

# Método das diferenças finitas

O método se baseia na aproximação de derivadas por diferenças finitas (relembrando da 1ª aula). A aproximação pode ser feita a partir da expansão em série de Taylor:

$$f(x+h) = f(x) + hf'(x) + \frac{h^2 f''(x)}{2!} + \frac{h^3 f'''(x)}{3!} + \mathcal{O}(h^4)$$

## Forward Euler

$$f'(x) \approx \frac{f(x+h) - f(x)}{h} + \mathcal{O}(h)$$

## Backward Euler

$$f'(x) \approx \frac{f(x) - f(x-h)}{h} + \mathcal{O}(h)$$

## Diferença centrada

$$f'(x) \approx \frac{f(x+h) - f(x-h)}{2h} + \mathcal{O}(h^2)$$

## Expressão para a derivada segunda

$$f''(x) \approx \frac{f(x+h) - 2f(x) + f(x-h)}{h^2} + \mathcal{O}(h^2)$$

# Aplicação em problema de contorno

$$-\frac{d^2 f}{dx^2} = 2$$

**Caso fixo-fixo** → condições de contorno:  $f(0) = 0$  e  $f(1) = 0$

Solução analítica aplicando as condições de contorno?

```
• begin
•   using Plots
•   using LinearAlgebra
• end
```

analiticoFF (generic function with 1 method)

```
• analiticoFF(x) = -x^2 + x
```

Dividindo a barra em 9 nós ( $\Delta x = 0,125$ , índices de 0 a 8), sendo o primeiro nó e o nono nó localizados nas extremidades e apresentando, pelas condições de contorno deslocamento nulo, pode-se escrever o problema no formato discreto:

$$\frac{-f_{i+1} + 2f_i - f_{i-1}}{(0,125)^2} = 2$$

ou no formato matricial:

$$\frac{1}{(0,125)^2} \begin{bmatrix} 2 & -1 & 0 & \cdots & 0 & 0 & 0 \\ -1 & 2 & -1 & \cdots & 0 & 0 & 0 \\ 0 & -1 & 2 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \\ f_7 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \\ \vdots \\ 2 \end{bmatrix}$$

```
7x7 Matrix{Float64}:
128.0  -64.0   0.0   0.0   0.0   0.0   0.0
-64.0  128.0  -64.0   0.0   0.0   0.0   0.0
 0.0  -64.0  128.0 -64.0   0.0   0.0   0.0
 0.0   0.0 -64.0  128.0 -64.0   0.0   0.0
 0.0   0.0   0.0 -64.0  128.0 -64.0   0.0
 0.0   0.0   0.0   0.0 -64.0  128.0 -64.0
 0.0   0.0   0.0   0.0   0.0 -64.0  128.0
```

