CS 452 Operating Systems

# Main Memory

Dr. Denton Bobeldyk

#### Main Memory

- \* Background
- \* Swapping
- \* Contiguous Memory Allocation
- \* Segmentation

# Background

- \* Basic Hardware
- \* Address Binding
- \* Logical vs Physical Address Space
- \* Dynamic Loading
- \* Dynamic Linking and Shared Libraries

#### Basic Hardware

- \* CPU can directly access (for general storage):
  - \* Registers built into the processor
  - \* Main memory (also includes cache)
  - \* If the data isn't in one of these locations, the CPU can not operate on them

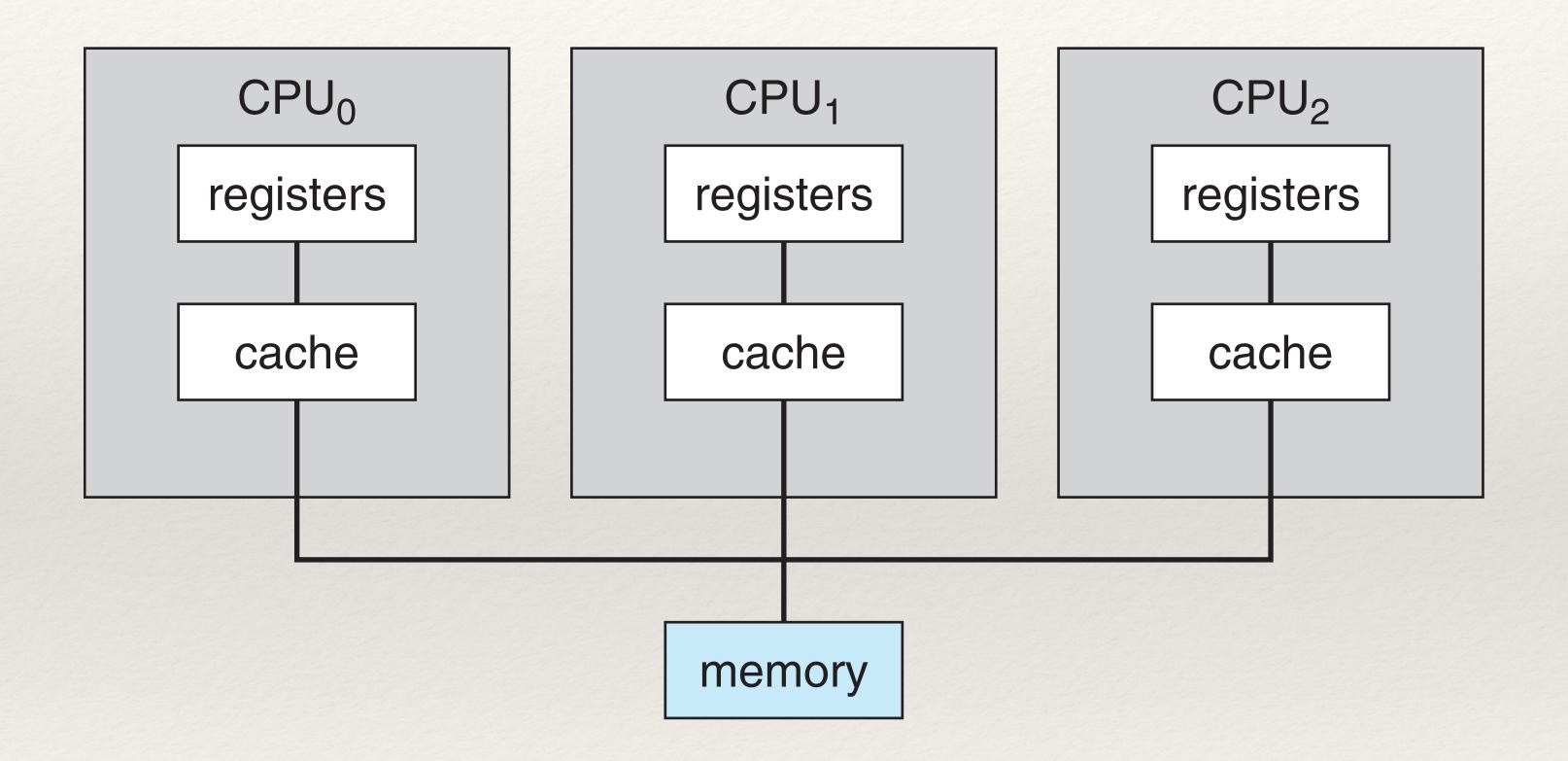
# How much main memory on a system?

- \* Individual exercise:
  - \* How much RAM for a home PC? Find prices for a few...
  - \* How much RAM is available for:
    - \* Nvidia Jetson
    - \* Nvidia Jetson Nano
    - \* Raspberry PI

#### Basic Hardware

- \* Registers fast access, generally within one cycle of the CPU clock
- \* Main Memory accessed via memory bus. Access time can take many cycles
  - \* The processor normally needs to stall while waiting

#### Slow Memory Access Solution



Solution: Add cache to speed up memory access

#### Individual Exercise

- \* How many cpu cycles does it take to access:
  - \* Main Memory
  - \* Cache

#### Individual Exercise

- \* How many cpu cycles does it take to access (rough approximates):
  - \* Main Memory: 100-200 cycles
  - \* Cache
    - \* L1: 1-4 cycles
    - \* L2: 5-12 cycles
    - \* L3: 12-40 cycles (or more)

#### Individual Exercise 5-10 minutes

#### How much cache is available??

Lookup a CPU manufacturer (e.g., Intel, AMD) and find 3 different CPU models. Determine how much L1/L2/L3 cache they each have. Also include the price in your findings.

