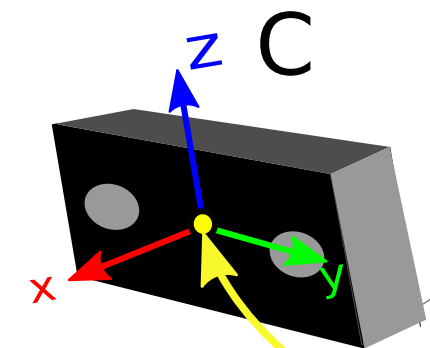


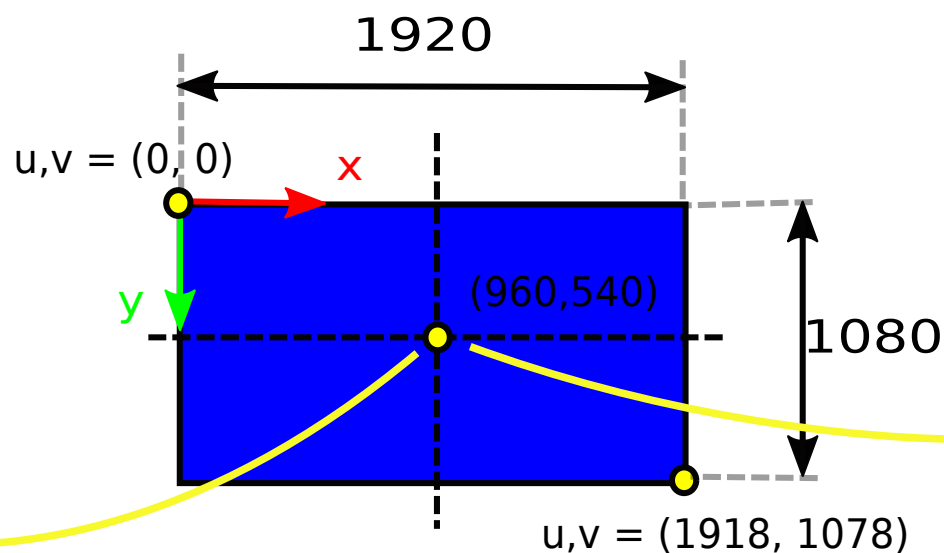
ZED2 CAMERA

Real Robot

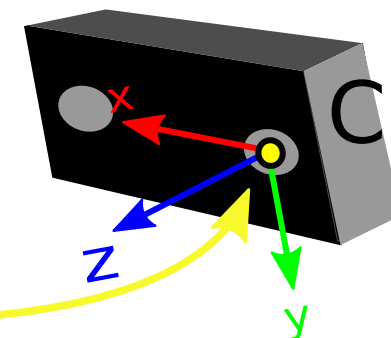


zed2_camera_frame

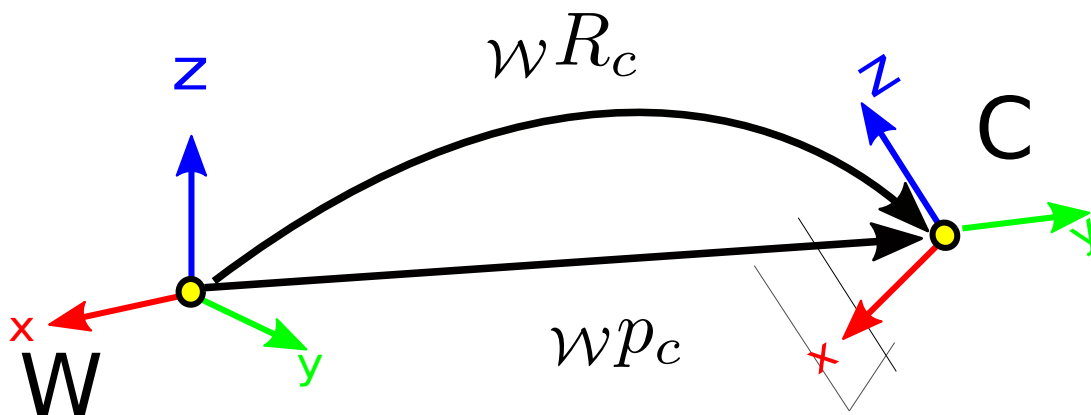
Image plane
(seen from backwards)



Simulation



zed2_left_camera_optical_frame



$$w p_i = w p_c + w R_{cc} p_i$$