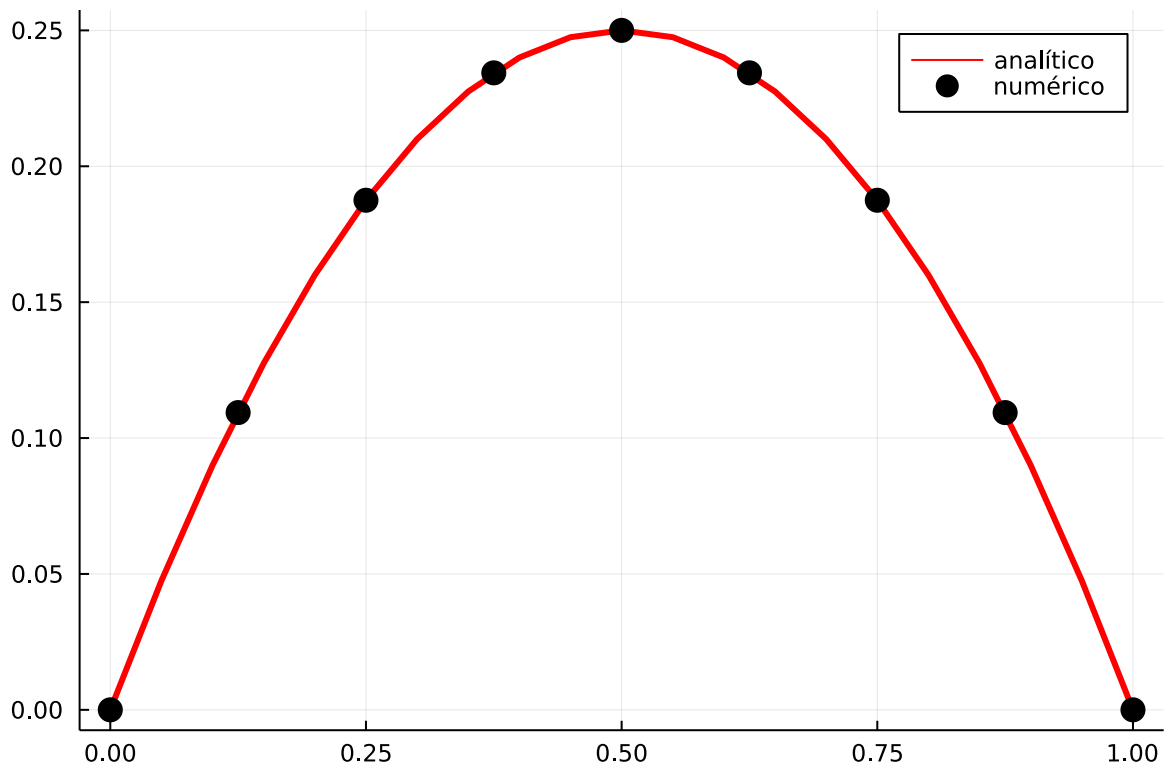
```
• begin
•     Δx = 0.125
•     b = fill(2,7)
•     K = (1/Δx^2).*SymTridiagonal(fill(2,7), fill(-1,6))
• end
```

```
solFF = [0.109375, 0.1875, 0.234375, 0.25, 0.234375, 0.1875, 0.109375]
```

```
• solFF = K \ b
```

```
Float64[
 1: 0.0
 2: 0.109375
 3: 0.1875
 4: 0.234375
 5: 0.25
 6: 0.234375
 7: 0.1875
 8: 0.109375
 9: 0.0
]
```

```
• begin
•     pushfirst!(solFF, 0)
•     push!(solFF, 0)
• end
```



```

• # Plotando resultados
• begin
•   plot(0:0.05:1, analiticoFF.(0:0.05:1), linecolor="red", linewidth=3,
•       label="analítico")
•   scatter!(0:Δx:1, solFF, markercolor="black", markersize=7, label="numérico")
• end

```

**Caso livre-fixo** → condições de contorno:  $\frac{df}{dx}(0) = 0$  e  $f(1) = 0$

Solução analítica?

analiticoLF (generic function with 1 method)

```

• analiticoLF(x) = -x^2 + 1

```

Como a condição de contorno do primeiro nó é dada por sua derivada, a primeira linha da matriz simétrica utilizada no caso fixo-fixo precisa ser alterada.

Aplicando uma aproximação de primeira ordem para a derivada, temos

$$\frac{f_1 - f_0}{\Delta x} = 0$$

logo

$$f_1 = f_0$$

e na primeira linha...

$$\frac{-f_2 + 2f_1 - f_0}{\Delta x^2} = \frac{-f_2 + 2f_1 - f_1}{\Delta x^2} = \frac{-f_2 + f_1}{\Delta x^2} = 2$$

No formato matricial:

$$\frac{1}{(0,125)^2} \begin{bmatrix} 1 & -1 & 0 & \cdots & 0 & 0 & 0 \\ -1 & 2 & -1 & \cdots & 0 & 0 & 0 \\ 0 & -1 & 2 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ \vdots \\ f_7 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 2 \\ \vdots \\ 2 \end{bmatrix}$$

7x7 Matrix{Float64}:

```
64.0  -64.0   0.0   0.0   0.0   0.0   0.0
-64.0  128.0 -64.0   0.0   0.0   0.0   0.0
 0.0  -64.0  128.0 -64.0   0.0   0.0   0.0
 0.0   0.0 -64.0  128.0 -64.0   0.0   0.0
 0.0   0.0   0.0 -64.0  128.0 -64.0   0.0
 0.0   0.0   0.0   0.0 -64.0  128.0 -64.0
 0.0   0.0   0.0   0.0   0.0 -64.0  128.0
```

