## Package 'ChangePointInference'

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Title Inference for Change Points in Piecewise Polynomials via Differencing

Version 0.0.0.9000

**Description** R implementation of the procedure introduced in the paper

``Fast and Optimal Inference for Change Points in Piecewise Polynomials via Differencing". Given a vector of observations from a one dimensional signal + noise model, where the signal is a piecewise polynomial function of known degree, the procedure returns disjoint intervals which must each contain a change point location uniformly at some level specified by the parameter `alpha`.

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cpt

Estimate Change Point Locations

#### **Description**

Estimates the most likely change point location within each of the intervals obtained by calling diffInf.

#### Usage

```
cpt(obj, cpt_loc = "RSS")
```

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#### **Arguments**

obj An object of class cptInference returned by diffInf.

cpt\_loc

Determines how the change point locations will be estimated. Should be one of "midpoint" or "RSS". If <code>cpt\_loc == "midpoint"</code> the change point locations are simply taken to be the midpoints of each interval. If <code>cpt\_loc == "RSS"</code> the change point locations are chosen to be the split points within each interval associated with the piecewsie polynomial fit providing the lowest sum of squared residuals.

#### Value

A vector of estimated change point locations.

```
# Piecewise linear mean with i.i.d. Gaussian noise
set.seed(42)

waves_signal <- c((1:150) * (2**-3), (150:1) * (2**-3), (1:150) * (2**-3), (150:1) * (2**
yy <- waves_signal + rnorm(length(waves_signal), sd = 5)

#' Recover intervals of significance

diffInf_obj <- diffInf(yy, degree = 1)

diffInf_obj

#' plot the intervals of significance

diffInf_obj |> plot(type = "l", col = "grey")

waves_signal |> lines(lty = 2, lwd = 2)

#' recover likely change point locations

cpt(diffInf_obj, "RSS")

cpt(diffInf_obj, "midpoint")

abline(v = cpt(diffInf_obj, "RSS"), col = "red", lty = 2)

abline(v = cpt(diffInf_obj, "midpoint"), col = "blue", lty = 3)
```

diffInf 3

#### **Description**

Identifies sub-intervals of the data sequence which each must contain a change point, in the sense that the mean function cannot be described as a polynomial of degree p, uniformly with probability asymptotically larger than  $1 - \alpha + o(1)$  where  $\alpha \in (0,1)$  can be set by adjusting the parameter alpha. The object returned by this function can be passed to:

- plot: for potting the data along with the intervals of significance returned.
- cpt: for estimating the most probable change point location within each interval recovered.
- predict: for estimating the unobserved piecewise polynomial mean function, using the most likely change point locations recovered by cpt.

#### Usage

```
diffInf(
  yy,
  degree,
  alpha = 0.1,
  gaussian_noise = TRUE,
  independent_noise = TRUE,
  tau = NULL,
  aa = sqrt(2),
  min_scale = floor(sqrt(length(yy))/2),
  HH = NULL
)
```

#### **Arguments**

A numeric vector containing the data to be inspected for change points. уу

degree The degree of polynomial parametrization of the mean of the data.

alpha Desired maximum probability of obtaining an interval that does not contain a change point.

gaussian\_noise

Set to TRUE if the contaminating noise noise is assumed to be independently distributed and Gaussian, with common variance, else set to FALSE.

independent\_noise

Set to TRUE if the contaminating noise is assumed to be independently distributed, else set to FALSE.

Noise level in as measured by the (long run) standard deviation of the noise, if tau know. If tau=NULL the noise level will be estimated via:

- mad\_diff if gaussian\_noise = TRUE and independent\_noise = TRUE.
- sd\_diff if gaussian\_noise = FALSE and independent\_noise = TRUE.
- lrsd\_block\_diff if independent\_noise = FALSE.

Decay parameter controlling the density of the grid on which local tests for the presence of a change point will be performed. Tests will be performed on all contiguous sub-intervals of  $\{1, \ldots, n\}$  whose length is larger than min\_scale and can be expressed as an integer power of aa.

Minimum scale at which local tests for the presence of a change point will be performed.

aa

min\_scale

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НН

Numeric constant appearing in the extreme value limit of the supremum over all local tests, under the null of no change points. If pre-computed the value can be passed to the function. Otherwise, the value is computed automatically using.

#### **Details**

The data supplied in yy are assumed to follow the 'signal + noise' model:

$$Y_t = f_{\circ}(t/n) + \zeta_t \qquad t = 1, \dots, n.$$

Where n is the length of the data sequence,  $f_{\circ}(t/n)$  is a piecewise polynomial function of know degree p, and the noise terms are one of:

- 1. Independently distributed and Gaussian, with common variance.
- 2. Independently distributed with common variance, but not necessarily Gaussian.
- 3. Weakly stationary with strictly positive long run variance.

