

# SINGULAR VALUE DECOMPOSITION (SVD)

&

# PRINCIPAL COMPONENT ANALYSIS (PCA)

CS115

# MỤC LỤC

01. Singular Value Decomposition

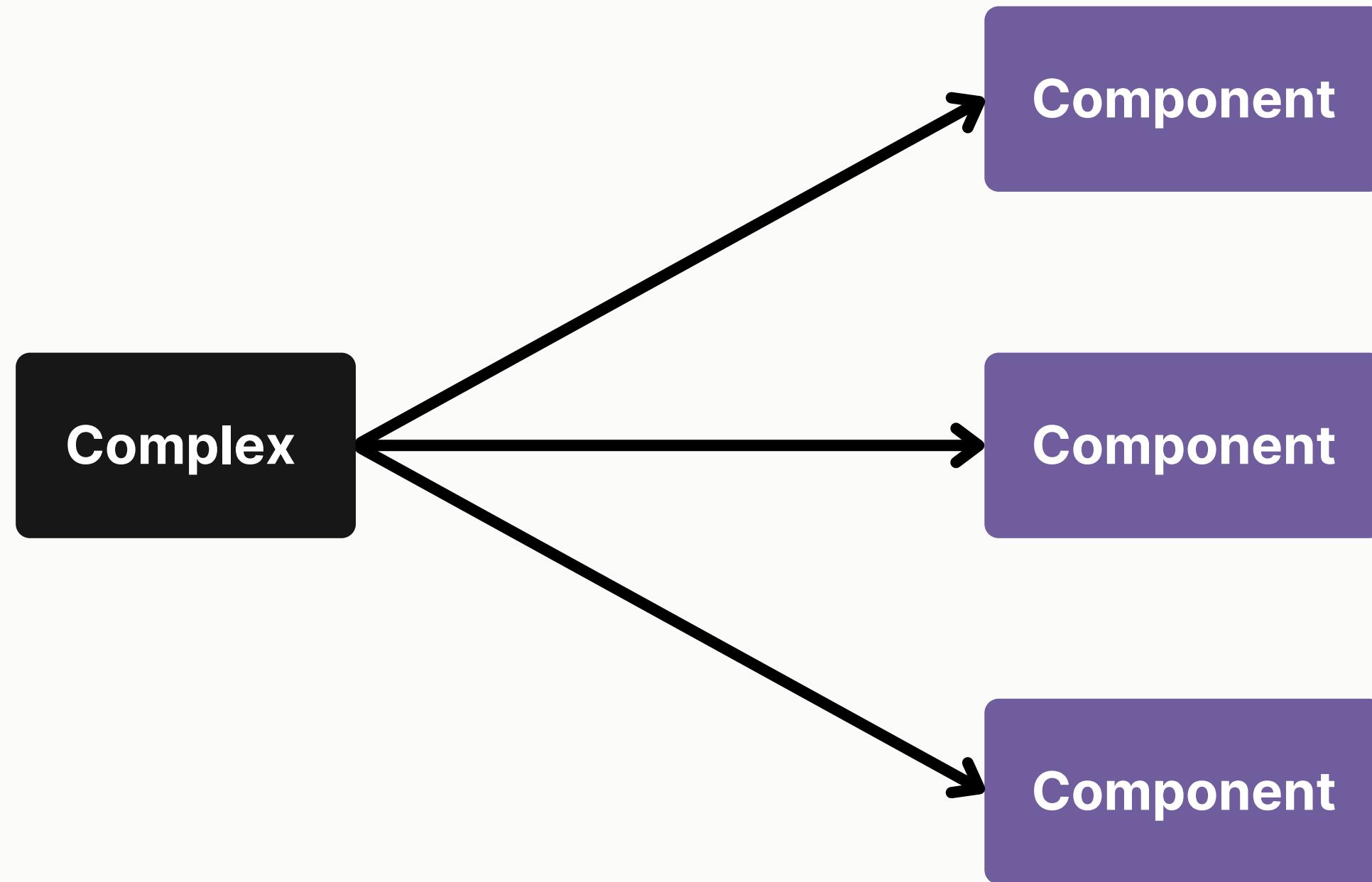
02. Principle Component Analysis

03. Implement in Python

# **1. Singular Value Decomposition (SVD)**

# 1.1. What is SVD?

Idea



## 1.1. What is SVD?

Eigen decomposition

$$A = PDP^{-1}$$

## 1.1. What is SVD?

### Eigen decomposition

Eigen Decomposition.



$$A = PDP^{-1}$$

## 1.1. What is SVD?

### Eigen decomposition

Eigen Decomposition.



$$A = PDP^{-1}$$

$$AP = PD$$

$$Ap_i = Pd_i$$

$$Ap_i = p_i d_{ii}$$

## 1.1. What is SVD?

### Eigen decomposition

Eigen Decomposition.

$$A = PDP^{-1}$$

$$AP = PD$$

$$Ap_i = Pd_i$$

$$Ap_i = p_i d_{ii}$$

Eigen vector

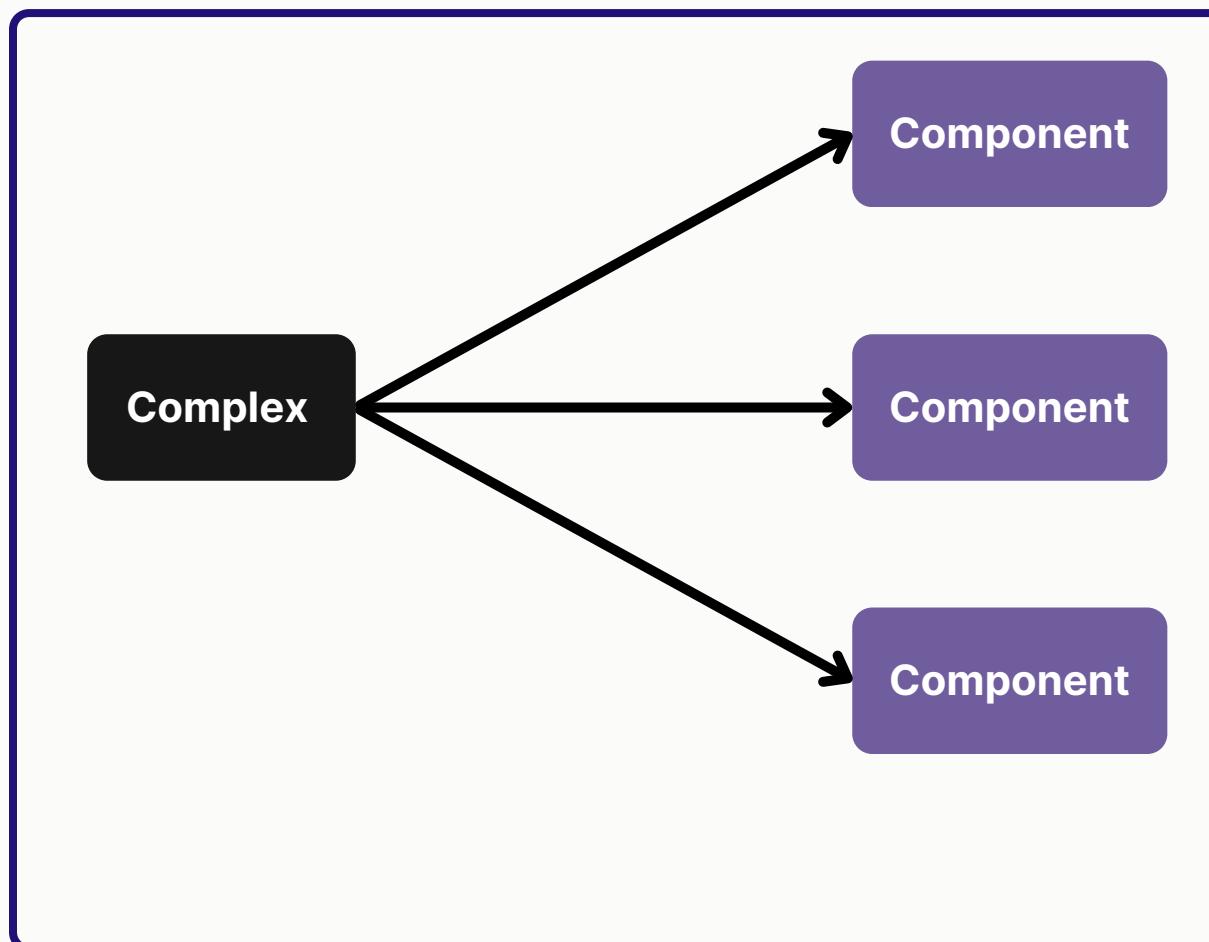
Eigen value

# 1.1. What is SVD?

## Singular Value Composition (SVD)



## Matrix factorization



$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \times \begin{pmatrix} \Sigma_{m \times n} & \\ & \ddots \end{pmatrix} \times \mathbf{V}_{n \times n}^T \quad (m < n)$$
$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \times \begin{pmatrix} \Sigma_{m \times n} & \\ & \ddots \end{pmatrix} \times \mathbf{V}_{n \times n}^T \quad (m > n)$$

idea

$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \Sigma_{m \times n} (\mathbf{V}_{n \times n})^T$$

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## 1.1. What is SVD?

