```
Training for 1700000 steps ...
     811/1700000: episode: 1, duration: 7.589s, episode steps: 811, steps per second: 107, episode reward: -21.000, mean reward: -0.026 [-1.000, 0.000], mean action: 2.466 [0.000, 5.000], mean observation: 105.597 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    1744/1700000: episode: 2, duration: 2.283s, episode steps: 933, steps per second: 409, episode reward: -21.000, mean reward: -0.023 [-1.000, 0.000], mean action: 2.382 [0.000, 5.000], mean observation: 105.628 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    2719/1700000: episode: 3, duration: 2.482s, episode steps: 975, steps per second: 393, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 2.385 [0.000, 5.000], mean observation: 105.647 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    3599/1700000: episode: 4, duration: 2.223s, episode steps: 880, steps per second: 396, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.499 [0.000, 5.000], mean observation: 105.621 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    4526/1700000: episode: 5, duration: 2.321s, episode steps: 927, steps per second: 399, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 2.436 [0.000, 5.000], mean observation: 105.484 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    5407/1700000: episode: 6, duration: 2.244s, episode steps: 881, steps per second: 393, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.431 [0.000, 5.000], mean observation: 105.626 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    6227/1700000: episode: 7, duration: 2.031s, episode steps: 820, steps per second: 404, episode reward: -21.000, mean reward: -0.026 [-1.000, 0.000], mean action: 2.511 [0.000, 5.000], mean observation: 105.610 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    7238/1700000: episode: 8, duration: 2.525s, episode steps: 1011, steps per second: 400, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.415 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    8002/1700000: episode: 9, duration: 1.846s, episode steps: 764, steps per second: 414, episode reward: -21.000, mean reward: -0.027 [-1.000, 0.000], mean action: 2.438 [0.000, 5.000], mean observation: 105.612 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    9010/1700000: episode: 10, duration: 2.396s, episode steps: 1008, steps per second: 421, episode reward: -19.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.474 [0.000, 5.000], mean observation: 105.523 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
    9942/1700000: episode: 11, duration: 2.160s, episode steps: 932, steps per second: 431, episode reward: -21.000, mean reward: -0.023 [-1.000, 0.000], mean action: 2.423 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: --, mean_absolute_error: --, mean_q: --, mean_eps: --
   10872/1700000: episode: 12, duration: 6.288s, episode steps: 930, steps per second: 148, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 2.605 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.011428, mean_absolute_error: 0.032554, mean_q: -0.006886, mean_eps: 0.897727
   11862/1700000: episode: 13, duration: 5.701s, episode steps: 990, steps per second: 174, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.514 [0.000, 5.000], mean observation: 105.570 [87.000, 236.000], loss: 0.009789, mean_absolute_error: 0.029668, mean_q: -0.018523, mean_eps: 0.888613
   12897/1700000: episode: 14, duration: 6.058s, episode steps: 1035, steps per second: 171, episode reward: -20.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.576 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.013541, mean_absolute_error: 0.043013, mean_q: -0.021418, mean_eps: 0.878676
   13795/1700000: episode: 15, duration: 5.289s, episode steps: 898, steps per second: 170, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 2.596 [0.000, 5.000], mean observation: 105.519 [87.000, 236.000], loss: 0.008730, mean_absolute_error: 0.053450, mean_q: -0.025527, mean_eps: 0.869209
   14764/1700000: episode: 16, duration: 5.625s, episode steps: 969, steps per second: 172, episode reward: -19.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.609 [0.000, 5.000], mean observation: 105.497 [87.000, 236.000], loss: 0.007746, mean_absolute_error: 0.063952, mean_q: -0.032840, mean_eps: 0.860076
   15679/1700000: episode: 17, duration: 5.278s, episode steps: 915, steps per second: 173, episode reward: -21.000, mean reward: -0.023 [-1.000, 0.000], mean action: 2.401 [0.000, 5.000], mean observation: 105.629 [87.000, 236.000], loss: 0.007307, mean_absolute_error: 0.079699, mean_q: -0.045070, mean_eps: 0.850844
   16654/1700000: episode: 18, duration: 5.659s, episode steps: 975, steps per second: 172, episode reward: -21.000, mean reward: -0.022 [-1.000, 0.000], mean action: 2.491 [0.000, 5.000], mean observation: 105.589 [87.000, 236.000], loss: 0.006668, mean_absolute_error: 0.079448, mean_q: -0.053107, mean_eps: 0.841573
   17673/1700000: episode: 19, duration: 5.907s, episode steps: 1019, steps per second: 173, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.447 [0.000, 5.000], mean observation: 105.489 [87.000, 236.000], loss: 0.006463, mean_absolute_error: 0.088345, mean_q: -0.062270, mean_eps: 0.831793
   18796/1700000: episode: 20, duration: 6.464s, episode steps: 1123, steps per second: 174, episode reward: -19.000, mean reward: -0.017 [-1.000, 1.000], mean action: 2.529 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.006799, mean_absolute_error: 0.093293, mean_q: -0.066449, mean_eps: 0.821307
   19928/1700000: episode: 21, duration: 6.542s, episode steps: 1132, steps per second: 173, episode reward: -19.000, mean reward: -0.017 [-1.000, 1.000], mean action: 2.363 [0.000, 5.000], mean observation: 105.543 [87.000, 236.000], loss: 0.006080, mean_absolute_error: 0.101364, mean_q: -0.077983, mean_eps: 0.810272
   20886/1700000: episode: 22, duration: 5.583s, episode steps: 958, steps per second: 172, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 2.375 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.006125, mean_absolute_error: 0.114426, mean_q: -0.079845, mean_eps: 0.800021