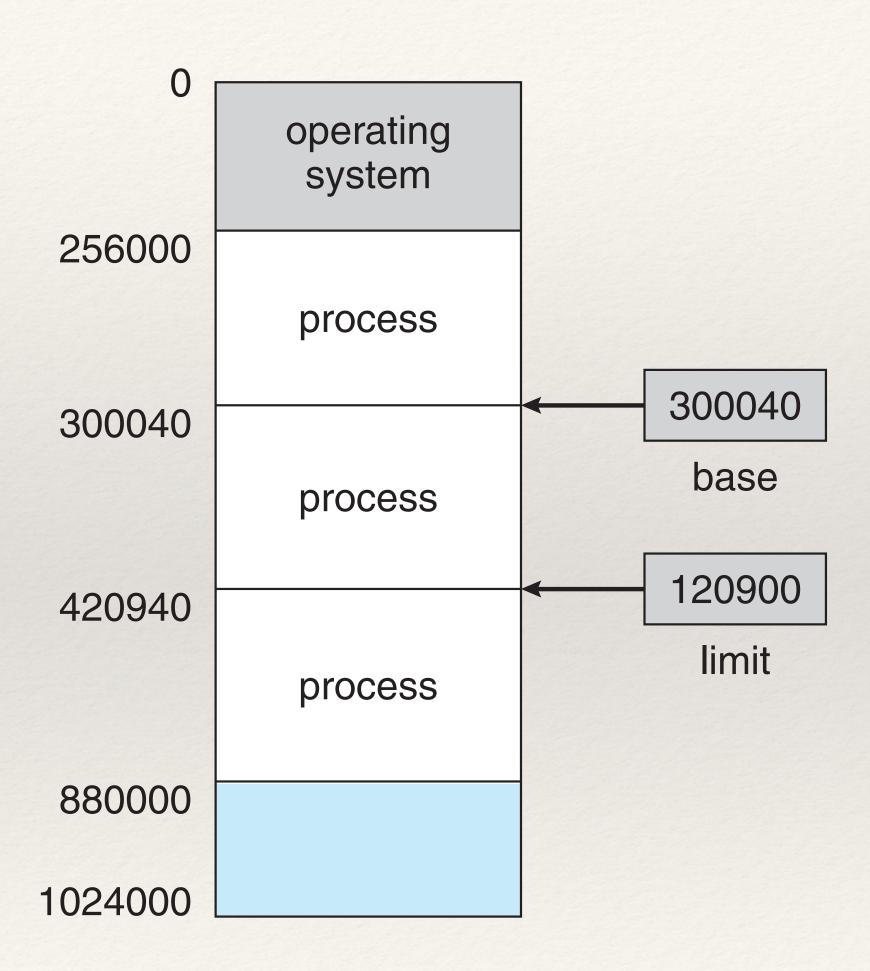
#### Memory Access - Protection

- \* Concerned not only about speed, but security
- \* Need to ensure each process is only accessing it's own memory space
- \* Create separate memory space for each process