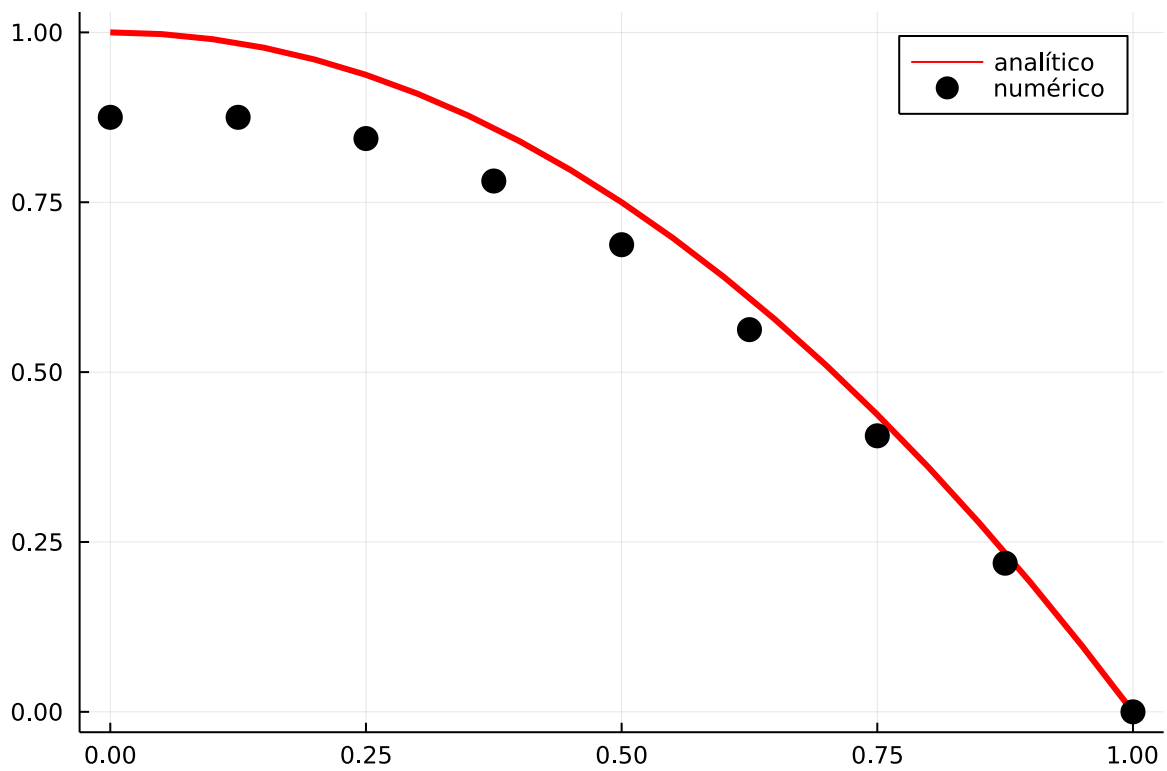
```
• begin
•   T = SymTridiagonal(fill(2,7), fill(-1,6))
•   T[1,1] = 1
•   T = (1/Dx^2).*T
• end
```

```
solLF = [0.875, 0.84375, 0.78125, 0.6875, 0.5625, 0.40625, 0.21875]
```

```
• solLF = T \ b
```

```
[0.875, 0.875, 0.84375, 0.78125, 0.6875, 0.5625, 0.40625, 0.21875, 0.0]
```

```
• begin
•   pushfirst!(solLF, solLF[1])
•   push!(solLF, 0)
• end
```



```
. # Plotando resultados
. begin
.   plot(0:0.05:1, analíticoLF.(0:0.05:1), linecolor="red", linewidth=3,
.   label="analítico")
.   scatter!(0:Δx:1, solLF, markercolor="black", markersize=7, label="numérico")
. end
```

Por que encontramos o erro na extremidade livre??

Aproximação de segunda ordem

$$\frac{f_1 - f_{-1}}{2\Delta x} = 0$$

Logo

$$f_1 = f_{-1}$$

A matriz terá, portanto, uma linha adicional.

$$\frac{-f_1 + 2f_0 - f_{-1}}{(\Delta x)^2} = \frac{-2f_1 + 2f_0}{(\Delta x)^2} = 2$$

Dividir por dois para manter a simetria.

$$\frac{-f_1 + f_0}{(\Delta x)^2} = 1$$

No formato matricial:

$$\frac{1}{(0,125)^2} \begin{bmatrix} 1 & -1 & 0 & \cdots & 0 & 0 & 0 \\ -1 & 2 & -1 & \cdots & 0 & 0 & 0 \\ 0 & -1 & 2 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ \vdots \\ f_7 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 2 \\ \vdots \\ 2 \end{bmatrix}$$