   21669/1700000: episode: 23, duration: 4.592s, episode steps: 783, steps per second: 171, episode reward: -21.000, mean reward: -0.027 [-1.000, 0.000], mean action: 2.603 [0.000, 5.000], mean observation: 105.594 [87.000, 236.000], loss: 0.006529, mean_absolute_error: 0.124697, mean_q: -0.089104, mean_eps: 0.791476
   22493/1700000: episode: 24, duration: 4.850s, episode steps: 824, steps per second: 170, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.458 [0.000, 5.000], mean observation: 105.605 [87.000, 236.000], loss: 0.004475, mean_absolute_error: 0.121179, mean_q: -0.087454, mean_eps: 0.783596
   23406/1700000: episode: 25, duration: 5.369s, episode steps: 913, steps per second: 170, episode reward: -21.000, mean reward: -0.023 [-1.000, 0.000], mean action: 2.502 [0.000, 5.000], mean observation: 105.614 [87.000, 236.000], loss: 0.005465, mean_absolute_error: 0.135765, mean_q: -0.107250, mean_eps: 0.775090
   24249/1700000: episode: 26, duration: 4.923s, episode steps: 843, steps per second: 171, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.569 [0.000, 5.000], mean observation: 105.598 [87.000, 236.000], loss: 0.005224, mean_absolute_error: 0.152923, mean_q: -0.137403, mean_eps: 0.766486
   25255/1700000: episode: 27, duration: 5.889s, episode steps: 1006, steps per second: 171, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.517 [0.000, 5.000], mean observation: 105.424 [87.000, 236.000], loss: 0.005366, mean_absolute_error: 0.178568, mean_q: -0.169292, mean_eps: 0.757430
   26019/1700000: episode: 28, duration: 4.440s, episode steps: 764, steps per second: 172, episode reward: -21.000, mean reward: -0.027 [-1.000, 0.000], mean action: 2.550 [0.000, 5.000], mean observation: 105.610 [87.000, 236.000], loss: 0.005661, mean_absolute_error: 0.198764, mean_q: -0.198741, mean_eps: 0.748767
   27153/1700000: episode: 29, duration: 6.700s, episode steps: 1134, steps per second: 169, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 2.731 [0.000, 5.000], mean observation: 105.573 [87.000, 236.000], loss: 0.004535, mean_absolute_error: 0.205736, mean_q: -0.207562, mean_eps: 0.739457
   28054/1700000: episode: 30, duration: 5.202s, episode steps: 901, steps per second: 173, episode reward: -21.000, mean reward: -0.023 [-1.000, 0.000], mean action: 2.502 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.004727, mean_absolute_error: 0.213569, mean_q: -0.218860, mean_eps: 0.729481
   28865/1700000: episode: 31, duration: 4.705s, episode steps: 811, steps per second: 172, episode reward: -21.000, mean reward: -0.026 [-1.000, 0.000], mean action: 2.552 [0.000, 5.000], mean observation: 105.612 [87.000, 236.000], loss: 0.004891, mean_absolute_error: 0.214035, mean_q: -0.218114, mean_eps: 0.721092
   30077/1700000: episode: 32, duration: 7.014s, episode steps: 1212, steps per second: 173, episode reward: -19.000, mean reward: -0.016 [-1.000, 1.000], mean action: 2.717 [0.000, 5.000], mean observation: 105.503 [87.000, 236.000], loss: 0.004098, mean_absolute_error: 0.213204, mean_q: -0.216912, mean_eps: 0.711174
   30963/1700000: episode: 33, duration: 5.103s, episode steps: 886, steps per second: 174, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.673 [0.000, 5.000], mean observation: 105.625 [87.000, 236.000], loss: 0.003981, mean_absolute_error: 0.215078, mean_q: -0.217198, mean_eps: 0.700904
   31895/1700000: episode: 34, duration: 5.416s, episode steps: 932, steps per second: 172, episode reward: -19.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.622 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.003542, mean_absolute_error: 0.222944, mean_q: -0.228072, mean_eps: 0.692006
   32720/1700000: episode: 35, duration: 4.812s, episode steps: 825, steps per second: 171, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.838 [0.000, 5.000], mean observation: 105.578 [87.000, 236.000], loss: 0.003949, mean_absolute_error: 0.229195, mean_q: -0.233835, mean_eps: 0.683401
   33591/1700000: episode: 36, duration: 5.114s, episode steps: 871, steps per second: 170, episode reward: -20.000, mean reward: -0.023 [-1.000, 1.000], mean action: 2.563 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.004566, mean_absolute_error: 0.240053, mean_q: -0.245625, mean_eps: 0.675091
   34582/1700000: episode: 37, duration: 5.801s, episode steps: 991, steps per second: 171, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.694 [0.000, 5.000], mean observation: 105.443 [87.000, 236.000], loss: 0.005585, mean_absolute_error: 0.247847, mean_q: -0.250830, mean_eps: 0.665957
   35487/1700000: episode: 38, duration: 5.284s, episode steps: 905, steps per second: 171, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 2.565 [0.000, 5.000], mean observation: 105.574 [87.000, 236.000], loss: 0.005971, mean_absolute_error: 0.250669, mean_q: -0.250032, mean_eps: 0.656667
   36429/1700000: episode: 39, duration: 5.501s, episode steps: 942, steps per second: 171, episode reward: -21.000, mean reward: -0.022 [-1.000, 0.000], mean action: 2.473 [0.000, 5.000], mean observation: 105.619 [87.000, 236.000], loss: 0.004738, mean_absolute_error: 0.269002, mean_q: -0.278156, mean_eps: 0.647612
   37446/1700000: episode: 40, duration: 5.893s, episode steps: 1017, steps per second: 173, episode reward: -19.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.622 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.005335, mean_absolute_error: 0.274941, mean_q: -0.292109, mean_eps: 0.638008
   38530/1700000: episode: 41, duration: 6.252s, episode steps: 1084, steps per second: 173, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 2.672 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.004988, mean_absolute_error: 0.272332, mean_q: -0.287451, mean_eps: 0.627718
   39576/1700000: episode: 42, duration: 6.109s, episode steps: 1046, steps per second: 171, episode reward: -18.000, mean reward: -0.017 [-1.000, 1.000], mean action: 2.718 [0.000, 5.000], mean observation: 105.519 [87.000, 236.000], loss: 0.005357, mean_absolute_error: 0.286078, mean_q: -0.301329, mean_eps: 0.617290
   40569/1700000: episode: 43, duration: 5.800s, episode steps: 993, steps per second: 171, episode reward: -21.000, mean reward: -0.021 [-1.000, 0.000], mean action: 2.528 [0.000, 5.000], mean observation: 105.631 [87.000, 236.000], loss: 0.005043, mean_absolute_error: 0.281674, mean_q: -0.294408, mean_eps: 0.607294
