

EsbRootView, a portable event display for the ESSnuSB project

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Abstract. EsbRootView is an event display for the detectors of ESSnuSB able to exploit natively all the nice devices that we have in hands today; desktop, laptops, but also smartphones and tablets.

1 Introduction

The goal of the ESSnuSB project [1] is to discover and measure neutrino charge-parity violation with unprecedented sensitivity. The ESSnuSB concept takes advantage of two outstanding opportunities. The first is the construction in Europe of the European Spallation Source, ESS, the world's most intense proton source, with a beam power almost one order of magnitude higher than any other accelerator. The second is the measured unexpectedly large value of the oscillation mixing angle θ_{13} . The latter fact implies that to obtain maximum sensitivity, the neutrino detector shall be placed at the second neutrino oscillation maximum, not at the first as implemented by other proposed experiments. The Garpenberg mine in Sweden, in which it is proposed to install the underground neutrino detector, is situated at a distance from ESS that corresponds to the second maximum. The goal of the ESSnuSB H2020 Design Study is to organise European physicists and accelerator engineers in co-operation with the ESS Laboratory and the Garpenberg Mining Company to study and produce a Conceptual Design Report for the ESSnuSB project.

In the work package five of the ESSnuSB project we developed an event display based on the graphics technology developed at Orsay from 2010 (developments done at LAL up to 2020 and now continued in the new Orsay IN2P3 IJCLab laboratory that absorbed LAL). This technology permits to have programs running natively on most of today's interactive devices as desktop/laptop under Linux, macOS or Windows-10 but also on iOS/Android smartphones and tablets. Since 2019, with the same core technology we can run in most web browsers by using the WebAssembly and WebGL technologies.

Today's versions 3.x can visualise simulations data of the “neard”, “fard” and “fgd” detectors. The small neard is intended to monitor the beam of neutrinos and the fard is the big Cherenkov one placed at the second neutrino oscillation maximum. The fgd is a detector composed of a 3D array of scintillator cubes, which can be read out semi-independently, and placed in front of the neard. The ESSnuSB setup is nicely explained in the “ESSnuSB Design Study Project” video that could be found on YouTube or through the main web page of the project at <https://essnusb.eu>.

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2 Main ideas

EsbRootView is fully written in C++ (98 flavour) with good part of the code being pure header. Being able to run on most interactive devices, including iOS and Android, is made possible by the fact that since C++98 and GL-ES (OpenGL for Embedded Systems, a graphics rendering standard), are available for all of them. A key point is that at Orsay we have light portable code (inlib/root classes) to read ROOT files and then we can read on all our devices the files describing the detectors and the events issued from the ESSnuSB detector simulations.

We have implemented an event model with a `one_event` class managing instances of `EsbMCTrack`, `EsbDetectorPoint`, `EsbHit`, `EsbFgdHit` classes describing data issued from the simulation. All the items of the event model received one or more graphical representations. For the geometries, we can read the `TGeo` classes stored in the ROOT files and we have graphical representations of them in our inlib library. To view geometries, we have nothing specific to ESSnuSB.

To let the user customise things, we have a default Bourne shell like scripting, the “insh”, which is described below in section 6.

About our event model, we are aware that this duplicates the event model code found in the EsbRoot framework used for the simulation, but for the moment this one is not portable, in particular because it is tied to CERN-ROOT [2], and then not usable for us. Being able to have a portable unique event model shared with the simulation and analysis would be a nice target to aim for the mid and long range term of the ESSnuSB project.

3 inlib/sg

The core of our graphics technology is the usage of a scene graph logic developed at Orsay; the inlib/sg classes (sg for scene graph). inlib/sg is strongly inspired of the great OpenInventor developed by Silicon Graphics Inc in the 1980’s [3]. The idea is to describe a scene by using a graph of nodes. A node could be an instance of a camera class (`inlib::sg::ortho`, `perspective`) specifying the position, orientation and depth of view of a camera, an instance of a 4D matrix class (`inlib::sg::matrix`) to position an object in a 3D space (rotation and translation) or an instance of a shape node describing for example a cube (`inlib::sg::cube`). A key node is a group (`inlib::sg::group`) to gather nodes.