8x8 Matrix{Float64}:

```
64.0  -64.0   0.0   0.0   0.0   0.0   0.0   0.0
-64.0  128.0 -64.0   0.0   0.0   0.0   0.0   0.0
 0.0  -64.0  128.0 -64.0   0.0   0.0   0.0   0.0
 0.0   0.0 -64.0  128.0 -64.0   0.0   0.0   0.0
 0.0   0.0   0.0 -64.0  128.0 -64.0   0.0   0.0
 0.0   0.0   0.0   0.0 -64.0  128.0 -64.0   0.0
 0.0   0.0   0.0   0.0   0.0 -64.0  128.0 -64.0
 0.0   0.0   0.0   0.0   0.0   0.0 -64.0  128.0
```

```
• begin
•     Tb = SymTridiagonal(fill(2,8), fill(-1,7))
•     Tb[1,1] = 1
•     Tb = (1/dx^2).*Tb
• end
```

1

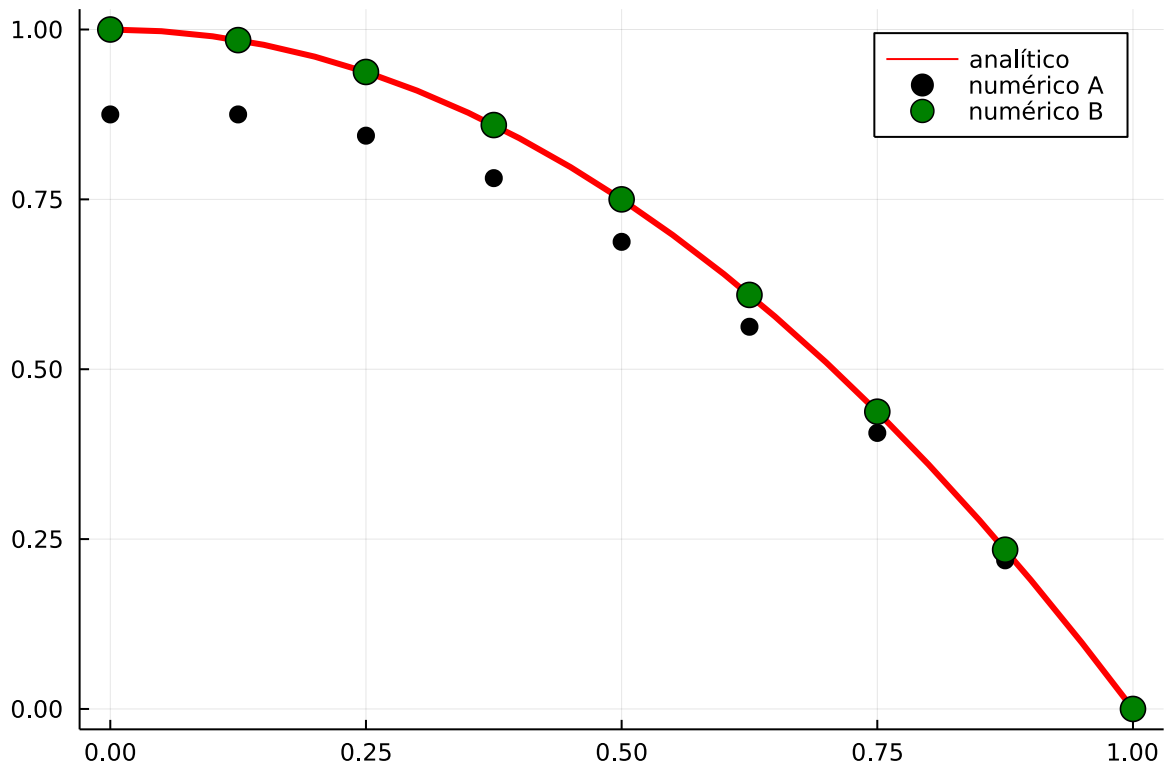
```
• begin
•     bb = fill(2,8)
•     bb[1] = 1
• end
```

```
solLf = [1.0, 0.984375, 0.9375, 0.859375, 0.75, 0.609375, 0.4375, 0.234375]
```

```
• solLf = Tb \ bb
```