   41459/1700000: episode: 44, duration: 5.175s, episode steps: 890, steps per second: 172, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.597 [0.000, 5.000], mean observation: 105.607 [87.000, 236.000], loss: 0.005109, mean_absolute_error: 0.288835, mean_q: -0.301629, mean_eps: 0.598063
   42311/1700000: episode: 45, duration: 4.931s, episode steps: 852, steps per second: 173, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.640 [0.000, 5.000], mean observation: 105.572 [87.000, 236.000], loss: 0.005106, mean_absolute_error: 0.293455, mean_q: -0.307968, mean_eps: 0.589537
   43182/1700000: episode: 46, duration: 4.987s, episode steps: 871, steps per second: 175, episode reward: -20.000, mean reward: -0.023 [-1.000, 1.000], mean action: 2.635 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.004895, mean_absolute_error: 0.297966, mean_q: -0.315140, mean_eps: 0.581089
   44006/1700000: episode: 47, duration: 4.746s, episode steps: 824, steps per second: 174, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.783 [0.000, 5.000], mean observation: 105.610 [87.000, 236.000], loss: 0.004976, mean_absolute_error: 0.312490, mean_q: -0.327717, mean_eps: 0.572779
   45010/1700000: episode: 48, duration: 5.835s, episode steps: 1004, steps per second: 172, episode reward: -21.000, mean reward: -0.021 [-1.000, 0.000], mean action: 2.611 [0.000, 5.000], mean observation: 105.594 [87.000, 236.000], loss: 0.004273, mean_absolute_error: 0.340476, mean_q: -0.364432, mean_eps: 0.563822
   45863/1700000: episode: 49, duration: 4.917s, episode steps: 853, steps per second: 173, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.899 [0.000, 5.000], mean observation: 105.610 [87.000, 236.000], loss: 0.003524, mean_absolute_error: 0.353653, mean_q: -0.386642, mean_eps: 0.554727
   46843/1700000: episode: 50, duration: 5.629s, episode steps: 980, steps per second: 174, episode reward: -19.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.722 [0.000, 5.000], mean observation: 105.467 [87.000, 236.000], loss: 0.003853, mean_absolute_error: 0.362587, mean_q: -0.400046, mean_eps: 0.545750
   47895/1700000: episode: 51, duration: 6.071s, episode steps: 1052, steps per second: 173, episode reward: -20.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.689 [0.000, 5.000], mean observation: 105.506 [87.000, 236.000], loss: 0.003798, mean_absolute_error: 0.380703, mean_q: -0.421336, mean_eps: 0.535794
   48824/1700000: episode: 52, duration: 5.360s, episode steps: 929, steps per second: 173, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 2.487 [0.000, 5.000], mean observation: 105.441 [87.000, 236.000], loss: 0.003766, mean_absolute_error: 0.382258, mean_q: -0.424835, mean_eps: 0.526092
   49833/1700000: episode: 53, duration: 5.838s, episode steps: 1009, steps per second: 173, episode reward: -19.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.466 [0.000, 5.000], mean observation: 105.500 [87.000, 236.000], loss: 0.003886, mean_absolute_error: 0.396095, mean_q: -0.442810, mean_eps: 0.516586
   50979/1700000: episode: 54, duration: 6.578s, episode steps: 1146, steps per second: 174, episode reward: -18.000, mean reward: -0.016 [-1.000, 1.000], mean action: 2.701 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.003729, mean_absolute_error: 0.423623, mean_q: -0.477950, mean_eps: 0.506021
   52049/1700000: episode: 55, duration: 6.212s, episode steps: 1070, steps per second: 172, episode reward: -20.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.691 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.004350, mean_absolute_error: 0.458920, mean_q: -0.520514, mean_eps: 0.495163
   53013/1700000: episode: 56, duration: 5.595s, episode steps: 964, steps per second: 172, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 2.415 [0.000, 5.000], mean observation: 105.450 [87.000, 236.000], loss: 0.004142, mean_absolute_error: 0.446420, mean_q: -0.503826, mean_eps: 0.485186
   53898/1700000: episode: 57, duration: 5.149s, episode steps: 885, steps per second: 172, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.699 [0.000, 5.000], mean observation: 105.576 [87.000, 236.000], loss: 0.004044, mean_absolute_error: 0.477763, mean_q: -0.544639, mean_eps: 0.476131
   54769/1700000: episode: 58, duration: 5.085s, episode steps: 871, steps per second: 171, episode reward: -20.000, mean reward: -0.023 [-1.000, 1.000], mean action: 2.782 [0.000, 5.000], mean observation: 105.462 [87.000, 236.000], loss: 0.004390, mean_absolute_error: 0.497428, mean_q: -0.566562, mean_eps: 0.467527
   55684/1700000: episode: 59, duration: 5.359s, episode steps: 915, steps per second: 171, episode reward: -21.000, mean reward: -0.023 [-1.000, 0.000], mean action: 2.889 [0.000, 5.000], mean observation: 105.578 [87.000, 236.000], loss: 0.004071, mean_absolute_error: 0.492145, mean_q: -0.559705, mean_eps: 0.458785
   56467/1700000: episode: 60, duration: 4.721s, episode steps: 783, steps per second: 166, episode reward: -21.000, mean reward: -0.027 [-1.000, 0.000], mean action: 2.822 [0.000, 5.000], mean observation: 105.563 [87.000, 236.000], loss: 0.004238, mean_absolute_error: 0.494261, mean_q: -0.560320, mean_eps: 0.450475
   57355/1700000: episode: 61, duration: 5.336s, episode steps: 888, steps per second: 166, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.829 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.004315, mean_absolute_error: 0.499911, mean_q: -0.568405, mean_eps: 0.442282
   58147/1700000: episode: 62, duration: 4.621s, episode steps: 792, steps per second: 171, episode reward: -21.000, mean reward: -0.027 [-1.000, 0.000], mean action: 2.961 [0.000, 5.000], mean observation: 105.576 [87.000, 236.000], loss: 0.004590, mean_absolute_error: 0.509478, mean_q: -0.578616, mean_eps: 0.434050
   59081/1700000: episode: 63, duration: 5.412s, episode steps: 934, steps per second: 173, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 2.715 [0.000, 5.000], mean observation: 105.524 [87.000, 236.000], loss: 0.004177, mean_absolute_error: 0.544596, mean_q: -0.623919, mean_eps: 0.425583
