PyTorch + Slurm Tutorial on Pawsey

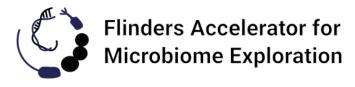
Protein Language Model Training

George Bouras

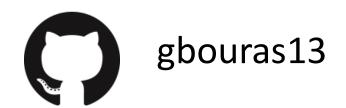
University of Adelaide Australia







GitHub Repository



Follow along https://github.com/gbouras13/ABACBS2024-GPU-workshop-demo-plm-training-slurm-setonix

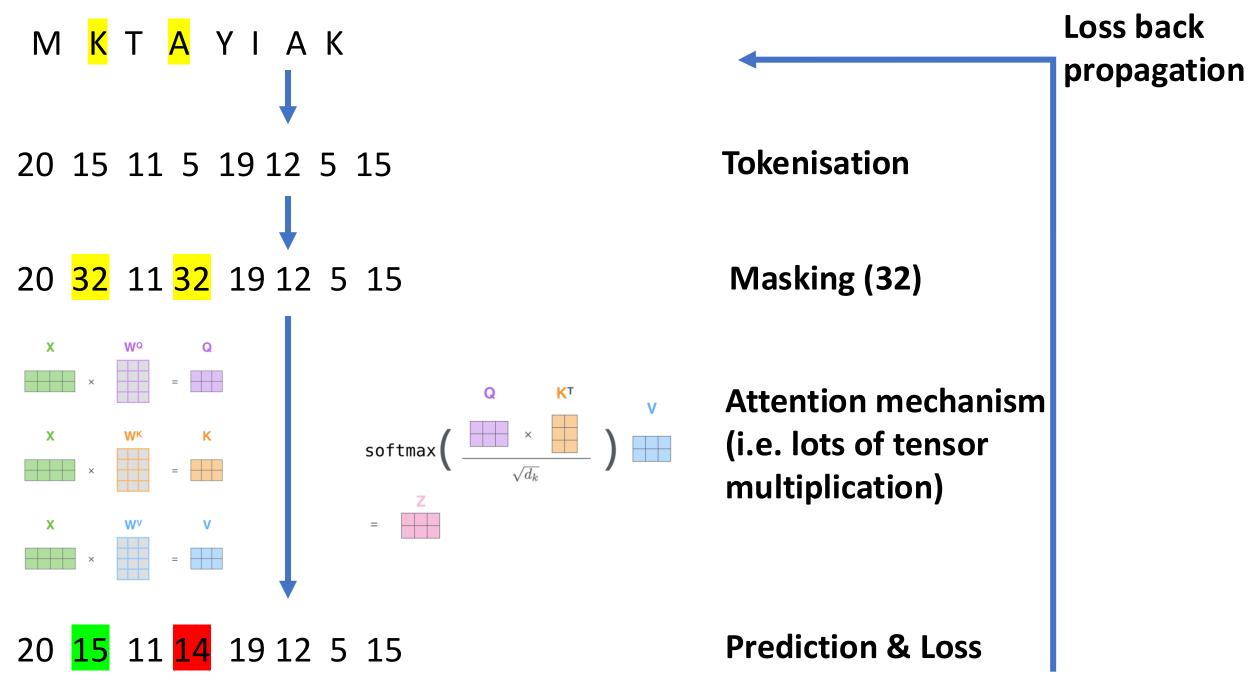


(Masked) Language Models 101

- 1. Split your data into "training" and "evaluation" sets
- 2. "Tokenise" your input data into small chunks, make them numbers, pad them to a consistent length, batch them (i.e. make a tensor)
- 3. Hide some tokens ("masking")
- 4. Multiply these numbers with weights (i.e. another tensors) to get representations
- 5. Multiply these representations with more weights (i.e. other tensors) to **predict** the masked input
- 6. Measure difference between your prediction & actual output ("loss")
- 7. Backpropagate the loss into your model to optimise the weights
- 8. Repeat on more data

Protein Language Models (pLMs)

- Tokens individual amino acids
- Loss predicting randomly masked amino acids
- Dataset millions of proteins –> hold a few thousand out for evaluation
- Representations "Embeddings" contain evolutionary, structural and functional information about proteins
- Famous models:
 - ESM-2 (Lin et al 2023 Science)
 - ProtT5 (Elnaggar et al 2021 IEEE Trans Pattern Anal Mach Intell)
 - ProstT5 (Heinzinger et al 2023 bioRxiv)
 - ProtBERT (Brandes et al 2022 Bioinformatics)



After Using Your GPUs For a While

- After the loss flattens off "enough" for "a while", you are "done"
- Use your trained embeddings to predict or understanding things about your protein(s)

PyTorch

- Nice framework for implementing tensor multiplication
- Almost everything you need for (protein) language model training is implemented in PyTorch functions "out of the box"
- Hides the low-level GPU code from you
 - Mostly well optimized
- PyTorch DDP makes distributing PyTorch across multiple GPUs easy

Scaling Language Model Training

- For each step, a copy of model is distributed to each GPU with a (different) batch of data
- During training, each GPU computes the associated loss for its batch
- After each step, loss from all GPUs are pooled and averaged via inter-GPU communication, which then updates the parameters across all GPU nodes as it is back-propagated through the model

Some Practical Things

- "batch size" number of sequences per batch
- Maximise batch size to use all GPU VRAM
 - nvidia-smi or rocm-smi or wait for crashes
- Save intermediate models often ("checkpointing")
- "Rank" = GPU number for all GPUs
- "Local rank" = GPU number on your GPU node
- "World size" = Total number of GPUs
- "epoch" 1 total pass through all training data

Live Demo: ESM2-Finetuning



Other Comments + Conclusions

- Wrapping everything in containers is ideal on HPC
- Print out your tensors in testing and debugging
- Do overfitting experiments on small datasets before scaling
- Often, data-loading (CPU) or filesystem limitations need more optimisation/thought than GPU training code
- Popular frameworks (PyTorch DDP) make it easy to run multi-GPU jobs
- ROCm (AMD) support is improving for popular frameworks
- Training big models on lots of GPUs can be unstable and tricky go with the flow and do your best