[1.0, 0.984375, 0.9375, 0.859375, 0.75, 0.609375, 0.4375, 0.234375, 0.0]

```
• push!(solLFb, 0)
```



```
• # Plotando resultados
• begin
•   plot(0:0.05:1, analiticoLF.(0:0.05:1), linecolor="red", linewidth=3,
•       label="analítico")
•   scatter!(0:Δx:1, solLF, markercolor="black", markersize=5, label="numérico A")
•   scatter!(0:Δx:1, solLFb, markercolor="green", markersize=7, label="numérico B")
• end
```

## Aplicação em problema de valor inicial

Problema de oscilação de um sistema massa-mola de 1 GDL

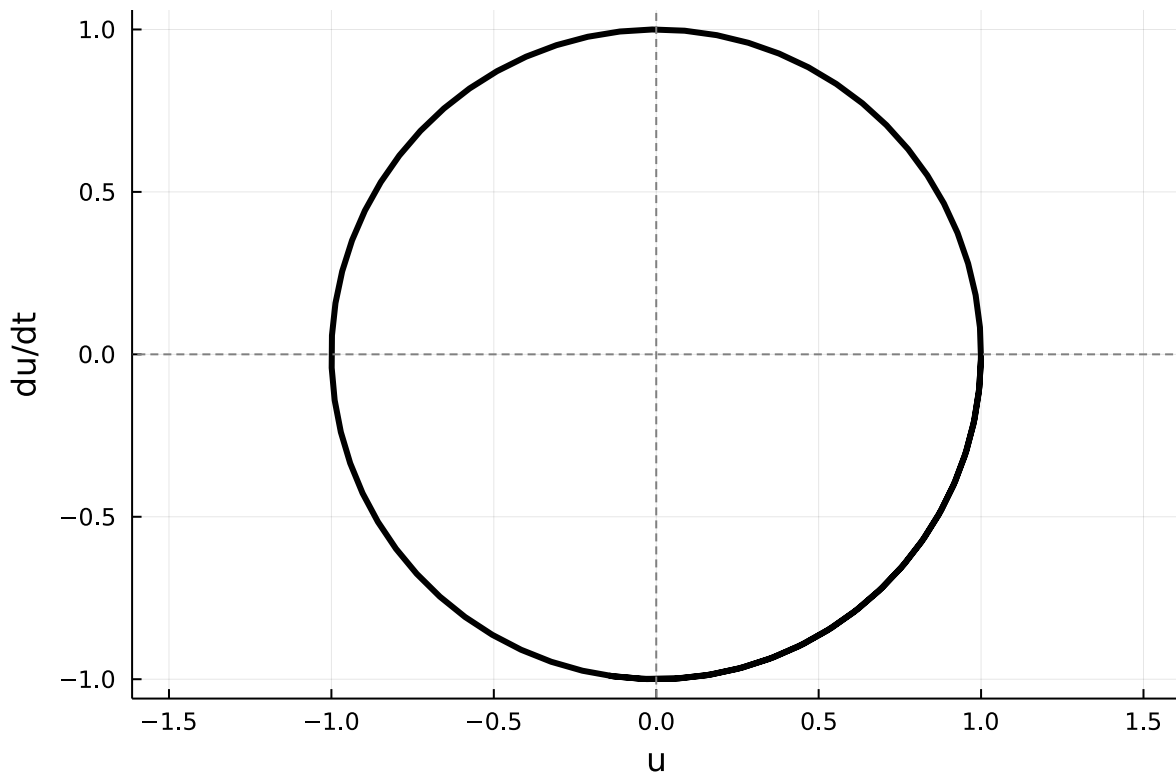
$$m \frac{d^2 u}{dt^2} + ku = 0$$

Condições de contorno  $\rightarrow u(0) = 1$  e  $u'(0) = 0$

Solução exata

Considerando  $m = k = 1$ , qual a solução exata para o problema?

