving the development of gratia was to provide equivalent plotting capabilities for GAMs fitted by mgcv using the ggplot2 package and the grammar of graphics. To facilitate this, gratia provides functions for representing the model terms using tidy principles that are suited to plotting via ggplot2 or manipulation within the tidyverse ecosystem of packages. This functionality allows for high-level plotting using the draw() method, as well as easily customisable plot generation using lower-level functionality.

Taking a Bayesian approach to smoothing with penalized splines, it can be shown that GAMs fitted by mgcv are an empirical Bayes model with improper multivariate normal priors on the basis function coeficients.

```
library("mgcv")
library("gamair")
library("gratia")
library("ggplot2")
library("dplyr")
##
## Attaching package: 'dplyr'
## The following object is masked from 'package:nlme':
##
##
       collapse
## The following objects are masked from 'package:stats':
##
##
       filter, lag
## The following objects are masked from 'package:base':
##
##
       intersect, setdiff, setequal, union
data(chl, package = "gamair")
chl <- chl |>
  as_tibble()
chl
## # A tibble: 13,840 x 6
                lat jul.day bath
##
          lon
                                     chl chl.sw
##
        <dbl> <dbl>
                                          <dbl>
                       <int> <int> <dbl>
##
    1 -0.0018 60.0
                         148
                               120
                                    1.5
                                          1.01
    2 -0.002
               60.4
                         267
                               110
                                    0.9
                                          1.23
##
    3 -0.0058 72.7
                         204
                              2739
                                    0.4
                                          0.391
##
    4 -0.0173 50.6
                         110
                                    0.48
                                44
                                          1.76
    5 -0.0227 53.9
                         212
                                 4
                                    0.4
                                          2.06
    6 -0.0277 53.9
                         212
                                    0.6
                                          2.06
    7 -0.0327 50.3
                                    1.05
##
                         124
                                50
                                         1.73
    8 -0.0671
               55.5
                         273
                                62
                                    1.1
                                          1.17
##
    9 -0.0704
               50.6
                         109
                                44
                                    1.5
                                          1.75
## 10 -0.0707
               53.6
                         137
                                 6
                                   2.65 12.3
## # i 13,830 more rows
m <- gam(chl ~ s(lon, lat, bs = "sos"), data = chl, method = "REML")
summary(m)
##
## Family: gaussian
## Link function: identity
```



```
## Formula:
## chl ~ s(lon, lat, bs = "sos")
##
## Parametric coefficients:
##
             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 1.59802 0.01766 90.51 <2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Approximate significance of smooth terms:
               edf Ref.df F p-value
## s(lon,lat) 45.42
                     49 65.38 <2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## R-sq.(adj) = 0.188 Deviance explained = 19.1%
## -REML = 29847 Scale est. = 4.3144
```