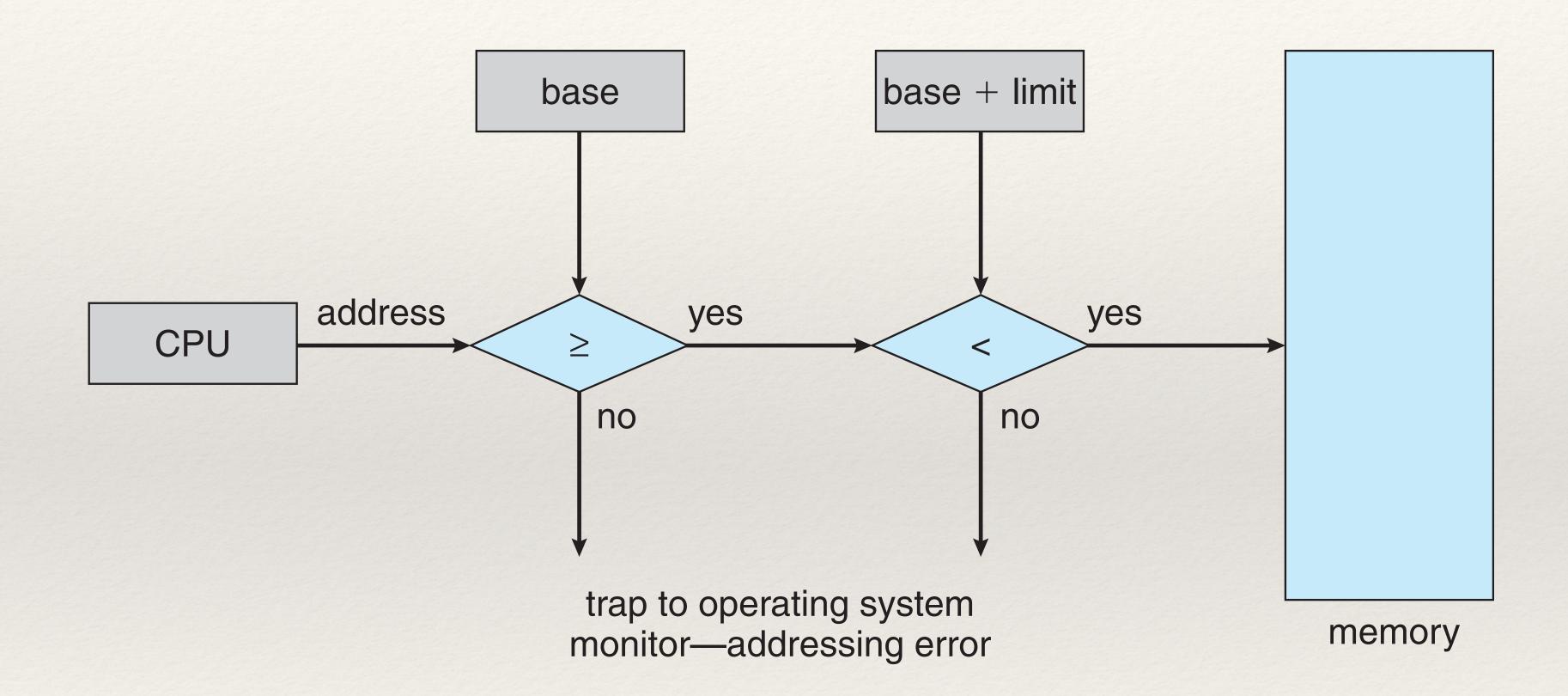
#### Memory Access - Protection

- \* Range of address spaces for each process
  - \* Base register smallest legal physical memory address
  - \* Limit register specifies the size of the range

## Memory Protection



## Memory Protection



# Memory Protection

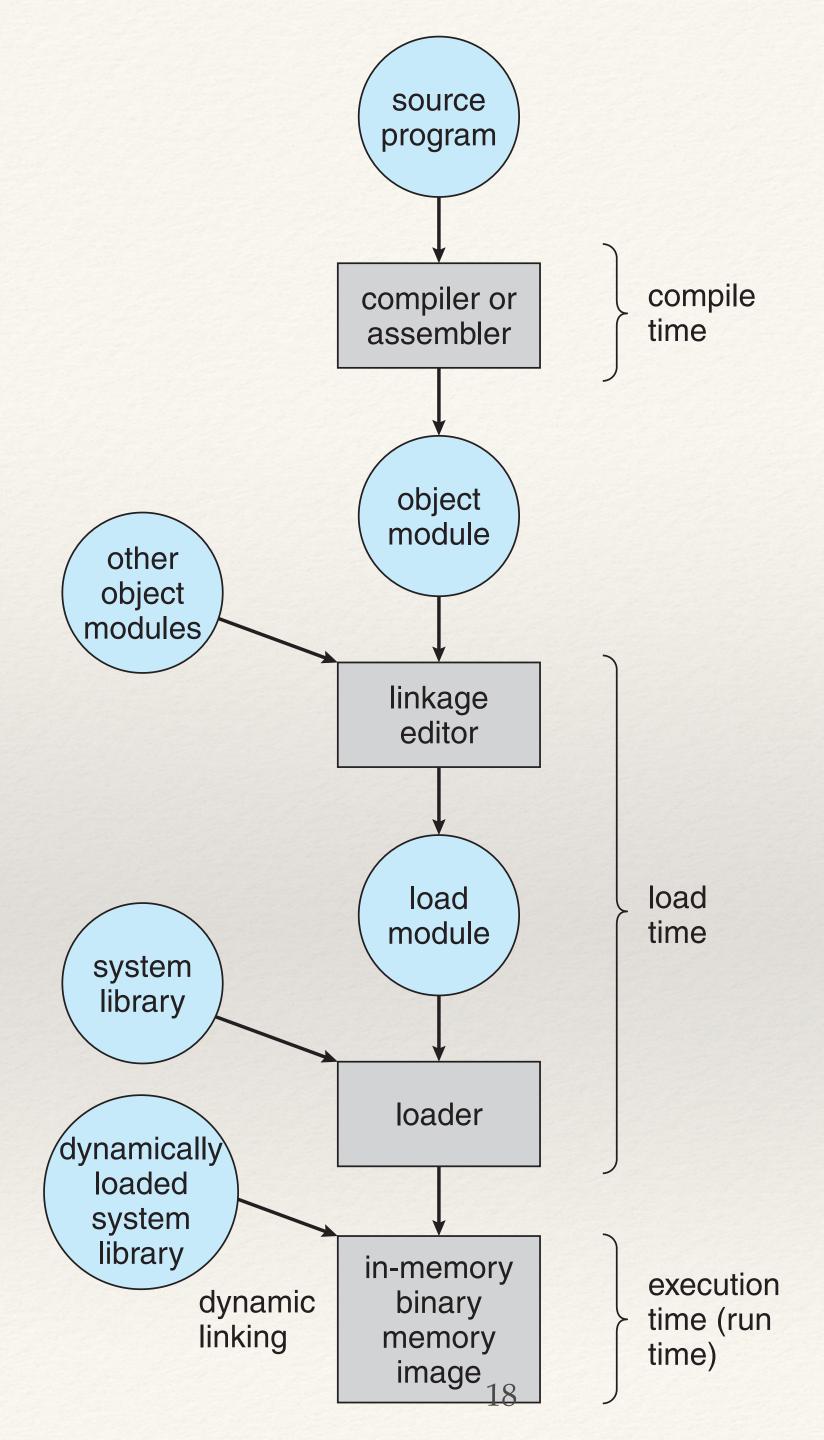
- \* Only the operating system can change the value of the base and limit
- \* Operating system, executing in kernel mode, has unrestricted access to all memory locations

# Background

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# Loading a program into memory

- \* A program must be brought into memory to execute
- \* The processes on the disk that are waiting to be brought into memory form the **input queue**
- \* After a process finishes executing, it's memory is declared available



#### Address Binding

- \* Compile time If you know where the code will reside in memory, then absolute code can be generated.
  - \* If location changes, need to recompile
- \* Load time compiler generates relocatable code. Binding to memory happens at load time.
  - \* If location changes, reload the user code to incorporate this change
- \* **Execution time** process can be moved during its execution from one memory segment to another.
  - \* Most general-purpose operating system use this method

