Repressilator

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1 Introduction

This Jupyter notebook (Repressilator.ipynb) contains the code used to generate the following examples for the paper "Analysis of Biochemical Oscillators Using Bond Graphs and Linear Control Theory" by Peter Gawthrop and Michael Pan:

• 5. The Repressilator

The examples

- 3. Illustrative Example (system Toy)
- 4. The Sel'kov Oscillator (system Selkov)

are in the notebook Oscillation.ipynb

```
[1]: import BondGraphTools as bgt
     from BondGraphTools.reaction_builder import Reaction_Network
     import numpy as np
     import IPython.display as disp
     import copy
     import scipy.optimize as opt
     import scipy.integrate as int
     ## Control systems package
     import control as con
     con.config.defaults['xferfcn.display_format'] = 'zpk'
     ## Stoichiometric analysis
     import stoich as st
     ## BG from stoichiometry
     import stoichBondGraph as stbg
     # Allow output from within functions
     from IPython.core.interactiveshell import InteractiveShell
     InteractiveShell.ast_node_interactivity = "all"
     #Plotting
     import matplotlib.pyplot as plt
     from cycler import cycler
     ## For reimporting: use imp.reload(module)
     import importlib as imp
     ## Saving data
     import pickle
     quiet = True
     Original = False
     Plotting=False
     SavingData = False
```

```
[2]: ## System
     SystemName = 'Repressilator'
[3]: ## Reduced system order
     redOrder = 3
     largeOrder = 30
[4]: ## Set up parameters to change
     muA\_nom\_0 = 20
     muA_nom = 1.0*muA_nom_0
[5]: def zero_crossings(a):
         """Zero crossings from positive to negative
         return np.where(np.diff(np.sign(a))>0)[0]
[6]: def rn2bg(rn,name):
         n n n
         Reaction network to Bond Graph.
         Creates BG file name.py
         Returns basic stoichiometry
         # Extract stoichiometry from reaction network
         Nf_0 = np.array(rn.forward_stoichiometry)
         Nr_0 = np.array(rn.reverse_stoichiometry)
         N_0 = Nr_0 - Nf_0
         ## sanity check
         SanityCheck(N_0,rn.stoichiometry)
         ## Species and reactions
         species = rn.species
         n_X = len(species)
         reaction = []
         for Reaction in reactions:
             reaction.append(Reaction[1])
         ## Create BG from stoichiometry
         s_0 = \{\}
         s_0['N'] = N_0
         s_0['Nf'] = Nf_0
         s_0['Nr'] = Nr_0
         s_0['species'] = species
         s_0['n_X'] = len(species)
         s_0['reaction'] = reaction
         s_0['name'] = name
         stbg.model(s_0)
         return s_0
```

```
[7]: # def SaveFig(SystemName, PlotName, Plotting=True, fontsize=14, linewidth=5):
            if Plotting:
      #
                plt.rcParams.update({'font.size': fontsize})
                plt.rcParams.update({'lines.linewidth': linewidth})
      #
                plotname = f'Figs/{SystemName}_{PlotName}.pdf'
                plt.savefig(plotname)
 [8]:
      # def SaveFig(SystemName, PlotName, Plotting=True, fontsize=14, linewidth=5):
            if Plotting:
      #
                plt.rcParams.update({'font.size': fontsize})
      #
                plt.rcParams.update({'lines.linewidth': linewidth})
                plt.rcParams.update({'lines.markersize': 4*linewidth})
      #
                plotname = f'Figs/{SystemName}_{PlotName}.pdf'
                plt.savefig(plotname)
 [9]: def SetPlot(fontsize=14,linewidth=5,RL=False):
              ## Sizes
              plt.rcParams.update({'font.size': fontsize})
              plt.rcParams.update({'lines.linewidth': linewidth})
              plt.rcParams.update({'lines.markersize': 6*linewidth})
              ## set up colour cycling for plot
              if RL:
                  ## Root locus colors
                  default_cycler = (cycler(color=['grey', 'grey', 'r', 'g', 'b']))
              else:
                  default_cycler = (cycler(color=['r', 'g', 'b']))
              plt.rc('axes', prop_cycle=default_cycler)
      SetPlot()
[10]: def SaveFig(SystemName, PlotName, fontsize=14, linewidth=5, RL=False):
          if Plotting:
              SetPlot(RL=RL)
              plotname = f'Figs/{SystemName}_{PlotName}.pdf'
              plt.tight_layout()
              plt.savefig(plotname)
[11]: def step_response(sys,T=None):
          resp = con.step_response(sys,T=T)
          t = resp.t
          y = np.array(resp.y).flatten()
          plt.plot(t,y)
          return y
[12]: def impulse_response(sys, T=None):
          resp = con.impulse_response(sys,T=T)
          t = resp.t
          y = np.array(resp.y).flatten()
          plt.plot(t,y)
          return y
```

```
[13]: def initial_response(sys,T=None,x0=0):
          resp = con.initial_response(sys,T=T,x0=x0)
          t = resp.t
          y = np.array(resp.y).flatten()
          plt.plot(t,y)
          return y
[14]: def ExtractSubsystem(Sys,i_in,i_out):
          A_sub = Sys.A
          B_sub = Sys.B[:,i_in]
          C_sub = Sys.C[i_out,:]
          D_sub = Sys.D[i_out,i_in]
          return con.minreal(con.ss(A_sub,B_sub,C_sub,D_sub))
[15]: def SanityCheck(m_1,m_2):
          err = np.max(abs(np.array(m_1)-np.array(m_2)))
          if not err==0:
              print(f'Warning: sanity check failure. err={err}')
[16]: def extractSysdX(Sys,s,chemo,chemostats,outp):
          ## Index of output
          species = s['species']
          i_v = species.index(outp)
          ## Index of input
          i = chemostats.index(chemo)
          sys = con.ss(Sys.A,Sys.B[:,i],Sys.C[i_v,:],Sys.D[i_v,i])
          return sys
      def
       \rightarrowLin(s,sc,parameter=None,x_ss=None,chemostats=[],outvar='dX',Inp=['P','E'],__

→Outp=['P','E'],quiet=True):
          ## Linearise
          SYS = st.lin(s,sc,x_ss=x_ss,parameter=parameter,outvar='dX',quiet=quiet)
          # Extract individual transfer functions
          TF = \{\}
          for inp in Inp:
              for outp in Outp:
                  if not quiet:
                      print(inp,'-->',outp)
                  tf = con.tf(extractSysdX(SYS,s,inp,chemostats,outp))
                  TF[f'\{inp\}_{outp}'] = tf
                  if not quiet:
                      print(tf)
```

```
return TF
```

```
[17]: def SteadyState(s,sc,parameter,x0,OutpVar='P3',Last=150,returnAll=False):
          t = np.linspace(0,Last,1000)
          ndat = st.sim(s,sc=sc,t=t,parameter=parameter,X0=x0,quiet=True)
          x_s = ndat['X'][-1,:]
          # st.plot(s,ndat,dX=False,x_ss=x_ss,species=['P1','P2','P3'],reaction=[])
          # st.plot(s,ndat,dX=True,species=[OutpVar],reaction=[])
          ## Flow into P
          species = s['species']
          v_ss = ndat['dX'][-1, species.index(OutpVar)]
          print('v_ss=',v_ss)
          if returnAll:
              SS = \{\}
              ## Save up all steady-state data
              for key in ndat:
                  if not key in ['t']:
                        print(key)
                      SS[key] = ndat[key][-1,:]
              return x_ss,v_ss,SS
          else:
              return x_ss,v_ss
      def func(x_P):
          print('***', x_P)
          x0[species.index('P3')] = x_P
          x_ss,v_ss = SteadyState(s,OLsc,parameter,x0,OutpVar='P3')
          return v_ss
      def findSteadyState(s,sc,parameter,x0,OutpVar='P3',returnAll=False):
          species = s['species']
          root = opt.fsolve(func,x0[species.index(OutpVar)],xtol=1e-3)
          x_P_ss = root[0]
          x0[species.index(OutpVar)] = x_P_ss
          if returnAll:
              x_s, v_s, S = 
       →SteadyState(s,sc,parameter,x0,OutpVar=OutpVar,returnAll=returnAll)
              return x_ss,SS
          else:
              x_ss,v_ss =
       →SteadyState(s,sc,parameter,x0,OutpVar=OutpVar,returnAll=returnAll)
              return x_ss,x_P_ss
```

```
[18]: def IntegrateTF(L0,crite=1e-4):
          L0_tf = con.tf(L0)
          num0 = LO_tf.num[0][0]
          den0 = L0_tf.den[0][0]
            print(den0)
          ln = len(num0)
          if (abs(num0[ln-1])<crite):
              ## remove s factor in numerator
              num = num0[:ln-1]
              den = den0
          else:
              ## Integrator
              ld = len(den0)
              num = num0
              den = np.zeros(ld+1)
              den[:ld] = den0
          L = con.tf(num,den)
          return L
```

2 Define Model as Reaction Network and Create BondGraph-Tools Model

Define model

```
[19]: reactions = [
          ("A + G1_E = G1_EA", "G1_Tc1"),
          ("G1_EA = G1_E + G1_M", "G1_Tc2"),
          ("G1_E + 2*P2 = G1_EI", "G1_Tc3"),
          ("G1_EA + 2*P2 = G1_EAI", "G1_Tc4"),
          ("G1_M + R = G1_C0", "G1_rb"),
          ("G1_C0 + A = G1_C1 + G1_M", "G1_r1"),
          ("G1_C1 + A = G1_C2", "G1_r2"),
          ("G1_C2 + A = G1_C3", "G1_r3"),
          ("G1_C3 + A = G1_C4", "G1_r4"),
          ("G1_C4 + A = G1_C5", "G1_r5"),
          ("G1\_C5 + A = G1\_C6", "G1\_r6"),
          ("G1\_C6 + A = G1\_C7", "G1\_r7"),
          ("G1_C7 + A = G1_C8", "G1_r8"),
          ("G1_C8 = R + P1", "G1_rt"),
          ("G1_M = G1_XM", "G1_degM"),
          ("P1 = G1_XP", "G1_degP"),
          ("A + G2_E = G2_EA", "G2_Tc1"),
          ("G2\_EA = G2\_E + G2\_M", "G2\_Tc2"),
          ("G2_E + 2*P3 = G2_EI", "G2_Tc3"),
          ("G2\_EA + 2*P3 = G2\_EAI", "G2\_Tc4"),
          ("G2_M + R = G2_{C0}", "G2_{rb}"),
          ("G2_C0 + A = G2_C1 + G2_M", "G2_r1"),
          ("G2_C1 + A = G2_C2", "G2_r2"),
```

```
("G2\_C5 + A = G2\_C6", "G2\_r6"),
          ("G2\_C6 + A = G2\_C7", "G2\_r7"),
          ("G2_C7 + A = G2_C8", "G2_r8"),
          ("G2\_C8 = R + P2", "G2\_rt"),
          ("G2_M = G2_XM", "G2_degM"),
          ("P2 = G2_XP", "G2_degP"),
          ("A + G3_E = G3_EA", "G3_Tc1"),
          ("G3\_EA = G3\_E + G3\_M", "G3\_Tc2"),
          ("G3_E + 2*P1 = G3_EI", "G3_Tc3"),
          ("G3\_EA + 2*P1 = G3\_EAI", "G3\_Tc4"),
          ("G3_M + R = G3_{C0}", "G3_{rb}"),
          ("G3_C0 + A = G3_C1 + G3_M", "G3_r1"),
          ("G3_C1 + A = G3_C2", "G3_r2"),
          ("G3_C2 + A = G3_C3", "G3_r3"),
          ("G3\_C3 + A = G3\_C4", "G3\_r4"),
          ("G3_C4 + A = G3_C5", "G3_r5"),
          ("G3\_C5 + A = G3\_C6", "G3\_r6"),
          ("G3\_C6 + A = G3\_C7", "G3\_r7"),
          ("G3_C7 + A = G3_C8", "G3_r8"),
          ("G3\_C8 = R + P3", "G3\_rt"),
          ("G3_M = G3_XM", "G3_degM"),
          ("P3 = G3_XP", "G3_degP"),
      ]
      rn = Reaction_Network(name="RepressilatorFB")
      for (reaction_string,reaction_name) in reactions:
          rn.add_reaction(reaction_string, name=reaction_name)
      rn.add_chemostat("A")
      rn.add_chemostat("G1_XM")
      rn.add_chemostat("G1_XP")
      rn.add_chemostat("G2_XM")
      rn.add_chemostat("G2_XP")
      rn.add_chemostat("G3_XM")
      rn.add_chemostat("G3_XP")
      if not Original:
          chemostats = ['A', 'G1_XM', 'G1_XP', 'G2_XM', 'G2_XP', 'G3_XM', 'G3_XP']
[20]: if Original: # Use Michaels original version
          model = rn.as_network_model(normalised=True)
      else: # Use the stoichiometric aproach to build model
          s0 = rn2bg(rn, 'RepressilatorFB_abg')
          species = s0['species']
          reaction = s0 ['reaction']
          n_X = s0['n_X']
                                               9
```

 $("G2_C2 + A = G2_C3", "G2_r3"),$ $("G2_C3 + A = G2_C4", "G2_r4"),$ $("G2_C4 + A = G2_C5", "G2_r5"),$

```
import RepressilatorFB_abg as sys_abg
model = sys_abg.model()
```