### Singular Value Composition (SVD)

$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \boldsymbol{\Sigma}_{m \times n} (\mathbf{V}_{n \times n})^T$$

$$\mathbf{A}\mathbf{A}^T = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T(\mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T)^T = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T\mathbf{V}\boldsymbol{\Sigma}^T\mathbf{U}^T = \mathbf{U}\boldsymbol{\Sigma}\boldsymbol{\Sigma}^T\mathbf{U}^T = \mathbf{U}\boldsymbol{\Sigma}\boldsymbol{\Sigma}^T\mathbf{U}^{-1}$$

# 1.1. What is SVD?

## Singular Value Composition (SVD)

$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \boldsymbol{\Sigma}_{m \times n} (\mathbf{V}_{n \times n})^T$$

$$A = PDP^{-1}$$

$$Ap_i = p_id_{ii}$$

$$\mathbf{A}\mathbf{A}^T = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T(\mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T)^T = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T\mathbf{V}\boldsymbol{\Sigma}^T\mathbf{U}^T = \mathbf{U}\boldsymbol{\Sigma}\boldsymbol{\Sigma}^T\mathbf{U}^T = \mathbf{U}\boxed{\boldsymbol{\Sigma}\boldsymbol{\Sigma}^T}\mathbf{U}^{-1}$$

$$\begin{pmatrix} \lambda_1 & 0 & 0 & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & 0 & \lambda_3 & 0 & \dots & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \lambda_4 & \dots & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \ddots & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \dots & \lambda_K & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \dots & 0 & \lambda_{K+1} & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \dots & \vdots & \vdots & \vdots & \lambda_N \end{pmatrix} \quad \lambda_i = \sigma_i^2$$

$\sigma_1^2, \sigma_2^2 \dots \sigma_m^2$

$\sigma_j$

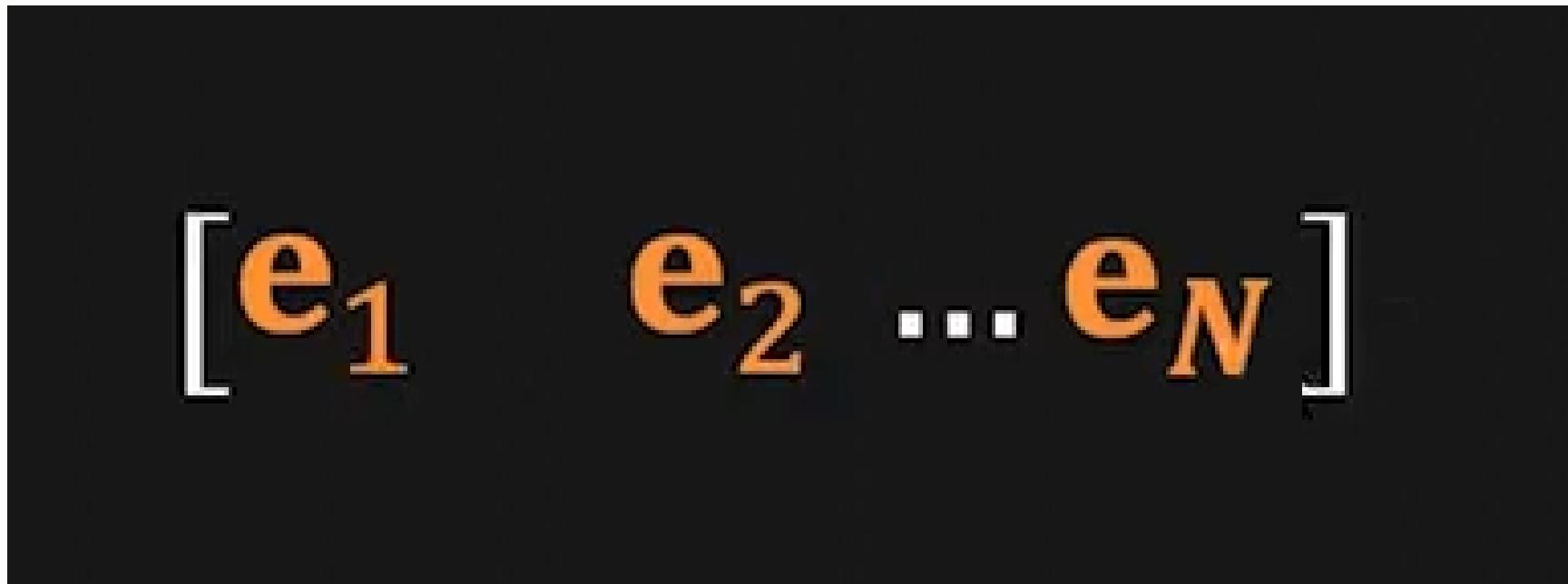
**Singular Value**

## 1.1. What is SVD?

### Singular Value Composition (SVD)

$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \boldsymbol{\Sigma}_{m \times n} (\mathbf{V}_{n \times n})^T$$

$$\mathbf{A}\mathbf{A}^T = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T(\mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T)^T = \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^T\mathbf{V}\boldsymbol{\Sigma}^T\mathbf{U}^T = \boxed{\mathbf{U}}\boldsymbol{\Sigma}\boldsymbol{\Sigma}^T\mathbf{U}^T = \mathbf{U}\boldsymbol{\Sigma}\boldsymbol{\Sigma}^T\mathbf{U}^{-1}$$



column

left-singular vectors

## 1.1. What is SVD?

### Singular Value Composition (SVD)

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left-singular vectors column

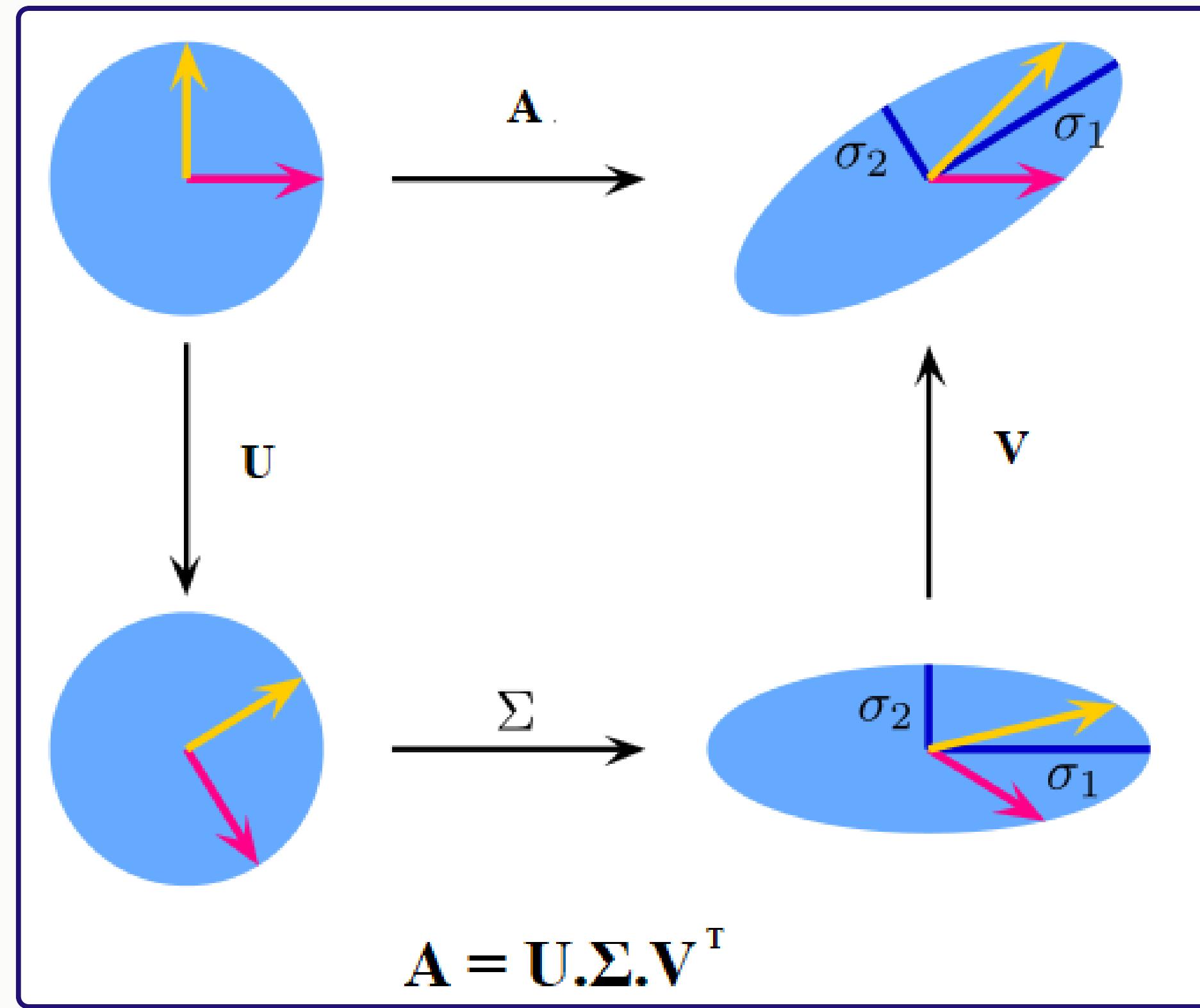
$\sigma_1^2, \sigma_2^2 \dots \sigma_m^2$

