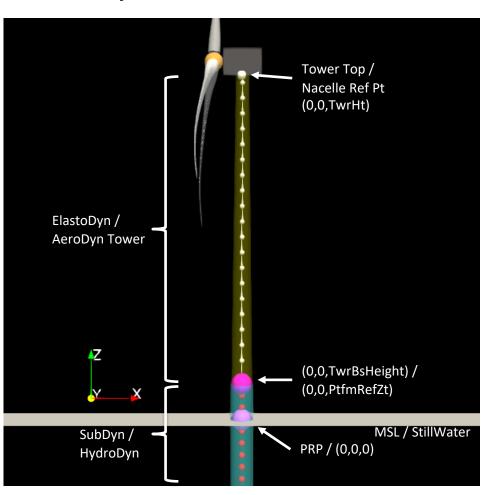


ElastoDyn Tower



ElastoDyn:

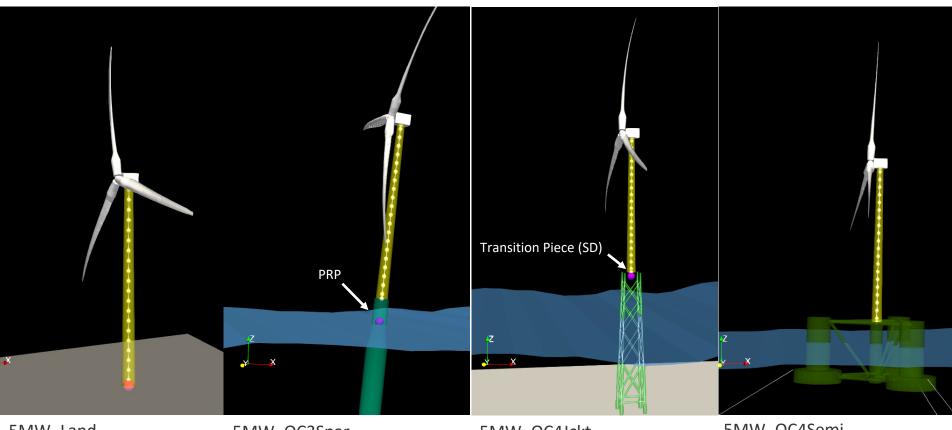
- TwrHt height above MSL/ground
- TwrBsHeight height above MSL/ground
- PtfmRefZt platform connection to tower

HydroDyn / SeaState:

- MSL mean sea level (0 m)
- MSL2SWL offset from MSL to still water
- PRP principle reference point for HydroDyn. Used for single body potential flow (internally used).

IEA 15 (v1.1.8) Monopile

- 144.386 m TwrHt:
- TwrBsHeight: 15.0 m
- MSL2SWL: $0.0 \, \text{m}$



5MW_Land

TwrHt: 87.6 m

TwrBsHeight: 0.0 m

5MW_OC3Spar

TwrHt: 87.6 m

TwrBsHeight: 10.0 m

5MW_OC4Jckt

TwrHt: 88.15 m

TwrBsHeight: 20.15 m

5MW_OC4Semi

TwrHt: 87.6 m

TwrBsHeight: 10.0 m

NREL | 3

OpenFAST reference frame

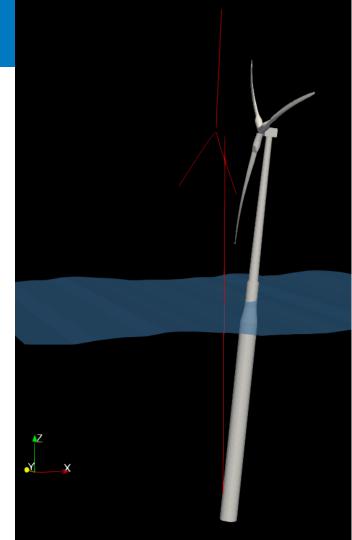
Equivalent initial conditions:

```
----- INITIAL CONDITIONS -----
OoPDefl - Initial out-of-plane blade-tip displacement (m) [not BD]
IPDefl
           - Initial in-plane blade-tip deflection (m) [not BD]
BlPitch(1) - Blade 1 initial pitch (deg)
BlPitch(2) - Blade 2 initial pitch (deg)
BlPitch(3) - Blade 3 initial pitch (deg)
Azimuth
           - Initial azimuth angle for blade 1 (deg)
      - Initial or fixed nacelle-yaw angle (deg)
NacYaw
TTDspFA - Initial fore-aft tower-top displacement (m)
           - Initial side-to-side tower-top displacement (m)
TTDspSS
PtfmSurge
           - horizontal surge translational displacement of platform (m)
           - horizontal sway translational displacement of platform (m)
PtfmSway
Pt.fmHeave
           - vertical heave translational displacement of platform (m)
PtfmRoll
           - roll tilt rotational displacement of platform (deg)
PtfmPitch
           - pitch tilt rotational displacement of platform (deg)
Pt.fmYaw
           - yaw rotational displacement of platform (deg)
```