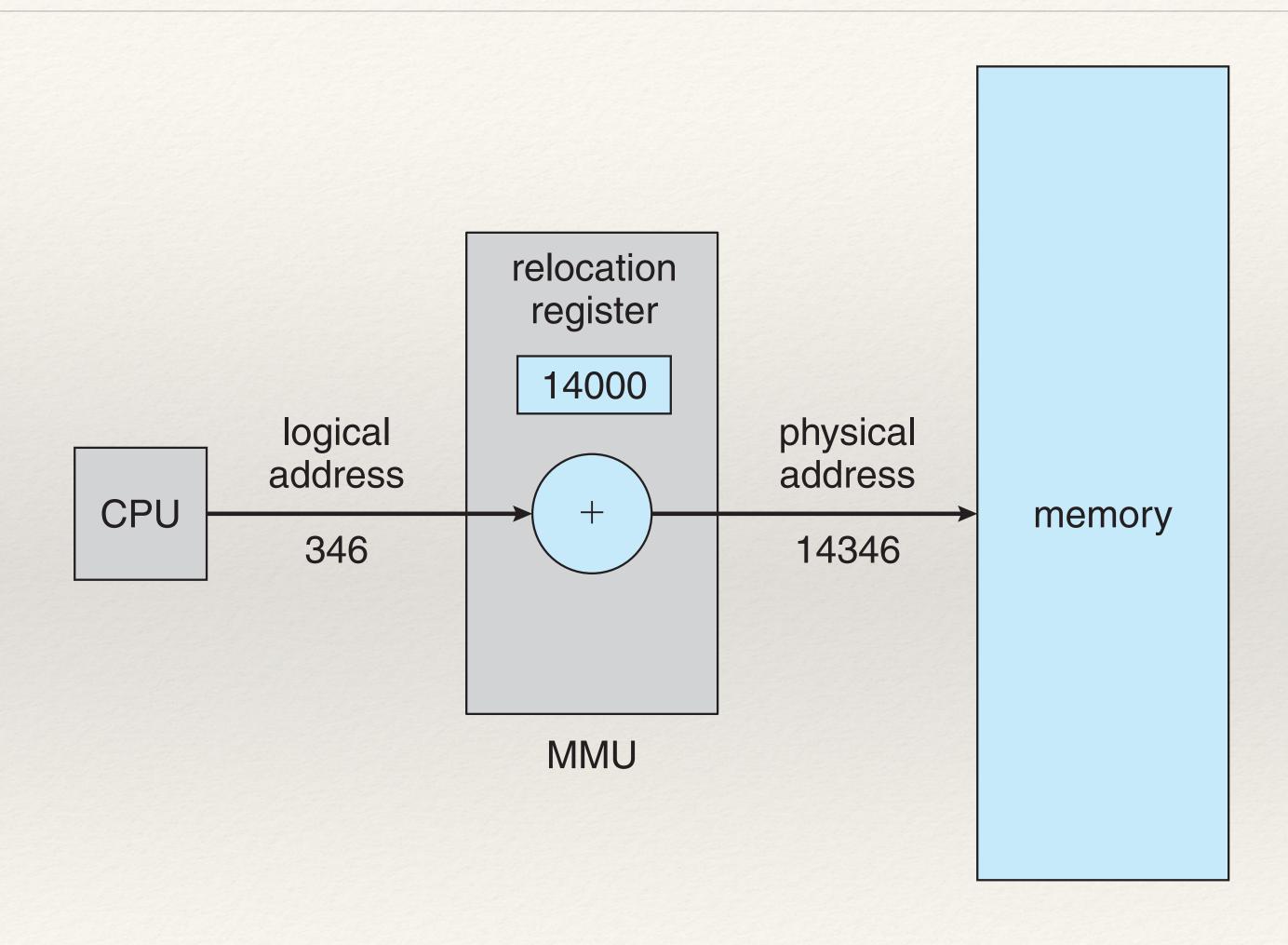
#### Memory

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- \* Logical address address generated by the CPU
- \* Physical address actual address loaded into the memory-address-register of the memory

- \* Same address: compile-time and load-time address binding
- \* Different logical and physical addresses: execution-time address-binding.

- \* Logical address space: set of all addresses generated by a program
- \* Physical address space: set of all physical addresses corresponding to the logical addresses.
- \* Mapping is performed by the memory-management unit (MMU)



- \* The user program never sees the real physical address
- \* Logical address range: 0 to max
- \* Physical address range: R + 0 to R+max

#### Memory

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# Dynamic Loading

- \* The main program is loaded into memory and executed
- \* A routine isn't loaded until it is called
- \* The calling routine checks to see if it's in memory, if not the relocatable linking loader is called to load it into memory

# Dynamic Loading

- \* Advantageous especially when large amounts of code handle infrequently occurring cases (e.g., error routines)
- \* Programmers can design their program to take advantage of this method

#### Memory

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- \* Dynamically linked libraries system libraries linked to a user program when they are run
- \* Static linking libraries that are combined by the loader into the binary image
- \* Dynamic linking linking is postponed until execution time
  - \* Useful for system libraries, so every program doesn't have to load the same library into memory

- \* Stub a small piece of code that indicates how to locate the appropriate memory-resident library routine (or how to load if it's not already present)
- \* The first time the stub is executed, it will check to see if the routine is already in memory, if it's not, it will load it into memory
- \* When the stub is executed the second time, it replaces itself with the address of the routine and executes the routine.
  - \* No cost for dynamic linking the second time

- \* Library updates can be replaced with a new version and all programs that reference the library can automatically update to use the new version
- \* Without dynamic linking, all programs would need to be relinked to gain access to the new library

