

Gavin Tranquilino

Mechatronics Engineering Student

gtranqui@uwaterloo.ca

gavintranquilino.com

linkedin.com/in/gavintranquilino

github.com/gavintranquilino

EXPERIENCE

Undergraduate Research Assistant

September 2024 – December 2024

University of Waterloo - Engineering IDEAs Clinic

Waterloo, ON

- Instrumented a wearable knee crutch, allowing force readings for gait analysis and material selection via **FEA**.
- Led a **ROS2** workshop for 100+ students, introducing fundamental concepts and streamlining **Docker** installations.
- Built wall-following and swarm robots using **Gazebo** and **TurtleBot3**, showcasing **LIDAR** integration and sensor interfacing in Python.
- Implemented **PID** control algorithms in **C++** and **Python** packages, providing practical demos for 100+ attendees.

Mechanical Engineering Associate

January 2024 – April 2024

Sheartak Tools Ltd.

Waterloo, ON

- Designed 15 custom mechanical assemblies in **SolidWorks** for woodworking machinery to ensure precise fit and function.
- Applied **GD&T** principles to guarantee manufacturing accuracy for custom machine parts.
- Created 25 detailed installation manuals, including parts lists and assembly instructions, ensuring ease of use for customers.
- Developed a **Python** script to upload 2000+ products on Shopify, saving 5 hours of manual work per week.

Robotics Engineering Team Lead

February 2023 – May 2023

Skills Ontario

Etobicoke, ON

- Developed embedded **C/C++** Arduino program to drive 3-phase motors and bluetooth controls.
- Designed custom protoboard assembly using **SMD** and **TH soldering**, saving 30% chassis space.
- Routed electronics using **KiCAD**, resulting in efficient and customized layouts for a custom robot from scratch.
- Drafted aluminum chassis using **AutoCAD**, increasing durability and space in the robot chassis.

PROJECTS

Instrumented Knee Crutch

- Designed a digital CAD twin of an existing knee crutch in **SolidWorks**.
- Established **I2C** and serial comms via Arduino, converting a bathroom scale for real-time load measurements.
- Researched and integrated strain gauges and load cells, raising load measurement range from 10kg to 50kg.
- Prototyped **3D-printed** mounts and knee platforms for strain gauges, ensuring user comfort.
- Built **Python** scripts for force distribution visualization in Matplotlib, with data logging for gait analysis.

Blink Twice If You Need Help

- Designed a computer vision wearable using **OpenCV** for real time eye tracking, triggering immediate calls for assistance.
- Integrated Twilio with **Python** for swift automated emergency calls, reducing response time.

IoT Light Switch Bot/Mount

- Designed a **3D-printed** mount with an integrated web application for remote light switch control.
- Implemented an Ubuntu **Linux** web server, enabling remote **HTTP** access to room lights globally.
- Innovatively enhanced safety by designing a physical light switch mount, eliminating high-voltage work.

TECHNICAL SKILLS

Mechanical: SolidWorks, AutoCAD, GD&T, CAD, 3D Printing, Machine Tools

Electrical: KiCAD, I2C, SPI, UART, Arduino, ESP-IDF, Soldering, Oscilloscope

Software: Python, C, C++, ROS2, Docker, CMake, OpenGL, OpenCV, Linux, Ubuntu, Git

EDUCATION

University of Waterloo

June 2028

Candidate for BAsC in Mechatronics Engineering

Waterloo, ON

- Coursework:** Data Structures, Algorithms, Linear Algebra, Circuits, Structure and Properties of Materials, Object Oriented Programming