Whence having built a scene graph, the rendering is done, typically after having received some expose event in a drawing area window, by applying a “render_action” that traverses the scene graph and asks to the nodes the actions that will be passed to a specific graphics engine. For example a shape node (cube, sphere, polyhedron), when traversed, will give to the render_action the graphics primitives (points, lines, segments, triangles) representing that shape. A camera node will give a projection matrix, a matrix node will give a model matrix. A common graphics engine being GL-ES, we have the `exlib::sg::GL_action` class that does that for GL-ES. But we have also various render_action to do offscreen rendering, web rendering (using WebGL) or to handle private company specific engine, such as the Apple/Metal one.

Note that we keep within the namespace “inlib” only code that relies on the STD/STL and on some few system functions not being in C++98.

4 exlib

The code that depends on external libraries, as GL-ES, is within the exlib namespace. A typical example is the GL-ES related code in `exlib::sg::GL_action`, or the code that handles various “windowing” technologies, for example the `exlib::X11::viewer` and

exlib::Windows::viewer classes for X11 or Windows. By windowing we mean the code to create a window to draw in and get events as click or touch on it. Note that the `exlib::sg::GL_action` inherits the virtual `inlib::sg::render_action` which is the only one seen by the `inlib::sg` nodes. The relation of the rendering toward the scene graph nodes is abstracted.

5 Graphical User Interface

In `EsbRootView` the GUI is done with `inlib/sg` scene graphs. This permits to have the same look and feel on all platforms. For the moment we follow the logic of video games, mainly we give high priority to the “scene” which takes the full window (then full screen on smartphones and tablets), and we pass in “GUI mode” when needed by clicking/touching the bottom area of the window. The GUI mode leads to a central menu list with, for example, the “setup” menu items permitting to choose which detector to work with (neard, fard, fgd). Central menu items may lead to sub menus. A bottom-left “home” button permits to return to the top menu list. A bottom-right “back” button permits to return one level back in the central menu tree. A left “params” button permits to setup global parameters. And at last, a “camera” button on the right permits to return also to the “scene mode” but by mapping tiles of squared buttons at left and right of the window to do various common actions; the right tiles are dedicated to camera settings and the left ones to common actions as doing a “next event”, clearing the scene, do a “view all”, switching on/off the light, producing a jpeg or png, etc... When in scene mode, a “background popup” leads to a shortcut to various global actions, and if in “picking mode” (setup from a tile button on the right), a contextual popup appears when picking an object in the scene. Contextual menu items permit for example to center the camera on the picked object, get infos about it, change its colour, etc...

Our GUI is perhaps not the most beautiful and sophisticated, but it is functional and works the same on all platforms. Due to the fact that it is based on the same graphics technology as the scenes, it does not have to involve an extra third party package, which simplifies a lot the building of the application and its distribution.

6 scripting with insh

`EsbRootView` is equipped with the core of a Bourne like shell called “insh” for `INlib SHell`. It had been introduced to have a way to customise things by using a scripting syntax known by any UNIX pedestrian and easily implementable by a “doer” in a light way. insh has the basic mechanisms found on any bash shell: variables, env variables, dollar replacement of a variable, backquoting, execute other scripts, source other scripts and, obviously, execute commands with options. For example, in a “next event” insh script, you may see:

```
# this is a comment.
event_index='event_index'
gui_show_console ${event_index}
scene_clear_dynamic
event_vis MCTrack -color=red
event_vis WCDetectorPoint -color=green
```

6.1 Terminal mode

On desktop versions (macOS, Linux, Windows), the program can be started with the “-terminal” option that permits to type insh commands from the terminal. The behaviour is

similar to the bash prompt. In particular by typing twice the tab key you activate the completion and have the list of available commands. For all commands, the user has a help text that can be read by using the help command:

```
EsbRootView> help echo
EsbRootView> help event_model
```

Around two hundred commands exist now in EsbRootView. The reference manual of all of them can be found in the web pages (see section 10).