$\sigma_j$  Singular Value

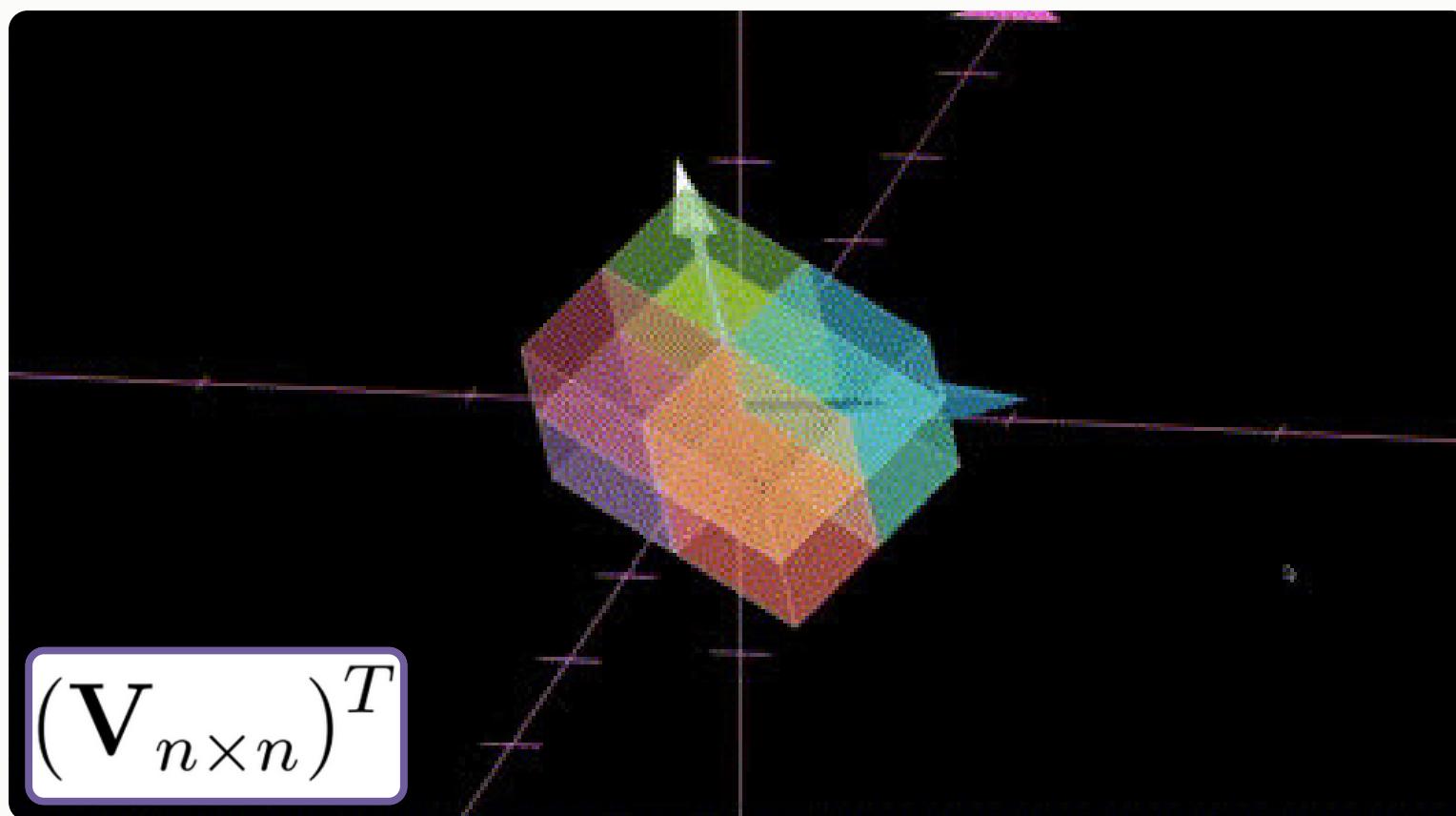
right-singular vectors column

$$\mathbf{A}^T\mathbf{A} = (\mathbf{U}\Sigma\mathbf{V}^T)^T\mathbf{U}\Sigma\mathbf{V}^T = \mathbf{V}\Sigma^T\mathbf{U}^T\mathbf{U}\Sigma\mathbf{V}^T = \boxed{\mathbf{V}}\Sigma^T\Sigma\mathbf{V}^T = \mathbf{V}\Sigma^T\Sigma\mathbf{V}^{-1}$$

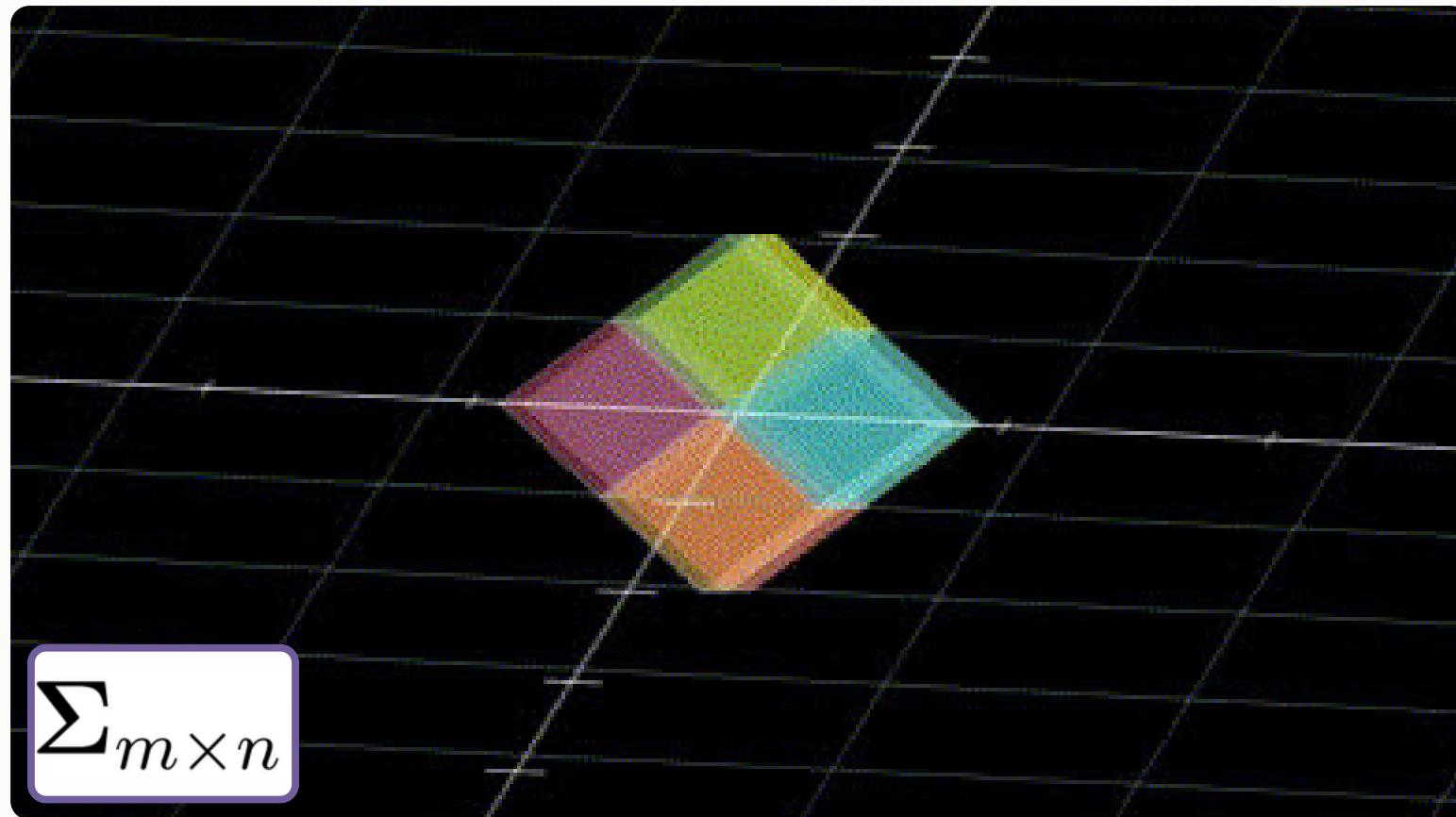
## 1.1. What is SVD?



