datacamp

Python For Data Science
SciPy Cheat Sheet

Learn SciPy online at **www.DataCamp.com**

SciPy

The **SciPy** library is one of the core packages for scientific computing that provides mathematical algorithms and convenience functions built on the NumPy extension of Python.

> Interacting With NumPy   *Also see NumPy*

```
>>> import numpy as np
>>> a = np.array([1,2,3])
>>> b = np.array([(1+5j,2j,3j), (4j,5j,6j)])
>>> c = np.array([[(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)]])
```

Index Tricks

```
>>> np.mgrid[0:5,0:5]  #Create a dense meshgrid
>>> np.ogrid[0:2,0:2]  #Create an open meshgrid
>>> np.r_[[3,[0]*5,-1:1:10j] #Stack arrays vertically (row-wise)
>>> np.c_[b,c] #Create stacked column-wise arrays
```

Shape Manipulation

```
>>> np.transpose(b)  #Permute array dimensions
>>> b.flatten() #Flatten the array
>>> np.hstack((b,c)) #Stack arrays horizontally (column-wise)
>>> np.vstack((a,b)) #Stack arrays vertically (row-wise)
>>> np.hsplit(c,2) #Split the array horizontally at the 2nd index
>>> np.vpsplit(d,2) #Split the array vertically at the 2nd index
```

Polynomials

```
>>> from numpy import poly1d
>>> p = poly1d([3,4,5]) #Create a polynomial object
```

Vectorizing Functions

```
>>> def myfunc(a): if a < 0:
        return a*2
        else:
        return a/2
>>> np.vectorize(myfunc) #Vectorize functions
```

Type Handling

```
>>> np.real(c)  #Return the real part of the array elements
>>> np.imag(c)  #Return the imaginary part of the array elements
>>> np.real_if_close(c,tol=1000)  #Return a real array if complex parts close to 0
>>> np.cast['f'](np.pi) #Cast object to a data type
```

Other Useful Functions

```
>>> np.angle(b,deg=True) #Return the angle of the complex argument
>>> g = np.linspace(0,np.pi,num=5) #Create an array of evenly spaced values(number of samples)
>>> g [3:] += np.pi
>>> np.unwrap(g) #Unwrap
>>> np.logspace(0,10,3) #Create an array of evenly spaced values (log scale)
>>> np.select([c<4],[c*2]) #Return values from a list of arrays depending on conditions
>>> misc.factorial(a) #Factorial
>>> misc.comb(10,3,exact=True) #Combine N things taken at k time
>>> misc.central_diff_weights(3) #Weights for Np-point central derivative
>>> misc.derivative(myfunc,1.0) #Find the n-th derivative of a function at a point
```

> Linear Algebra   *Also see NumPy*

You'll use the `linalg` and `sparse` modules.
Note that `scipy.linalg` contains and expands on `numpy.linalg`.

```
>>> from scipy import linalg, sparse
```

Creating Matrices

```
>>> A = np.matrix(np.random.random((2,2)))
>>> B = np.asmatrix(b)
>>> C = np.mat(np.random.random((10,5)))
>>> D = np.mat([[3,4], [5,6]])
```

Basic Matrix Routines

Inverse
```
>>> A.I #Inverse
>>> linalg.inv(A) #Inverse
>>> A.T #Tranpose matrix
>>> A.H #Conjugate transposition
>>> np.trace(A) #Trace
```

Norm
```
>>> linalg.norm(A) #Frobenius norm
>>> linalg.norm(A,1) #L1 norm (max column sum)
>>> linalg.norm(A,np.inf) #L inf norm (max row sum)
```

Rank
```
>>> np.linalg.matrix_rank(C) #Matrix rank
```

Determinant
```
>>> linalg.det(A) #Determinant
```

Solving linear problems
```
>>> linalg.solve(A,b) #Solver for dense matrices
>>> E = np.mat(a).T #Solver for dense matrices
>>> linalg.lstsq(D,E) #Least-squares solution to linear matrix equation
```