   60043/1700000: episode: 64, duration: 5.545s, episode steps: 962, steps per second: 173, episode reward: -21.000, mean reward: -0.022 [-1.000, 0.000], mean action: 2.931 [0.000, 5.000], mean observation: 105.609 [87.000, 236.000], loss: 0.004182, mean_absolute_error: 0.563167, mean_q: -0.646333, mean_eps: 0.416292
   60836/1700000: episode: 65, duration: 4.569s, episode steps: 793, steps per second: 174, episode reward: -21.000, mean reward: -0.026 [-1.000, 0.000], mean action: 2.620 [0.000, 5.000], mean observation: 105.582 [87.000, 236.000], loss: 0.004499, mean_absolute_error: 0.564419, mean_q: -0.648356, mean_eps: 0.407708
   61780/1700000: episode: 66, duration: 5.457s, episode steps: 944, steps per second: 173, episode reward: -21.000, mean reward: -0.022 [-1.000, 0.000], mean action: 2.309 [0.000, 5.000], mean observation: 105.628 [87.000, 236.000], loss: 0.004318, mean_absolute_error: 0.574902, mean_q: -0.660965, mean_eps: 0.399201
   62742/1700000: episode: 67, duration: 5.647s, episode steps: 962, steps per second: 170, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 2.390 [0.000, 5.000], mean observation: 105.443 [87.000, 236.000], loss: 0.004029, mean_absolute_error: 0.585553, mean_q: -0.675396, mean_eps: 0.389852
   63568/1700000: episode: 68, duration: 4.796s, episode steps: 826, steps per second: 172, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.892 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.004096, mean_absolute_error: 0.592096, mean_q: -0.686586, mean_eps: 0.381091
   64637/1700000: episode: 69, duration: 6.244s, episode steps: 1069, steps per second: 171, episode reward: -20.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.505 [0.000, 5.000], mean observation: 105.483 [87.000, 236.000], loss: 0.004050, mean_absolute_error: 0.595324, mean_q: -0.688660, mean_eps: 0.371800
   65480/1700000: episode: 70, duration: 5.006s, episode steps: 843, steps per second: 168, episode reward: -21.000, mean reward: -0.025 [-1.000, 0.000], mean action: 2.690 [0.000, 5.000], mean observation: 105.599 [87.000, 236.000], loss: 0.004190, mean_absolute_error: 0.607656, mean_q: -0.701938, mean_eps: 0.362432
   66607/1700000: episode: 71, duration: 6.616s, episode steps: 1127, steps per second: 170, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 2.115 [0.000, 5.000], mean observation: 105.551 [87.000, 236.000], loss: 0.004143, mean_absolute_error: 0.616097, mean_q: -0.711465, mean_eps: 0.352788
   67691/1700000: episode: 72, duration: 6.358s, episode steps: 1084, steps per second: 170, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 2.045 [0.000, 5.000], mean observation: 105.411 [87.000, 236.000], loss: 0.004032, mean_absolute_error: 0.600707, mean_q: -0.692595, mean_eps: 0.341950
   68575/1700000: episode: 73, duration: 5.155s, episode steps: 884, steps per second: 171, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.650 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.004879, mean_absolute_error: 0.588738, mean_q: -0.676409, mean_eps: 0.332306
   69367/1700000: episode: 74, duration: 4.634s, episode steps: 792, steps per second: 171, episode reward: -21.000, mean reward: -0.027 [-1.000, 0.000], mean action: 2.668 [0.000, 5.000], mean observation: 105.590 [87.000, 236.000], loss: 0.004227, mean_absolute_error: 0.588376, mean_q: -0.677220, mean_eps: 0.324094
   70313/1700000: episode: 75, duration: 5.542s, episode steps: 946, steps per second: 171, episode reward: -21.000, mean reward: -0.022 [-1.000, 0.000], mean action: 2.090 [0.000, 5.000], mean observation: 105.608 [87.000, 236.000], loss: 0.004938, mean_absolute_error: 0.597306, mean_q: -0.685943, mean_eps: 0.315568
   71245/1700000: episode: 76, duration: 5.430s, episode steps: 932, steps per second: 172, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 2.006 [0.000, 5.000], mean observation: 105.474 [87.000, 236.000], loss: 0.004592, mean_absolute_error: 0.597617, mean_q: -0.686897, mean_eps: 0.306356
   72129/1700000: episode: 77, duration: 5.161s, episode steps: 884, steps per second: 171, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.258 [0.000, 5.000], mean observation: 105.570 [87.000, 236.000], loss: 0.004880, mean_absolute_error: 0.588913, mean_q: -0.676183, mean_eps: 0.297458
   73074/1700000: episode: 78, duration: 5.545s, episode steps: 945, steps per second: 170, episode reward: -21.000, mean reward: -0.022 [-1.000, 0.000], mean action: 2.281 [0.000, 5.000], mean observation: 105.572 [87.000, 236.000], loss: 0.004403, mean_absolute_error: 0.602171, mean_q: -0.692621, mean_eps: 0.288500
   74079/1700000: episode: 79, duration: 5.860s, episode steps: 1005, steps per second: 172, episode reward: -21.000, mean reward: -0.021 [-1.000, 0.000], mean action: 2.515 [0.000, 5.000], mean observation: 105.604 [87.000, 236.000], loss: 0.004522, mean_absolute_error: 0.608107, mean_q: -0.699500, mean_eps: 0.278955
   74993/1700000: episode: 80, duration: 5.367s, episode steps: 914, steps per second: 170, episode reward: -21.000, mean reward: -0.023 [-1.000, 0.000], mean action: 2.402 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.004655, mean_absolute_error: 0.604833, mean_q: -0.696455, mean_eps: 0.269547
   75915/1700000: episode: 81, duration: 5.348s, episode steps: 922, steps per second: 172, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 1.918 [0.000, 5.000], mean observation: 105.487 [87.000, 236.000], loss: 0.004618, mean_absolute_error: 0.596284, mean_q: -0.683303, mean_eps: 0.260551
   76726/1700000: episode: 82, duration: 4.758s, episode steps: 811, steps per second: 170, episode reward: -21.000, mean reward: -0.026 [-1.000, 0.000], mean action: 2.342 [0.000, 5.000], mean observation: 105.612 [87.000, 236.000], loss: 0.004313, mean_absolute_error: 0.622132, mean_q: -0.716639, mean_eps: 0.252064
   77659/1700000: episode: 83, duration: 5.469s, episode steps: 933, steps per second: 171, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 2.113 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.003783, mean_absolute_error: 0.632195, mean_q: -0.729513, mean_eps: 0.243518
