Scene Recognition with the MiniPlaces Dataset
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Abstract

ADD ABSTRACT

1. Introduction

Paper on creating the disparity map [1]

References

[1] H. Hirschmuller. Accurate and efficient stereo processing by semi-global matching and mutual information. In *2005 IEEE Computer Society Conference on Computer Vision and Pattern Recognition (CVPR'05)*, volume 2, pages 807–814 vol. 2, June 2005.