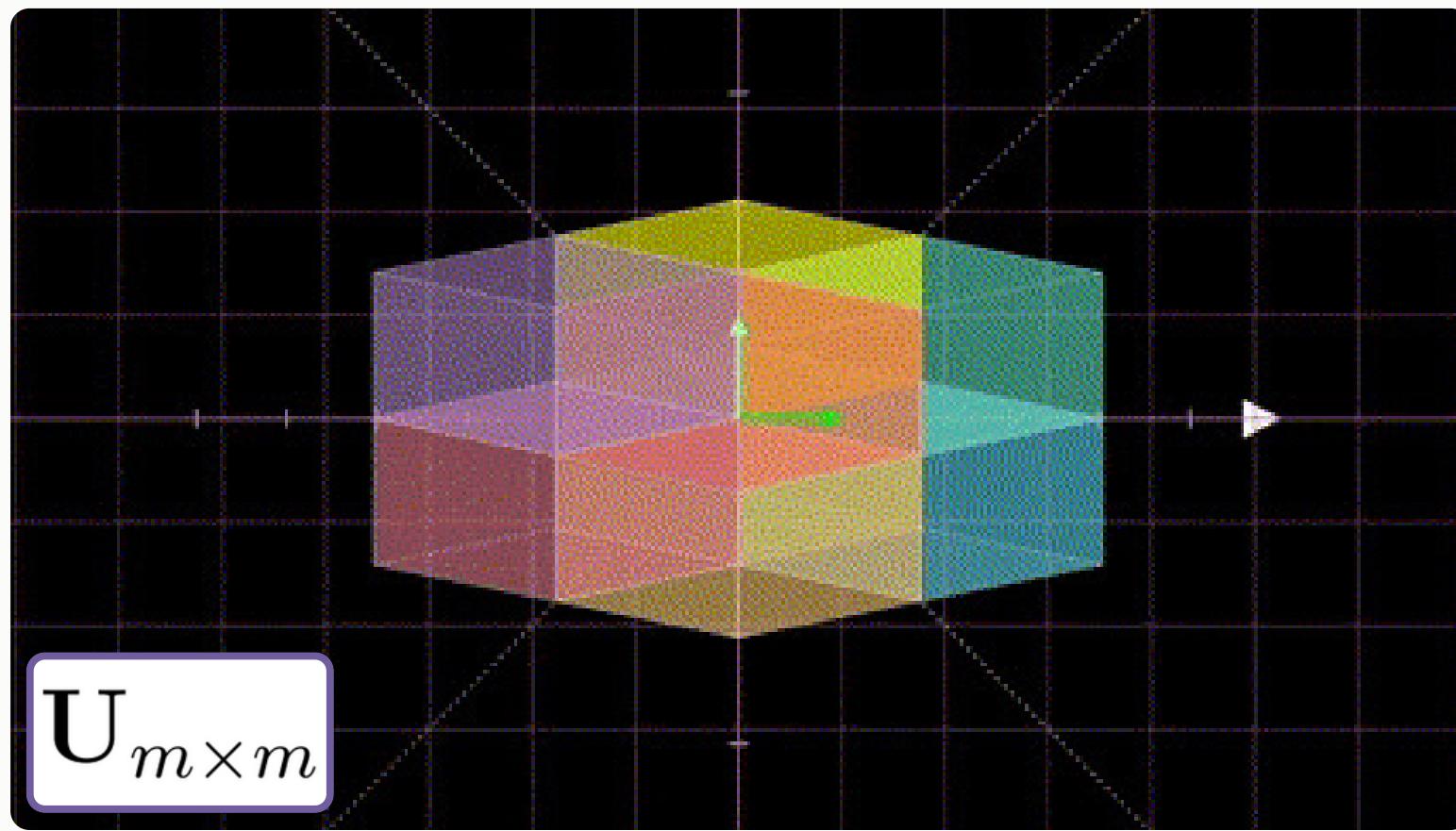
$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \boldsymbol{\Sigma}_{m \times n} (\mathbf{V}_{n \times n})^T$$



$$(\mathbf{V}_{n \times n})^T$$



$$\boldsymbol{\Sigma}_{m \times n}$$



$$\mathbf{U}_{m \times m}$$

01

# 1.1. What is SVD?

## Procedure

**Step 1: Finding the eigenvalues**

**Step 2: Finding left/ right singular vectors**

**Step 3: Finding right/ left singular vectors**

# 1.1. What is SVD?

## Procedure

### Step 1: Finding the eigenvalues and right singular vectors.

```
#Define svd function
def mySVD(A):
    m, n= A.shape

    #calculate eigen values and right singular vectors
    eigenvalues, V = np.linalg.eig(A.T @ A)
    eigenvalues = np.round(eigenvalues, decimals = 4)

    #sort the eigen values and right singular vectors descending
    idx = eigenvalues.argsort()[-1:-n]
    eigenvalues = (eigenvalues[idx])
    V = V[:,idx]
    VT = V.T
```

## 1.1. What is SVD?

### Procedure

**Step 2: Finding the singular values by square root eigen values.**

```
#calc the singular values by square root eigen values  
singularvalues = np.sqrt(eigenvalues)
```

## 1.1. What is SVD?

### Procedure

#### Step 3: Finding the right singular vectors.

```
#calc left singular vectors
U = (A @ V)[:, 0:m] / singularvalues[0:m]
U = U[:, :m]

S = np.diag(singularvalues)[0:m, :] #truncate the 0 values

return U, S, VT
```

## 1.2. SVD - How?

### Some SVDs

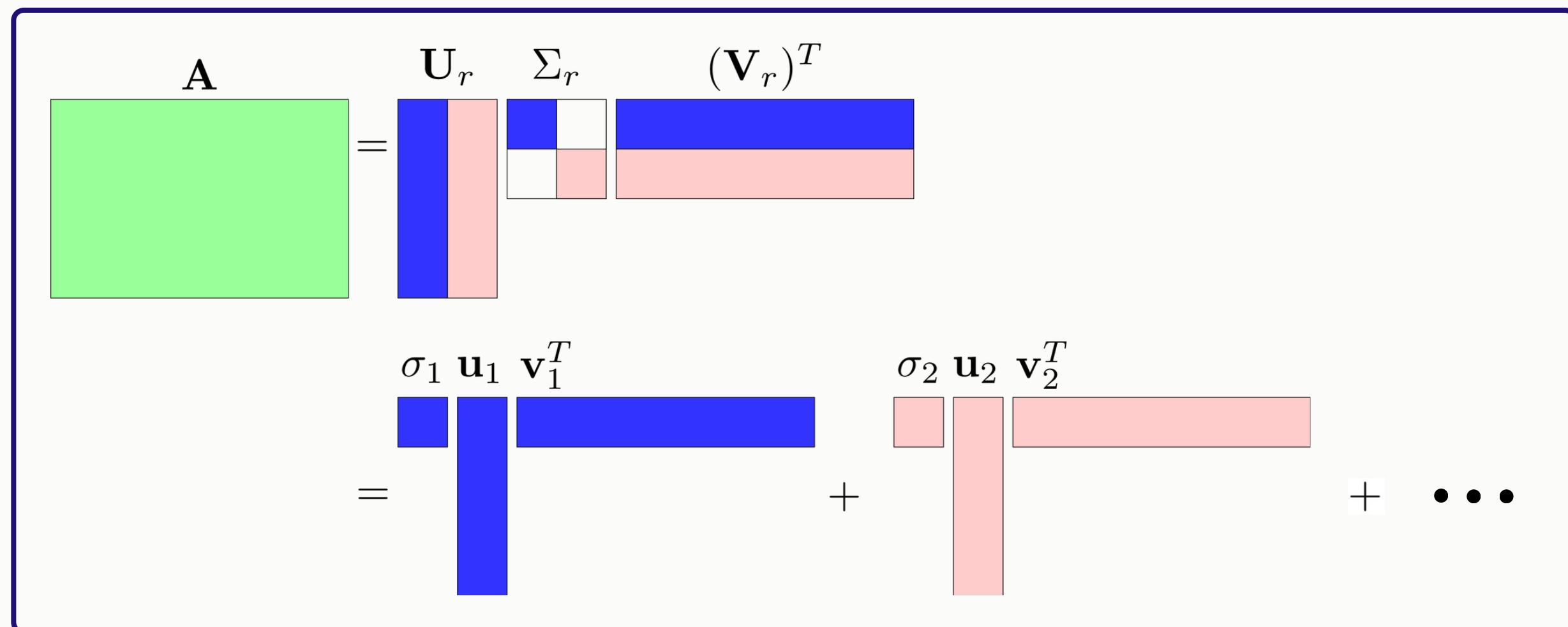
- Compact SVD
- Truncate SVD
- Best(Low) Rank 'k' Approximation