Diagrama de fase da solução analítica



```

• begin
•   plot(cos.(0:0.1:8), -sin.(0:0.1:8), linecolor="black", linewidth=3,
•       label=false, ratio=1)
•   vline!([0], linecolor="gray", linestyle=:dash, label=false)
•   hline!([0], linecolor="gray", linestyle=:dash, label=false)
•   xlabel!("u")
•   ylabel!("du/dt")
• end

```

## Solução numérica utilizando o método das diferenças finitas

Sempre é possível escrever uma ODE de segunda ordem em um sistema de equações de primeira ordem.

$$\begin{cases} u' = w \\ w' = -u \end{cases}$$

Utilizando **Forward Euler**:

$$\begin{cases} u_{n+1} = u_n + \Delta t w_n \\ w_{n+1} = w_n - \Delta t u_n \end{cases}$$



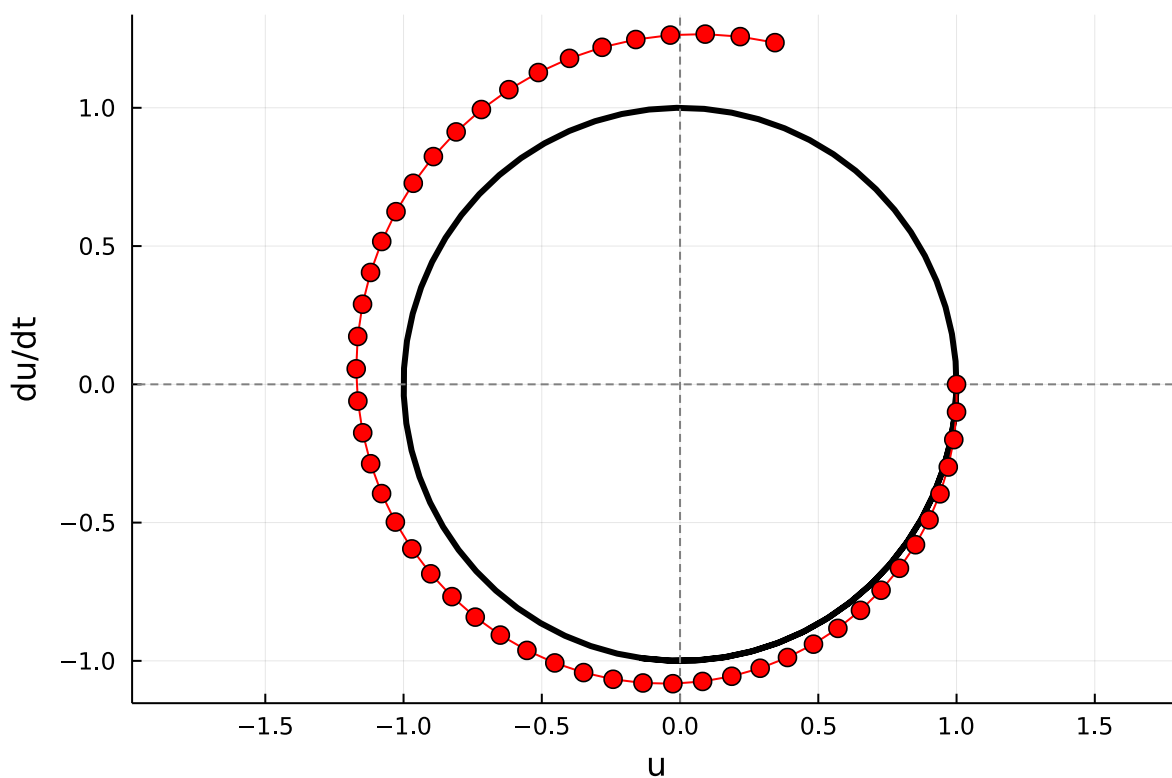
forwardEuler (generic function with 1 method)

```
• function forwardEuler(dt,u₀,w₀,nsteps)
•   u = [u₀]
•   w = [w₀]
•   steps = collect(1:nsteps)
•   for i in steps
•       uk = u[i] + dt*w[i]
•       wk = w[i] - dt*u[i]
•       push!(u, uk)
•       push!(w, wk)
•   end
•   return [u, w]
• end
```

df =

[1.0, 1.0, 0.99, 0.97, 0.9401, 0.9005, 0.851499, 0.793493, 0.726972, more ,0.343355],

```
• df = forwardEuler(0.1, 1.0, 0.0, 50)
```



```
• # Plotando dados
• begin
•   plot(cos.(0:0.1:8), -sin.(0:0.1:8), linecolor="black", linewidth=3,
•         label=false, ratio=1)
•   vline!([0], linecolor="gray", linestyle=:dash, label=false)
•   hline!([0], linecolor="gray", linestyle=:dash, label=false)
•   xlabel!("u")
•   ylabel!("du/dt")
•   plot!(df[1], df[2], linecolor="red", label=false)
•   scatter!(df[1], df[2], markercolor="red", markersize=5, label=false)
• end
```