The terminal prompt handles a history maintained under the user Documents/EsbRootView/.insh_history file. The history logic is the same as for a bash prompt; type "history" to see the numbered past commands, "exclamation mark and number" to recall a numbered command, and twice exclamation mark to execute again the last command.

6.2 The startup, event, anim.insh scripts

The "setup" main menu item permits to choose which detector to work with. Depending on the selection, dedicated startup.insh, event.insh, anim.insh scripts are copied from internal versions coming with the installation (from the "resources" directory) into the user Documents/EsbRootView directory. The startup.insh script is executed at each startup of EsbRootView, the event.insh when doing a "next event" and the anim.insh when applying the "scene anims" main menu item. These scripts are good starting points to customise the general overall behaviour of EsbRootView.

6.3 event_model, event_next, event_vis: the commands to know

The event_model command lists the event model classes (MCTrack, WCDetectorPoint, FgdDetectorPoint, FgdHit from 2.x versions) along their fields (for example MCTrack pdg, x, y, z, p, E, etc...). The event_next permits to have an event taken from the current opened event file. The event_vis permits to visualise an item of the event model instances in the current loaded event. Its first argument is the wanted item and other arguments are "-options". For example:

```
event_vis <event_model_class> [options]

event_vis MCTrack -cut=(pdg==500000050) -color=red

event_vis WCDetectorPoint-cut=pdg==500000050 -color=red
event_vis WCDetectorPoint -cut=pdg!=500000050 -color=blue -point_size=4
```

The -cut logic, as described below in 6.5, applies also for the event_count, event_stats and event_print commands:

```
event_print <event_model_class> [options] [fields]

event_print MCTrack -cut=(pdg==500000050)
event_print MCTrack -cut=(pdg==500000050) x y z p

event_count MCTrack -cut=(pdg==500000050)

event_stats MCTrack -cut=(pdg==500000050) p t
```

As explained in "help event_stats", event_stats prints the sum/min/max/mean/rms for the fields of the selected/cut objects.

6.4 The -cut option

A useful option found on all “event_” commands is the “-cut” option that permits to filter instances of an event model item according to their field values. This option is implemented with a little interpreter (done with lex and yacc) that has the syntax of a C conditional statement. For example, in an insh script, it permits to do:

```
cut_first="(pdg==500000050)&&(is_secondary==true)"
cut_second="(pdg==500000050)&&(is_secondary==false)"
...
event_vis MCTrack -cut=${cut_first} -color=red
event_vis MCTrack -cut=${cut_second} -color=green
...
event_vis WCDetectorPoint -cut='x>0' -color=blue
```

6.5 The -modeling option

We can have multiple representations for an event model item. For example, the MCTrack has the “point” (default), “arrow” and “markers” ones. (“arrow” draws an arrow at MCTrack position in the direction of its momentum). By playing with the -cut and -modeling options, someone can view the topology of a muon decay as in figure 1.

6.6 The pdg and particle_print commands

Among commands, must be mentioned the pdg and particle_print ones that permit to dump tabular informations about particles. Type “help pdg” or “help particle_print” for more.

7 Plotting. event_histo, event_plot commands

Making histograms and filling ntuple are basic tools in HEP. Plotting used to visualise histograms (and ntuple “projections”) is an important tool in HEP for doing analysis. The inlib/sg library comes with the inlib::sg::plotter node that permits to visualise histograms done with the inlib::histo::h1d, h2d classes. The plotting is then done with the same scene graph logic as for visualising detectors, events and making the GUI: in EsbRootView we have a unified graphics. See figure 2 and figure 3 for examples.