Set parameters

```
[21]: n = 8
      alpha = np.exp(1.25)
      mu_folding = 20.0
      KP = alpha**n/np.exp(mu_folding)
      mu0_P = n*np.log(alpha) - mu_folding
      A_nom=5800000
      # muA_nom=20
      Kd = 30
      h = 2
      # Calculate thermodynamic constant from amount and chemical potential
      def compute_K(x, mu):
          return (1 / x) * np.exp(mu)
      # Thermodynamic constants
      KR = 1.0
      KM = 1.0
      (model/"C:G1_M").set_param("k",KM)
      (model/"C:G2_M").set_param("k",KM)
      (model/"C:G3_M").set_param("k",KM)
      # Transcription
      w = 4.14
      theta = 4.38
      K_A = compute_K(A_nom, muA_nom)
      r_Tc = w / (K_A * theta)
      RbA = K_A * theta
      RbM = 1e6
      RbI = (100*KP)**h \#Kd*muO_P
      r2 = (1+RbA/RbM)*r_Tc
      r1 = r2*RbM/RbA
      KE = 1
      KEA = KE*RbA*r1/(r1+r2)
      KEI = RbI*KE*KP
      KEAI = RbI*KEA*KP
      r3 = 1e6
      r4 = 1e6
      (rTc1, rTc2, rTc3, rTc4) = (r1, r2, r3, r4)
      (model/"C:G1_E").set_param("k",KE)
      (model/"C:G1_EA").set_param("k",KEA)
      (model/"C:G1_EI").set_param("k",KEI)
      (model/"C:G1_EAI").set_param("k",KEAI)
      (model/"R:G1_Tc1").set_param("r",r1)
      (model/"R:G1_Tc2").set_param("r",r2)
      (model/"R:G1_Tc3").set_param("r",r3)
```

```
(model/"R:G1_Tc4").set_param("r",r4)
(model/"C:G2_E").set_param("k",KE)
(model/"C:G2_EA").set_param("k",KEA)
(model/"C:G2_EI").set_param("k",KEI)
(model/"C:G2_EAI").set_param("k",KEAI)
(model/"R:G2_Tc1").set_param("r",r1)
(model/"R:G2_Tc2").set_param("r",r2)
(model/"R:G2_Tc3").set_param("r",r3)
(model/"R:G2_Tc4").set_param("r",r4)
(model/"C:G3_E").set_param("k",KE)
(model/"C:G3_EA").set_param("k",KEA)
(model/"C:G3_EI").set_param("k",KEI)
(model/"C:G3_EAI").set_param("k",KEAI)
(model/"R:G3_Tc1").set_param("r",r1)
(model/"R:G3_Tc2").set_param("r",r2)
(model/"R:G3_Tc3").set_param("r",r3)
(model/"R:G3_Tc4").set_param("r",r4)
# Translation
\gamma_{max} = 1260
kf = 4 * \gamma_max # Multiplied by 4 to account for 4 ATP molecules per amino_
\rightarrow acid
KCO = 1.0
(model/"C:G1_CO").set_param("k",KCO)
(model/"C:G2_C0").set_param("k",KC0)
(model/"C:G3_C0").set_param("k",KC0)
KC1 = alpha
(model/"C:G1_C1").set_param("k",KC1)
(model/"C:G2_C1").set_param("k",KC1)
(model/"C:G3_C1").set_param("k",KC1)
r1 = kf/np.exp(muA_nom)
(model/"R:G1_r1").set_param("r",r1)
(model/"R:G2_r1").set_param("r",r1)
(model/"R:G3_r1").set_param("r",r1)
for i in range(2, n+1):
    KCi = alpha**i
    (model/f"C:G1_C{i}").set_param("k",KCi)
    (model/f"C:G2_C{i}").set_param("k",KCi)
    (model/f"C:G3_C{i}").set_param("k",KCi)
    ri = kf/np.exp(muA_nom)/(alpha**(i-1))
    (model/f"R:G1_r{i}").set_param("r",ri)
    (model/f"R:G2_r{i}").set_param("r",ri)
    (model/f"R:G3_r{i}").set_param("r",ri)
rd = 100 * kf/(alpha**n)
```

```
(model/"R:G1_rt").set_param("r",rd)
      (model/"R:G2_rt").set_param("r",rd)
      (model/"R:G3_rt").set_param("r",rd)
      rb = 1e-2
      (model/"R:G1_rb").set_param("r",rb)
      (model/"R:G2_rb").set_param("r",rb)
      (model/"R:G3_rb").set_param("r",rb)
      # Degradation
      rdegM = np.log(2)/2
      (model/"R:G1_degM").set_param("r",rdegM)
      (model/"R:G2_degM").set_param("r",rdegM)
      (model/"R:G3_degM").set_param("r",rdegM)
      rdegP = np.log(2)/4/KP
      (model/"R:G1_degP").set_param("r",rdegP)
      (model/"R:G2_degP").set_param("r",rdegP)
      (model/"R:G3_degP").set_param("r",rdegP)
      (model/"C:R").set_param("k",1.0)
      (model/"C:P1").set_param("k",KP)
      (model/"C:P2").set_param("k",KP)
      (model/"C:P3").set_param("k",KP)
[22]: ## Set chemostats
      Large = 1e6
      print(muA_nom)
      mu_XM = np.log(1e-6)
      mu_XP = np.log(1e-10)
      if Original:
          (model/"SS:A").set_param("e",muA_nom)
          (model/"SS:G1_XM").set_param("e",mu_XM)
          (model/"SS:G2_XM").set_param("e",mu_XM)
          (model/"SS:G3_XM").set_param("e",mu_XM)
          (model/"SS:G1_XP").set_param("e",mu_XP)
          (model/"SS:G2_XP").set_param("e",mu_XP)
          (model/"SS:G3_XP").set_param("e",mu_XP)
      else:
          (model/"C:A").set_param("k",np.exp(muA_nom)/Large)
          (model/"C:G1_XM").set_param("k",np.exp(mu_XM)/Large)
          (model/"C:G2_XM").set_param("k",np.exp(mu_XM)/Large)
          (model/"C:G3_XM").set_param("k",np.exp(mu_XM)/Large)
          (model/"C:G1_XP").set_param("k",np.exp(mu_XP)/Large)
```

```
(model/"C:G2_XP").set_param("k",np.exp(mu_XP)/Large)
(model/"C:G3_XP").set_param("k",np.exp(mu_XP)/Large)
```

20.0

3 Set parameters

```
[23]: def SetParameter(Unit=False):
          parameter = {}
          for spec in species:
              comp = 'C:'+spec
              val = (model/comp).params['k']['value']
              if Unit:
                  val=1
              if spec in chemostats:
                   print('chemostat')
                  # val = np.exp(val)
                  print(f'Chemostat {spec}: {val:.2e}')
                  if Unit:
                      val=1
                print(f'{spec} \t{val:.2e}')
              name = f'K_{spec}'
              parameter[name] = val
          for reac in reaction:
              comp = 'R:'+reac
              val = (model/comp).params['r']['value']
              if Unit:
                  val=1
                print(f'{reac} \t{val:.2e}')
              name = f'kappa_{reac}'
              parameter[name] = val
          return parameter
      parameter = SetParameter()
     Chemostat A: 4.85e+02
     Chemostat G1_XM: 1.00e-12
     Chemostat G1_XP: 1.00e-16
     Chemostat G2_XM: 1.00e-12
     Chemostat G2_XP: 1.00e-16
     Chemostat G3_XM: 1.00e-12
     Chemostat G3_XP: 1.00e-16
[24]: ## Write parameters to a function
      f = open('SetParameterRepressilator.py','w')
      chars = f.write('def SetParameterRepressilator():\n')
      for key in parameter:
          str = f"parameter['{key}'] = {parameter[key]}\n"
```

```
# print(str)
chars = f.write(str)
f.close()
```

[25]: # model.constitutive_relations

4 List of Parameters

```
[26]: for par in parameter:
          print(f'{par} = {parameter[par]:.4g}')
     K_A = 485.2
     K_G1_E = 1
     K_G1_EA = 366.2
     K_G1_M = 1
     K_P2 = 4.54e-05
     K_G1_EI = 9.358e-10
     K_G1_EAI = 3.427e-07
     K_R = 1
     K_G1_C0 = 1
     K_G1_C1 = 3.49
     K_G1_C2 = 12.18
     K_G1_C3 = 42.52
     K_G1_C4 = 148.4
     K_G1_C5 = 518
     K_G1_C6 = 1808
     K_G1_C7 = 6311
     K_G1_C8 = 2.203e+04
     K_P1 = 4.54e-05
     K_G1_XM = 1e-12
     K_G1_XP = 1e-16
     K_G2_E = 1
     K_G2_EA = 366.2
     K_G2_M = 1
     K_P3 = 4.54e-05
     K_G2_EI = 9.358e-10
     K_G2_EAI = 3.427e-07
     K_G2_C0 = 1
     K_G2_C1 = 3.49
     K_G2_C2 = 12.18
     K_G2_C3 = 42.52
     K_G2_C4 = 148.4
     K_G2_C5 = 518
     K_G2_C6 = 1808
     K_G2_C7 = 6311
     K_G2_C8 = 2.203e+04
     K_G2_XM = 1e-12
     K_G2_XP = 1e-16
     K_G3_E = 1
     K_G3_EA = 366.2
     K_G3_M = 1
```

- $K_G3_EI = 9.358e-10$
- $K_G3_EAI = 3.427e-07$
- $K_G3_C0 = 1$
- $K_G3_C1 = 3.49$
- $K_G3_C2 = 12.18$
- $K_G3_C3 = 42.52$
- $K_G3_C4 = 148.4$
- $K_G3_C5 = 518$
- $K_G3_C6 = 1808$
- $K_G3_C7 = 6311$
- $K_G3_C8 = 2.203e+04$
- $K_G3_XM = 1e-12$
- $K_G3_XP = 1e-16$
- $kappa_G1_Tc1 = 30.85$
- $kappa_G1_Tc2 = 0.0113$
- $kappa_G1_Tc3 = 1e+06$
- $kappa_G1_Tc4 = 1e+06$
- $kappa_G1_rb = 0.01$
- $kappa_G1_r1 = 1.039e-05$
- $kappa_G1_r2 = 2.976e-06$
- $kappa_G1_r3 = 8.527e-07$
- $kappa_G1_r4 = 2.443e-07$
- $kappa_G1_r5 = 7e-08$
- $kappa_G1_r6 = 2.005e-08$
- $kappa_G1_r7 = 5.746e-09$
- $kappa_G1_r8 = 1.646e-09$
- $kappa_G1_rt = 22.88$
- $kappa_G1_degM = 0.3466$
- $kappa_G1_degP = 3817$
- $kappa_G2_Tc1 = 30.85$
- $kappa_G2_Tc2 = 0.0113$
- $kappa_G2_Tc3 = 1e+06$
- $kappa_G2_Tc4 = 1e+06$
- $kappa_G2_rb = 0.01$
- $kappa_G2_r1 = 1.039e-05$
- $kappa_G2_r2 = 2.976e-06$
- $kappa_G2_r3 = 8.527e-07$
- $kappa_G2_r4 = 2.443e-07$
- $kappa_G2_r5 = 7e-08$
- $kappa_G2_r6 = 2.005e-08$
- $kappa_G2_r7 = 5.746e-09$
- $kappa_G2_r8 = 1.646e-09$
- $kappa_G2_rt = 22.88$
- $kappa_G2_degM = 0.3466$
- $kappa_G2_degP = 3817$
- $kappa_G3_Tc1 = 30.85$
- $kappa_G3_Tc2 = 0.0113$
- $kappa_G3_Tc3 = 1e+06$
- $kappa_G3_Tc4 = 1e+06$
- $kappa_G3_rb = 0.01$
- $kappa_G3_r1 = 1.039e-05$

```
kappa_G3_r2 = 2.976e-06
kappa_G3_r3 = 8.527e-07
kappa_G3_r4 = 2.443e-07
kappa_G3_r5 = 7e-08
kappa_G3_r6 = 2.005e-08
kappa_G3_r7 = 5.746e-09
kappa_G3_r8 = 1.646e-09
kappa_G3_rt = 22.88
kappa_G3_degM = 0.3466
kappa_G3_degP = 3817
```

5 Set initial conditions

```
[27]: # model.state_vars
[28]: def SetState(n_X):
          X0 = np.ones(n_X)
          small = 1e-6
          X0[species.index('G1_E')] =
          X0[species.index('G1_EA')] =
                                         0.25
          X0[species.index('G1_M')] =
          X0[species.index('P2')] = 100.0
          X0[species.index('G1_EI')] =
                                         0.25
          X0[species.index('G1_EAI')] =
                                          0.25
          X0[species.index('R')] = 5000.0
          X0[species.index('G1_C0')] =
                                         small
          X0[species.index('G1_C1')] =
                                         small
          X0[species.index('G1_C2')] =
                                         small
          X0[species.index('G1_C3')] =
                                         small
          X0[species.index('G1_C4')] =
                                         small
          X0[species.index('G1_C5')] =
                                         small
          X0[species.index('G1_C6')] =
                                         small
          X0[species.index('G1_C7')] =
                                         small
          X0[species.index('G1_C8')] =
                                         small
          X0[species.index('P1')] = 100.0
          X0[species.index('G2_E')] =
          X0[species.index('G2_EA')] =
                                         0.25
          X0[species.index('G2_M')] =
                                        small
          X0[species.index('P3')] = 1000.0
          X0[species.index('G2_EI')] =
                                         0.25
          X0[species.index('G2_EAI')] =
                                          0.25
                                         small
          X0[species.index('G2_C0')] =
          X0[species.index('G2_C1')] =
                                         small
          X0[species.index('G2_C2')] =
                                         small
          X0[species.index('G2_C3')] =
                                         small
          X0[species.index('G2_C4')] =
                                         small
          X0[species.index('G2_C5')] =
                                         small
          X0[species.index('G2_C6')] =
                                         small
```

```
X0[species.index('G2_C7')] =
                                         small
         X0[species.index('G2_C8')] =
                                         small
         X0[species.index('G3_E')] =
                                       0.25
         X0[species.index('G3_EA')] =
                                        0.25
         X0[species.index('G3_M')] =
                                       small
         X0[species.index('G3_EI')] =
                                        0.25
         X0[species.index('G3_EAI')] =
                                         0.25
         X0[species.index('G3_C0')] =
                                         small
         X0[species.index('G3_C1')] =
                                         small
         X0[species.index('G3_C2')] =
                                        small
         X0[species.index('G3_C3')] =
                                        small
         X0[species.index('G3_C4')] =
                                         small
         X0[species.index('G3_C5')] =
                                         small
         X0[species.index('G3_C6')] =
                                         small
         X0[species.index('G3_C7')] =
                                         small
         X0[species.index('G3_C8')] =
                                        small
          ## Reset chemostat states with large state so that ln Kx = mu
         for chem in chemostats:
              print('Resetting chemostat:', chem, ' to', Large)
              X0[species.index(chem)] = Large
         return X0
[29]: if Original:
         x0 = np.array([
             0.25, #C: G1_E
             0.25, #C: G1_EA
             1e-6, #C: G1_M
             100.0, #C: P2
             0.25, #C: G1_EI
             0.25, #C: G1\_EAI
             5000.0, #C: R
             1e-6, #C: G1_C0
            1e-6, #C: G1_C1
             1e-6, #C: G1_C2
             1e-6, #C: G1_C3
            1e-6, #C: G1_C4
             1e-6, #C: G1_C5
            1e-6, #C: G1_C6
             1e-6, #C: G1_C7
             1e-6, #C: G1_C8
             100.0, #C: P1
             0.25, #C: G2_E
             0.25, #C: G2_EA,
             1e-6, #C: G2_M,
            1000.0, #C: P3
             0.25, #C: G2_EI
```