## 1.2. SVD - How?

SVDs -> Compact SVD

$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \Sigma_{m \times n} (\mathbf{V}_{n \times n})^T$$

$$\mathbf{A} = \mathbf{U}_r \Sigma_r (\mathbf{V}_r)^T = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \cdots + \sigma_r \mathbf{u}_r \mathbf{v}_r^T$$

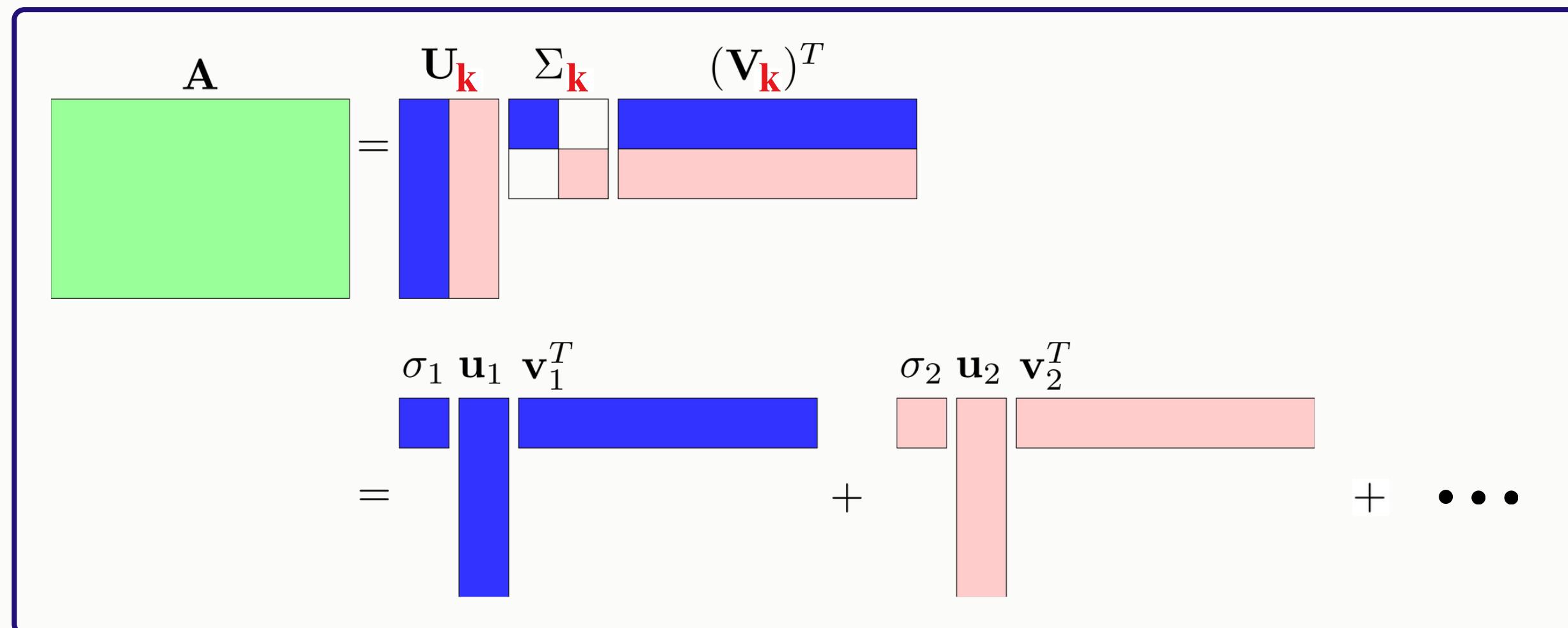


## 1.2. SVD - How?

SVDs -> Truncated SVD

$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \Sigma_{m \times n} (\mathbf{V}_{n \times n})^T$$

$$\mathbf{A} \approx \hat{\mathbf{A}} = U_k \Sigma_k V_k^T = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \cdots + \sigma_k \mathbf{u}_k \mathbf{v}_k^T$$



## 1.2. SVD - How?

SVDs -> Truncated SVD

Theorem:

$$\|\mathbf{A} - \mathbf{A}_k\|_F^2 = \sum_{i=k+1}^r \sigma_i^2$$

**The error will equal to total square of the cut-off eigenvalues in truncated SVD.**

With  $k = 0$ , we got:

$$\|\mathbf{A}\|_F^2 = \sum_{i=1}^r \sigma_i^2$$

$$\frac{\|\mathbf{A} - \mathbf{A}_k\|_F^2}{\|\mathbf{A}\|_F^2} = \frac{\sum_{i=k+1}^r \sigma_i^2}{\sum_{j=1}^r \sigma_j^2}$$

## 1.2. SVD - How?

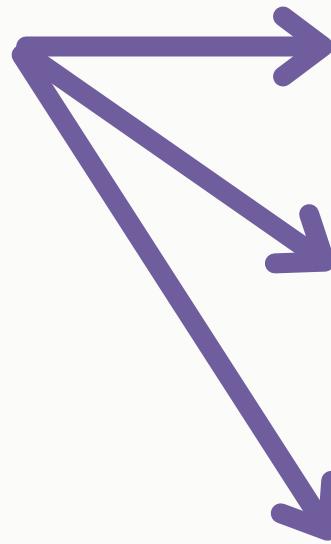
SVDs -> Best(Low) Rank 'k' Approximation

$$\begin{aligned} \min_{\mathbf{A}} & \quad ||\mathbf{X} - \mathbf{A}||_F \\ \text{s.t. } & \quad \text{rank}(\mathbf{A}) = K \end{aligned}$$

$$\mathbf{A} \approx \hat{\mathbf{A}} = U_k \Sigma_k V_k^T = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \cdots + \sigma_k \mathbf{u}_k \mathbf{v}_k^T$$

## 1.3. SVD - Summarise

SVD



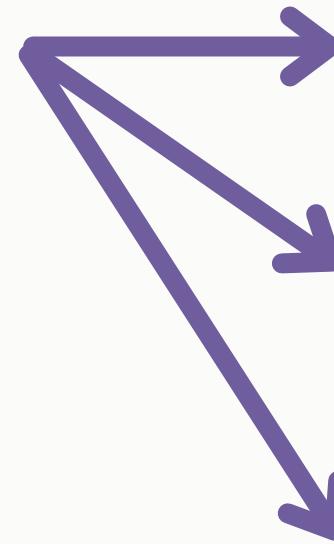
untangle data into independent components

$$A_{m \times n} = U_{m \times m} \Sigma_{m \times n} (V_{n \times n})^T$$

$$A \approx \hat{A} = U_k \Sigma_k V_k^T = \sigma_1 u_1 v_1^T + \sigma_2 u_2 v_2^T + \dots + \sigma_k u_k v_k^T$$

## 1.3. SVD - Summarise

SVD



**untangle data into independent components**

$$\mathbf{A}_{m \times n} = \mathbf{U}_{m \times m} \boldsymbol{\Sigma}_{m \times n} (\mathbf{V}_{n \times n})^T$$

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### Pros:

- Simplifies data
- Removes noise
- Data compression
- ...

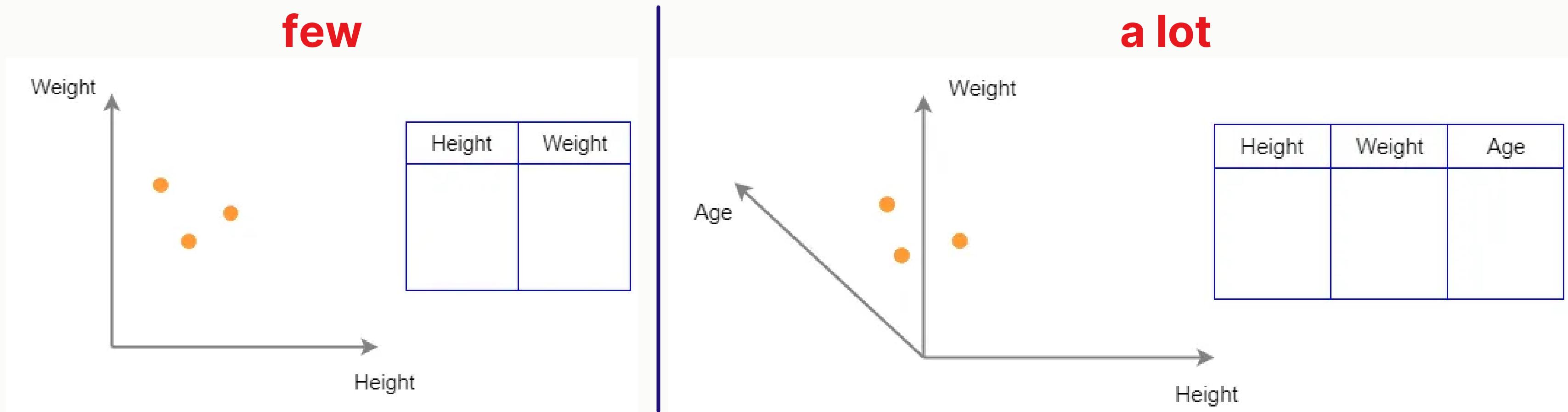
### Cons:

- Transformed data may be difficult to understand
- Limitations in non-linear relationships
- ...