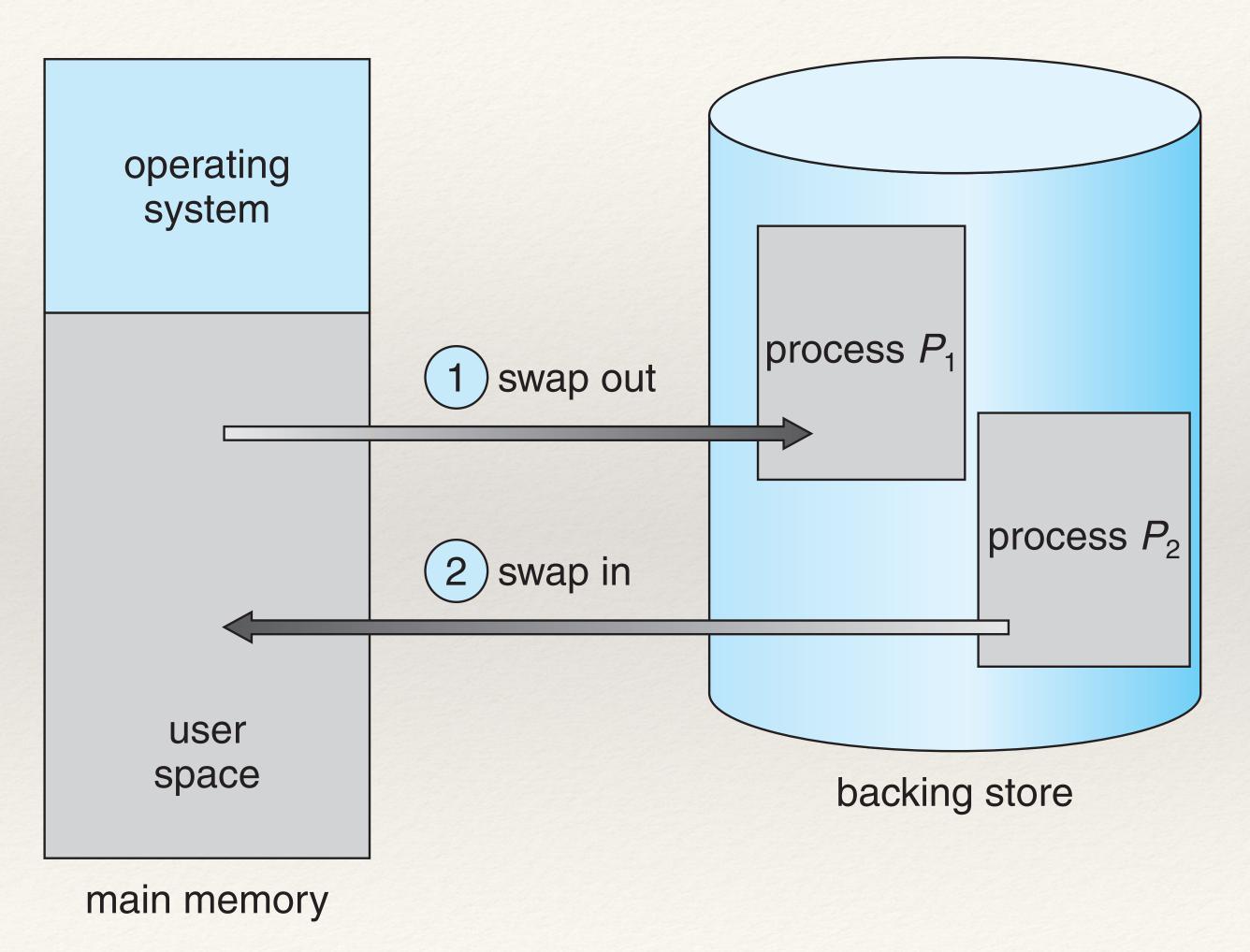
\* Version information can be included, so programs will not accidentally use a library they may be incompatible with

\* Operating system needs to be utilized to check another process's memory space for routines as user processes can not access another processes memory space

#### Main Memory

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# Swapping



- \* System maintains a ready queue consisting of all processes whose memory images are on the backing store or in memory ready to run
- \* Dispatcher loads the next process into memory, if there is not enough free memory for it, the dispatcher swaps out a process currently in memory

- \* Swapping to the backup store is expensive!
- \* For example, 100MB program transfers to a standard hard disk at the transfer rate of 50MB/second. That takes 2 seconds!

- \* A process should be completely idle
- \* A process should not be waiting for I/O??

- \* A process awaiting I/O could still be swapped out if:
  - \* Only execute I/O operations into operating system buffers
  - \* Transfer then occurs from the OS buffer to the process memory.
    - \* This is called double buffering
      - \* This causes additional overhead!!

- \* Modified versions of swapping exist:
  - \* Swap a portion of the process, rather than the entire process
  - \* Swapping can be disabled but will start if the amount of free memory falls below a certain threshold

## Swapping on Mobile Systems

- \* Mobile systems do not typically support swapping
  - \* Generally use flash memory rather than more spacious hard disks for persistent storage (limiting the space to swap)
  - \* Flash memory will tolerate a limited number of writes before it starts to become unreliable

## Swapping on Mobile Systems

- \* Apple iOS asks applications to relinquish memory
- \* Applications can be terminated if they don't free up the memory...