EsbRootView permits to create histograms from items in the event model and plots them in scene mode by using the event_histo and event_plot commands. For example:

```
event_histo MCTrack -name=h_MCTrack -cut=(pdg!=500000050) -xfill=p
event_plot MCTrack -cut=(pdg!=500000050) -xfill=p
```

Type “help event_histo” or “help event_plot” for more.

8 Animations

EsbRootView comes with a nice mechanism to do animations. The 3.x versions come with animations showing the tracking of optical photons coming from the Cherenkov effect of charged particles in water. It permits to see the “smoke rings” of a muon and how photomultipliers switch on when receiving light. It reinforces the intuition about how things happen when, for example, a muon decays in the near or far detector. These rings could be seen in the YouTube video “ESSnuSB Design Study Project” both for the near and in the far. See figure 4, figure 5.

9 Platforms

In general, we arrange to use the default solutions provided by the device providers for the windowing, the rendering and the compiler. This permits to get the best performances on each kind of device and also simplifies the build by not having to install too many third party packages.

9.1 Linux

On Linux, we use X11 for the windowing, the Mesa OpenGL for the rendering and the g++ compiler. The build is done by using our “bush” set of bash scripts. (Bush is for BUild with (Bourne) SHell).

9.2 macOS

On macOS, we use Cocoa for the windowing, the Apple OpenGL for the rendering and the clang++ compiler coming with Xcode. Since at the 2018 WWDC conference Apple deprecated its OpenGL in favour of its Apple/Metal rendering layer, in 2020, we did a first version of a `exlib::metal::action` to switch to Apple/Metal when needed. We have a first version of `EsbRootView` that works on Metal, but it is not yet fully implemented and optimised. Therefore, we prefer to deliver with Apple/OpenGL as long as it is still available.

9.3 Windows

On Windows, we use the standard WIN32 API for the windowing, the Microsoft `opengl32.lib` for the rendering and VisualC++ for the compiler (the `cl.exe` command). VisualC++ can be installed and used with a free version of VisualStudio brought from Microsoft web sites. The build is done under CYGWIN by using our “bush” set of bash scripts. The usage of the VisualC++ from here is done by using a “bush/vc++” script encapsulating the usage of the `cl.exe` command in a way that the arguments passed to `bush/vc++` have the same syntax than for a g++ command.

Note that today we do not use DirectX for the rendering, but our architecture would permit to have a straight `exlib::Windows::DirectX_action` class for the rendering if one day or another Microsoft would deprecate its OpenGL implementation.

9.4 iOS

On iOS we use the UIKit for the windowing, the Apple GL-ES for the rendering and the clang++ compiler coming with Xcode. We have not yet an Apple/Metal version for the rendering. It is in the job list, but in principle the `exlib::metal::action` done for macOS should be reusable “as is” for iOS.

Note that here we use Xcode on a Mac to build the application. Xcode is more or less mandatory if wanting to deliver for the iOS App Store or upload, in a simple way, the cross compiled application on an iPhone or iPad.

Today `EsbRootView` had not been deposited on the macOS and iOS App Stores, but it is in the job list to do so.

9.5 Android

To build for Android, we use the SDK and NDK developments kits to cross compile the application from a Mac. We use some minimal java for the windowing (to create an “activity”) but use the C EGL library of the NDK for the rendering. We build the “EsbRootView.apk” by using the SDK tools (ant and GNUMake) along the adb program to upload the apk on a device connected to the Mac.

Today EsbRootView had not been deposited yet on the Google Play Store, but it is in the job list to do so.