0.25, #C: G2_EAI 1e-6, #C: G2_C0 1e-6, #C: G2_C1

```
1e-6, #C: G2_C2
      1e-6, #C: G2_C3
      1e-6, #C: G2_C4
      1e-6, #C: G2_C5
      1e-6, #C: G2_C6
      1e-6, #C: G2_C7
      1e-6, #C: G2_C8
      0.25, #C: G3_E
      0.25, #C: G3_EA
      1e-6, #C: G3_M
      0.25, #C: G3_EI
      0.25, #C: G3_EAI
      1e-6, #C: G3_C0
      1e-6, #C: G3_C1
      1e-6, #C: G3_C2
      1e-6, #C: G3_C3
      1e-6, #C: G3_C4
      1e-6, #C: G3_C5
      1e-6, #C: G3_C6
      1e-6, #C: G3_C7
      1e-6, #C: G3_C8
   1)
else:
   x0 = SetState(n_X)
```

```
Resetting chemostat: A to 1000000.0
Resetting chemostat: G1_XM to 1000000.0
Resetting chemostat: G1_XP to 1000000.0
Resetting chemostat: G2_XM to 1000000.0
Resetting chemostat: G2_XP to 1000000.0
Resetting chemostat: G3_XM to 1000000.0
Resetting chemostat: G3_XP to 1000000.0
```

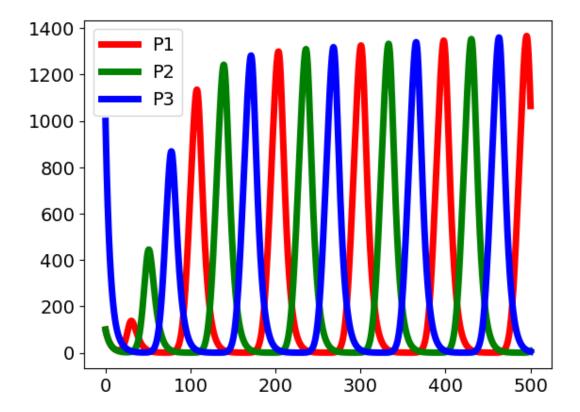
6 Simulate

```
[30]: timespan = [0.0, 500.0] t, x = bgt.simulate(model, timespan=timespan, x0=x0, dt=1e-3)
```

```
[31]: # Protein amounts
    from matplotlib import pyplot as plt
    plt.figure()
    ## Proteins
    iP = [species.index('P1'), species.index('P2'), species.index('P3')]
    ## mRNA
    iM = [species.index('G1_M'), species.index('G2_M'), species.index('G3_M')]
    plt.plot(t,x[:,iP])
    plt.legend(['P1','P2','P3'])
    plt.show()
    plt.plot(t,x[:,iM])
    plt.legend(['M1','M2','M3'])
    plt.show()
```

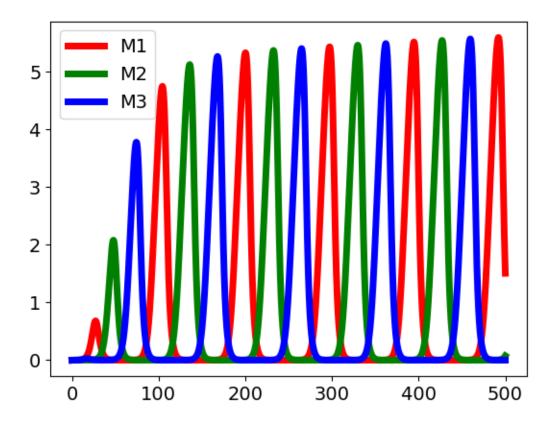
[31]: <Figure size 640x480 with 0 Axes>

[31]: <matplotlib.legend.Legend at 0x7253a3dd7130>



[31]: [<matplotlib.lines.Line2D at 0x7253a3851640>, <matplotlib.lines.Line2D at 0x7253a38516a0>, <matplotlib.lines.Line2D at 0x7253a38435b0>]

[31]: <matplotlib.legend.Legend at 0x7253a3dd7160>

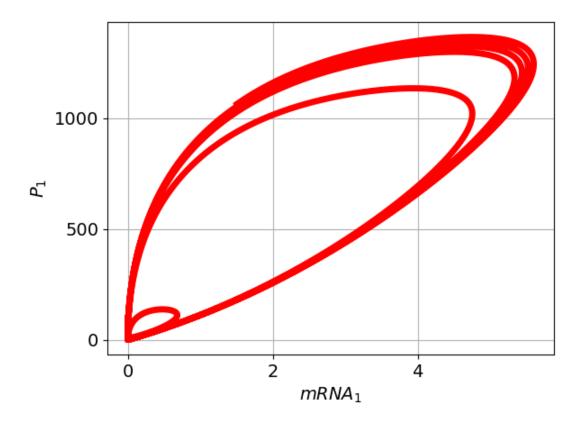


```
[32]: # # mRNA amounts
# plt.figure()
# plt.plot(t,x[:,[2,19,34]])
# plt.show()

[33]: plt.plot(x[:,iM[0]],x[:,iP[0]])
# plt.plot(x_ss[iM[0]],x_ss[iP[0]],marker='+')
plt.locator_params(nbins=4)
plt.grid()
plt.xlabel('$mRNA_1$')
plt.ylabel('$P_1$')
# SaveFig(SystemName, 'PhasePlane')

[33]: [<matplotlib.lines.Line2D at 0x7253a37c40d0>]

[33]: Text(0.5, 0, '$mRNA_1$')
[33]: Text(0, 0.5, '$P_1$')
```



7 Redo with stoichiometric approach

```
[34]: if not Original:
    ## Recreate stoichiometry
        s = st.stoich(sys_abg.model(),quiet=quiet)
        N = s['N']
        Nf = s['Nf']
        Nr = s['Nr']

        ## Sanity check
        SanityCheck(N,s0['N'])
        SanityCheck(Nf,s0['Nf'])
        SanityCheck(Nr,s0['Nr'])
[35]: ## Chemostats
if not Original:
        sc = st.statify(s,chemostats=chemostats)
```

8 Save data - for use in Supplementary.ipynb

```
[36]: if SavingData:
    ## Save data
    SavedData = {}
    StoichData = {}
```

```
StoichData['s'] = s
StoichData['sc'] = sc
StoichData['parameter'] = parameter
SavedData['Stoich'] = StoichData

SysName = 'Repressilator'
file = open(f'{SysName}.dat', 'wb')
pickle.dump(SavedData, file)
file.close()
```

9 List of Reactions

```
[37]: ## Reactions
disp.Latex(st.sprintrl(s,chemformula=False,split=10,all=True))
```

[37]:

$$A + G1E \Leftrightarrow G1EA \tag{1}$$

$$G1EA \Leftrightarrow G1E + G1M \tag{2}$$

$$G1E + 2P2 \Leftrightarrow G1EI \tag{3}$$

$$G1EA + 2P2 \Leftrightarrow G1EAI \tag{4}$$

$$G1M + R \Leftrightarrow G1C0 \tag{5}$$

$$A + G1C0 \Leftrightarrow G1M + G1C1 \tag{6}$$

$$A + G1C1 \Leftrightarrow G1C2 \tag{7}$$

$$A + G1C2 \Leftrightarrow G1C3 \tag{8}$$

$$A + G1C3 \Leftrightarrow G1C4 \tag{9}$$

$$A + G1C4 \Leftrightarrow G1C5 \tag{10}$$

$$A + G1C5 \Leftrightarrow G1C6 \tag{11}$$

$$A + G1C6 \Leftrightarrow G1C7 \tag{12}$$

$$A + G1C7 \Leftrightarrow G1C8 \tag{13}$$

$$G1C8 \Leftrightarrow R + P1 \tag{14}$$

$$G1M \Leftrightarrow G1XM \tag{15}$$

$$P1 \Leftrightarrow G1XP \tag{16}$$

$$A + G2E \Leftrightarrow G2EA \tag{17}$$

$$G2EA \Leftrightarrow G2E + G2M \tag{18}$$

$$G2E + 2P3 \Leftrightarrow G2EI \tag{19}$$

$$G2EA + 2P3 \Leftrightarrow G2EAI \tag{20}$$

$$R + G2M \Leftrightarrow G2C0$$
 (21)
 $A + G2C0 \Leftrightarrow G2M + G2C1$ (22)
 $A + G2C1 \Leftrightarrow G2C2$ (23)
 $A + G2C2 \Leftrightarrow G2C3$ (24)
 $A + G2C3 \Leftrightarrow G2C4$ (25)
 $A + G2C4 \Leftrightarrow G2C5$ (26)
 $A + G2C5 \Leftrightarrow G2C6$ (27)
 $A + G2C6 \Leftrightarrow G2C7$ (28)
 $A + G2C7 \Leftrightarrow G2C8$ (29)
 $G2C8 \Leftrightarrow P2 + R$ (30)