# **2. Principle Component Analysis (PCA)**

## 2.1. Why PCA?

### Dataset's high dimensionality



**a lot of variables to consider.**

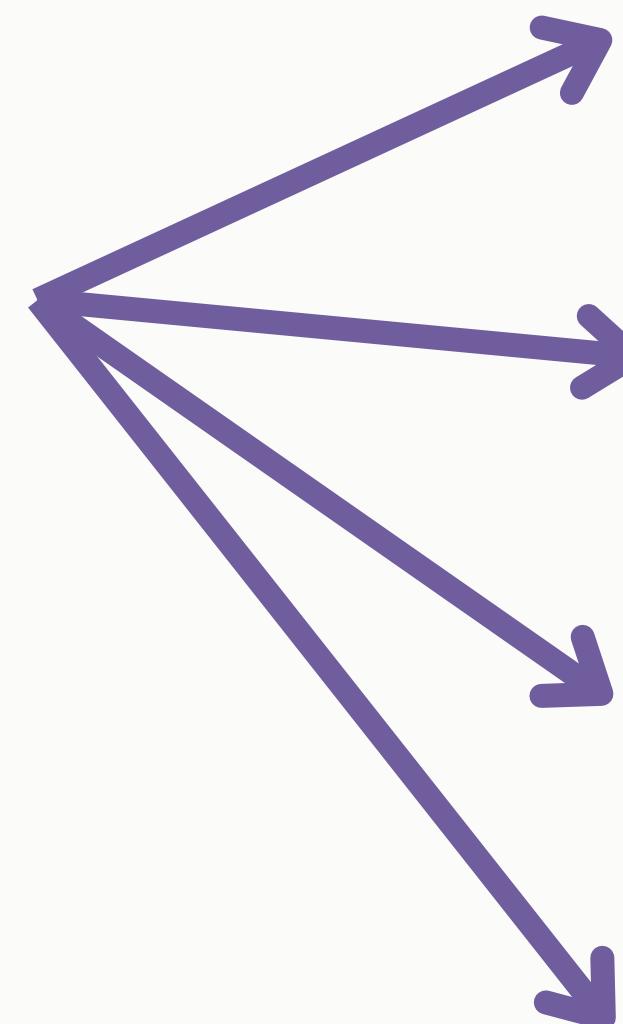


**high-dimensional data causes challenges**

## 2.1. Why PCA?

### Dimensionality reduction

lose some percentage but



less cost

prevent overfitting

data visualization

...

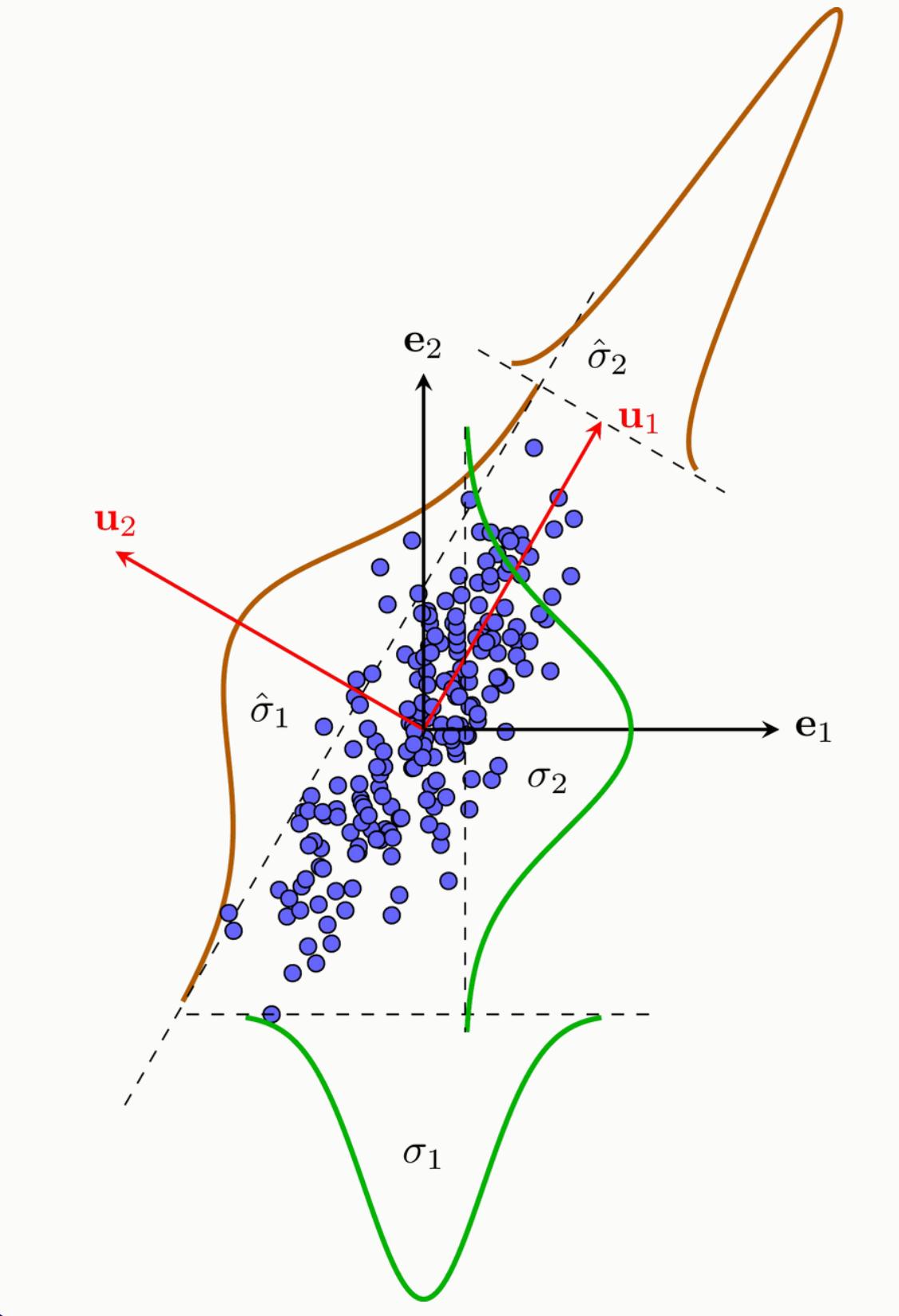
## 2.2. What is PCA?

Idea

$$D \longrightarrow K$$

$(K < D)$

- The idea of PCA is plotting the data into a **new basis system**
- The importance of the components is **significantly different**
  - > ignoring the **least important** component



## 2.2. What is PCA?

$$\begin{array}{c}
 \begin{array}{c}
 N \\
 D \quad \mathbf{X}
 \end{array} = \begin{array}{c}
 K \quad D - K \\
 D \mathbf{U}_K \quad \bar{\mathbf{U}}_K
 \end{array} \times \begin{array}{c}
 N \\
 K \quad \mathbf{Z} \\
 D - K \quad \mathbf{Y}
 \end{array} \\
 \text{Original data} \qquad \qquad \text{An orthogonal matrix} \qquad \qquad \text{Coordinates in new basis}
 \end{array}$$
  

