# **Machine learning introduction**

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#### What is the purpose of this session?

- Learning (and recognizing) the most common forms of Al
  - ... And the application domain of each form
- Being able to implement basic mechanisms of a neural network
- Being able to use high level tools to implement a deep neural network

#### What we will not do

- Creating a complete deep learning AI from scratch
- Creating a AI to dominate the world

People with no idea about AI saying it will take over the world:

My Neural Network:



- Introduction
- I From neuron to multi-layer network
  - The biological neuron
  - The formal neuron
  - Multi-layer networks
- II Deep learning
  - Deep neural networks
  - Generative antagonist networks
  - Libraries for deep learning : TensorFlow and Keras
- Github : https://github.com/gaysimon/ARTISAN2022

## What is (artificial) Intelligence?

- Learning capacities (Beckmann, 2006)
- Abilities to adapt to a context (Piaget, 1953)
- Ability to solve problems using new solutions (Gardner, 1989)
- Artificial Intelligence aims at reproducing these properties on an artificial system

Several approaches were created to reach this goal

• Since the begining of AI, two main approaches emerged :

 Symbolic AI: algorithms manipulating symbols and logic rules (inference and deduction)

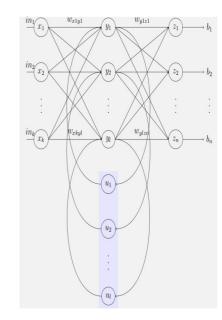
```
mother_child(trude, sally).
father_child(tom, sally).
father_child(tom, erica).
father_child(mike, tom).

sibling(X, Y) :- parent_child(Z, X), parent_child(Z, Y).

parent_child(X, Y) :- father_child(X, Y).
parent_child(X, Y) :- mother_child(X, Y).

?- sibling(sally, erica).
```

 Connectionist AI: algorithms made of elements connected with values, and learning mechanisms modifying these values to converge to a solution



- History of artificial Intelligence
- Antiquity: myths of artificial persons...
  - ... but also first automatons



- Mechanical knight (Leonardo da Vinci)
- Vaucanson's automatons (18th)
- The first robot ? Tea serving doll automaton (17<sup>th</sup>)



- First electromecanical mobile systems (1912)
- Karel Čapek : Rossum's Universal Robots (1921)
- emergence of *cybernetics* en 1942
- First forms of Machine Learning (1951)
  - Logistic Regression (1944?), K-nearest neighbors
- 1956: Artificial Intelligence officially becomes a research domain (Dartmouth conference)

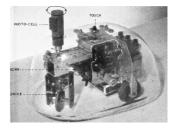






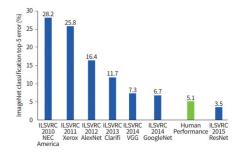






- 1956: Effervescence and optimism.
  - First neural networks (1957), Logic programming (symbolic AI, 1958), K-means (1967)...
- 1974 : crash of Al
  - Facing the lack of results, funds are canceled in laboratories all around the world
- Beginning of 80s: renewed interest due to expert systems
  - Total reign of symbolic approaches
  - Reinforcement Learning (1988), Multi-Agent Systems (middle of 80s)
  - First multi-layer neural systems (but nobody cares)
- Middle of 90s: lack of progress in expert systems → Second crash of Al
- 1997: Chess computer Deep Blue defeats world champion Kasparov: Strongly renewed interest in research and industry
  - Developmental robotics (middle 90s) and intelligence (middle 2000s)
  - Emergence of neural networks with high number of layers (~2010) (but nobody believes in it)
- 2012: A deep learning model breaks all records at ILSVRC
  - Total reign of connectionism approaches





Different types of AI

/!\ there is no official classification

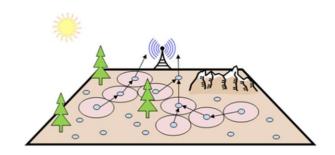
- Symbolic: inference and deduction from symbols and rules
  - Logic programming
  - Expert Systems
- Connectionism: adjustment of numerical values and connections between entities
  - Neural networks
  - Logistic regression
  - Genetic algorithms
  - Reinforcement learning
  - ....
- Emergence: solving problems through interaction between simple entities
  - Multi-agent systems



- Partially inspired by social insects (ants, bees...)
- Systems based on interacting simple entities
- Complex global behavior emerges from simple individual behaviors of entities (The whole is more than the sum of parts)

#### Applications

- Simulation of complex phenomena (crowd, fire propagation, ...)
- Optimization of systems, message routing
- Cinema and video games (simulation of large armies, e.g. The Lord of the Rings)





Different types of Al

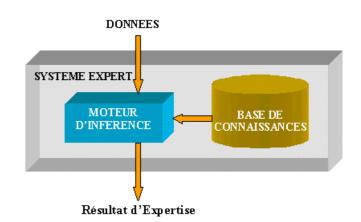
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#### Symbolic AI

- Set of rules provided by the conceptor
- Relies on the manipulation of symbols
- Most known model: The expert system
  - Aims at reproducing the knowledge of an expert human in a specific domain
- Logic programming languages
  - PROLOG
- No learning (in most models)

#### Applications

Widely used to assist decision making in specific domains (e.g. medical fields, diagnostic...)



