## **Network Settings**

IP: 10.196.80.36

**Network Settings** 

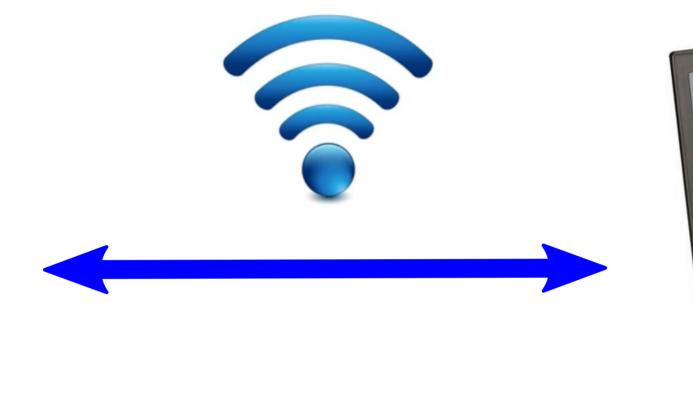
WIFI IP: 10.196.80.1

ETH IP: 192.168.0.101

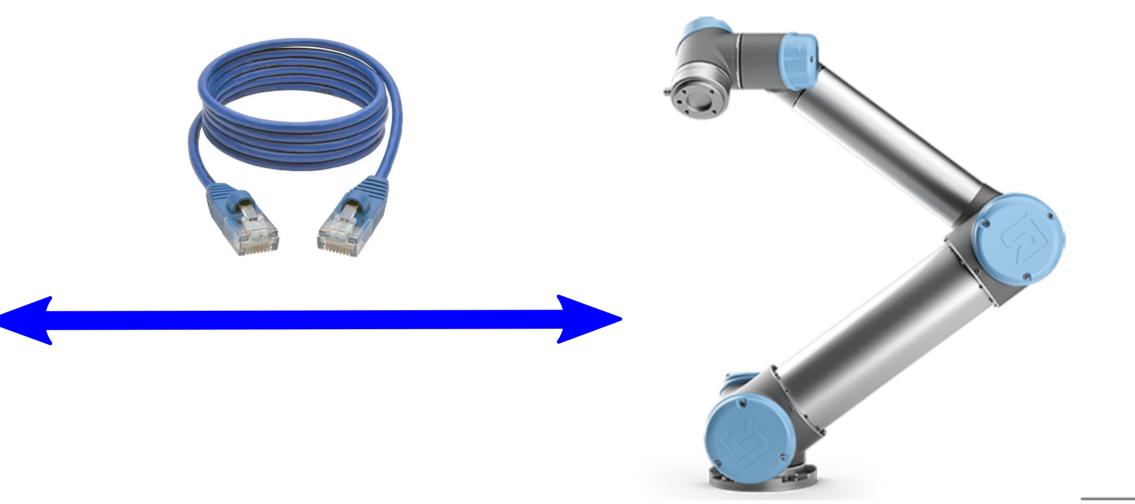
**Network Settings** 

IP: 192.168.0.100









## .bashrc

export ROS\_IP=10.196.80.36

ROS\_MASTER\_URI=http://localhost:11311

.bashrc

export ROS\_IP=192.168.0.100

ROS\_MASTER\_URI=10.196.80.36:11311

## execution

\$: roscore

## execution

\$: roslaunch ur\_robot\_driver ur5e\_bringup.launch ...