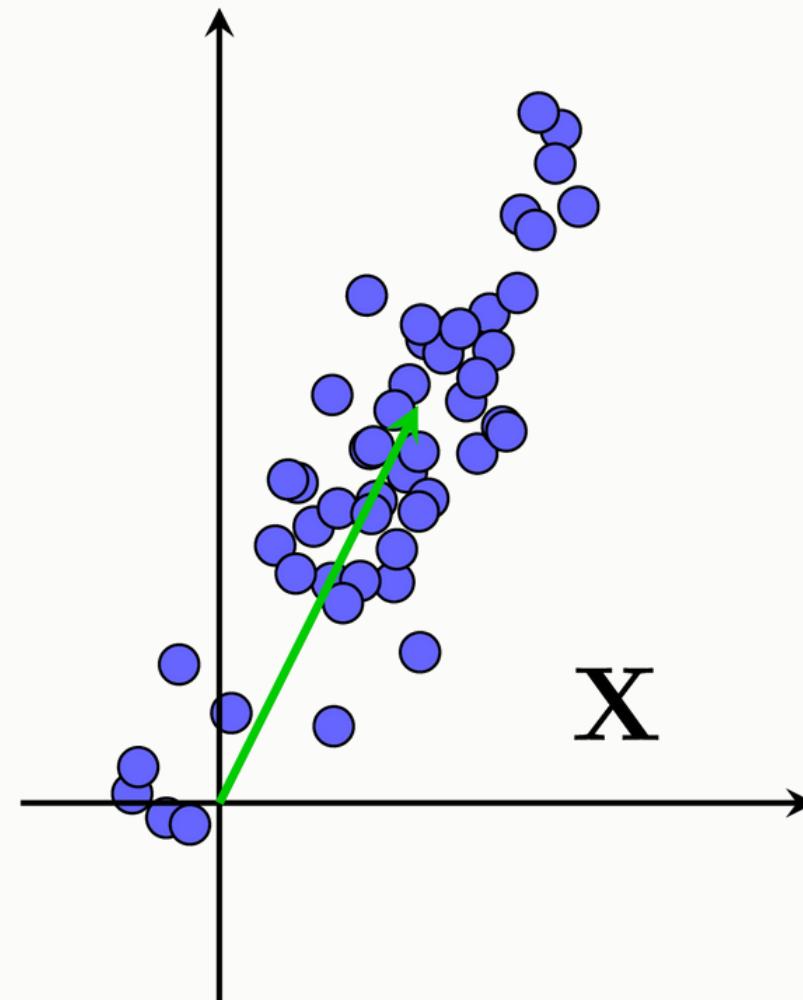
$$= \begin{array}{c}
 K \\
 D \mathbf{U}_K
 \end{array} \times \begin{array}{c}
 N \\
 K \quad \mathbf{Z} \\
 D
 \end{array} + \begin{array}{c}
 \bar{\mathbf{U}}_K
 \end{array} \times \begin{array}{c}
 \mathbf{Y}
 \end{array}$$

$$\mathbf{X} = \mathbf{U}_K \mathbf{Z} + \bar{\mathbf{U}}_K \mathbf{Y}$$

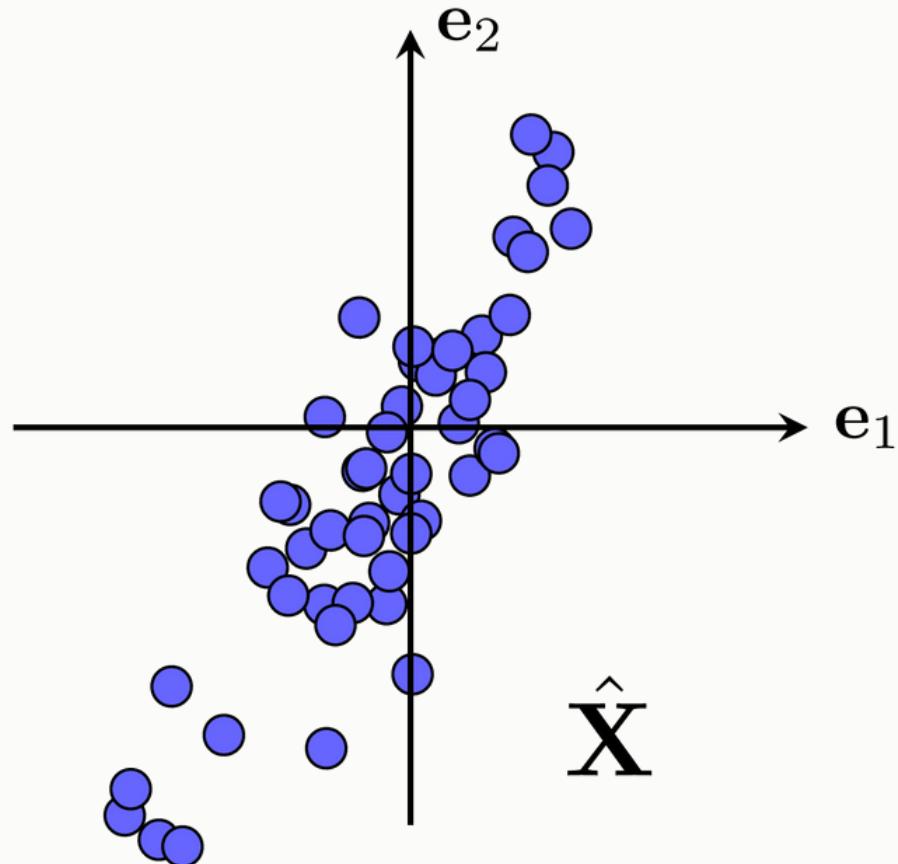
$$\mathbf{X} \approx \tilde{\mathbf{X}} = \mathbf{U}_K \mathbf{Z} + \bar{\mathbf{U}}_K \bar{\mathbf{U}}_K^T \bar{\mathbf{x}} \mathbf{1}^T$$