$$G2M \Leftrightarrow G2XM \tag{31}$$

$$P2 \Leftrightarrow G2XP \tag{32}$$

$$A + G3E \Leftrightarrow G3EA \tag{33}$$

$$G3EA \Leftrightarrow G3E + G3M \tag{34}$$

$$2P1 + G3E \Leftrightarrow G3EI \tag{35}$$

$$2P1 + G3EA \Leftrightarrow G3EAI \tag{36}$$

$$R + G3M \Leftrightarrow G3C0 \tag{37}$$

$$A + G3C0 \Leftrightarrow G3M + G3C1 \tag{38}$$

$$A + G3C1 \Leftrightarrow G3C2 \tag{39}$$

$$A + G3C2 \Leftrightarrow G3C3 \tag{40}$$

$$A + G3C3 \Leftrightarrow G3C4 \tag{41}$$

$$A + G3C4 \Leftrightarrow G3C5 \tag{42}$$

$$A + G3C5 \Leftrightarrow G3C6 \tag{43}$$

$$A + G3C6 \Leftrightarrow G3C7 \tag{44}$$

$$A + G3C7 \Leftrightarrow G3C8 \tag{45}$$

$$G3C8 \Leftrightarrow R + P3 \tag{46}$$

$$G3M \Leftrightarrow G3XM \tag{47}$$

$$P3 \Leftrightarrow G3XP \tag{48}$$

10 List of Flows v as Function of States x

```
[38]: ## Flows
disp.Latex(st.sprintvl(s))
```

[38]:

```
v_{G1Tc1} = \kappa_{G1Tc1} \left( K_A K_{G1E} x_A x_{G1E} - K_{G1EA} x_{G1EA} \right)
                                                                                                                           (49)
v_{G1Tc2} = \kappa_{G1Tc2} \left( -K_{G1E}K_{G1M}x_{G1E}x_{G1M} + K_{G1EA}x_{G1EA} \right)
                                                                                                                           (50)
v_{G1Tc3} = \kappa_{G1Tc3} \left( K_{G1E} K_{P2}^2 x_{G1E} x_{P2}^2 - K_{G1EI} x_{G1EI} \right)
                                                                                                                           (51)
v_{G1Tc4} = \kappa_{G1Tc4} \left( K_{G1EA} K_{P2}^2 x_{G1EA} x_{P2}^2 - K_{G1EAI} x_{G1EAI} \right)
                                                                                                                           (52)
  v_{G1rb} = \kappa_{G1rb} \left( -K_{G1C0} x_{G1C0} + K_{G1M} K_R x_{G1M} x_R \right)
                                                                                                                           (53)
  v_{G1r1} = \kappa_{G1r1} \left( K_A K_{G1C0} x_A x_{G1C0} - K_{G1C1} K_{G1M} x_{G1C1} x_{G1M} \right)
                                                                                                                           (54)
  v_{G1r2} = \kappa_{G1r2} \left( K_A K_{G1C1} x_A x_{G1C1} - K_{G1C2} x_{G1C2} \right)
                                                                                                                           (55)
  v_{G1r3} = \kappa_{G1r3} \left( K_A K_{G1C2} x_A x_{G1C2} - K_{G1C3} x_{G1C3} \right)
                                                                                                                           (56)
  v_{G1r4} = \kappa_{G1r4} \left( K_A K_{G1C3} x_A x_{G1C3} - K_{G1C4} x_{G1C4} \right)
                                                                                                                           (57)
  v_{G1r5} = \kappa_{G1r5} \left( K_A K_{G1C4} x_A x_{G1C4} - K_{G1C5} x_{G1C5} \right)
                                                                                                                           (58)
      v_{G1r6} = \kappa_{G1r6} \left( K_A K_{G1C5} x_A x_{G1C5} - K_{G1C6} x_{G1C6} \right)
                                                                                                                           (59)
      v_{G1r7} = \kappa_{G1r7} \left( K_A K_{G1C6} x_A x_{G1C6} - K_{G1C7} x_{G1C7} \right)
                                                                                                                           (60)
      v_{G1r8} = \kappa_{G1r8} \left( K_A K_{G1C7} x_A x_{G1C7} - K_{G1C8} x_{G1C8} \right)
                                                                                                                           (61)
       v_{G1rt} = \kappa_{G1rt} \left( K_{G1C8} x_{G1C8} - K_{P1} K_R x_{P1} x_R \right)
                                                                                                                           (62)
  v_{G1degM} = \kappa_{G1degM} \left( K_{G1M} x_{G1M} - K_{G1XM} x_{G1XM} \right)
                                                                                                                           (63)
  v_{G1degP} = \kappa_{G1degP} \left( -K_{G1XP} x_{G1XP} + K_{P1} x_{P1} \right)
                                                                                                                           (64)
    v_{G2Tc1} = \kappa_{G2Tc1} \left( K_A K_{G2E} x_A x_{G2E} - K_{G2EA} x_{G2EA} \right)
                                                                                                                           (65)
    v_{G2Tc2} = \kappa_{G2Tc2} \left( -K_{G2E} K_{G2M} x_{G2E} x_{G2M} + K_{G2EA} x_{G2EA} \right)
                                                                                                                           (66)
    v_{G2Tc3} = \kappa_{G2Tc3} \left( K_{G2E} K_{P3}^2 x_{G2E} x_{P3}^2 - K_{G2EI} x_{G2EI} \right)
                                                                                                                           (67)
    v_{G2Tc4} = \kappa_{G2Tc4} \left( K_{G2EA} K_{P3}^2 x_{G2EA} x_{P3}^2 - K_{G2EAI} x_{G2EAI} \right)
                                                                                                                           (68)
 v_{G2rb} = \kappa_{G2rb} \left( -K_{G2C0} x_{G2C0} + K_{G2M} K_R x_{G2M} x_R \right)
                                                                                                                           (69)
 v_{G2r1} = \kappa_{G2r1} \left( K_A K_{G2C0} x_A x_{G2C0} - K_{G2C1} K_{G2M} x_{G2C1} x_{G2M} \right)
                                                                                                                           (70)
 v_{G2r2} = \kappa_{G2r2} \left( K_A K_{G2C1} x_A x_{G2C1} - K_{G2C2} x_{G2C2} \right)
                                                                                                                           (71)
 v_{G2r3} = \kappa_{G2r3} \left( K_A K_{G2C2} x_A x_{G2C2} - K_{G2C3} x_{G2C3} \right)
                                                                                                                           (72)
 v_{G2r4} = \kappa_{G2r4} \left( K_A K_{G2C3} x_A x_{G2C3} - K_{G2C4} x_{G2C4} \right)
                                                                                                                           (73)
 v_{G2r5} = \kappa_{G2r5} \left( K_A K_{G2C4} x_A x_{G2C4} - K_{G2C5} x_{G2C5} \right)
                                                                                                                           (74)
 v_{G2r6} = \kappa_{G2r6} \left( K_A K_{G2C5} x_A x_{G2C5} - K_{G2C6} x_{G2C6} \right)
                                                                                                                           (75)
 v_{G2r7} = \kappa_{G2r7} \left( K_A K_{G2C6} x_A x_{G2C6} - K_{G2C7} x_{G2C7} \right)
                                                                                                                           (76)
 v_{G2r8} = \kappa_{G2r8} \left( K_A K_{G2C7} x_A x_{G2C7} - K_{G2C8} x_{G2C8} \right)
                                                                                                                           (77)
 v_{G2rt} = \kappa_{G2rt} \left( K_{G2C8} x_{G2C8} - K_{P2} K_R x_{P2} x_R \right)
                                                                                                                           (78)
```

```
v_{G2deqM} = \kappa_{G2deqM} \left( K_{G2M} x_{G2M} - K_{G2XM} x_{G2XM} \right)
                                                                                                                          (79)
 v_{G2degP} = \kappa_{G2degP} \left( -K_{G2XP} x_{G2XP} + K_{P2} x_{P2} \right)
                                                                                                                          (80)
  v_{G3Tc1} = \kappa_{G3Tc1} (K_A K_{G3E} x_A x_{G3E} - K_{G3EA} x_{G3EA})
                                                                                                                          (81)
  v_{G3Tc2} = \kappa_{G3Tc2} \left( -K_{G3E} K_{G3M} x_{G3E} x_{G3M} + K_{G3EA} x_{G3EA} \right)
                                                                                                                          (82)
  v_{G3Tc3} = \kappa_{G3Tc3} \left( K_{G3E} K_{P1}^2 x_{G3E} x_{P1}^2 - K_{G3EI} x_{G3EI} \right)
                                                                                                                          (83)
  v_{G3Tc4} = \kappa_{G3Tc4} \left( K_{G3EA} K_{P1}^2 x_{G3EA} x_{P1}^2 - K_{G3EAI} x_{G3EAI} \right)
                                                                                                                          (84)
    v_{G3rb} = \kappa_{G3rb} \left( -K_{G3C0} x_{G3C0} + K_{G3M} K_R x_{G3M} x_R \right)
                                                                                                                          (85)
    v_{G3r1} = \kappa_{G3r1} \left( K_A K_{G3C0} x_A x_{G3C0} - K_{G3C1} K_{G3M} x_{G3C1} x_{G3M} \right)
                                                                                                                          (86)
    v_{G3r2} = \kappa_{G3r2} \left( K_A K_{G3C1} x_A x_{G3C1} - K_{G3C2} x_{G3C2} \right)
                                                                                                                          (87)
    v_{G3r3} = \kappa_{G3r3} \left( K_A K_{G3C2} x_A x_{G3C2} - K_{G3C3} x_{G3C3} \right)
                                                                                                                          (88)
              v_{G3r4} = \kappa_{G3r4} \left( K_A K_{G3C3} x_A x_{G3C3} - K_{G3C4} x_{G3C4} \right)
                                                                                                                          (89)
              v_{G3r5} = \kappa_{G3r5} \left( K_A K_{G3C4} x_A x_{G3C4} - K_{G3C5} x_{G3C5} \right)
                                                                                                                          (90)
              v_{G3r6} = \kappa_{G3r6} \left( K_A K_{G3C5} x_A x_{G3C5} - K_{G3C6} x_{G3C6} \right)
                                                                                                                          (91)
             v_{G3r7} = \kappa_{G3r7} \left( K_A K_{G3C6} x_A x_{G3C6} - K_{G3C7} x_{G3C7} \right)
                                                                                                                          (92)
             v_{G3r8} = \kappa_{G3r8} \left( K_A K_{G3C7} x_A x_{G3C7} - K_{G3C8} x_{G3C8} \right)
                                                                                                                          (93)
              v_{G3rt} = \kappa_{G3rt} \left( K_{G3C8} x_{G3C8} - K_{P3} K_R x_{P3} x_R \right)
                                                                                                                          (94)
         v_{G3deqM} = \kappa_{G3deqM} \left( K_{G3M} x_{G3M} - K_{G3XM} x_{G3XM} \right)
                                                                                                                          (95)
          v_{G3deqP} = \kappa_{G3deqP} \left( -K_{G3XP} x_{G3XP} + K_{P3} x_{P3} \right)
                                                                                                                          (96)
```

11 List of State x Derivatives as Function of Flows v.

```
[39]: ## State equations
      imp.reload(st)
      eqns = st.sprintdxl(s,sc)
      disp.Latex(eqns)
```

[39]: <module 'stoich' from

[39]:

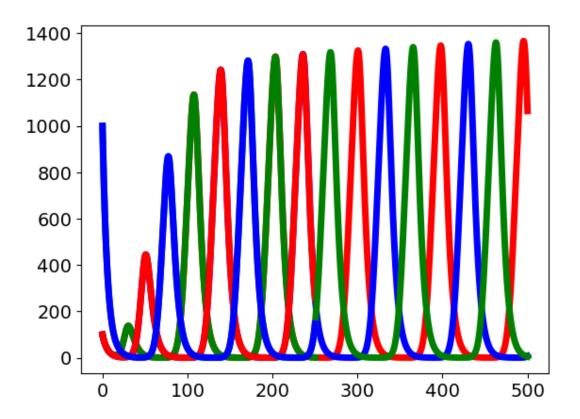
$$\dot{x}_{G1E} = -v_{G1Tc1} + v_{G1Tc2} - v_{G1Tc3} \qquad (97) \\ \dot{x}_{G1EA} = v_{G1Tc1} - v_{G1Tc2} - v_{G1Tc4} \qquad (98) \\ \dot{x}_{G1M} = v_{G1Tc2} - v_{G1rb} + v_{G1r1} - v_{G1degM} \qquad (99) \\ \dot{x}_{P2} = -2v_{G1Tc3} - 2v_{G1Tc4} + v_{G2rt} - v_{G2degP} \qquad (100) \\ \dot{x}_{G1EI} = v_{G1Tc3} \qquad (101) \\ \dot{x}_{G1EAI} = v_{G1Tc4} \qquad (102) \\ \dot{x}_{R} = -v_{G1rb} + v_{G1rt} - v_{G2rb} + v_{G2rt} - v_{G3rb} + v_{G3rt} \qquad (103) \\ \dot{x}_{G1C0} = v_{G1rb} - v_{G1r1} \qquad (104) \\ \dot{x}_{G1C1} = v_{G1r2} - v_{G1r2} \qquad (105) \\ \dot{x}_{G1C2} = v_{G1r2} - v_{G1r3} \qquad (106)$$

```
(107)
  \dot{x}_{G1C3} = v_{G1r3} - v_{G1r4}
                                                                                                 (108)
  \dot{x}_{G1C4} = v_{G1r4} - v_{G1r5}
                                                                                                 (109)
  \dot{x}_{G1C5} = v_{G1r5} - v_{G1r6}
  \dot{x}_{G1C6} = v_{G1r6} - v_{G1r7}
                                                                                                 (110)
  \dot{x}_{G1C7} = v_{G1r7} - v_{G1r8}
                                                                                                 (111)
  \dot{x}_{G1C8} = v_{G1r8} - v_{G1rt}
                                                                                                 (112)
     \dot{x}_{P1} = v_{G1rt} - v_{G1degP} - 2v_{G3Tc3} - 2v_{G3Tc4}
                                                                                                 (113)
   \dot{x}_{G2E} = -v_{G2Tc1} + v_{G2Tc2} - v_{G2Tc3}
                                                                                                 (114)
 \dot{x}_{G2EA} = v_{G2Tc1} - v_{G2Tc2} - v_{G2Tc4}
                                                                                                 (115)
   \dot{x}_{G2M} = v_{G2Tc2} - v_{G2rb} + v_{G2r1} - v_{G2degM}
                                                                                                 (116)
     \dot{x}_{P3} = -2v_{G2Tc3} - 2v_{G2Tc4} + v_{G3rt} - v_{G3deqP}
                                                                                                 (117)
 \dot{x}_{G2EI} = v_{G2Tc3}
                                                                                                 (118)
                                                                                                 (119)
\dot{x}_{G2EAI} = v_{G2Tc4}
                                                                                                 (120)
 \dot{x}_{G2C0} = v_{G2rb} - v_{G2r1}
                                                                                                 (121)
 \dot{x}_{G2C1} = v_{G2r1} - v_{G2r2}
                                                                                                 (122)
 \dot{x}_{G2C2} = v_{G2r2} - v_{G2r3}
                                                                                                 (123)
 \dot{x}_{G2C3} = v_{G2r3} - v_{G2r4}
                                                                                                 (124)
 \dot{x}_{G2C4} = v_{G2r4} - v_{G2r5}
 \dot{x}_{G2C5} = v_{G2r5} - v_{G2r6}
                                                                                                 (125)
                                                                                                 (126)
 \dot{x}_{G2C6} = v_{G2r6} - v_{G2r7}
     \dot{x}_{G2C7} = v_{G2r7} - v_{G2r8}
                                                                                                 (127)
                                                                                                 (128)
     \dot{x}_{G2C8} = v_{G2r8} - v_{G2rt}
                                                                                                 (129)
      \dot{x}_{G3E} = -v_{G3Tc1} + v_{G3Tc2} - v_{G3Tc3}
    \dot{x}_{G3EA} = v_{G3Tc1} - v_{G3Tc2} - v_{G3Tc4}
                                                                                                 (130)
                                                                                                 (131)
     \dot{x}_{G3M} = v_{G3Tc2} - v_{G3rb} + v_{G3r1} - v_{G3deqM}
                                                                                                 (132)
     \dot{x}_{G3EI} = v_{G3Tc3}
                                                                                                 (133)
   \dot{x}_{G3EAI} = v_{G3Tc4}
                                                                                                 (134)
     \dot{x}_{G3C0} = v_{G3rb} - v_{G3r1}
     \dot{x}_{G3C1} = v_{G3r1} - v_{G3r2}
                                                                                                 (135)
                                                                                                 (136)
     \dot{x}_{G3C2} = v_{G3r2} - v_{G3r3}
                                                                                                 (137)
                   \dot{x}_{G3C3} = v_{G3r3} - v_{G3r4}
                                                                                                 (138)
                   \dot{x}_{G3C4} = v_{G3r4} - v_{G3r5}
                   \dot{x}_{G3C5} = v_{G3r5} - v_{G3r6}
                                                                                                 (139)
                                                                                                 (140)
                   \dot{x}_{G3C6} = v_{G3r6} - v_{G3r7}
                   \dot{x}_{G3C7} = v_{G3r7} - v_{G3r8}
                                                                                                 (141)
                   \dot{x}_{G3C8} = v_{G3r8} - v_{G3rt}
                                                                                                 (142)
```

12 Simulate (using stoichiometric approach)

```
[40]: if not Original:
         ## Simulate
         tt = np.linspace(0,250,10000)
         ndat = st.
      ⇒sim(s,sc,reduced=False,t=tt,X0=x0,parameter=parameter,quiet=True)
[41]: ## Sizes
     species = s['species']
     print(f'Number of species = {len(species)} of which {len(chemostats)} are
      Number of species = 53 of which 7 are chemostats giving 46 states.
[42]: # Protein amounts
     iP = [species.index('P1'), species.index('P2'), species.index('P3')]
     for i in iP:
         plt.plot(t,x[:,i])
         plt.plot(tt,ndat['X'][:,i])
     plt.show()
[42]: [<matplotlib.lines.Line2D at 0x7253de9ba460>]
[42]: [<matplotlib.lines.Line2D at 0x7253f0309b20>]
[42]: [<matplotlib.lines.Line2D at 0x7253a3f3ee80>]
[42]: [<matplotlib.lines.Line2D at 0x7253de9ba220>]
[42]: [<matplotlib.lines.Line2D at 0x7253a3c477f0>]
```

[42]: [<matplotlib.lines.Line2D at 0x7253a3767ee0>]



```
[43]: # st.plot(s,ndat,species = ['P1'],reaction = [])

# st.plot(s,ndat,species = ['P2'],reaction = [])

# st.plot(s,ndat,species = ['P3'],reaction = [])

# print(species.index('P3'))
```