   78589/1700000: episode: 84, duration: 5.470s, episode steps: 930, steps per second: 170, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 2.441 [0.000, 5.000], mean observation: 105.496 [87.000, 236.000], loss: 0.003840, mean_absolute_error: 0.630512, mean_q: -0.729480, mean_eps: 0.234385
   79431/1700000: episode: 85, duration: 4.869s, episode steps: 842, steps per second: 173, episode reward: -20.000, mean reward: -0.024 [-1.000, 1.000], mean action: 2.049 [0.000, 5.000], mean observation: 105.465 [87.000, 236.000], loss: 0.003754, mean_absolute_error: 0.640916, mean_q: -0.740696, mean_eps: 0.225702
   80630/1700000: episode: 86, duration: 6.936s, episode steps: 1199, steps per second: 173, episode reward: -19.000, mean reward: -0.016 [-1.000, 1.000], mean action: 2.464 [0.000, 5.000], mean observation: 105.461 [87.000, 236.000], loss: 0.003780, mean_absolute_error: 0.639266, mean_q: -0.738020, mean_eps: 0.215706
   81666/1700000: episode: 87, duration: 6.030s, episode steps: 1036, steps per second: 172, episode reward: -21.000, mean reward: -0.020 [-1.000, 0.000], mean action: 2.225 [0.000, 5.000], mean observation: 105.611 [87.000, 236.000], loss: 0.003532, mean_absolute_error: 0.641840, mean_q: -0.741494, mean_eps: 0.204750
   82692/1700000: episode: 88, duration: 6.000s, episode steps: 1026, steps per second: 171, episode reward: -21.000, mean reward: -0.020 [-1.000, 0.000], mean action: 2.841 [0.000, 5.000], mean observation: 105.617 [87.000, 236.000], loss: 0.003476, mean_absolute_error: 0.640351, mean_q: -0.740725, mean_eps: 0.194656
   83857/1700000: episode: 89, duration: 6.784s, episode steps: 1165, steps per second: 172, episode reward: -19.000, mean reward: -0.016 [-1.000, 1.000], mean action: 2.069 [0.000, 5.000], mean observation: 105.528 [87.000, 236.000], loss: 0.003983, mean_absolute_error: 0.636897, mean_q: -0.734046, mean_eps: 0.183915
   84833/1700000: episode: 90, duration: 5.708s, episode steps: 976, steps per second: 171, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.559 [0.000, 5.000], mean observation: 105.468 [87.000, 236.000], loss: 0.003925, mean_absolute_error: 0.633140, mean_q: -0.728667, mean_eps: 0.173409
   85897/1700000: episode: 91, duration: 6.222s, episode steps: 1064, steps per second: 171, episode reward: -20.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.513 [0.000, 5.000], mean observation: 105.539 [87.000, 236.000], loss: 0.003695, mean_absolute_error: 0.644663, mean_q: -0.742951, mean_eps: 0.163413
   86986/1700000: episode: 92, duration: 6.346s, episode steps: 1089, steps per second: 172, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 2.297 [0.000, 5.000], mean observation: 105.442 [87.000, 236.000], loss: 0.004457, mean_absolute_error: 0.629591, mean_q: -0.721018, mean_eps: 0.152868
   88092/1700000: episode: 93, duration: 6.467s, episode steps: 1106, steps per second: 171, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 3.108 [0.000, 5.000], mean observation: 105.589 [87.000, 236.000], loss: 0.005106, mean_absolute_error: 0.617547, mean_q: -0.705123, mean_eps: 0.142128
   89068/1700000: episode: 94, duration: 5.707s, episode steps: 976, steps per second: 171, episode reward: -21.000, mean reward: -0.022 [-1.000, 0.000], mean action: 3.062 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.005063, mean_absolute_error: 0.607021, mean_q: -0.691572, mean_eps: 0.131936
   89912/1700000: episode: 95, duration: 4.935s, episode steps: 844, steps per second: 171, episode reward: -20.000, mean reward: -0.024 [-1.000, 1.000], mean action: 2.584 [0.000, 5.000], mean observation: 105.500 [87.000, 236.000], loss: 0.004968, mean_absolute_error: 0.581375, mean_q: -0.660215, mean_eps: 0.123018
   90923/1700000: episode: 96, duration: 5.902s, episode steps: 1011, steps per second: 171, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 1.832 [0.000, 5.000], mean observation: 105.502 [87.000, 236.000], loss: 0.005427, mean_absolute_error: 0.568418, mean_q: -0.644977, mean_eps: 0.113923
   91952/1700000: episode: 97, duration: 5.950s, episode steps: 1029, steps per second: 173, episode reward: -21.000, mean reward: -0.020 [-1.000, 0.000], mean action: 2.534 [0.000, 5.000], mean observation: 105.593 [87.000, 236.000], loss: 0.005371, mean_absolute_error: 0.565285, mean_q: -0.639909, mean_eps: 0.103927
   92850/1700000: episode: 98, duration: 5.416s, episode steps: 898, steps per second: 166, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 2.459 [0.000, 5.000], mean observation: 105.461 [87.000, 236.000], loss: 0.005790, mean_absolute_error: 0.584010, mean_q: -0.662851, mean_eps: 0.094480
   94293/1700000: episode: 99, duration: 8.796s, episode steps: 1443, steps per second: 164, episode reward: -19.000, mean reward: -0.013 [-1.000, 1.000], mean action: 2.832 [0.000, 5.000], mean observation: 105.567 [87.000, 236.000], loss: 0.005642, mean_absolute_error: 0.578402, mean_q: -0.657050, mean_eps: 0.082994
   95256/1700000: episode: 100, duration: 5.845s, episode steps: 963, steps per second: 165, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 1.808 [0.000, 5.000], mean observation: 105.444 [87.000, 236.000], loss: 0.004441, mean_absolute_error: 0.581592, mean_q: -0.664933, mean_eps: 0.071215
   96494/1700000: episode: 101, duration: 7.502s, episode steps: 1238, steps per second: 165, episode reward: -19.000, mean reward: -0.015 [-1.000, 1.000], mean action: 1.868 [0.000, 5.000], mean observation: 105.506 [87.000, 236.000], loss: 0.004669, mean_absolute_error: 0.578848, mean_q: -0.658754, mean_eps: 0.060435
   97397/1700000: episode: 102, duration: 5.448s, episode steps: 903, steps per second: 166, episode reward: -20.000, mean reward: -0.022 [-1.000, 1.000], mean action: 1.763 [0.000, 5.000], mean observation: 105.443 [87.000, 236.000], loss: 0.004104, mean_absolute_error: 0.567373, mean_q: -0.647190, mean_eps: 0.049929
   98862/1700000: episode: 103, duration: 8.891s, episode steps: 1465, steps per second: 165, episode reward: -20.000, mean reward: -0.014 [-1.000, 1.000], mean action: 1.750 [0.000, 5.000], mean observation: 105.586 [87.000, 236.000], loss: 0.003880, mean_absolute_error: 0.566024, mean_q: -0.643944, mean_eps: 0.038326