Generalized inverse
```
>>> linalg.pinv(C) #Compute the pseudo-inverse of a matrix (least-squares solver)
>>> linalg.pinv2(C) #Compute the pseudo-inverse of a matrix  (SVD)
```

Creating Sparse Matrices

```
>>> F = np.eye(3, k=1) #Create a 2X2 identity matrix
>>> G = np.mat(np.identity(2)) #Create a 2x2 identity matrix
>>> C[C > 0.5] = 0
>>> H = sparse.csr_matrix(C) #Compressed Sparse Row matrix
>>> I = sparse.csc_matrix(D) #Compressed Sparse Column matrix
>>> J = sparse.dok_matrix(A) #Dictionary Of Keys matrix
>>> E.todense() #Sparse matrix to full matrix
>>> sparse.isspmatrix_csc(A) #Identify sparse matrix
```

Sparse Matrix Routines

Inverse
```
>>> sparse.linalg.inv(I) #Inverse
```

Norm
```
>>> sparse.linalg.norm(I) #Norm
```

Solving linear problems
```
>>> sparse.linalg.spsolve(H,I) #Solver for sparse matrices
```

Sparse Matrix Functions

```
>>> sparse.linalg.expm(I) #Sparse matrix exponential
```

Sparse Matrix Decompositions

```
>>> la, v = sparse.linalg.eigs(F,1) #Eigenvalues and eigenvectors
>>> sparse.linalg.svds(H, 2) #SVD
```

> Asking For Help

```
>>> help(scipy.linalg.diagsvd)
>>> np.info(np.matrix)
```

Matrix Functions

Addition
```
>>> np.add(A,D) #Addition
```

Subtraction
```
>>> np.subtract(A,D) #Subtraction
```

Division
```
>>> np.divide(A,D) #Division
```

Multiplication
```
>>> np.multiply(D,A) #Multiplication
>>> np.dot(A,D) #Dot product
>>> np.vdot(A,D) #Vector dot product
>>> np.inner(A,D) #Inner product
>>> np.outer(A,D) #Outer product
>>> np.tensordot(A,D) #Tensor dot product
>>> np.kron(A,D) #Kronecker product
```

Exponential Functions
```
>>> linalg.expm(A) #Matrix exponential
>>> linalg.expm2(A) #Matrix exponential (Taylor Series)
>>> linalg.expm3(D) #Matrix exponential (eigenvalue decomposition)
```

Logarithm Function
```
>>> linalg.logm(A) #Matrix logarithm
```

Trigonometric Functions
```
>>> linalg.sinm(D) Matrix sine
>>> linalg.cosm(D) Matrix cosine
>>> linalg.tanm(A) Matrix tangent
```

Hyperbolic Trigonometric Functions
```
>>> linalg.sinhm(D) #Hyperbolic matrix sine
>>> linalg.coshm(D) #Hyperbolic matrix cosine
>>> linalg.tanhm(A) #Hyperbolic matrix tangent
```

Matrix Sign Function
```
>>> np.sigm(A) #Matrix sign function
```

Matrix Square Root
```
>>> linalg.sqrtm(A) #Matrix square root
```

Arbitrary Functions
```
>>> linalg.funm(A, lambda x: x*x) #Evaluate matrix function
```

Decompositions

Eigenvalues and Eigenvectors
```
>>> la, v = linalg.eig(A) #Solve ordinary or generalized eigenvalue problem for square matrix
>>> l1, l2 = la #Unpack eigenvalues
>>> v[:,0] #First eigenvector
>>> v[:,1] #Second eigenvector
>>> linalg.eigvals(A) #Unpack eigenvalues
```

Singular Value Decomposition
```
>>> U,s,Vh = linalg.svd(B) #Singular Value Decomposition (SVD)
>>> M,N = B.shape
>>> Sig = linalg.diagsvd(s,M,N) #Construct sigma matrix in SVD
```

LU Decomposition
```
>>> P,L,U = linalg.lu(C) #LU Decomposition
```