13 Power

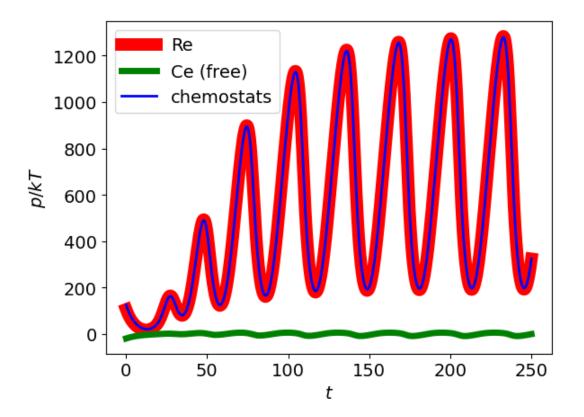
```
[44]: P_Re = ndat['P_Re']
P_C = -ndat['P_C']
i_chemo = []
for chemo in chemostats:
    i_chemo.append(species.index(chemo))

free = list(set(species)-set(chemostats))
print(free)
i_free = []
for fr in free:
    i_free.append(species.index(fr))

P_chemo = P_C[:,i_chemo]
P_free = P_C[:,i_free]

## Total power
PP_Re = np.sum(P_Re,axis=1)
PP_C = np.sum(P_C,axis=1)
```

```
PP_chemo = np.sum(P_chemo,axis=1)
      PP_free = np.sum(P_free,axis=1)
     ['G3_C2', 'G3_C7', 'G1_E', 'G1_EA', 'G3_C4', 'G1_C2', 'G2_EI', 'G1_EAI', 'P1',
     'G1_C0', 'G2_C6', 'G3_C5', 'G3_C8', 'G2_E', 'G1_C5', 'G2_C2', 'G3_C3', 'G2_EA',
     'G1_EI', 'G1_C7', 'G1_C1', 'G2_C1', 'G3_E', 'G3_EAI', 'G3_EI', 'G1_M', 'G1_C3',
     'P2', 'G3_EA', 'G1_C6', 'R', 'G2_C5', 'G2_C4', 'G3_C0', 'G1_C4', 'G2_C8', 'P3',
     'G2_C3', 'G3_C1', 'G3_C6', 'G2_EAI', 'G2_C0', 'G3_M', 'G1_C8', 'G2_M', 'G2_C7']
[45]: t = ndat['t']
      print(t)
      t0 = 0.1
      i0, = np.where(np.isclose(t, t0,atol=(t[1]-t[0])/2))[0]
      print(i0,t[i0])
      print(t[i0:])
      plt.plot(t[i0:],PP_Re[i0:],label='Re',lw=10)
      plt.plot(t[i0:],PP_free[i0:],label='Ce (free)',lw=5)
      plt.plot(t[i0:],PP_chemo[i0:],label='chemostats',lw=2)
      plt.legend()
      plt.xlabel('$t$')
      plt.ylabel('$p/kT$')
      SaveFig(SystemName, 'Power')
     [0.00000000e+00 2.50025003e-02 5.00050005e-02 ... 2.49949995e+02
      2.49974997e+02 2.50000000e+02]
     4 0.1000100010001
     [1.00010001e-01 1.25012501e-01 1.50015002e-01 ... 2.49949995e+02
      2.49974997e+02 2.50000000e+02]
[45]: [<matplotlib.lines.Line2D at 0x7253c420be50>]
[45]: [<matplotlib.lines.Line2D at 0x7253c420bc10>]
[45]: [<matplotlib.lines.Line2D at 0x7253c4844820>]
[45]: <matplotlib.legend.Legend at 0x7253de954190>
[45]: Text(0.5, 0, '$t$')
[45]: Text(0, 0.5, '$p/kT$')
```



```
[46]: t0 = 100
    i0, = np.where(np.isclose(t, t0,atol=(t[1]-t[0])/2))[0]
    print(i0,t[i0])

4000 100.0100010001

[47]: imp.reload(st)
    kT =st.kT()
    print(f'{kT*1e21:.4} zJ')

[47]: <module 'stoich' from
    '/home/peterg/WORK/Research/SystemsBiology/lib/python/stoich.py'>
    4.282 zJ
```

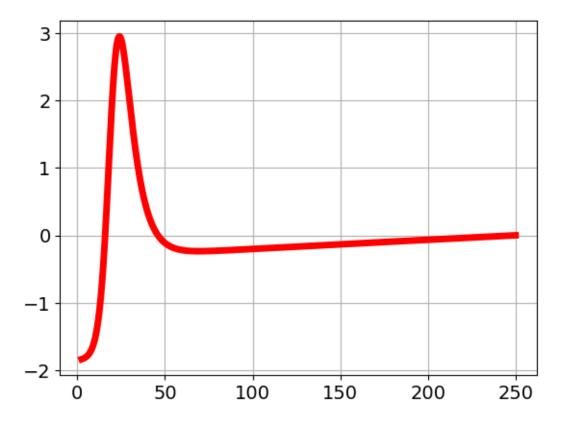
14 Steady state

```
[48]: ##Fix P3
    OLchemostats = copy.copy(chemostats)
    OLchemostats.append('P3')
    print(OLchemostats)
    OLsc = st.statify(s,chemostats=OLchemostats)

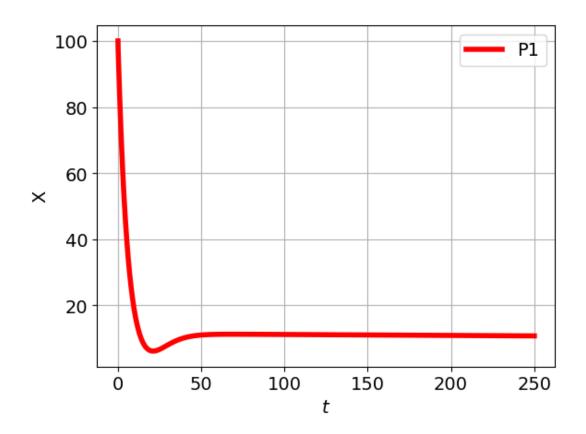
## Guess a vaue for x_P3 to give zero flow
    guess = 10.75855
# Guess = guess+0.0001*np.linspace(-1,1,5)
```

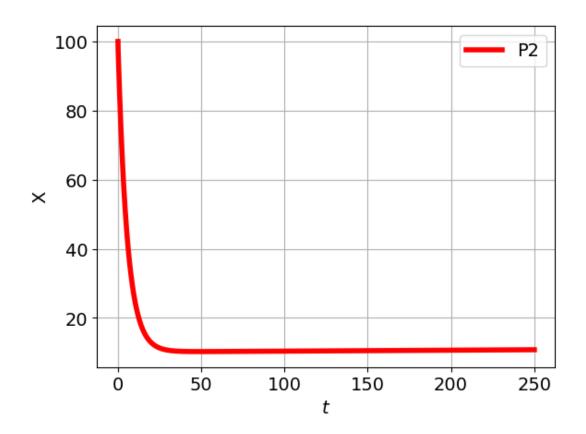
```
Guess = [guess]
      print(Guess)
      i3 = species.index('P3')
      for g in Guess:
          x0[i3] = g
          ## OL simulate
          OLndat = st.
       ⇒sim(s,OLsc,reduced=False,t=tt,X0=x0,parameter=parameter,quiet=True)
          dXP3 = OLndat['dX'][:,i3]
          v_ss = dXP3[-1]
          x_s = OLndat['X'][-1,:]
          print('guess',g, ': v_ss',v_ss)
      # print(x_ss)
      print(species)
     ['A', 'G1_XM', 'G1_XP', 'G2_XM', 'G2_XP', 'G3_XM', 'G3_XP', 'P3']
     [10.75855]
     guess 10.75855 : v_ss -1.3583868704980517e-05
      \hbox{['A', 'G1\_E', 'G1\_EA', 'G1\_M', 'P2', 'G1\_EI', 'G1\_EAI', 'R', 'G1\_CO', 'G1\_C1', } \\
     'G1_C2', 'G1_C3', 'G1_C4', 'G1_C5', 'G1_C6', 'G1_C7', 'G1_C8', 'P1', 'G1_XM',
     'G1_XP', 'G2_E', 'G2_EA', 'G2_M', 'P3', 'G2_EI', 'G2_EAI', 'G2_CO', 'G2_C1',
     'G2_C2', 'G2_C3', 'G2_C4', 'G2_C5', 'G2_C6', 'G2_C7', 'G2_C8', 'G2_XP',
     'G3_E', 'G3_EA', 'G3_M', 'G3_EI', 'G3_EAI', 'G3_CO', 'G3_C1', 'G3_C2', 'G3_C3',
     'G3_C4', 'G3_C5', 'G3_C6', 'G3_C7', 'G3_C8', 'G3_XM', 'G3_XP']
[49]: # for i, spec in enumerate(species):
          print(f"x_ss[species.index('{spec}')] = {x_ss[i]}")
[50]: plt.plot(tt[100:],dXP3[100:])
      plt.grid()
```

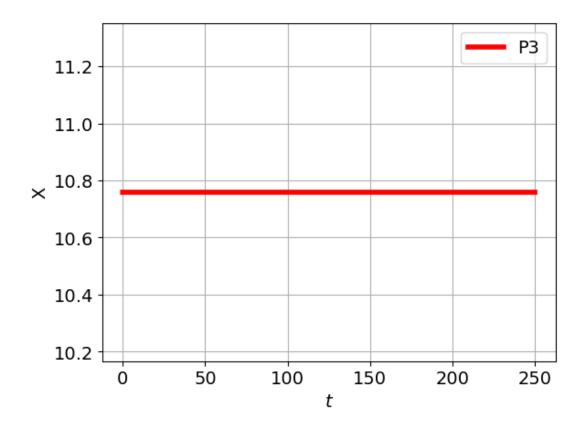
[50]: [<matplotlib.lines.Line2D at 0x7253c5228a60>]

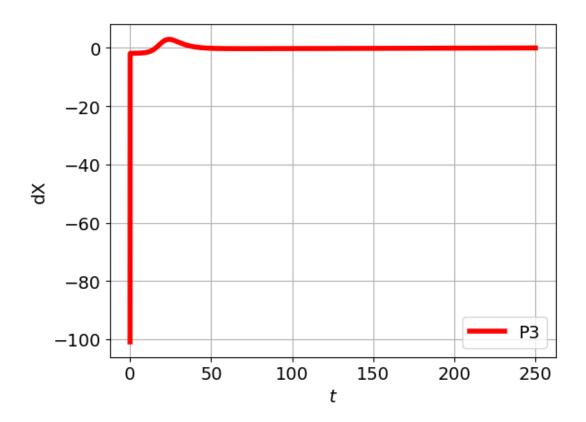


```
[51]: st.plot(s,0Lndat,species = ['P1'],reaction = [])
st.plot(s,0Lndat,species = ['P2'],reaction = [])
st.plot(s,0Lndat,species = ['P3'],reaction = [])
st.plot(s,0Lndat,dX=True,species = ['P3'],reaction=[])
```









```
[52]: ## Refine
    # x_ss,v_ss = SteadyState(s,OLsc,parameter,x0=x_ss)
    # print(v_ss)
    # x_ss,v_ss=findSteadyState(s,OLsc,parameter,x0)
[53]: ## replot with x_ss
```

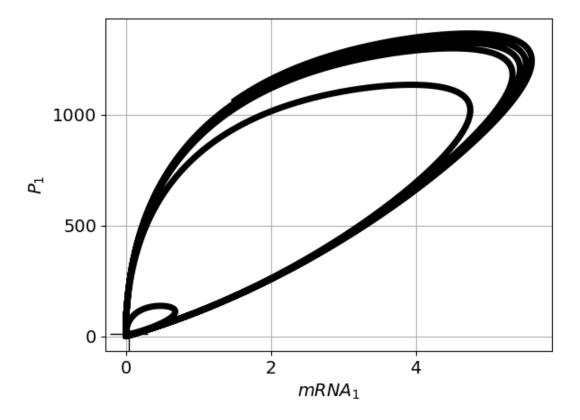
```
[53]: ## replot with x_ss
plt.plot(x[:,iM[0]],x[:,iP[0]],color='black')
plt.plot(x_ss[iM[0]],x_ss[iP[0]],marker='+',color='black')
plt.locator_params(nbins=4)
plt.grid()
plt.xlabel('$mRNA_1$')
plt.ylabel('$P_1$')
SaveFig(SystemName,'PhasePlane')
```

[53]: [<matplotlib.lines.Line2D at 0x7253c47aa340>]

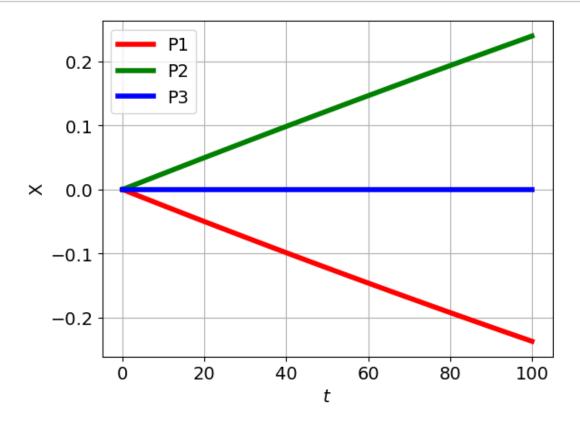
[53]: [<matplotlib.lines.Line2D at 0x7253c47aa820>]

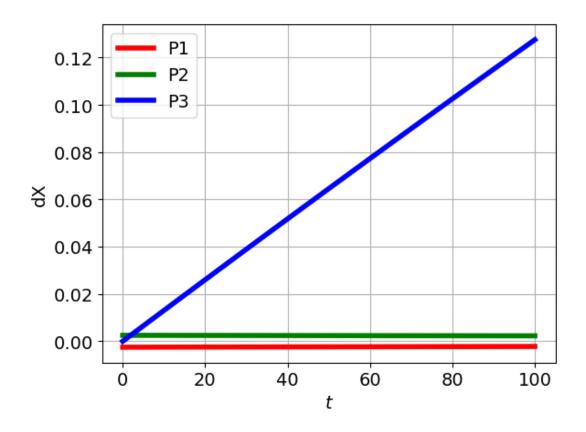
[53]: Text(0.5, 0, '\$mRNA_1\$')

[53]: Text(0, 0.5, '\$P_1\$')



```
[55]: st.plot(s,OLndat_ss,x_ss=x_ss,species=['P1','P2','P3'],reaction=[]) st.plot(s,OLndat_ss,dX=True,species=['P1','P2','P3'],reaction=[])
```





15 Simulate from perturbed steady-state

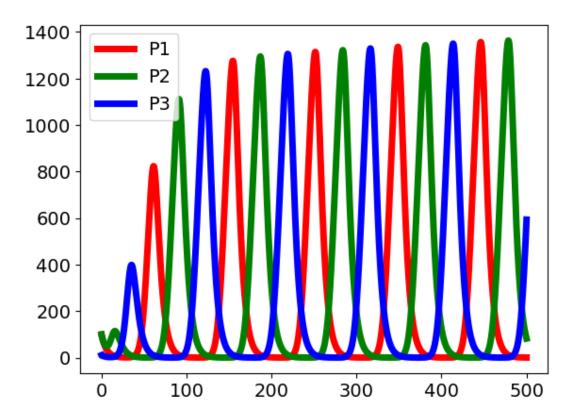
```
[56]: timespan = [0.0, 500.0]
    t_sim, x = bgt.simulate(model, timespan=timespan, x0=x0, dt=1e-3)

[57]: # Protein amounts
    plt.figure()
    ## Proteins
    iP = [species.index('P1'), species.index('P2'), species.index('P3')]
    ## mRNA
    iM = [species.index('G1_M'), species.index('G2_M'), species.index('G3_M')]
    plt.plot(t_sim,x[:,iP])
    plt.legend(['P1','P2','P3'])
    plt.show()
    plt.plot(t_sim,x[:,iM])
    plt.legend(['M1','M2','M3'])
    plt.show()
```

[57]: <Figure size 640x480 with 0 Axes>

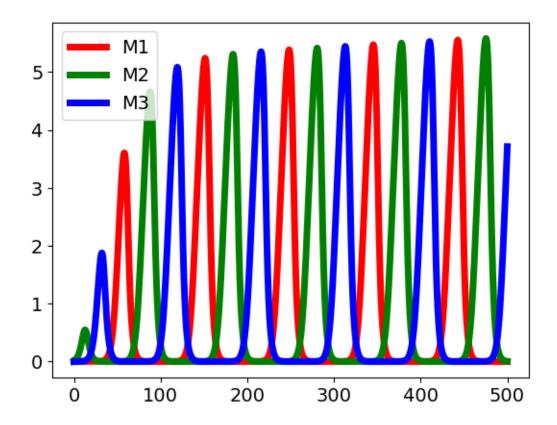
[57]: [<matplotlib.lines.Line2D at 0x7253a3b48550>, <matplotlib.lines.Line2D at 0x7253a3b48b50>, <matplotlib.lines.Line2D at 0x7253a3b487f0>]