Utilizando **Backward Euler**:

$$\begin{cases} u_{n+1} = u_n + \Delta t w_{n+1} \\ w_{n+1} = w_n - \Delta t u_{n+1} \end{cases}$$

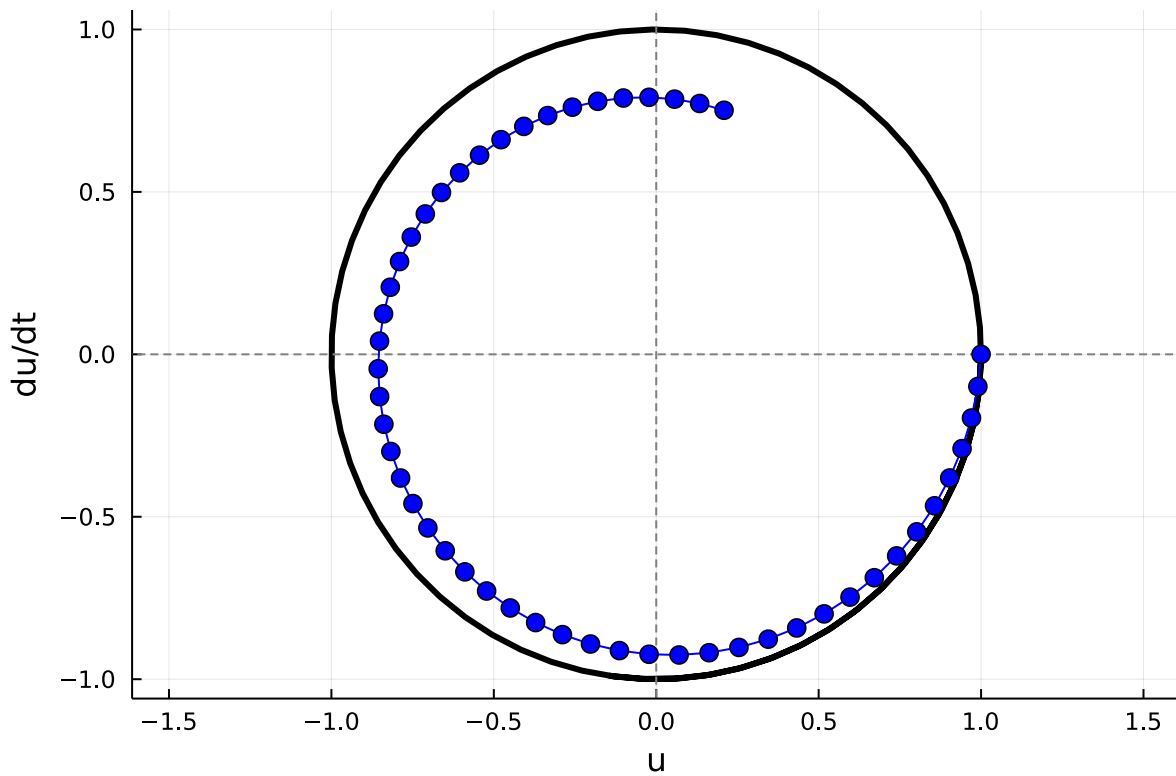
backwardEuler (generic function with 1 method)

```
• function backwardEuler(dt,u₀,w₀,nsteps)
•     u = [u₀]
•     w = [w₀]
•     steps = collect(1:nsteps)
•     for i in steps
•         uk = (u[i] + dt*w[i])/(1 + dt^2)
•         wk = w[i] - dt*uk
•         push!(u, uk)
•         push!(w, wk)
•     end
•     return [u,w]
• end
```

db =

[1.0, 0.990099, 0.970493, 0.941472, 0.903418, 0.856795, 0.802151, 0.740105, 0.671346,

• db = backwardEuler(0.1, 1.0, 0.0, 50)



```

• # Plotando dados
• begin
•   plot(cos.(0:0.1:8), -sin.(0:0.1:8), linecolor="black", linewidth=3,
•       label=false, ratio=1)
•   vline!([0], linecolor="gray", linestyle=:dash, label=false)
•   hline!([0], linecolor="gray", linestyle=:dash, label=false)
•   xlabel!("u")
•   ylabel!("du/dt")
•   plot!(db[1], db[2], linecolor="blue", label=false)
•   scatter!(db[1], db[2], markercolor="blue", markersize=5, label=false)
• end