Different types of AI

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- Connectionist AI: a whole family
  - Supervised learning: the model is trained on a dataset with known results, then exploited on data with unknown results.
  - Unsupervised learning: models that can be used with datasets with unknown results. The model must converge toward an optimal solution
  - Reinforcement learning: The system can interact with its environment and is actively involved in the learning process: the system (or agent) performs action and learns from obtained results.

#### Connectionist AI: supervised learning

- Learns from a dataset with known results
  - → Requires to first create a dataset of labeled data

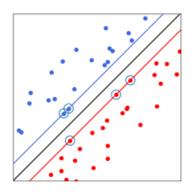


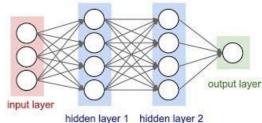
- K-NN
- Logistic regression
- Decision trees
- SVM
- Biologically inspired models:
  - Artificial neuron networks

#### Applications

- Classification and recognition of data, images, text, sound...
- Translation, decision assistance...
  - Note: even a deep learning model cannot 'understand' these data
- ... as soon as a sufficient training dataset is available

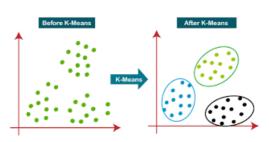


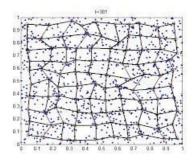




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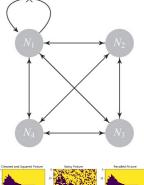
- Connectionist AI: unsupervised learning
  - Learning on data with unknown results
    - → These approaches are used to organize data
    - → The system converges to an optimal organization (or clustering) of data
  - Mathematical approaches:
    - K-means
    - Hierarchical clustering
  - Biologically inspired approaches:
    - Unsupervised neural networks

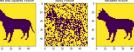




#### Some well-known unsupervised neural networks:

- Hopfield networks: associative memory
  - Recursive and asynchronous network
  - Trained on input data: the network will define a stable configuration for each data
  - When presenting an incomplete or noisy data, the network will converge to the closest configuration, reconstructing the original data
  - Used to study biological memory principles











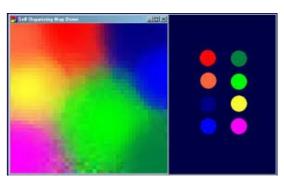






#### Self-organizing maps (or Kohonen maps)

- Inspired by brain's cortex principles
- 2-dimensions networks
- The self organizing map can remap data from a N-dimension space to a 2-D map, while respecting (as much as possible) distance between data.
- Used for complex data analysis and organization



Mapping RGB 3-D space on a 2-surface

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#### Connectionist AI: Reinforcement learning

- Embodied intelligence: an artificial agent interacts with an environment
- The agent perceives its environment, acts and analyzes changes
  - → The learning process is supervised by the agent itself
- Goal oriented approaches

A predefined reward is attributed when performing a specific task or action

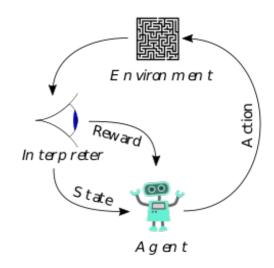
- Reinforcement Learning (1988)
- Q-Learning (1989)
- Behavior oriented approaches :

Used to study living beings development and behavior emergence

- Developmental robotics (middle of 90s)
- Developmental learning (middle of 2000s)

#### Reinforcement learning (RL): goal oriented approaches

- The agent can perform a set of actions and perceive the current state of the environment
- Rewards are given when reaching a certain state or performing a specific task
- The agent learns to link states and to define best states to cover to maximize future rewards



#### Q-Learning: a variant of reinforcement learning

 Consider the best actions to perform instead of state to reach (useful when we do not known how to reach a state)

#### Applications :

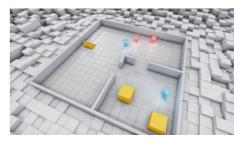
Robot control, trading, virtual bots, diagnostic (medical fields)...



Learning to Walk via Deep Reinforcement Learning, T. Haarnoja et al., 2019



Control of a Quadrotor with Reinforcement Learning, J. Hwangbo et al., 2017



Emergent Tool Use From Multi-Agent Autocurricula, B. Baker et al., 2019

#### • Reinforcement learning (RL): behavior oriented approaches

#### Developmental robotics

 Fundamental research domain: understanding sensorimotor development stages on humans (and sometime animals)

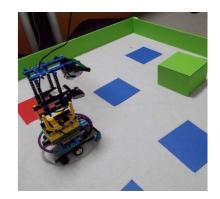
e.g. crawling, hand-eye coordination, standing up, grab an object...





#### Developmental learning

- Fundamental domain research: understanding the emergence of environment interpretation and behavior emergence on more simple agents through their whole 'life'
- No external reward, agents are fully autonomous and self-motivated
- Inspired by psychology theories of cognition (ex Piaget, Gibson)



#### Reinforcement learning (RL)

- A peculiar model: genetic algorithms
  - Inspired by species evolution
  - "learning" (optimization) through generations of a population of genes

#### - Principle:

- The problem is encoded as a set of parameters: genomes
- A population is created with random genomes
- Genomes are evaluated, best genomes are combined to create next generation
- The genomes are optimized at each new generation

#### - Applications:

• Optimization, routing, object design and architecture, electronic circuits, finance and economics...



Spacecraft antenna

