

Smart Water System

IoT Based Water Level Indicator using Ultrasonic Sensor

Source Codes for Blynk ESP32 Water Level Sensor:

```

/*****
**
*   TITLE: IoT-based Water Level Indicator using ESP32, Ultrasonic Sensor & Blynk
with 0.96" OLED
*   Click on the following links to learn more.
*   YouTube Video: https://youtu.be/9geREeE13jc
*   Related Blog : https://iotcircuithub.com/esp32-projects/
*
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*
*   Preferences--> Additional boards Manager URLs :
*   https://raw.githubusercontent.com/espressif/arduino-esp32/gh-
pages/package\_esp32\_dev\_index.json,
http://arduino.esp8266.com/stable/package\_esp8266com\_index.json
*
*   Download Board ESP32 (2.0.5) : https://github.com/espressif/arduino-esp32
*
*   Download the libraries
*   Blynk Library (1.1.0): https://github.com/blynkkk/blynk-library
*   Adafruit_SSD1306 Library (2.5.7):
https://github.com/adafruit/Adafruit\_SSD1306
*   AceButton Library (1.9.2): https://github.com/bxparks/AceButton
*****
**/

/* Fill-in your Template ID (only if using Blynk.Cloud) */
#define BLYNK_TEMPLATE_ID ""
#define BLYNK_DEVICE_NAME ""
#define BLYNK_AUTH_TOKEN ""

// Your WiFi credentials.
```

```
// Set password to "" for open networks.
char ssid[] = "";
char pass[] = "";

//Set Water Level Distance in CM
int emptyTankDistance = 70 ; //Distance when tank is empty
int fullTankDistance = 30 ; //Distance when tank is full

//Set trigger value in percentage
int triggerPer = 10 ; //alarm will start when water level drop below
triggerPer

#include <Adafruit_SSD1306.h>
#include <WiFi.h>
#include <WiFiClient.h>
#include <BlynkSimpleEsp32.h>
#include <AceButton.h>
using namespace ace_button;

// Define connections to sensor
#define TRIGPIN 27 //D27
#define ECHOPIN 26 //D26
#define wifiled 2 //D2
#define ButtonPin1 12 //D12
#define BuzzerPin 13 //D13
#define GreenLed 14 //D14

//Change the virtual pins according the rooms
#define VPIN_BUTTON_1 V1
#define VPIN_BUTTON_2 V2

#define SCREEN_WIDTH 128 // OLED display width, in pixels
#define SCREEN_HEIGHT 32 // OLED display height, in pixels

// Declaration for an SSD1306 display connected to I2C (SDA, SCL pins)
#define OLED_RESET -1 // Reset pin # (or -1 if sharing Arduino reset pin)
Adafruit_SSD1306 display(SCREEN_WIDTH, SCREEN_HEIGHT, &Wire, OLED_RESET);

float duration;
float distance;
int waterLevelPer;
bool toggleBuzzer = HIGH; //Define to remember the toggle state

char auth[] = BLYNK_AUTH_TOKEN;
```

```
ButtonConfig config1;
AceButton button1(&config1);

void handleEvent1(AceButton*, uint8_t, uint8_t);

BlynkTimer timer;

void checkBlynkStatus() { // called every 3 seconds by SimpleTimer

    bool isconnected = Blynk.connected();
    if (isconnected == false) {
        //Serial.println("Blynk Not Connected");
        digitalWrite(wifiLed, LOW);
    }
    if (isconnected == true) {
        digitalWrite(wifiLed, HIGH);
        //Serial.println("Blynk Connected");
    }
}

BLYNK_CONNECTED() {
    Blynk.syncVirtual(VPIN_BUTTON_1);
    Blynk.syncVirtual(VPIN_BUTTON_2);
}

void displayData(int value){
    display.clearDisplay();
    display.setTextSize(4);
    display.setCursor(8,2);
    display.print(value);
    display.print(" ");
    display.print("%");
    display.display();
}

void measureDistance(){
    // Set the trigger pin LOW for 2uS
    digitalWrite(TRIGPIN, LOW);
    delayMicroseconds(2);

    // Set the trigger pin HIGH for 20us to send pulse
    digitalWrite(TRIGPIN, HIGH);
    delayMicroseconds(20);
}
```

```
// Return the trigger pin to LOW
digitalWrite(TRIGPIN, LOW);

// Measure the width of the incoming pulse
duration = pulseIn(ECHOPIN, HIGH);

// Determine distance from duration
// Use 343 metres per second as speed of sound
// Divide by 1000 as we want millimeters

distance = ((duration / 2) * 0.343)/10;

if (distance > (fullTankDistance - 10) && distance < emptyTankDistance ){
    waterLevelPer = map((int)distance ,emptyTankDistance, fullTankDistance, 0,
100);
    displayData(waterLevelPer);
    Blynk.virtualWrite(VPIN_BUTTON_1, waterLevelPer);
    Blynk.virtualWrite(VPIN_BUTTON_2, (String(distance) + " cm"));

    // Print result to serial monitor
    Serial.print("Distance: ");
    Serial.print(distance);
    Serial.println(" cm");

    if (waterLevelPer < triggerPer){
        digitalWrite(GreenLed, HIGH);
        if (toggleBuzzer == HIGH){
            digitalWrite(BuzzerPin, HIGH);
        }
    }
    if (distance < fullTankDistance){
        digitalWrite(GreenLed, LOW);
        if (toggleBuzzer == HIGH){
            digitalWrite(BuzzerPin, HIGH);
        }
    }
}

if (distance > (fullTankDistance + 5) && waterLevelPer > (triggerPer + 5)){
    toggleBuzzer = HIGH;
    digitalWrite(BuzzerPin, LOW);
}
}

// Delay before repeating measurement
delay(100);
```

```
}

void setup() {
  // Set up serial monitor
  Serial.begin(115200);

  // Set pinmodes for sensor connections
  pinMode(ECHOPIN, INPUT);
  pinMode(TRIGPIN, OUTPUT);
  pinMode(wifiLed, OUTPUT);
  pinMode(GreenLed, OUTPUT);
  pinMode(BuzzerPin, OUTPUT);

  pinMode(ButtonPin1, INPUT_PULLUP);

  digitalWrite(wifiLed, LOW);
  digitalWrite(GreenLed, LOW);
  digitalWrite(BuzzerPin, LOW);

  config1.setEventHandler(button1Handler);

  button1.init(ButtonPin1);

  if(!display.begin(SSD1306_SWITCHCAPVCC, 0x3C)) {
    Serial.println(F("SSD1306 allocation failed"));
    for(;;);
  }
  delay(1000);
  display.setTextSize(1);
  display.setTextColor(WHITE);
  display.clearDisplay();

  WiFi.begin(ssid, pass);
  timer.setInterval(2000L, checkBlynkStatus); // check if Blynk server is
connected every 2 seconds
  Blynk.config(auth);
  delay(1000);
}

void loop() {

  measureDistance();

  Blynk.run();
}
```

```
    timer.run(); // Initiates SimpleTimer

    button1.check();

}

void button1Handler(AceButton* button, uint8_t eventType, uint8_t buttonState) {
    Serial.println("EVENT1");
    switch (eventType) {
        case AceButton::kEventReleased:
            //Serial.println("kEventReleased");
            digitalWrite(BuzzerPin, LOW);
            toggleBuzzer = LOW;
            break;
    }
}
```