[57]: <matplotlib.legend.Legend at 0x7253c4256df0>



```
[57]: [<matplotlib.lines.Line2D at 0x7253a36bb340>, <matplotlib.lines.Line2D at 0x7253a36bb3a0>, <matplotlib.lines.Line2D at 0x7253a36bb3d0>]
```

[57]: <matplotlib.legend.Legend at 0x7253a3520790>



```
[58]: plt.plot(x[:,iM[0]],x[:,iP[0]])
  plt.grid()
  plt.xlabel('$mRNA_1$')
  plt.ylabel('$P_1$')
  plt.plot(x_ss[iM[0]],x_ss[iP[0]],marker='+')
  plt.locator_params(nbins=4)

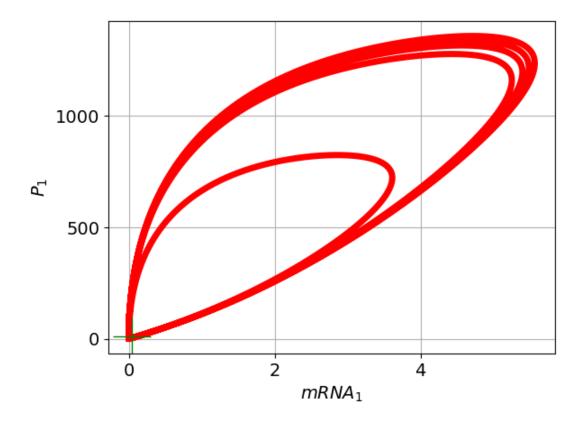
# SaveFig(SystemName, 'PhasePlane')
```

[58]: [<matplotlib.lines.Line2D at 0x7253a3b35e80>]

[58]: Text(0.5, 0, '\$mRNA_1\$')

[58]: Text(0, 0.5, '\$P_1\$')

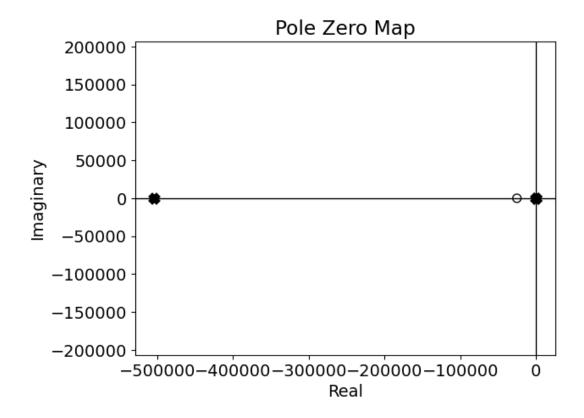
[58]: [<matplotlib.lines.Line2D at 0x7253c45df460>]



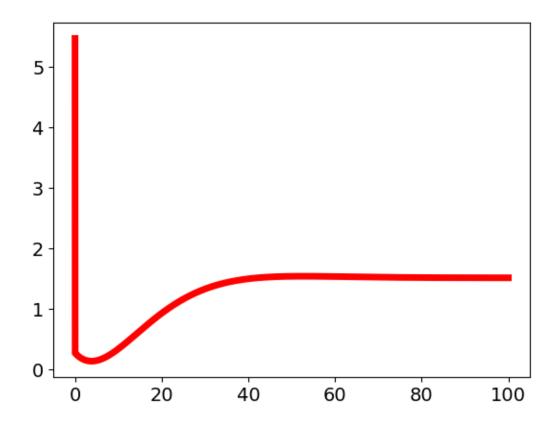
16 Linearise

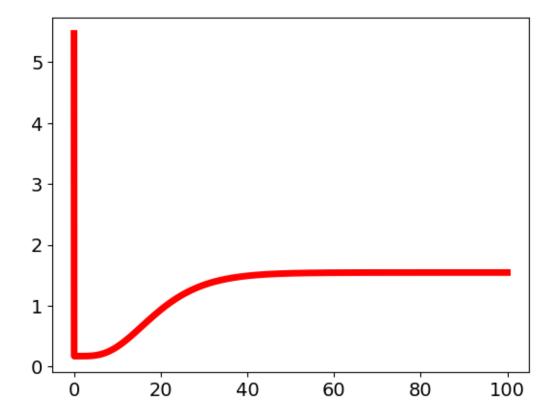
```
[59]: Sys = st.lin(s,OLsc,parameter=parameter,x_ss=x_ss,outvar='dX',quiet=True)
[60]: ## TF \ from \ x_P \ to \ dx_P
      sys = ExtractSubsystem(Sys,OLchemostats.index('P3'),species.index('P3'))
      L0 = -sys
      ## Tf from x_A to dx_P
      sys_F = ExtractSubsystem(Sys,OLchemostats.index('A'),species.index('P3'))
      F0 = sys_F
      # print(np.sort(con.poles(sys)))
      ## Reduced-order subsystems
      print('L0_r:')
      L0_r = con.balred(L0,redOrder)
      LO_lr = con.balred(LO,largeOrder) #make it numerically managable
      con.tf(L0_r)
      pole_r,zero_r = con.pzmap(L0_r,plot=None)
      for i in range(redOrder):
          print(f'Pole:{pole_r[i]:.2e}\t Zero:{zero_r[i]:.2e}')
```

```
print('F0_r:')
      F0_r = con.balred(F0,redOrder)
      con.tf(F0_r)
      ## System + integrator
      L_r = IntegrateTF(L0_r)
      L = IntegrateTF(LO_lr) #make it numerically managable
      \# con.tf(L_r)
     3 states have been removed from the model
     3 states have been removed from the model
     L0_r:
     /home/peterg/anaconda3/envs/bgt/lib/python3.8/site-
     packages/slycot/exceptions.py:241: SlycotResultWarning:
     The selected order 30 is greater
     than the order of a minimal realization of the
     given system. `nr` was set automatically to 15
     corresponding to the order of a minimal realization
     of the system
       warn(globals()[warning](fmessage, iwarn, info))
[60]:
               5.469(s - (0.05911 + 0.2379j))(s - (0.05911 - 0.2379j))(s + 2.535 \times 10^4)
                 (s + (0.08214 - 0.06437j))(s + (0.08214 + 0.06437j))(s + 5.04 \times 10^5)
     Pole:-5.04e+05+0.00e+00j
                                        Zero:-2.54e+04+0.00e+00j
     Pole:-8.21e-02+6.44e-02j
                                        Zero:5.91e-02+2.38e-01j
     Pole:-8.21e-02-6.44e-02j
                                        Zero:5.91e-02-2.38e-01j
     F0_r:
[60]:
                                   0.9396(s + 270.2)(s + 999.7)
                     (s + (484.5 - 1026j))(s + (484.5 + 1026j))(s + 5.045 \times 10^5)
```



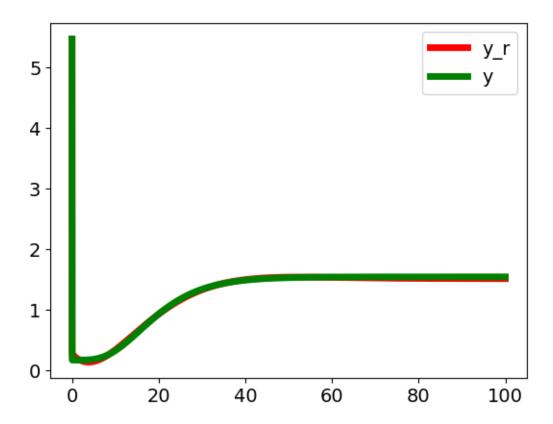
```
[61]: t_ol = np.linspace(0,100,10000)
y_r = step_response(L0_r,T=t_ol)
plt.show()
y = step_response(L0,T=t_ol)
plt.show()
plt.plot(t_ol,y_r,label='y_r')
plt.plot(t_ol,y,label='y')
plt.legend()
```





```
[61]: [<matplotlib.lines.Line2D at 0x7253c4424fd0>]
```

- [61]: [<matplotlib.lines.Line2D at 0x7253c441e310>]
- [61]: <matplotlib.legend.Legend at 0x7253c44214f0>

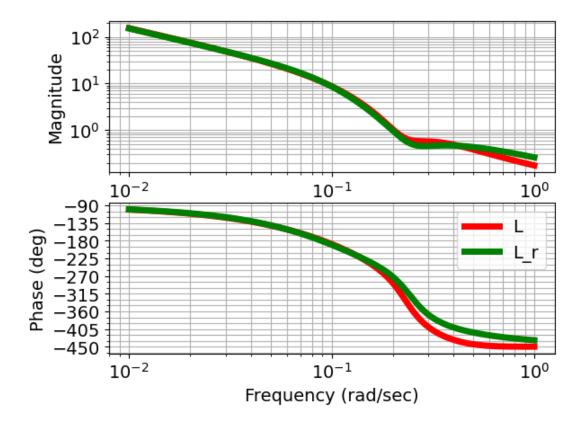


17 Bode Plots of loop-gain

Phase margin = -111 deg at w = 0.2026, f = 0.03225 Hz, period = 31.01 Gain margin = 0.0953 at f = 0.01449 Hz $\theta = -111^\circ$

 $\omega_{pm} = SI\{0.20\}{\radian\per\second}$

[62]: <matplotlib.legend.Legend at 0x7253a3cfb7f0>



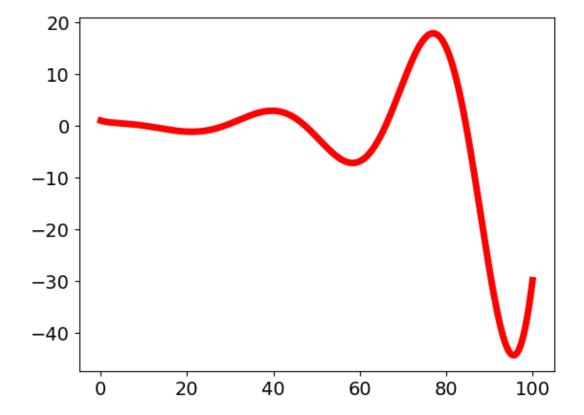
17.1 Linear closed-loop

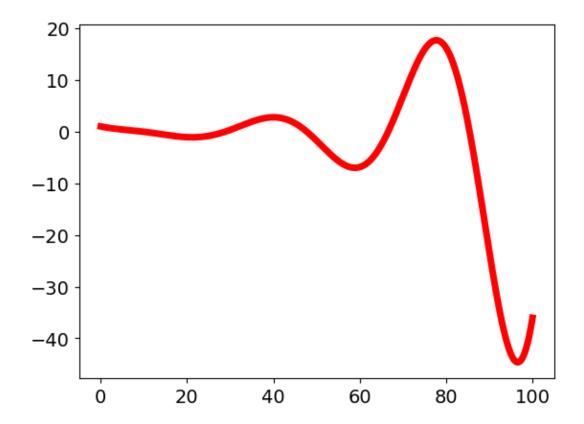
```
[63]: Integrator = con.tf(1,[1,0])
      CLsys = con.feedback(Integrator,L0)
      CLsys_r = con.feedback(Integrator,L0_r)
      # CLsys = con.minreal(con.series(F0,CLsys0))
      # CLsys_r = con.minreal(con.series(F0_r,CLsys0_r))
      con.tf(CLsys_r)
      poles = con.poles(CLsys_r)
      print(poles)
[63]:
                  (s + (0.08214 - 0.06437j))(s + (0.08214 + 0.06437j))(s + 5.04 \times 10^5)
               \overline{(s - (0.0488 + 0.1685j))(s - (0.0488 - 0.1685j))(s + 0.537)(s + 5.04 \times 10^5)}
      [-5.03998114e+05+0.j
                                     -5.36958776e-01+0.j
        4.87967143e-02+0.16850036j 4.87967143e-02-0.16850036j]
[64]: imag = np.imag(poles[2])
      print(imag)
      Freq = imag/(2*np.pi)
      print(Freq)
      print(1/Freq)
```

- 0.1685003566224878
- 0.026817664669216118

37.28885465362298

```
[65]: y_r = impulse_response(CLsys_r,T=t_ol)
plt.show()
y = impulse_response(CLsys,T=t_ol)
plt.show()
plt.plot(t_ol,y_r,label='y_r')
plt.plot(t_ol,y,label='y')
plt.legend()
```

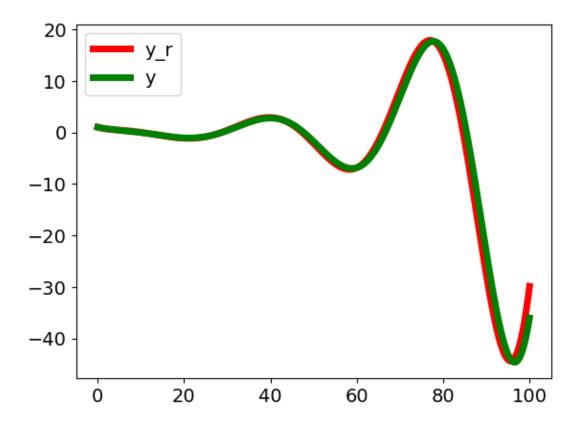




[65]: [<matplotlib.lines.Line2D at 0x7253a2dbf6a0>]

[65]: [<matplotlib.lines.Line2D at 0x7253a2dbfc70>]

[65]: <matplotlib.legend.Legend at 0x7253a2dcfc10>



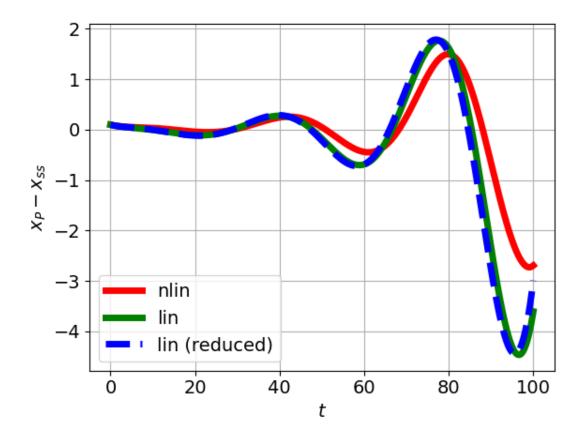
17.2 Non-linear simulation

```
[66]: ## Simulate
      X0 = copy.copy(x_s)
      pert = 0.1
      X0[i3] += pert
      \# t\_sim = np.linspace(0, 130, 10000)
      t_sim = t_ol
      ndat = st.sim(s,sc=sc,t=t_sim,X0=X0,parameter=parameter,quiet=True)
[67]: y_n = (ndat['X'][:,i3] - x_ss[i3])
      plt.plot(t_sim,y_n, label='nlin',lw=5)
      plt.plot(t_ol,pert*y,label='lin',lw=5)
      plt.plot(t_ol,pert*y_r,label='lin (reduced)',lw=5,ls='dashed')
      plt.grid()
      plt.legend()
      plt.xlabel('$t$')
      plt.ylabel('$x_P-x_{ss}$')
      # plt.xlim(right=max(t_ol))
      SaveFig(SystemName, 'Simulation')
[67]: [<matplotlib.lines.Line2D at 0x7253a2d98a00>]
```