```

Utilizando **Diferenças centradas**:

$$\begin{cases} u_{n+1} = u_n + \Delta t w_n \\ w_{n+1} = w_n - \Delta t u_{n+1} \end{cases}$$

centeredDiff (generic function with 1 method)

```

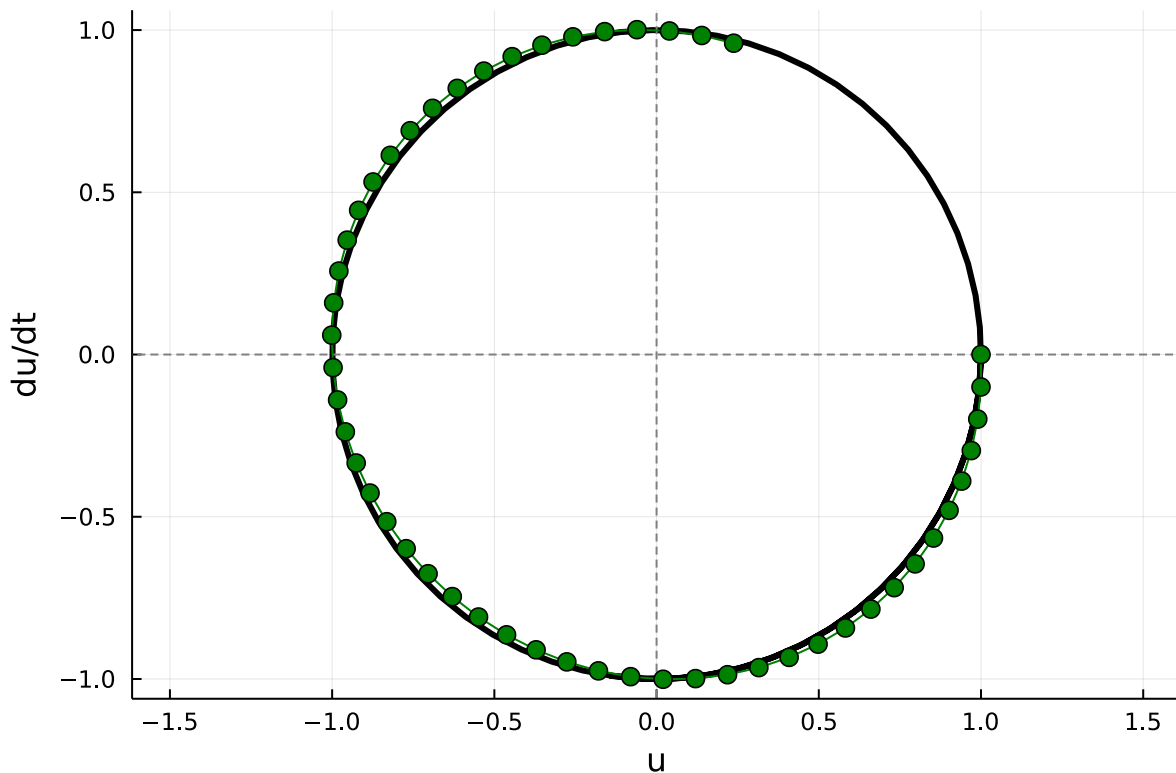
• function centeredDiff(dt,u₀,w₀,nsteps)
•   u = [u₀]
•   w = [w₀]
•   steps = collect(1:nsteps)
•   for i in steps
•       uk = u[i] + dt*w[i]
•       wk = w[i] - dt*uk
•       push!(u, uk)
•       push!(w, wk)
•   end
•   return [u, w]
• end

```

dc =

[1.0, 1.0, 0.99, 0.9701, 0.940499, 0.901493, 0.853472, 0.796916, 0.732392, more ,0.23

```
• dc = centeredDiff(0.1, 1.0, 0.0, 50)
```



```
• # Plotando dados
• begin
•   plot(cos.(0:0.1:8), -sin.(0:0.1:8), linecolor="black", linewidth=3,
•         label=false, ratio=1)
•   vline!([0], linecolor="gray", linestyle=:dash, label=false)
•   hline!([0], linecolor="gray", linestyle=:dash, label=false)
•   xlabel!("u")
•   ylabel!("du/dt")
•   plot!(dc[1], dc[2], linecolor="green", label=false)
•   scatter!(dc[1], dc[2], markercolor="green", markersize=5, label=false)
• end
```