9.6 WebAssembly

For visualisation in the WWW, we use WebAssembly [4]. In most web browsers there is a virtual machine (the wasm) that permits to execute a C++ application locally. By installing the emscripten SDK on a Mac or a Linux, someone can cross compile (with the emc++ compiler) a C++ application to produce a wasm binary. The windowing is done by using a “canvas” of the web browser, and the rendering is done by using WebGL. We did a `exlib::wasm::render` class that produces, then from the C++ in the wasm binary, a textual javascript code to order the rendering of primitives in the web browser by using WebGL. The SDK provides an `index.html` file along some javascript files to create the WebGL canvas, download and activate the wasm binary.

The overall build is done again with our “bush” set of bash scripts. At the end we have the wasm binary, several html and javascript files that can be deposited in static web pages. There is no need to have dedicated web servers to deliver this web application. There is a WebAssembly version of EsbRootView accessible from the EsbRootView section of the “softinex portale” under the `gbarrand.github.io` web pages. (“softinex” [5] is the entity that gather all our applications done with our inlib and exlib libraries).

After having passed the startup, that needs to download and activate the wasm binary, the user experience is rather good. Anyway the overall reactivity of the web app is not so good than the native application. This is due to the fact that here we are pilling up layers as running inside a virtual machine, doing “javascript string programming” to do the WebGL and then having the WebGL activating the native GL-ES from javascript. All these layers induce inefficiencies compared to a native version. This being said the fact to be able to deploy world wide so easily is definitely great.

Today the overall EsbRootView application probably asks too much at the level of the graphics to have a nice and fluid user experience with the web version. For the web, one idea would be to have a more light version dedicated for outreach.

10 Web pages and repositories

The web pages of EsbRootView are at <https://gbarrand.github.io> under the section “EsbRootView” at left. The source code of stable releases is on github at <https://github.com/gbarrand/EsbRootView.git>. The license is a customisation of the FreeType license. For each release, we arrange to provide binaries at least for Linux, macOS and Windows. A WebAssembly version is available through the web pages.

11 Geant4/g4tools

Must be mentioned that our inlib/exlib classes are not so foreign to HEP since it is delivered under the namespace “tools” in Geant4 [6] as a baselayer to the analysis “category” to do the

histograms, ntuples, IO at various formats (ROOT, csv, HDF5) and offscreen plotting with our scene graph logic. See [7] and [8] .

12 Conclusions

EsbRootView is probably the first HEP event display written in C++ able to exploit natively all the nice devices that we have in our hands today, including desktops, laptops but also smartphones and tablets. Its flexible architecture permits also to have a web version done on the same C++ core as for the other platforms. It permits to have animations that strengthen the intuition about what happens in the detectors. Its scripting mechanism, inspired by the Bourne shell permits a strong customisation with a short learning curve.

Up until now, EsbRootView proceeds well. The only downside that we see is the inability to have common event and detector models, along a coworking IO service, shared with the other parts of the ESSnuSB software. The lack of portability of the IO service and of frameworks in general is a quite common problem in HEP that, we think, refrains this field to enjoy fully all aspects of computing technologies that we have today. ESSnuSB being a long term initiative, if fully considering interactive technologies now, could show the way on these points.

13 Acknowledgments

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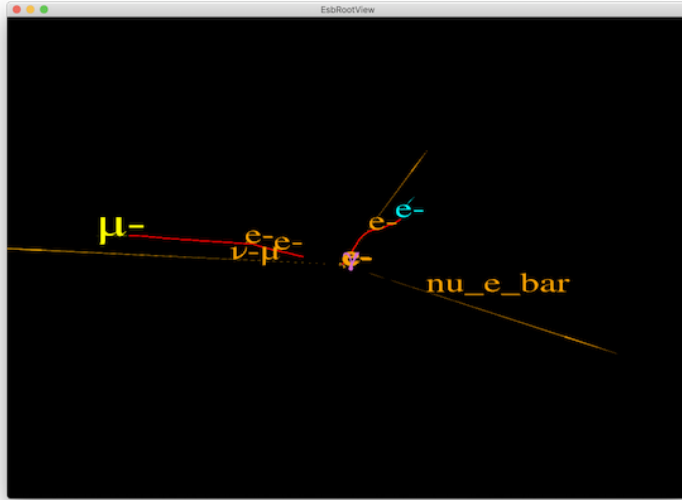


Figure 1. A muon decay topology.