The screenshot shows the Blynk Cloud dashboard for a project named "ESP32 WaterLevel". The "Datastreams" tab is selected, displaying a table of datastreams. The table has columns for ID, Name, Alias, Color, Pin, Data Type, Units, Is Raw, ID#, Max, Decimals, and Default Value. Two datastreams are listed: "WaterLevel" (ID 1, Integer type, Pin V1, Max 100) and "Distance" (ID 2, String type, Pin V2, Max -).

ID	Name	Alias	Color	Pin	Data Type	Units	Is Raw	ID#	Max	Decimals	Default Value
1	WaterLevel	WaterLevel		V1	Integer		false	1	100	-	0
2	Distance	Distance		V2	String		false			-	

The screenshot shows the Blynk Cloud dashboard for the same project, "ESP32 WaterLevel", but with the "Automations" tab selected. It displays a table of automations based on the two datastreams. The table has columns for Name, Pin, Data Type, Type Of Automation, Condition, and Action. Two automations are listed: "WaterLevel" (Integer type, Type Of Automation "Number", Condition "Greater Than", Action "Set Value") and "Distance" (String type, Type Of Automation "Color", Condition "Equal", Action "Set Value").

Name	Pin	Data Type	Type Of Automation	Condition	Action
WaterLevel	V1	Integer	Number	Greater Than	Set Value
Distance	V2	String	Color	Equal	Set Value