## Swapping on Mobile Systems

- \* Android does not support swapping
- \* May terminate a process if insufficient memory is available
  - \* Android writes its application state to flash memory so that it can be quickly restarted

### Main Memory

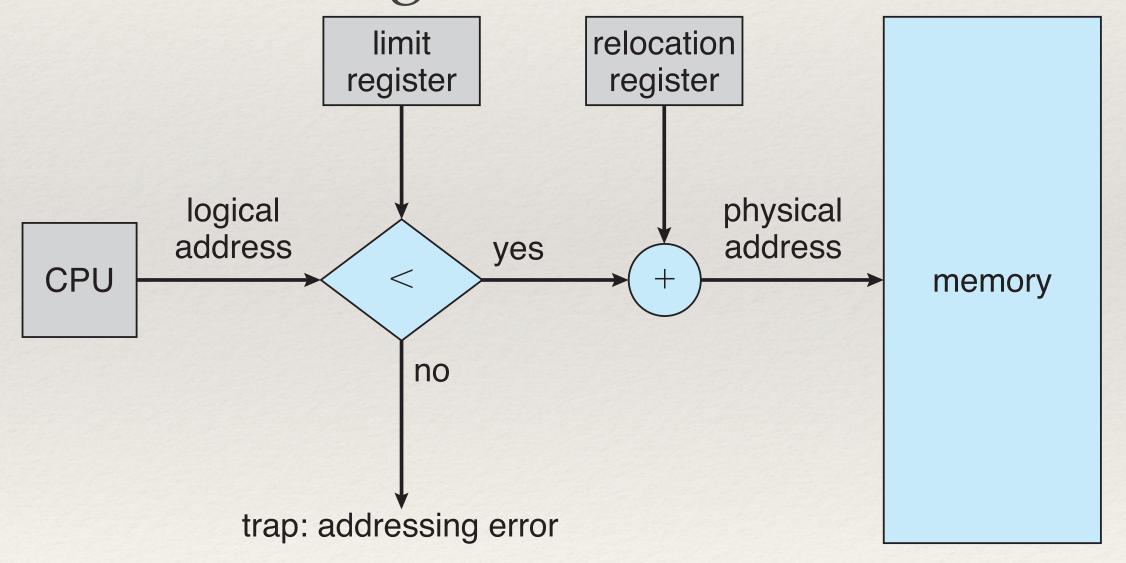
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## Contiguous Memory Allocation

- \* Memory is usually divided into two partitions
  - \* Resident Operating System
  - \* User Processes
- \* Contiguous memory allocation
  - \* Each process is brought into a single section of memory

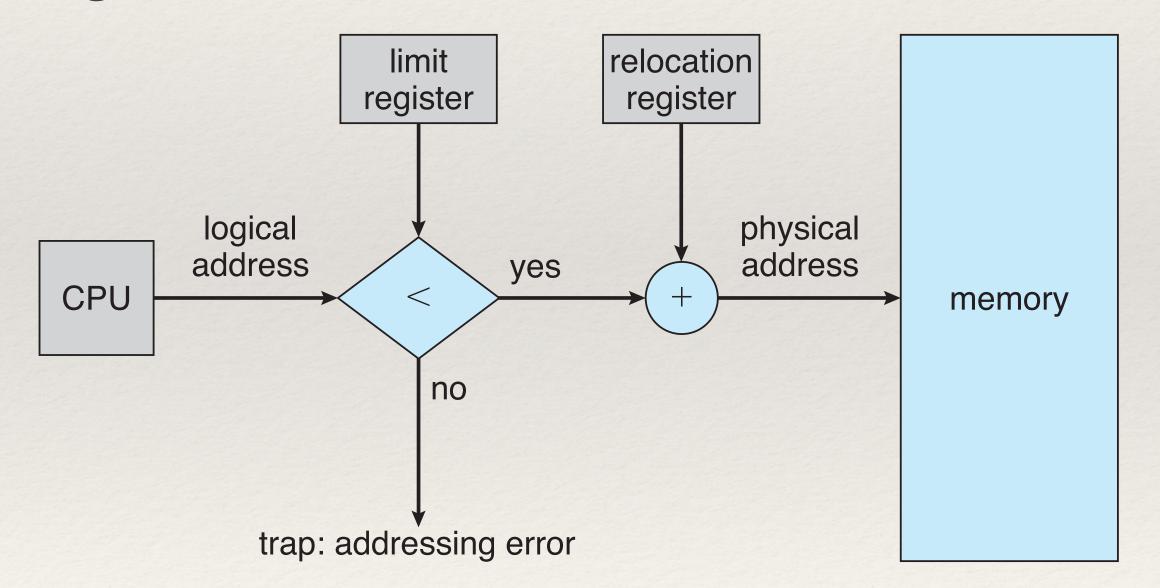
### Memory Protection

- \* Need to prevent processes from accessing memory they don't own
  - \* Define a limit and relocation register



#### Memory Protection

\* During the context switch, the dispatcher (OS) loads the values for the relocation and limit registers



- \* Divide memory into fixed size partitions
  - \* Each partition contains one process
  - \* Number of processes is bound by number of partitions?
- \* Variable partition scheme
  - \* Initially one large 'hole', eventually a set of 'holes'

- \* Processes are allocated space (loaded into memory) and can then compete for CPU time
- \* When a process terminates, it releases its memory

- \* Memory is allocated to each process from the input queue until no more memory or no more process are available
- \* If more processes are available, the OS can wait until a large enough memory block (hole) frees up, or move onto the next process in the input queue that may have a smaller memory requirement.