## Procedure

1. Find mean vector



2. Subtract mean

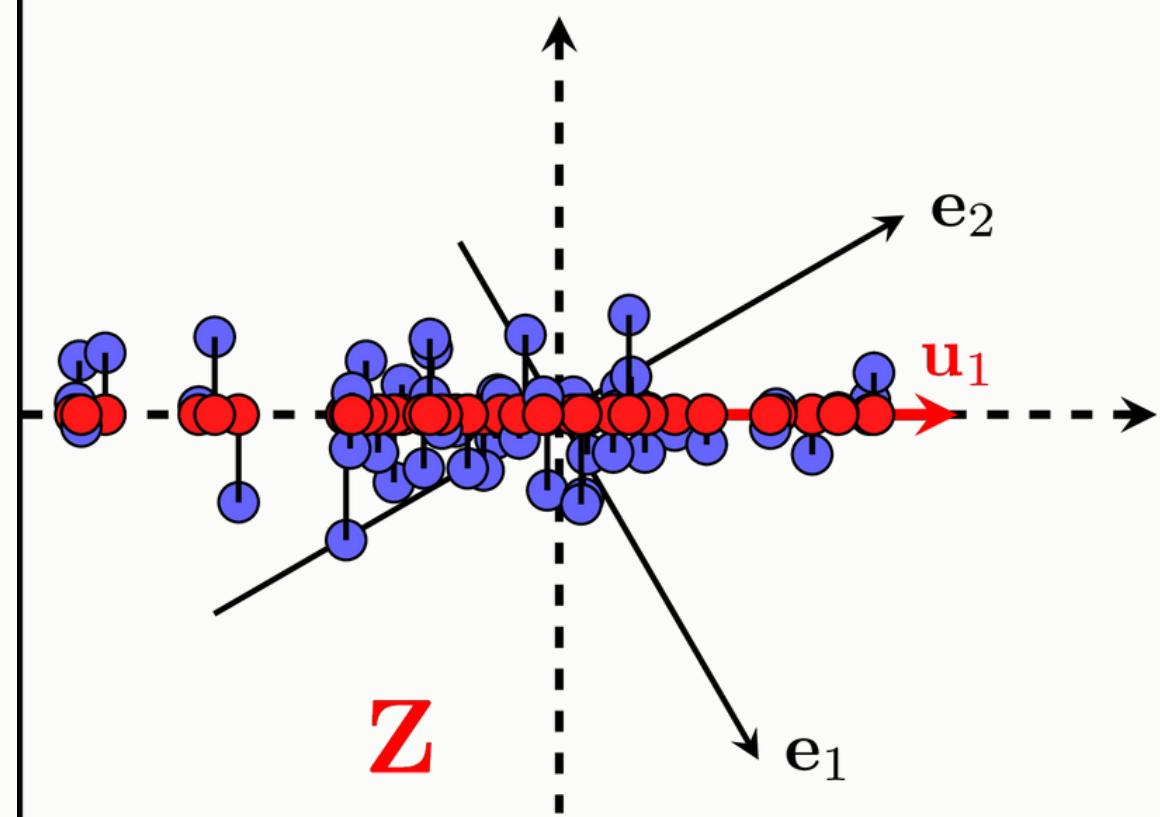


3. Compute covariance matrix:  
 $\mathbf{S} = \frac{1}{N} \hat{\mathbf{X}} \hat{\mathbf{X}}^T$

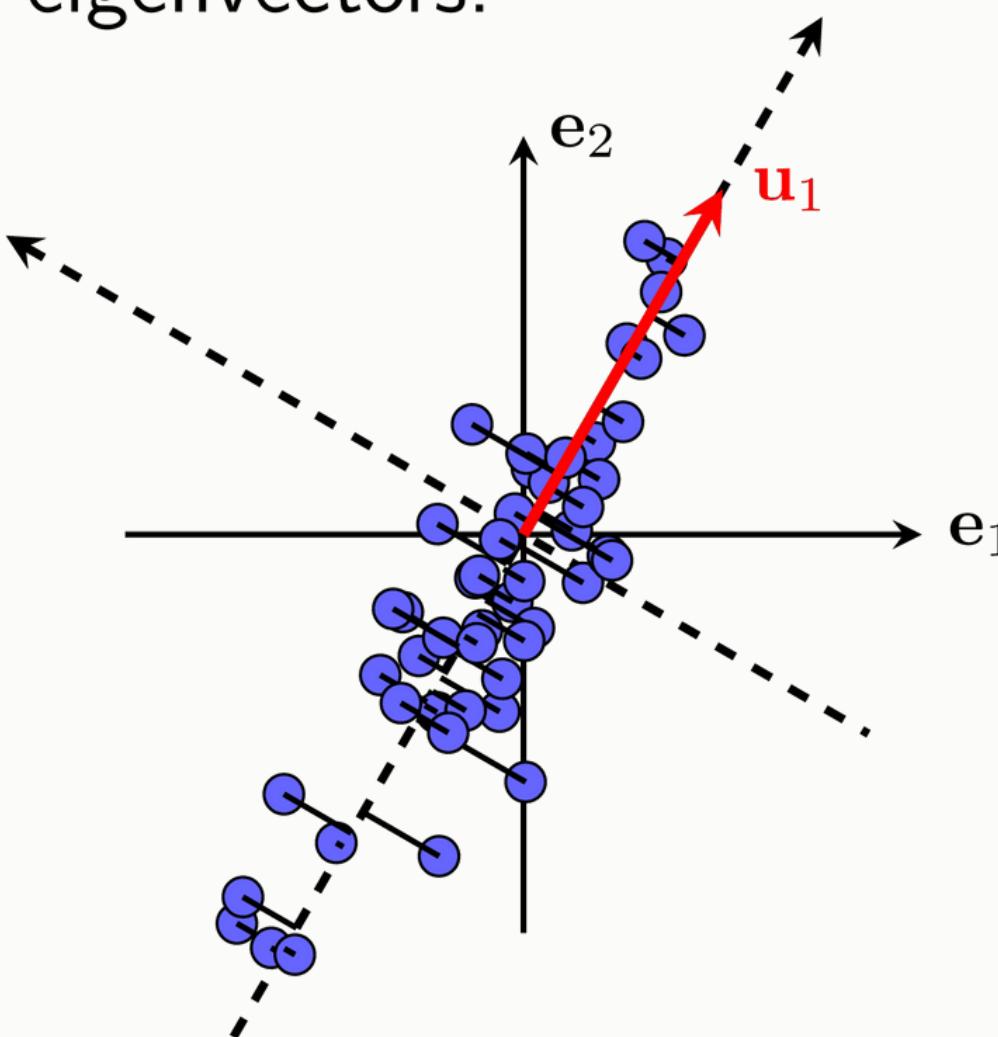
4. Computer eigenvalues  
and eigenvectors of  $\mathbf{S}$ :  
 $(\lambda_1, \mathbf{u}_1), \dots, (\lambda_D, \mathbf{u}_D)$   
Remember the or-  
thonormality of  $\mathbf{u}_i$ .

## Procedure

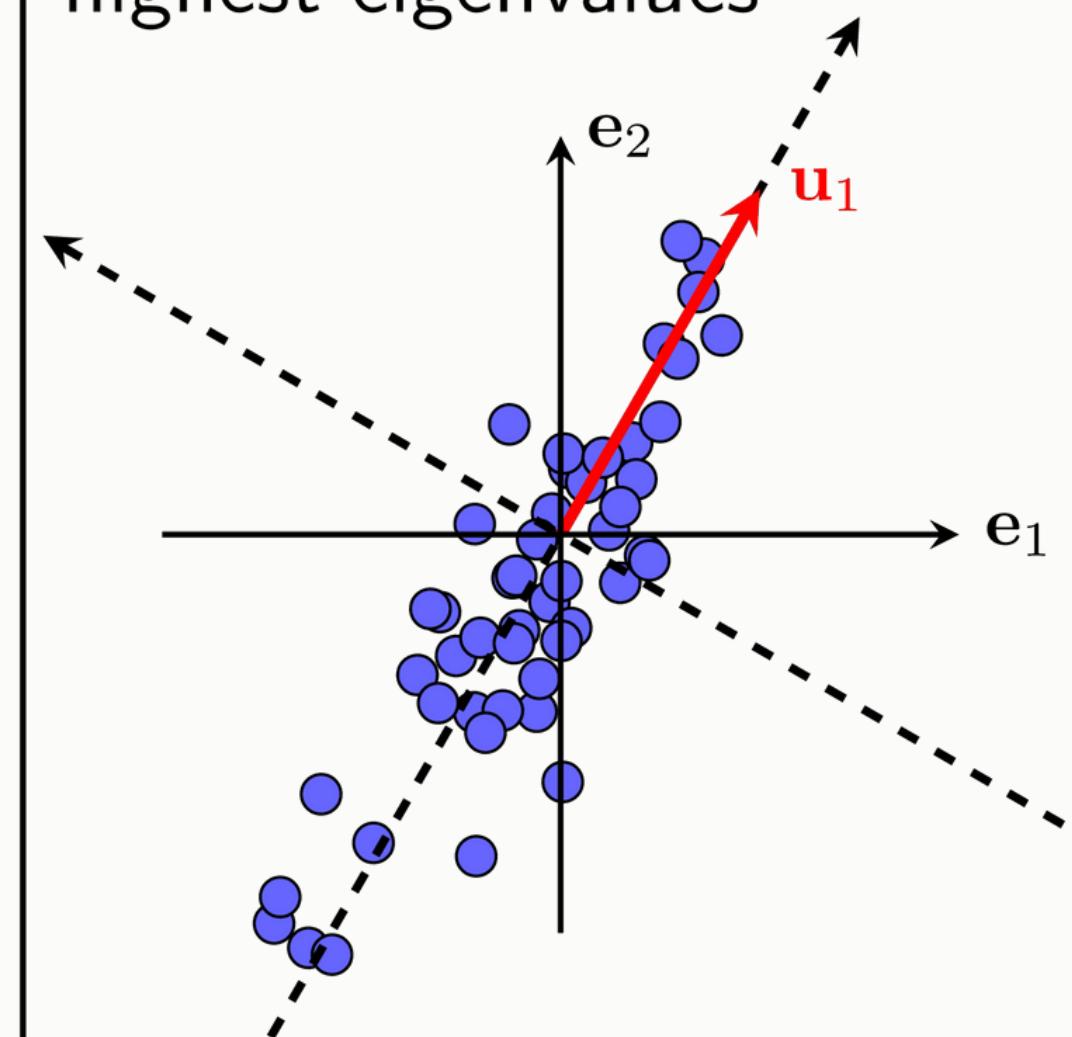
7. Obtain projected points in low dimension.



6. Project data to selected eigenvectors.



5. Pick  $K$  eigenvectors w. highest eigenvalues



## 2.4. PCA & SVD, any relationship?

### PCA

- PCA transforms data

$$\mathbf{U}_K, \mathbf{Z} = \min_{\mathbf{U}_K, \mathbf{Z}} \|\mathbf{X} - \mathbf{U}_K \mathbf{Z}\|_F$$

$$\text{s.t.: } \mathbf{U}_K^T \mathbf{U}_K = \mathbf{I}_K$$

$$\mathbf{X} \approx \tilde{\mathbf{X}} = \mathbf{U}_K \mathbf{Z}$$

### SVD

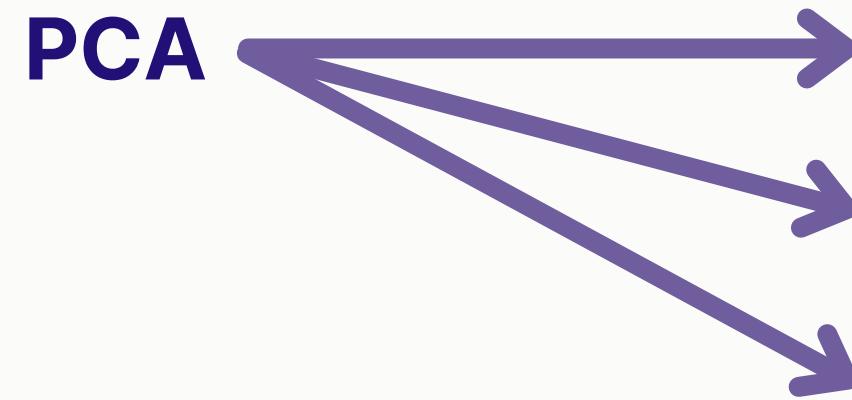
- SVD: Decompose matrix

$$\min_{\mathbf{A}} \|\mathbf{X} - \mathbf{A}\|_F$$

$$\text{s.t. } \text{rank}(\mathbf{A}) = K$$

$$\mathbf{A} = \mathbf{U}_K \Sigma_K \mathbf{V}_K^T$$

## 2.5. PCA - Summarise



**new basis system**  
**covariance matrix**  
**truncated SVD**

### Pros:

- Prevent overfitting
- Improve visualization
- Improve performance
- ...

### Cons:

- Information Loss
- Scaling data
- Same variance
- ...

# **3. Implement in Python**

**THAT'S IT**