  100169/1700000: episode: 104, duration: 7.885s, episode steps: 1307, steps per second: 166, episode reward: -20.000, mean reward: -0.015 [-1.000, 1.000], mean action: 1.579 [0.000, 5.000], mean observation: 105.455 [87.000, 236.000], loss: 0.004428, mean_absolute_error: 0.568361, mean_q: -0.647053, mean_eps: 0.024851
  101388/1700000: episode: 105, duration: 7.297s, episode steps: 1219, steps per second: 167, episode reward: -21.000, mean reward: -0.017 [-1.000, 0.000], mean action: 2.587 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.004050, mean_absolute_error: 0.545036, mean_q: -0.618646, mean_eps: 0.020000
  102454/1700000: episode: 106, duration: 6.429s, episode steps: 1066, steps per second: 166, episode reward: -21.000, mean reward: -0.020 [-1.000, 0.000], mean action: 1.386 [0.000, 5.000], mean observation: 105.606 [87.000, 236.000], loss: 0.004469, mean_absolute_error: 0.538100, mean_q: -0.607734, mean_eps: 0.020000
  103700/1700000: episode: 107, duration: 7.651s, episode steps: 1246, steps per second: 163, episode reward: -21.000, mean reward: -0.017 [-1.000, 0.000], mean action: 1.689 [0.000, 5.000], mean observation: 105.617 [87.000, 236.000], loss: 0.004144, mean_absolute_error: 0.538812, mean_q: -0.608646, mean_eps: 0.020000
  104692/1700000: episode: 108, duration: 6.018s, episode steps: 992, steps per second: 165, episode reward: -21.000, mean reward: -0.021 [-1.000, 0.000], mean action: 1.634 [0.000, 5.000], mean observation: 105.606 [87.000, 236.000], loss: 0.004093, mean_absolute_error: 0.548201, mean_q: -0.619046, mean_eps: 0.020000
  105830/1700000: episode: 109, duration: 6.909s, episode steps: 1138, steps per second: 165, episode reward: -19.000, mean reward: -0.017 [-1.000, 1.000], mean action: 1.995 [0.000, 5.000], mean observation: 105.473 [87.000, 236.000], loss: 0.004065, mean_absolute_error: 0.558674, mean_q: -0.631430, mean_eps: 0.020000
  106900/1700000: episode: 110, duration: 6.462s, episode steps: 1070, steps per second: 166, episode reward: -20.000, mean reward: -0.019 [-1.000, 1.000], mean action: 2.056 [0.000, 5.000], mean observation: 105.455 [87.000, 236.000], loss: 0.004115, mean_absolute_error: 0.555214, mean_q: -0.627901, mean_eps: 0.020000
  108031/1700000: episode: 111, duration: 6.836s, episode steps: 1131, steps per second: 165, episode reward: -21.000, mean reward: -0.019 [-1.000, 0.000], mean action: 2.295 [0.000, 5.000], mean observation: 105.598 [87.000, 236.000], loss: 0.004145, mean_absolute_error: 0.561095, mean_q: -0.633938, mean_eps: 0.020000
  109878/1700000: episode: 112, duration: 11.612s, episode steps: 1847, steps per second: 159, episode reward: -18.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.149 [0.000, 5.000], mean observation: 105.605 [87.000, 236.000], loss: 0.003770, mean_absolute_error: 0.574909, mean_q: -0.651016, mean_eps: 0.020000
  111239/1700000: episode: 113, duration: 8.163s, episode steps: 1361, steps per second: 167, episode reward: -19.000, mean reward: -0.014 [-1.000, 1.000], mean action: 1.537 [0.000, 5.000], mean observation: 105.519 [87.000, 236.000], loss: 0.004109, mean_absolute_error: 0.562093, mean_q: -0.633779, mean_eps: 0.020000
  112518/1700000: episode: 114, duration: 7.732s, episode steps: 1279, steps per second: 165, episode reward: -20.000, mean reward: -0.016 [-1.000, 1.000], mean action: 2.352 [0.000, 5.000], mean observation: 105.471 [87.000, 236.000], loss: 0.004204, mean_absolute_error: 0.554202, mean_q: -0.625679, mean_eps: 0.020000
  113585/1700000: episode: 115, duration: 6.397s, episode steps: 1067, steps per second: 167, episode reward: -21.000, mean reward: -0.020 [-1.000, 0.000], mean action: 1.931 [0.000, 5.000], mean observation: 105.609 [87.000, 236.000], loss: 0.004173, mean_absolute_error: 0.552240, mean_q: -0.621912, mean_eps: 0.020000
  114974/1700000: episode: 116, duration: 8.457s, episode steps: 1389, steps per second: 164, episode reward: -18.000, mean reward: -0.013 [-1.000, 1.000], mean action: 2.017 [0.000, 5.000], mean observation: 105.505 [87.000, 236.000], loss: 0.004497, mean_absolute_error: 0.550965, mean_q: -0.618889, mean_eps: 0.020000
  115936/1700000: episode: 117, duration: 5.869s, episode steps: 962, steps per second: 164, episode reward: -20.000, mean reward: -0.021 [-1.000, 1.000], mean action: 1.764 [0.000, 5.000], mean observation: 105.501 [87.000, 236.000], loss: 0.003901, mean_absolute_error: 0.535135, mean_q: -0.600099, mean_eps: 0.020000
  117040/1700000: episode: 118, duration: 6.812s, episode steps: 1104, steps per second: 162, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 2.081 [0.000, 5.000], mean observation: 105.614 [87.000, 236.000], loss: 0.003655, mean_absolute_error: 0.542606, mean_q: -0.609741, mean_eps: 0.020000
  118591/1700000: episode: 119, duration: 9.363s, episode steps: 1551, steps per second: 166, episode reward: -17.000, mean reward: -0.011 [-1.000, 1.000], mean action: 1.662 [0.000, 5.000], mean observation: 105.478 [87.000, 236.000], loss: 0.003556, mean_absolute_error: 0.564201, mean_q: -0.634229, mean_eps: 0.020000
  119475/1700000: episode: 120, duration: 5.392s, episode steps: 884, steps per second: 164, episode reward: -21.000, mean reward: -0.024 [-1.000, 0.000], mean action: 2.497 [0.000, 5.000], mean observation: 105.582 [87.000, 236.000], loss: 0.003444, mean_absolute_error: 0.581899, mean_q: -0.656800, mean_eps: 0.020000
  120933/1700000: episode: 121, duration: 8.733s, episode steps: 1458, steps per second: 167, episode reward: -18.000, mean reward: -0.012 [-1.000, 1.000], mean action: 1.822 [0.000, 5.000], mean observation: 105.597 [87.000, 236.000], loss: 0.003575, mean_absolute_error: 0.599509, mean_q: -0.677569, mean_eps: 0.020000
  122324/1700000: episode: 122, duration: 8.208s, episode steps: 1391, steps per second: 169, episode reward: -17.000, mean reward: -0.012 [-1.000, 1.000], mean action: 1.727 [0.000, 5.000], mean observation: 105.572 [87.000, 236.000], loss: 0.003972, mean_absolute_error: 0.617856, mean_q: -0.698180, mean_eps: 0.020000
  123329/1700000: episode: 123, duration: 5.904s, episode steps: 1005, steps per second: 170, episode reward: -21.000, mean reward: -0.021 [-1.000, 0.000], mean action: 1.429 [0.000, 5.000], mean observation: 105.612 [87.000, 236.000], loss: 0.003594, mean_absolute_error: 0.618268, mean_q: -0.697742, mean_eps: 0.020000