- \* Dynamic storage-allocation problem:
  - \* How to satisfy a request of size n, from a list of free holes
    - \* First-fit
    - \* Best-fit
    - \* Worst-fit

- \* First-fit
  - \* Allocate the first hole that is big enough
  - \* Search can be from the beginning or end of the list
- \* Best-fit
  - \* Allocate the smallest hole that is big enough
- \* Worst-fit
  - \* Allocate the largest hole

## Fragmentation

- \* External fragmentation
  - \* Enough memory to satisfy a request, but the memory isn't contiguous
- \* Amount of external fragmentation that exists will depend on the system and the algorithm used to assign memory holes
- \* Up to one third of memory may be unusable
  - \* Known as 50 percent rule
    - \* Given N allocated blocks, another 0.5 N blocks will be lost to fragmentation

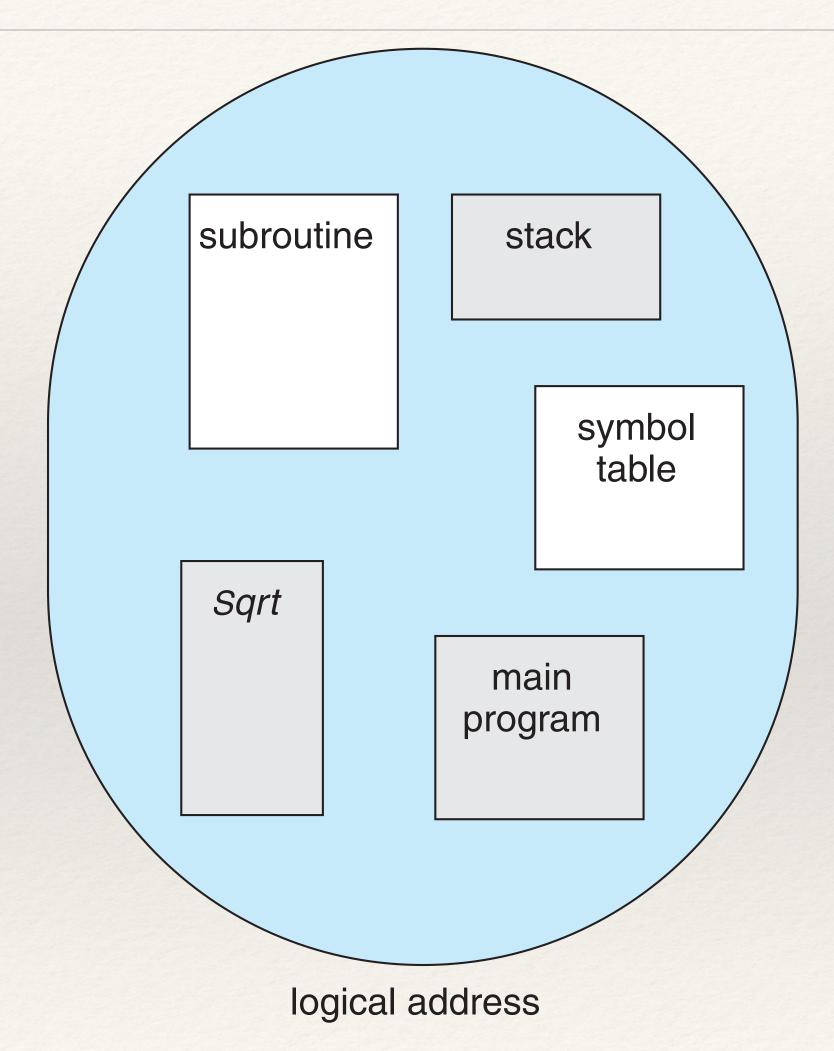
## Fragmentation

- \* Internal fragmentation
  - \* Unused memory internal to a partition
- \* How is it caused?
  - \* Processes can be allocated a fixed size block of memory
  - \* Process dynamically allocated a block slightly larger than its request
    - \* Request 18,462 bytes, available hole of 18,464. More overhead to keep track of those 2 bytes than to just allocate them to the process