[67]: [<matplotlib.lines.Line2D at 0x7253a2d98d60>]

```
[67]: [<matplotlib.lines.Line2D at 0x7253a2d98f10>]
[67]: <matplotlib.legend.Legend at 0x7253a2da6190>
[67]: Text(0.5, 0, '$t$')
```

[67]: Text(0, 0.5, '\$x_P-x_{ss}\$')



17.3 Period

```
[68]: # i_zc = zero_crossings(y_n)

# t_zc = t_sim[i_zc].T

# T_zc = np.diff(t_zc)

# print(t_zc)

# print(T_zc)

# plt.hlines([1/

→Freq],min(t_zc),max(t_zc),ls='dashed',color='grey',label='linear')

# plt.plot(t_zc[1:],T_zc, label='actual')

# plt.grid()

# plt.sqrid()

# plt.sqrid()

# plt.sqrid()(*ft$')

# plt.ylabel('$t$')
```

```
# SaveFig(SystemName, 'Period')
# # print(zc)
# print(1/Freq)
```

18 Split-loop model

```
[69]: OutpVar = 'P3'
      SplitVar = 'P3f'
[70]: | ## Modify orignal list of reactions to insert split-loop variable SplitVar
      SLreactions = []
      for reac in reactions:
          react = reac[0]
          name = reac[1]
          if '2*P3' in react:
              print(f'Reaction {name} is {react}')
              react = react.replace(OutpVar,SplitVar)
              print(f'Reaction {name} is now {react}')
          SLreactions.append((react,name))
      SLrn = Reaction_Network(name="RepressilatorSL")
      for (reaction_string,reaction_name) in SLreactions:
          # print(reaction_name, reaction_string)
          SLrn.add_reaction(reaction_string, name=reaction_name)
     Reaction G2_Tc3 is G2_E + 2*P3 = G2_EI
     Reaction G2_Tc3 is now G2_E + 2*P3f = G2_EI
     Reaction G2\_Tc4 is G2\_EA + 2*P3 = G2\_EAI
     Reaction G2\_Tc4 is now G2\_EA + 2*P3f = G2\_EAI
 []:
[71]: | SLs0 = rn2bg(SLrn, 'RepressilatorSL_abg')
      import RepressilatorSL_abg
      imp.reload(RepressilatorSL_abg)
[71]: <module 'RepressilatorSL_abg' from '/home/peterg/WORK/Research/SystemsBiology/
       →No
      tes/2024/Repressilator/RepressilatorSL_abg.py'>
     18.1
            Stoichiometry
[72]: SLs = st.stoich(RepressilatorSL_abg.model(),quiet=True)
      species_sl = SLs['species']
[73]: for spec in SLs['species']:
          if spec[0] == 'P':
              print(spec)
```

P2 P1

```
A + G2E \Leftrightarrow G2EA
                                                                              (159)
           G2EA \Leftrightarrow G2E + G2M
                                                                              (160)
  G2E + 2P3f \Leftrightarrow G2EI
                                                                              (161)
G2EA + 2P3f \Leftrightarrow G2EAI
                                                                              (162)
      R + G2M \Leftrightarrow G2C0
                                                                              (163)
     A + G2C0 \Leftrightarrow G2M + G2C1
                                                                              (164)
     A + G2C1 \Leftrightarrow G2C2
                                                                              (165)
     A + G2C2 \Leftrightarrow G2C3
                                                                              (166)
     A + G2C3 \Leftrightarrow G2C4
                                                                              (167)
     A + G2C4 \Leftrightarrow G2C5
                                                                              (168)
     A + G2C5 \Leftrightarrow G2C6
                                                                              (169)
     A + G2C6 \Leftrightarrow G2C7
                                                                              (170)
     A + G2C7 \Leftrightarrow G2C8
                                                                              (171)
            G2C8 \Leftrightarrow P2 + R
                                                                              (172)
            G2M \Leftrightarrow G2XM
                                                                              (173)
                P2 \Leftrightarrow G2XP
                                                                              (174)
      A + G3E \Leftrightarrow G3EA
                                                                              (175)
          G3EA \Leftrightarrow G3E + G3M
                                                                              (176)
   2P1 + G3E \Leftrightarrow G3EI
                                                                              (177)
2P1 + G3EA \Leftrightarrow G3EAI
                                                                              (178)
     R + G3M \Leftrightarrow G3C0
                                                                              (179)
    A + G3C0 \Leftrightarrow G3M + G3C1
                                                                              (180)
    A + G3C1 \Leftrightarrow G3C2
                                                                              (181)
    A + G3C2 \Leftrightarrow G3C3
                                                                              (182)
    A + G3C3 \Leftrightarrow G3C4
                                                                              (183)
    A + G3C4 \Leftrightarrow G3C5
                                                                              (184)
    A + G3C5 \Leftrightarrow G3C6
                                                                              (185)
    A + G3C6 \Leftrightarrow G3C7
                                                                              (186)
     A + G3C7 \Leftrightarrow G3C8
                                                                              (187)
           G3C8 \Leftrightarrow R + P3
                                                                              (188)
           G3M \Leftrightarrow G3XM
                                                                              (189)
               P3 \Leftrightarrow G3XP
                                                                              (190)
```

```
[76]: species_sl = SLs['species']
species = s['species']
# print(len(species_sl), species_sl)
```

18.2 Steady-state analysis

```
[77]: ## Create the steady state corresponding to open loop with x_inh=x_P:S
    x_sl_ss = np.ones(SLs['n_X'])
    X_ss = copy.copy(x_ss)
    for i,spec in enumerate(species):
        # print(spec)
        x_sl_ss[species_sl.index(spec)] = X_ss[i]
    x_sl_ss[species_sl.index(SplitVar)] = X_ss[species.index(OutpVar)]

## Make parameters the same
    K_out = parameter['K_'+OutpVar]
    # print(K_out)
    parameter['K_'+SplitVar] = K_out
```

18.3 Linearise

```
[79]: Sys = st.lin(SLs,SLsc,parameter=parameter,x_ss=x_sl_ss,outvar='dX',quiet=True)
```

```
[80]: Inp = [SplitVar,OutpVar]
      Outp = Inp
      TF = \{\}
      for inp in Inp:
          for outp in Outp:
              key = inp+'_'+outp
              print(key)
              sys = ExtractSubsystem(Sys,SLchemostats.index(inp),species_sl.
       →index(outp))
              degree = len(sys.B)
              print(degree)
              # maxdegree = 4
              print('gain',con.dcgain(sys))
              if degree>redOrder:
                  sys_r = con.balred(sys,redOrder)
              else:
                  sys_r = sys
              sys_r = con.minreal(sys_r,tol = 1e-6)
              print('gain_r',con.dcgain(sys_r))
              con.tf(sys_r)
              print(con.poles(sys_r))
              TF[key] = con.tf(sys_r)
```

```
P3f_P3f
39 states have been removed from the model
2
```

```
gain -7.202571872255703e-15
     O states have been removed from the model
     gain_r 9.202361095361766e-13
[80]:
                             \frac{-0.1019(s - 2.262 \times 10^{-9})(s + 1.497 \times 10^{10})}{(s + 87.72)(s + 1.497 \times 10^{10})}
      [-1.49684864e+10+0.j -8.77191299e+01+0.j]
     P3f P3
     3 states have been removed from the model
     gain -1.3731107731905767
     O states have been removed from the model
     gain_r -1.3875522550223096
[80]:
                        -0.005713(s - (0.6279 + 0.494j))(s - (0.6279 - 0.494j))
                     \overline{(s+0.08603)(s+(0.1119-0.1342j))(s+(0.1119+0.1342j))}
      [-0.08602848+0.j
                                 -0.11193919+0.13422377j -0.11193919-0.13422377j]
     P3_P3f
     5 states have been removed from the model
     gain -7.622218992898018e-17
     3 states have been removed from the model
     gain_r 0.0
     /home/peterg/anaconda3/envs/bgt/lib/python3.8/site-
     packages/scipy/signal/_filter_design.py:1746: BadCoefficients: Badly conditioned
     filter coefficients (numerator): the results may be meaningless
        warnings.warn("Badly conditioned filter coefficients (numerator): the "
     /home/peterg/anaconda3/envs/bgt/lib/python3.8/site-
     packages/scipy/signal/_filter_design.py:1091: RuntimeWarning: invalid value
     encountered in divide
        b /= b[0]
[80]:
                                                  0
      P3_P3
     4 states have been removed from the model
     gain -0.17328680660197282
     2 states have been removed from the model
     gain_r -0.1732867955062929
[80]:
                                       \frac{-5.367(s+1.627\times10^4)}{s+5.04\times10^5}
      [-504000.0112114+0.j]
```

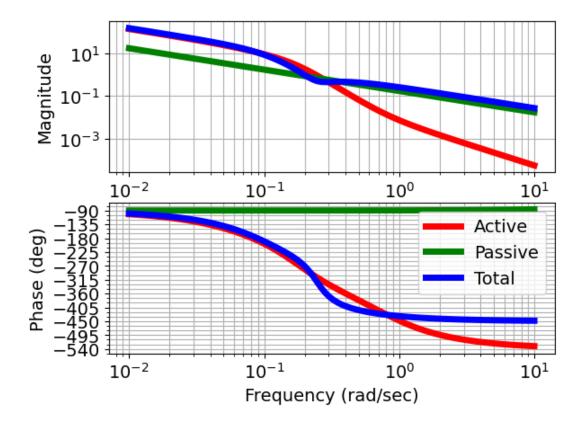
18.4 Active and passive loop gains

```
[81]: \# print(f'Gain L0 = \{con.dcgain(L0):.2f\}')
      \# LO_pas_P = TF['P_P']
      # K = parameter['K_decr3_A']*parameter['kappa_decr3_r']
      # K_f = parameter['kappa_decr3_rf']
      # print(f'Gain LO_pas_P = {con.dcgain(LO_pas_P):0.2f} ({K_f:0.2f})')
[82]: LL0 = con.tf(0,1)
      for index in TF:
          LLO = con.parallel(LLO,-TF[index])
      LL = IntegrateTF(LL0)
      LLO_r = con.tf(con.balred(con.ss(LLO),redOrder))
      LL_r = IntegrateTF(LL0_r)
      ## Check the same as derived from OL analysis
      print('LLO_r (from open-loop')
      con.tf(LLO_r)
      print('L0_r (from split-loop)')
      con.tf(L0_r)
      LO_act = -TF[SplitVar+'_'+OutpVar]
      L_act = IntegrateTF(L0_act)
      L0_act_r = con.tf(con.balred(con.ss(L0_act),redOrder))
      print(f'L0_act_r: ({con.dcgain(L0_act_r):0.2f})')
      con.tf(L0_act_r)
      LO_pas = con.minreal(con.
      →parallel(-TF[OutpVar+'_'+OutpVar],-TF[SplitVar+'_'+SplitVar]),tol=1e-3)
      print('L0_pas')
      print(f'L0_pas: ({con.dcgain(L0_pas):0.2f})')
      con.tf(L0_pas)
      L_pas = IntegrateTF(L0_pas)
      \# LO_pas_r = con.tf(con.balred(con.ss(LO_pas), redOrder))
      # print('L0_pas_r')
      # con.tf(L0_pas)
      LO_pas_P = con.minreal(-TF[OutpVar+'_'+OutpVar])
      L_pas_P = IntegrateTF(L0_pas_P)
      # L0_pas_P_r = con.tf(con.balred(con.ss(L0_pas_P),red0rder))
      print(f'L0_pas_P: ({con.dcgain(L0_pas_P):0.2f})')
      con.tf(L0_pas_P)
      LO_pas_Inh = con.minreal(-TF[SplitVar+'_'+SplitVar])
      L_pas_Inh = IntegrateTF(L0_pas_Inh)
      print(f'L0_pas_Inh: ({con.dcgain(L0_pas_Inh):0.2f})')
      con.tf(L0_pas_Inh)
```

LLO_r (from open-loop

```
[82]:
                   5.469(s - (0.0591 + 0.2379j))(s - (0.0591 - 0.2379j))(s + 2.535 \times 10^4)
                    (s + (0.08215 - 0.06438j))(s + (0.08215 + 0.06438j))(s + 5.04 \times 10^5)
      L0_r (from split-loop)
[82]:
                  5.469(s - (0.05911 + 0.2379j))(s - (0.05911 - 0.2379j))(s + 2.535 \times 10^4)
                    (s + (0.08214 - 0.06437i))(s + (0.08214 + 0.06437i))(s + 5.04 \times 10^5)
      L0_act_r: (1.39)
[82]:
                           0.005713(s - (0.6279 + 0.494j))(s - (0.6279 - 0.494j))
                        \overline{(s+0.08603)(s+(0.1119-0.1342i))(s+(0.1119+0.1342i))}
      1 states have been removed from the model
      L0_pas
      LO_pas: (0.17)
[82]:
                                      \frac{5.469(s+55.17)(s+2.539\times 10^4)}{(s+87.72)(s+5.04\times 10^5)}
      O states have been removed from the model
      LO_pas_P: (0.17)
[82]:
                                            \frac{5.367(s+1.627\times10^4)}{s+5.04\times10^5}
      1 states have been removed from the model
      L0_pas_Inh: (-0.00)
[82]:
                                           \frac{0.1019(s - 2.262 \times 10^{-9})}{s + 87.72}
[83]: L_list = [L_act,L_pas,LL_r]
       Omega = np.logspace(-2,1,100)
       mag,phase,om=con.bode_plot(L_list,omega=Omega)
       plt.legend(['Active','Passive','Total','Reduced'])
       # SaveFig(SystemName, 'SplitBode')
```

[83]: <matplotlib.legend.Legend at 0x7253c41c2fa0>



```
[84]: ## Margins
gm, pm, wcg, wcp = con.margin(LL_r)
print(pm,wcp)
```

-89.798689160331 0.19851803296821272

[]:

18.5 Nichols plots

```
[85]: # ## Nichols
# con.nichols_plot(L_list,omega)
# plt.legend(['Active', 'Passive', 'Total'])
# SaveFig(SystemName, 'SplitNichols')
```