  124334/1700000: episode: 124, duration: 5.847s, episode steps: 1005, steps per second: 172, episode reward: -21.000, mean reward: -0.021 [-1.000, 0.000], mean action: 1.532 [0.000, 5.000], mean observation: 105.570 [87.000, 236.000], loss: 0.003937, mean_absolute_error: 0.626268, mean_q: -0.708867, mean_eps: 0.020000
  125354/1700000: episode: 125, duration: 5.981s, episode steps: 1020, steps per second: 171, episode reward: -20.000, mean reward: -0.020 [-1.000, 1.000], mean action: 2.128 [0.000, 5.000], mean observation: 105.477 [87.000, 236.000], loss: 0.004392, mean_absolute_error: 0.636413, mean_q: -0.722238, mean_eps: 0.020000
  126467/1700000: episode: 126, duration: 6.479s, episode steps: 1113, steps per second: 172, episode reward: -20.000, mean reward: -0.018 [-1.000, 1.000], mean action: 2.323 [0.000, 5.000], mean observation: 105.525 [87.000, 236.000], loss: 0.005184, mean_absolute_error: 0.628392, mean_q: -0.713656, mean_eps: 0.020000
  128110/1700000: episode: 127, duration: 9.500s, episode steps: 1643, steps per second: 173, episode reward: -18.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.447 [0.000, 5.000], mean observation: 105.543 [87.000, 236.000], loss: 0.004618, mean_absolute_error: 0.634481, mean_q: -0.720639, mean_eps: 0.020000
  129550/1700000: episode: 128, duration: 8.379s, episode steps: 1440, steps per second: 172, episode reward: -19.000, mean reward: -0.013 [-1.000, 1.000], mean action: 2.047 [0.000, 5.000], mean observation: 105.583 [87.000, 236.000], loss: 0.004819, mean_absolute_error: 0.641036, mean_q: -0.726341, mean_eps: 0.020000
  131178/1700000: episode: 129, duration: 9.467s, episode steps: 1628, steps per second: 172, episode reward: -20.000, mean reward: -0.012 [-1.000, 1.000], mean action: 1.978 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.004432, mean_absolute_error: 0.633584, mean_q: -0.716579, mean_eps: 0.020000
  132735/1700000: episode: 130, duration: 8.991s, episode steps: 1557, steps per second: 173, episode reward: -19.000, mean reward: -0.012 [-1.000, 1.000], mean action: 1.850 [0.000, 5.000], mean observation: 105.602 [87.000, 236.000], loss: 0.003933, mean_absolute_error: 0.630819, mean_q: -0.714427, mean_eps: 0.020000
  133941/1700000: episode: 131, duration: 7.045s, episode steps: 1206, steps per second: 171, episode reward: -21.000, mean reward: -0.017 [-1.000, 0.000], mean action: 2.509 [0.000, 5.000], mean observation: 105.610 [87.000, 236.000], loss: 0.003706, mean_absolute_error: 0.617119, mean_q: -0.696932, mean_eps: 0.020000
  135459/1700000: episode: 132, duration: 8.839s, episode steps: 1518, steps per second: 172, episode reward: -21.000, mean reward: -0.014 [-1.000, 0.000], mean action: 2.092 [0.000, 5.000], mean observation: 105.625 [87.000, 236.000], loss: 0.004221, mean_absolute_error: 0.611504, mean_q: -0.687790, mean_eps: 0.020000
  136996/1700000: episode: 133, duration: 8.808s, episode steps: 1537, steps per second: 174, episode reward: -20.000, mean reward: -0.013 [-1.000, 1.000], mean action: 2.324 [0.000, 5.000], mean observation: 105.603 [87.000, 236.000], loss: 0.004712, mean_absolute_error: 0.589694, mean_q: -0.660255, mean_eps: 0.020000
  138784/1700000: episode: 134, duration: 10.406s, episode steps: 1788, steps per second: 172, episode reward: -17.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.152 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.004730, mean_absolute_error: 0.581763, mean_q: -0.649545, mean_eps: 0.020000
  140381/1700000: episode: 135, duration: 9.148s, episode steps: 1597, steps per second: 175, episode reward: -19.000, mean reward: -0.012 [-1.000, 1.000], mean action: 2.242 [0.000, 5.000], mean observation: 105.617 [87.000, 236.000], loss: 0.004488, mean_absolute_error: 0.589218, mean_q: -0.656679, mean_eps: 0.020000
  142464/1700000: episode: 136, duration: 12.018s, episode steps: 2083, steps per second: 173, episode reward: -16.000, mean reward: -0.008 [-1.000, 1.000], mean action: 1.988 [0.000, 5.000], mean observation: 105.578 [87.000, 236.000], loss: 0.004444, mean_absolute_error: 0.582214, mean_q: -0.646720, mean_eps: 0.020000
  144320/1700000: episode: 137, duration: 10.807s, episode steps: 1856, steps per second: 172, episode reward: -16.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.115 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.004633, mean_absolute_error: 0.573820, mean_q: -0.637627, mean_eps: 0.020000
  146150/1700000: episode: 138, duration: 10.553s, episode steps: 1830, steps per second: 173, episode reward: -20.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.038 [0.000, 5.000], mean observation: 105.589 [87.000, 236.000], loss: 0.004447, mean_absolute_error: 0.563662, mean_q: -0.625674, mean_eps: 0.020000
  147926/1700000: episode: 139, duration: 10.178s, episode steps: 1776, steps per second: 174, episode reward: -17.000, mean reward: -0.010 [-1.000, 1.000], mean action: 1.939 [0.000, 5.000], mean observation: 105.545 [87.000, 236.000], loss: 0.004751, mean_absolute_error: 0.562244, mean_q: -0.619477, mean_eps: 0.020000
  150020/1700000: episode: 140, duration: 12.056s, episode steps: 2094, steps per second: 174, episode reward: -16.000, mean reward: -0.008 [-1.000, 1.000], mean action: 1.982 [0.000, 5.000], mean observation: 105.587 [87.000, 236.000], loss: 0.004600, mean_absolute_error: 0.550472, mean_q: -0.608249, mean_eps: 0.020000
  151456/1700000: episode: 141, duration: 8.326s, episode steps: 1436, steps per second: 172, episode reward: -20.000, mean reward: -0.014 [-1.000, 1.000], mean action: 2.490 [0.000, 5.000], mean observation: 105.492 [87.000, 236.000], loss: 0.004472, mean_absolute_error: 0.547658, mean_q: -0.605603, mean_eps: 0.020000
  153110/1700000: episode: 142, duration: 9.591s, episode steps: 1654, steps per second: 172, episode reward: -18.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.221 [0.000, 5.000], mean observation: 105.508 [87.000, 236.000], loss: 0.004314, mean_absolute_error: 0.547652, mean_q: -0.605448, mean_eps: 0.020000