#### Main Memory

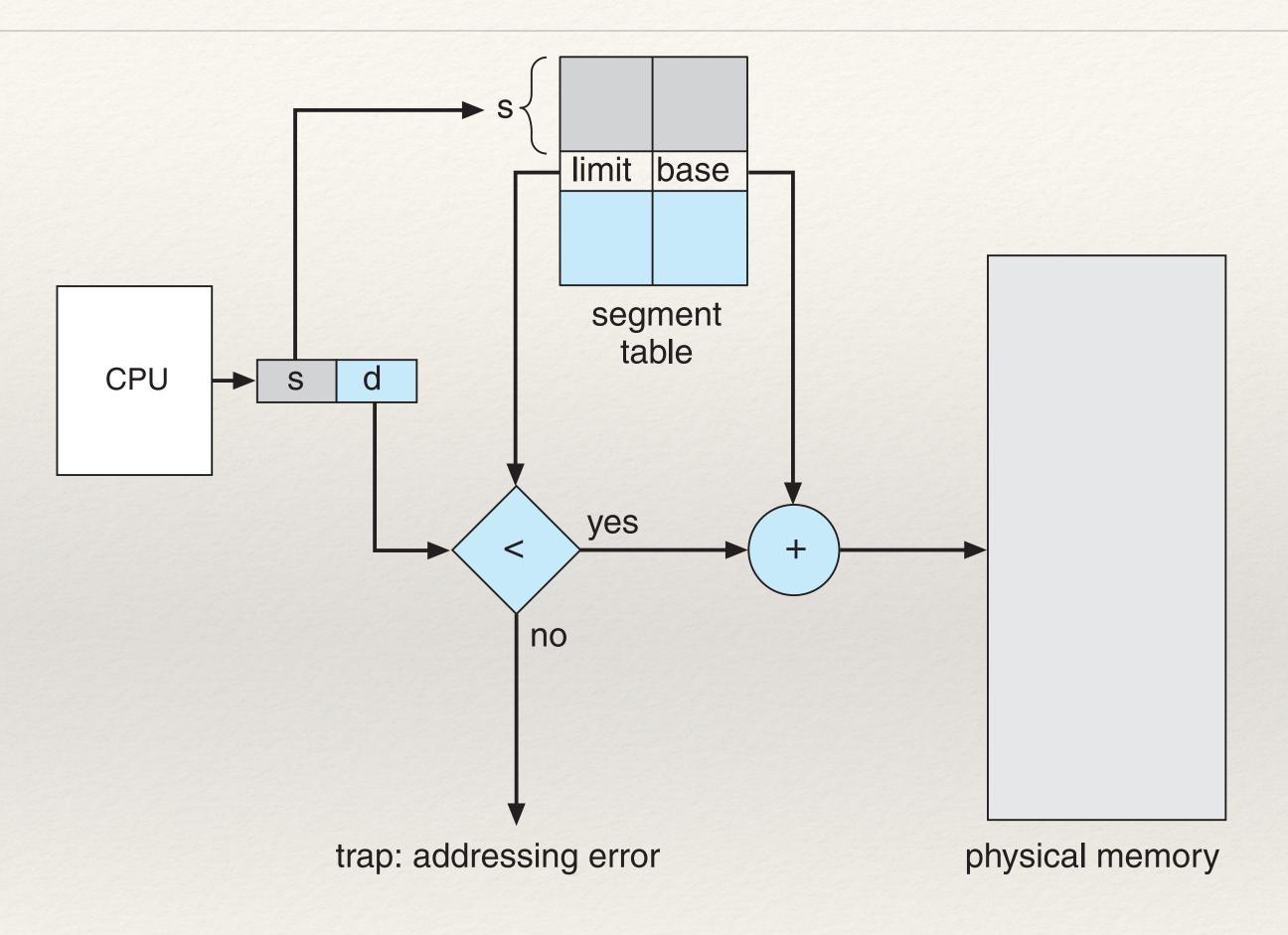
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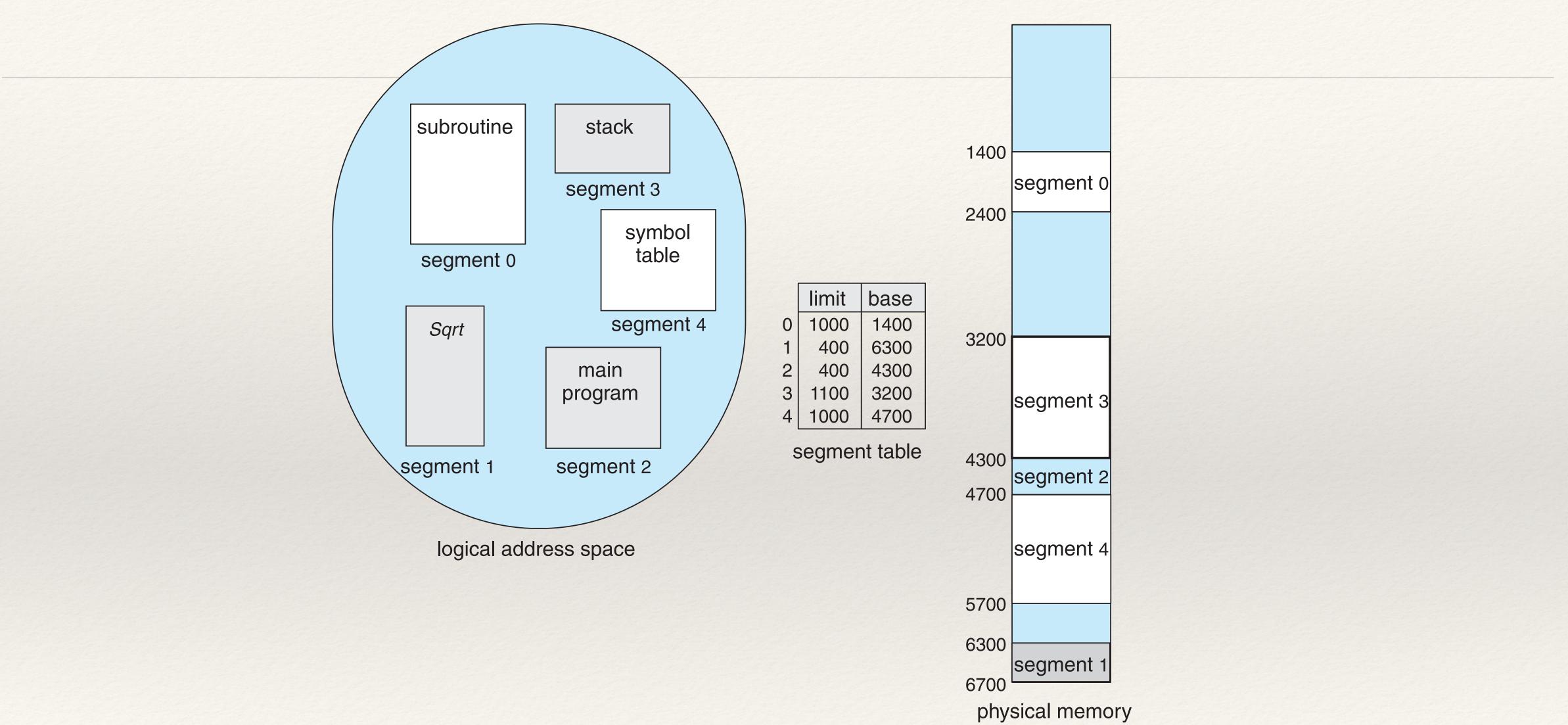
- \* Memory management scheme where the address space is viewed as a collection of segments
- \* Each logical address consists of a two tuple:
  - \* <segment-number, offset>



- \* C compiler might create separate segments for:
  - \* The code
  - \* Global variables
  - \* The heap, from which memory is allocated
  - \* The stacks used by each thread
  - \* The standard C library

- \* Segment table keeps track of mapping logical to physical address space
- \* Table consists of:
  - \* Segment base: starting physical address
  - \* Segment limit: length of the segment





#### End