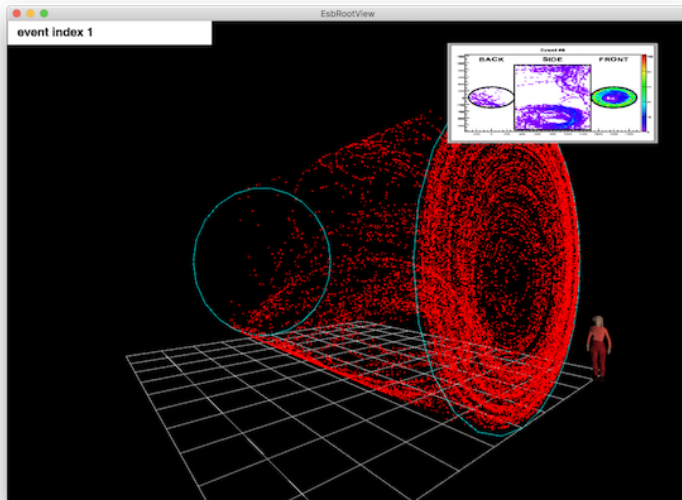


Figure 2. DetectorPoint instances in the neard.

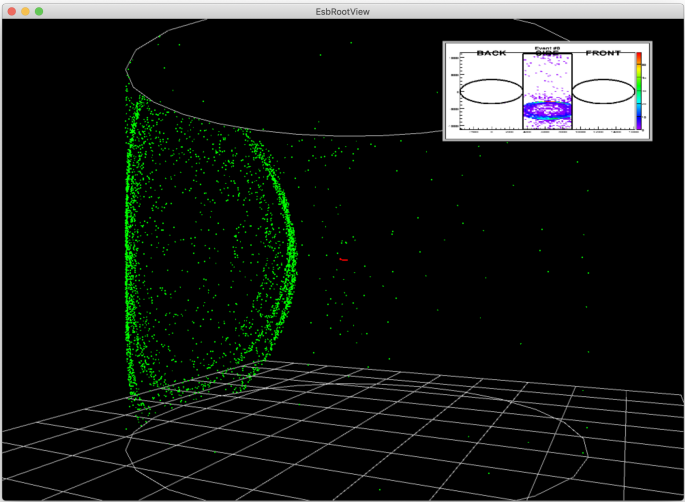


Figure 3. DetectorPoint instances in the fard.

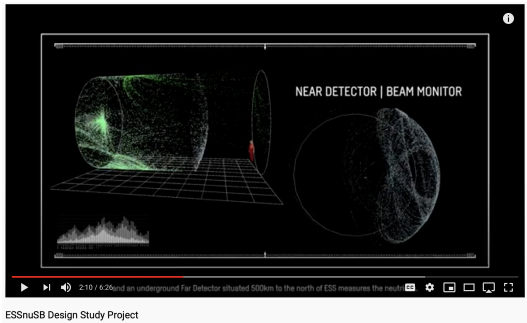


Figure 4. Cherenkov light deployment in the neard

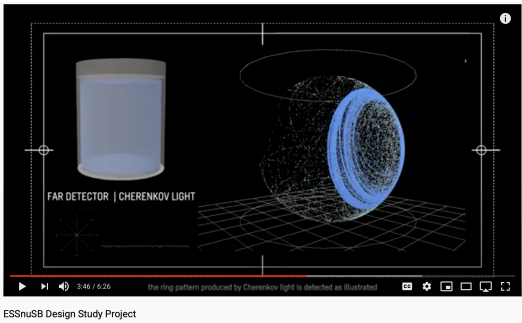


Figure 5. Cherenkov light deployment in the fard.