#### Value

An object of class "list" and "not", which contains the following fields:

- intervals: intervals of significance returned by the procedure.
- thresh: the threshold used to for each local test.
- data: the original input data yy.
- degree: degree of polynomial parametrization of the mean of the data.

```
## Piecewise constant mean with i.i.d. Gaussian noise
set.seed(42)
blocks_signal <- c(rep(0,205),rep(14.64,62),rep(-3.66,41),rep(7.32,164),rep(-7.32,40))
yy <- blocks_signal + rnorm(length(blocks_signal), sd = 5)

## Recover intervals of significance
diffInf_obj <- diffInf(yy, degree = 0)
diffInf_obj

## some examples of how the `diffInf` object can be used
# plot the intervals of significance
diffInf_obj |> plot(type = "l", col = "grey")
blocks_signal |> lines(lty = 2, lwd = 2)
# recover likely change point locations
```

lrsd\_block\_diff 5

```
cpt(diffInf_obj)
abline(v = cpt(diffInf_obj), col = "red", lty = 2)
# estimate the best piecewise polynomial fit based on the change point locations
predict(diffInf_obj)
lines(predict(diffInf_obj), col = "red")
```

lrsd\_block\_diff

(Long Run) Standard Deviation Estimator Based on (p+1)-th Differences of Local Sums of the Data

#### **Description**

Estimates the (long run) standard deviation based on (p+1)-th differences of non-overlapping local sums of the data.

#### Usage

```
lrsd_block_diff(
   yy,
   ww = length(yy)^{
        (1/3)
},
   degree = 0
)
```

#### **Arguments**

yy A numeric vector containing the data.

ww The scale at which local sums of the data will be calculated.

degree The degree of polynomial parametrization of the mean of the data.

```
degree <- 3
nn <- 500

yy <- arima.sim(model = list(ar = 0.5), n = nn) + (1:nn)^{degree}

sd_diff(yy, degree)</pre>
```

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mad\_diff

*Median Absolute Deviation Estimator Using* (p+1)*-th Differences* 

#### **Description**

Estimates the standard deviation using the median of the (p+1)-th difference of the data. Suitable for estimating the scale of the noise when the data sequence is Gaussian with a piecewise polynomial mean of degree p.

#### Usage

```
mad_diff(yy, degree)
```

#### **Arguments**

yy A numeric vector containing the data.

degree The degree of polynomial parametrization of the mean of the data.

#### **Examples**

```
degree <- 3
nn <- 500

yy <- rnorm(nn) + (1:nn)^{degree}

mad_diff(yy, degree)</pre>
```

```
plot.cptInference Plot a 'cptInference' Object
```

#### **Description**

Plots the data and as well as intervals of significance returned by the diffinf.

#### Usage

```
## S3 method for class 'cptInference'
plot(obj, cpt_loc_est = FALSE, ...)
```

#### Arguments

```
obj An object of class 'cptInference'.

cpt_loc_est One of "RSS", "midpoint", or FALSE. If "RSS" or "midpoint" the mosyt likely change pint location within each interval will be plotted. If FALSE only the intervals are plotted.

Additional graphical parameters passed to plot.
```

predict.cptInference 7

#### **Examples**

```
# Piecewise linear mean with i.i.d. Gaussian noise
set.seed(42)
waves_signal <- c((1:150) * (2**-3), (150:1) * (2**-3), (1:150) * (2**-3), (150:1) * (2**
yy <- waves_signal + rnorm(length(waves_signal), sd = 5)

# Recover intervals of significance
diffInf_obj <- diffInf(yy, degree = 1)
diffInf_obj
# plot the intervals of significance
diffInf_obj |> plot("RSS", type = "l", col = "grey")
# plot intervals and minimum RSS split points
diffInf_obj |> plot("RSS", type = "l", col = "grey")
# plot the intervals and their midpoints
diffInf_obj |> plot("midpoint", type = "l", col = "grey")
```

```
predict.cptInference
```

Predict a 'cptInference' Object

#### **Description**

Fits a piecewise polynomial signal to the to the data, using change point locations recovered by cpt

#### Usage

```
## S3 method for class 'cptInference'
predict(obj, cpt_loc = "RSS")
```

#### Arguments

obj An object of class 'cptInference'.

Determines how the change points will be estimated. If <code>cpt\_loc = "RSS"</code> the change points are taken to be the split points within each interval which provide the lowest RSS when a piecewise polynomial function is fitted on the same interval. If <code>cpt\_loc = "midpoint"</code> the change points are taken to be the midpoint of each interval.

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#### **Examples**

```
#' Piecewise linear mean with i.i.d. Gaussian noise
set.seed(42)
waves_signal <- c((1:150) * (2**-3), (150:1) * (2**-3), (1:150) * (2**-3), (150:1) * (2**
yy <- waves_signal + rnorm(length(waves_signal), sd = 5)

#' Recover intervals of significance
diffInf_obj <- diffInf(yy, degree = 1)
diffInf_obj
#' plot the intervals of significance
diffInf_obj |> plot(type = "l", col = "grey")
waves_signal |> lines(lty = 2, lwd = 2)

#' recover fitted signal
lines(predict(diffInf_obj, "RSS"), col = "red", lty = 2, lwd = 2)
lines(predict(diffInf_obj, "midpoint"), col = "blue", lty = 3, lwd = 2)
```

sd\_diff

Standard Deviation Estimator Based On (p+1)-th Differences

#### **Description**

Estimates the standard deviation of the data using the mean on the squared (p+1)-th difference of the data sequence. Suitable for estimating the scale of the noise when the data sequence consists of a piecewise polynomial function contaminated with independently distributed noise having bounded fourth moment.

#### Usage

```
sd_diff(yy, degree)
```

#### **Arguments**

yy A numeric vector containing the data.

degree The degree of polynomial parametrization of the mean of the data.

sd\_diff

```
degree <- 3
nn <- 500

yy <- rt(nn, df = 5) * sqrt(3/5) + (1:nn)^{degree}

sd_diff(yy, degree)</pre>
```

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