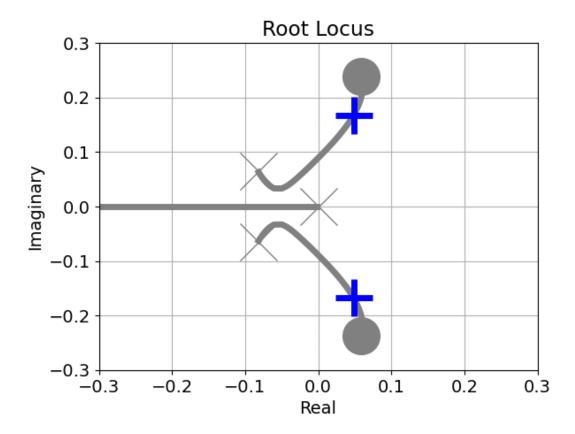
18.6 Root Locus

```
[86]: xlim=(-0.3,0.3)
ylim=(-0.3,0.3)
kvect = np.logspace(-3,1,100)
# roots1, gains1 = con.root_locus(L_r, kvect=[1], plot=False)
# roots, gains=con.root_locus(L_r, kvect=kvect, xlim=xlim, ylim=ylim, grid=False)
# plt.plot(np.real(roots1), np.imag(roots1), color='red', marker='+', \_
\timestyle='dashed', markersize=16)
# plt.grid()
# SetPlot(RL=True)
```

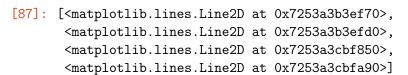
```
# SaveFig(SystemName, 'SplitRootLocus', RL=True)
# SetPlot()

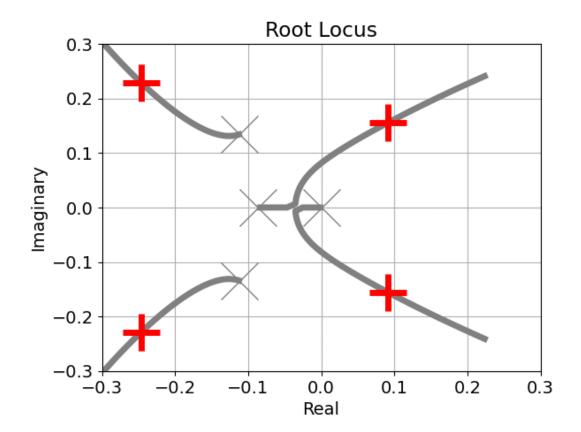
SetPlot(RL=True)
roots1,gains1 = con.root_locus(L,kvect=[1],plot=False)
roots,gains=con.root_locus(L_r,kvect=kvect,xlim=xlim,ylim=ylim,grid=False)
plt.plot(np.real(roots1),np.imag(roots1),color='b', marker='+',mew=5)
plt.grid()
SaveFig(SystemName, 'SplitRootLocus', RL=True)
SetPlot()
```

```
[86]: [<matplotlib.lines.Line2D at 0x7253a36d4550>,
       <matplotlib.lines.Line2D at 0x7253a36d4a00>,
       <matplotlib.lines.Line2D at 0x7253a36d49d0>,
       <matplotlib.lines.Line2D at 0x7253c494e3a0>,
       <matplotlib.lines.Line2D at 0x7253c494edf0>,
       <matplotlib.lines.Line2D at 0x7253c494e610>,
       <matplotlib.lines.Line2D at 0x7253c494ef40>,
       <matplotlib.lines.Line2D at 0x7253de827160>,
       <matplotlib.lines.Line2D at 0x7253de827040>,
       <matplotlib.lines.Line2D at 0x7253de827d90>,
       <matplotlib.lines.Line2D at 0x7253de827d30>,
       <matplotlib.lines.Line2D at 0x7253de827b80>,
       <matplotlib.lines.Line2D at 0x7253de827610>,
       <matplotlib.lines.Line2D at 0x7253de8270a0>,
       <matplotlib.lines.Line2D at 0x7253c4735190>,
       <matplotlib.lines.Line2D at 0x7253c4735580>]
```



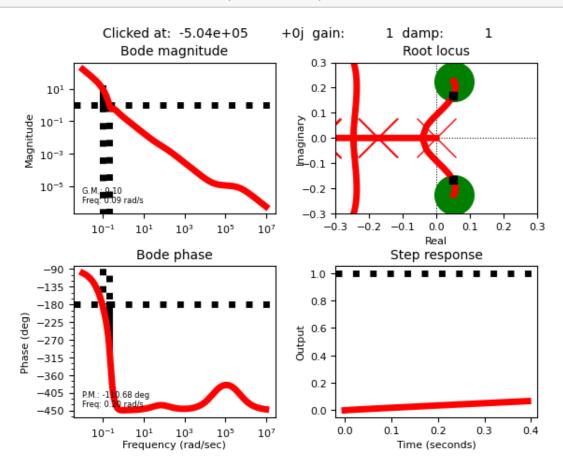
```
[87]: xlim=(-0.3,0.3)
      ylim=(-0.3,0.3)
      kvect = np.logspace(-3,1,100)
      # roots1, gains1 = con.root_locus(L_act,kvect=[1],plot=False)
      # roots, gains=con.root_locus(L_act, kvect=kvect, xlim=xlim, ylim=ylim, grid=False)
      # plt.plot(np.real(roots1),np.imag(roots1),color='red', marker='+',
      → linestyle='dashed', markersize=16)
      # plt.grid()
      # SetPlot(RL=True)
      # SaveFig(SystemName, 'SplitRootLocus_act', RL=True)
      # SetPlot()
      SetPlot(RL=True)
      roots1,gains1 = con.root_locus(L_act,kvect=[1],plot=False)
      roots,gains=con.root_locus(L_act,kvect=kvect,xlim=xlim,ylim=ylim,grid=False)
      plt.plot(np.real(roots1),np.imag(roots1),color='r', marker='+',mew=5)
      SaveFig(SystemName, 'SplitRootLocus_act', RL=True)
      SetPlot()
```





18.7 Sisotool

[88]: con.sisotool(L,xlim_rlocus=xlim,ylim_rlocus=ylim)



18.8 Bode (replotted)

```
[89]: Name = ['Active', 'Passive', 'Total', 'Reduced']
# Omega = np.logspace(-2,0)
for i,1 in enumerate(L_list):
# print(i,l)
    mag,phase,omega = con.bode_plot(1,omega=Omega,plot=False)
    plt.loglog(omega,mag,label=Name[i])
# plt.hlines(1,min(omega),max(omega),ls='dashed',color='black',label='Unit_\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\te\
```

```
# print(f'{wcp:.2f}')
# print(f'$\\omega$ rad/sec ($\\omega_c = {int(wcp)}$)')
plt.xlabel(f'$\\omega$ rad/sec ($\\omega_c = {wcp:.2f}$)')
plt.ylabel(r'$|L|$')
SaveFig(SystemName,'SplitBodeMag')
```

[89]: [<matplotlib.lines.Line2D at 0x7253a2753a60>]

[89]: [<matplotlib.lines.Line2D at 0x7253a2753df0>]

[89]: [<matplotlib.lines.Line2D at 0x7253a2768100>]

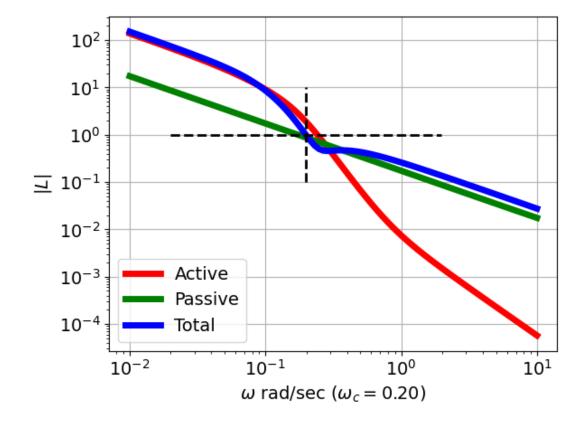
[89]: <matplotlib.collections.LineCollection at 0x7253a27b4460>

[89]: <matplotlib.collections.LineCollection at 0x7253a2753fd0>

[89]: <matplotlib.legend.Legend at 0x7253a2946be0>

[89]: Text(0.5, 0, '\$\\omega\$ rad/sec (\$\\omega_c = 0.20\$)')

[89]: Text(0, 0.5, '\$|L|\$')



```
[90]: for i,l in enumerate(L_list):
    # print(i,l)
    mag,phase,omega= con.bode_plot(l,omega=Omega,plot=False)
    plt.semilogx(omega,phase*180/np.pi,label=Name[i])
```

```
plt.legend()
# plt.hlines(-180,min(omega),max(omega),ls='dashed',color='black')
plt.hlines(-180,wcp/10,wcp*10,ls='dashed',color='black',lw=2)
plt.vlines(wcp,-300,-100,ls='dashed',color='black',lw=2)
# plt.xlabel(r'$\omega$')
print(f'{pm:.0f}')
plt.xlabel(f'$\\omega$ rad/sec ($\\theta_{{pm}} = {pm:.0f}^\circ$)')
plt.ylabel(r'$\angle{L}$')
plt.grid()
SaveFig(SystemName, 'SplitBodePha')
```

[90]: [<matplotlib.lines.Line2D at 0x7253a249fa60>]

[90]: [<matplotlib.lines.Line2D at 0x7253a249f940>]

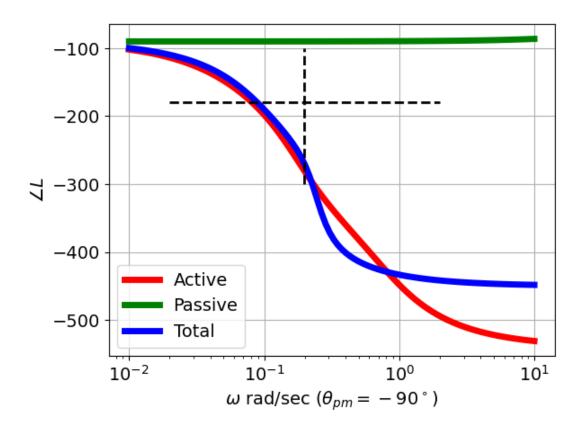
[90]: [<matplotlib.lines.Line2D at 0x7253a249ff70>]

[90]: <matplotlib.legend.Legend at 0x7253a2565b80>

[90]: <matplotlib.collections.LineCollection at 0x7253a249ffa0>

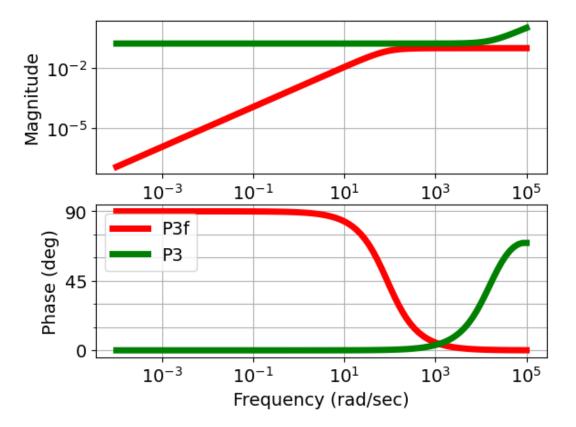
[90]: <matplotlib.collections.LineCollection at 0x7253a24b20a0> -90

[90]: Text(0, 0.5, '\$\\angle{L}\$')



```
[91]: L_list = [LO_pas_Inh,LO_pas_P]
    Omega = np.logspace(-4,5,100)
    mag,phase,om=con.bode_plot(L_list,omega=Omega,initial_phase=90)
    plt.legend(['P3f','P3'])
# SaveFig(SystemName,'SplitBode')
```

[91]: <matplotlib.legend.Legend at 0x7253a236bc40>

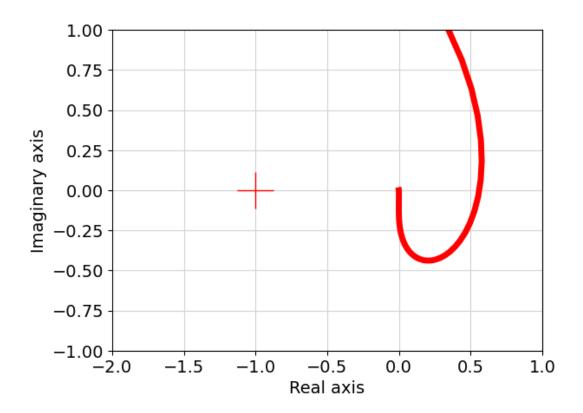


```
[92]: con.nyquist_plot([LL],mirror_style=False)
    plt.xlim(-2,1)
    plt.ylim(-1,1)
```

[92]: 2

[92]: (-2.0, 1.0)

[92]: (-1.0, 1.0)

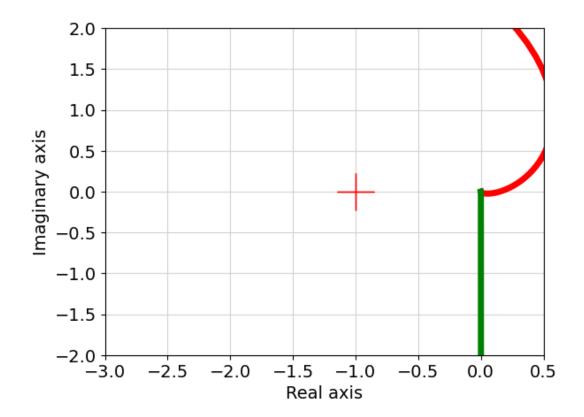


```
[93]: con.nyquist_plot([L_act,L_pas],mirror_style=False)
   plt.xlim(-3,0.5)
   plt.ylim(-2,2)
```

[93]: [2, 0]

[93]: (-3.0, 0.5)

[93]: (-2.0, 2.0)



$$\begin{array}{l} \hbox{ [94]: } \hline \texttt{con.tf(L0_r)} \\ \hline \texttt{con.tf(con.balred(L0_r,2))} \\ \hline \\ \hbox{ [94]: } \hline \\ \hline \underbrace{\frac{5.469(s-(0.05911+0.2379j))(s-(0.05911-0.2379j))(s+2.535\times10^4)}{(s+(0.08214-0.06437j))(s+(0.08214+0.06437j))(s+5.04\times10^5)}}_{\hbox{ [94]: }} \\ \hline \\ \hbox{ [94]: } \hline \\ \hline \underbrace{\frac{5.469(s+0.1267)(s+2.535\times10^4)}{(s+0.01552)(s+5.04\times10^5)}}_{\hbox{ $(s+0.01552)(s+5.04\times10^5)$}} \\ \hline \end{array}$$

References