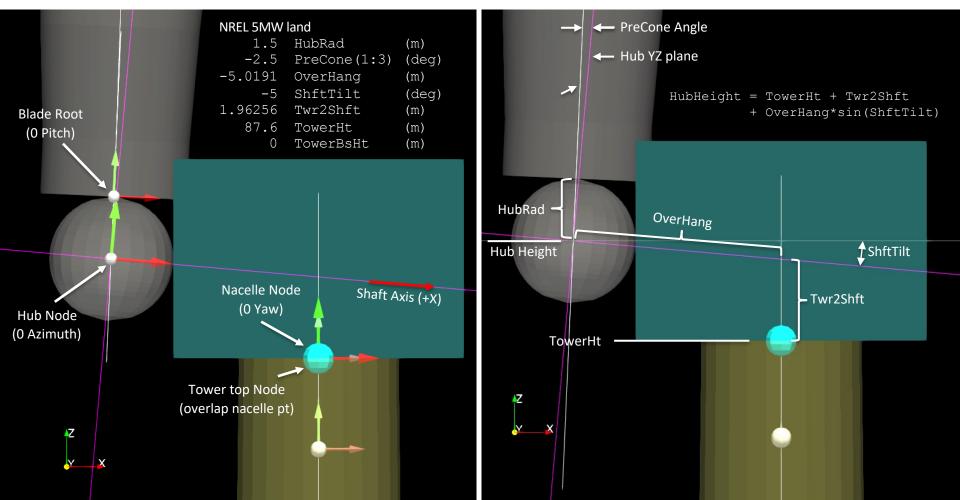
------TURBINE CONFIGURATION ------

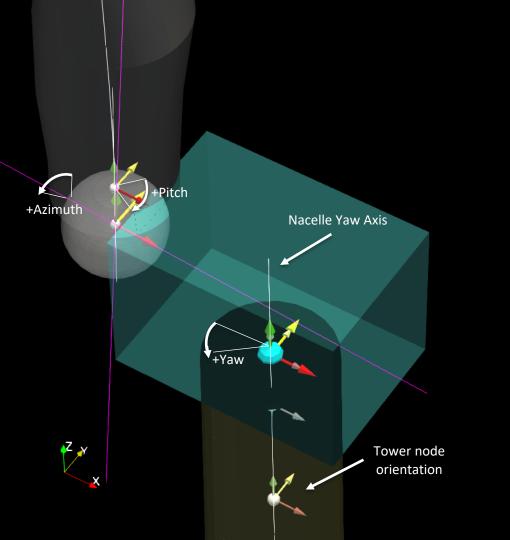
Included in reference frame

HubRad PreCone(1:3). AzimB1Up
OverHang ShftTilt Twr2Shft
TowerHt TowerBsHt PtfmRefzt



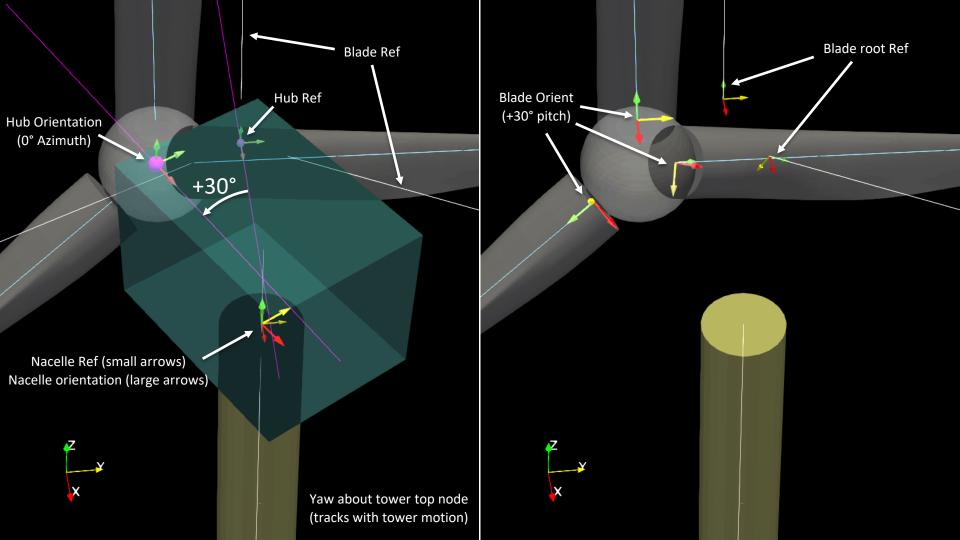
Hub location





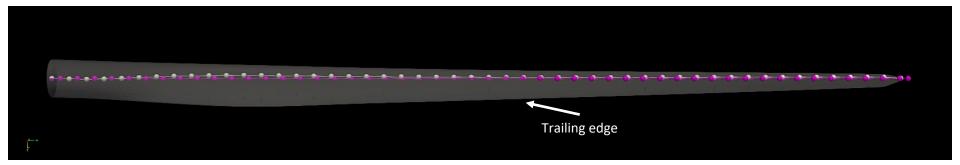
Coordinate frames:

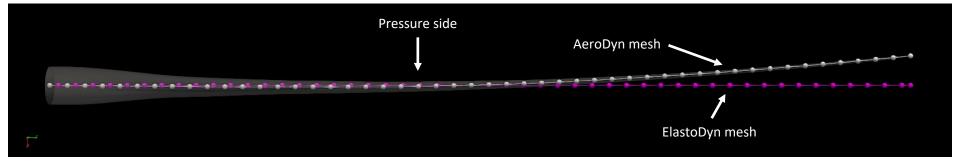
- Tower reference frame aligned with global frame, attached at TowerBsHt to ground/SubDyn/HydroDyn
- Nacelle attached to top node of tower, rotates about tower top local Z axis
- Yaw about tower top node Z axis (right hand rotation)
- Hub rotates about shaft X axis, follows rotor azimuth (right hand rotation)
- Blade root mesh attached to hub with cone angle, offset by hub radius along coned angle. Blade pitches about local Z axis (left hand rotation)
- AD/ED/BD blade attaches to blade root mesh, first node Z axis aligns to root mesh Z axis.



ElastoDyn blades

IEA15





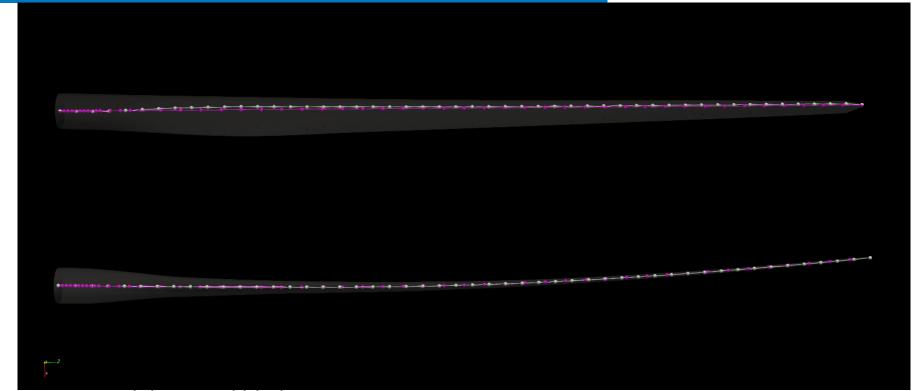
ElastoDyn models structuraly straight blades

- 2 Flap modes, 1 Edge mode, no torsion
- Mass and stiffness along straight blade

ElastoDyn is **not** ideally suited for

- Highly flexible blades
- Lots of prebend/precurve

BeamDyn blades



BeamDyn models curved blades

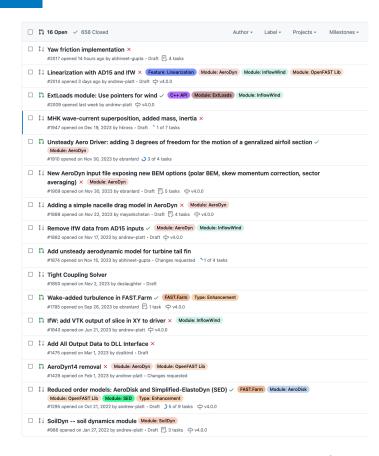
- Geometrically exact beam theory
- Mass and stiffness curvature defined by keypoints

OpenFAST timesteps

- For ElastoDyn:
 - 5e-3 land, maybe smaller floating
- For BeamDyn:
 - Depends on the model
 - IEA15/IEA22 + steady: 4e-5
 - IEA15/IEA22 + turbulent: 1e-5
 - IEA22 still fails on occasion
 - Wish I had better guidance to give here.
 - OpenFAST v5.0 will include tight-coupling
 - Timesteps up to 0.005 with BeamDyn

OpenFAST roadmap

- X.Y.Z
 - X major new features or restructuring. New input files
 - Y minor new features. New input files
 - Z bugfix, no input file changes
- 3.x series ends with 3.5.z
 - 3.5 LTS
 - 3.5.3 in progress (backports of fixes)
- 4.0 (end Feb. 2024?)
 - Includes FSI
 - 4.0 or 4.1 LTS
- 5.0 (end April 2024?)
 - Tight coupling solver
 - 5.Y not planned yet





- Figures generated with
 - IEA 15, v1.1.8 (https://github.com/IEAWindTask37/IEA-15-240-RWT/releases/tag/v1.1.8)
 - OpenFAST 3.5.2,gcc 10.5.0, double precision
 - ROSCO 1.8
 - Paraview 5.11.1