  155204/1700000: episode: 143, duration: 12.124s, episode steps: 2094, steps per second: 173, episode reward: -19.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.619 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.004867, mean_absolute_error: 0.546544, mean_q: -0.601344, mean_eps: 0.020000
  156713/1700000: episode: 144, duration: 8.749s, episode steps: 1509, steps per second: 172, episode reward: -20.000, mean reward: -0.013 [-1.000, 1.000], mean action: 2.566 [0.000, 5.000], mean observation: 105.490 [87.000, 236.000], loss: 0.004416, mean_absolute_error: 0.538634, mean_q: -0.592407, mean_eps: 0.020000
  158387/1700000: episode: 145, duration: 9.760s, episode steps: 1674, steps per second: 172, episode reward: -18.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.629 [0.000, 5.000], mean observation: 105.469 [87.000, 236.000], loss: 0.004124, mean_absolute_error: 0.536166, mean_q: -0.590699, mean_eps: 0.020000
  160235/1700000: episode: 146, duration: 10.671s, episode steps: 1848, steps per second: 173, episode reward: -19.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.495 [0.000, 5.000], mean observation: 105.597 [87.000, 236.000], loss: 0.004098, mean_absolute_error: 0.524180, mean_q: -0.576009, mean_eps: 0.020000
  162373/1700000: episode: 147, duration: 12.637s, episode steps: 2138, steps per second: 169, episode reward: -16.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.514 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.004359, mean_absolute_error: 0.520952, mean_q: -0.570626, mean_eps: 0.020000
  164238/1700000: episode: 148, duration: 10.935s, episode steps: 1865, steps per second: 171, episode reward: -17.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.384 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.004465, mean_absolute_error: 0.519980, mean_q: -0.567315, mean_eps: 0.020000
  166129/1700000: episode: 149, duration: 10.874s, episode steps: 1891, steps per second: 174, episode reward: -18.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.511 [0.000, 5.000], mean observation: 105.507 [87.000, 236.000], loss: 0.004544, mean_absolute_error: 0.522257, mean_q: -0.569908, mean_eps: 0.020000
  168196/1700000: episode: 150, duration: 11.982s, episode steps: 2067, steps per second: 173, episode reward: -19.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.381 [0.000, 5.000], mean observation: 105.489 [87.000, 236.000], loss: 0.004696, mean_absolute_error: 0.516258, mean_q: -0.565889, mean_eps: 0.020000
  169884/1700000: episode: 151, duration: 9.886s, episode steps: 1688, steps per second: 171, episode reward: -19.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.743 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.004525, mean_absolute_error: 0.512861, mean_q: -0.562390, mean_eps: 0.020000
  171843/1700000: episode: 152, duration: 11.339s, episode steps: 1959, steps per second: 173, episode reward: -18.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.657 [0.000, 5.000], mean observation: 105.504 [87.000, 236.000], loss: 0.004274, mean_absolute_error: 0.509990, mean_q: -0.558736, mean_eps: 0.020000
  173291/1700000: episode: 153, duration: 8.405s, episode steps: 1448, steps per second: 172, episode reward: -18.000, mean reward: -0.012 [-1.000, 1.000], mean action: 2.651 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.004213, mean_absolute_error: 0.533544, mean_q: -0.588533, mean_eps: 0.020000
  174571/1700000: episode: 154, duration: 7.440s, episode steps: 1280, steps per second: 172, episode reward: -19.000, mean reward: -0.015 [-1.000, 1.000], mean action: 2.699 [0.000, 5.000], mean observation: 105.499 [87.000, 236.000], loss: 0.003730, mean_absolute_error: 0.529237, mean_q: -0.585767, mean_eps: 0.020000
  177509/1700000: episode: 155, duration: 17.013s, episode steps: 2938, steps per second: 173, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.754 [0.000, 5.000], mean observation: 105.591 [87.000, 236.000], loss: 0.004253, mean_absolute_error: 0.522359, mean_q: -0.577358, mean_eps: 0.020000
  179670/1700000: episode: 156, duration: 12.512s, episode steps: 2161, steps per second: 173, episode reward: -17.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.427 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.004988, mean_absolute_error: 0.516744, mean_q: -0.566149, mean_eps: 0.020000
  182486/1700000: episode: 157, duration: 16.203s, episode steps: 2816, steps per second: 174, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.478 [0.000, 5.000], mean observation: 105.608 [87.000, 236.000], loss: 0.005126, mean_absolute_error: 0.497265, mean_q: -0.537667, mean_eps: 0.020000
  184236/1700000: episode: 158, duration: 10.102s, episode steps: 1750, steps per second: 173, episode reward: -16.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.697 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.004503, mean_absolute_error: 0.464145, mean_q: -0.492938, mean_eps: 0.020000
  186044/1700000: episode: 159, duration: 10.512s, episode steps: 1808, steps per second: 172, episode reward: -19.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.587 [0.000, 5.000], mean observation: 105.476 [87.000, 236.000], loss: 0.005433, mean_absolute_error: 0.455511, mean_q: -0.477431, mean_eps: 0.020000
  188476/1700000: episode: 160, duration: 13.982s, episode steps: 2432, steps per second: 174, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.456 [0.000, 5.000], mean observation: 105.509 [87.000, 236.000], loss: 0.005422, mean_absolute_error: 0.439955, mean_q: -0.458231, mean_eps: 0.020000
  190987/1700000: episode: 161, duration: 14.502s, episode steps: 2511, steps per second: 173, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.851 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.005051, mean_absolute_error: 0.419287, mean_q: -0.430782, mean_eps: 0.020000
  192723/1700000: episode: 162, duration: 9.983s, episode steps: 1736, steps per second: 174, episode reward: -17.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.911 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.005648, mean_absolute_error: 0.422396, mean_q: -0.431707, mean_eps: 0.020000
  194052/1700000: episode: 163, duration: 7.631s, episode steps: 1329, steps per second: 174, episode reward: -19.000, mean reward: -0.014 [-1.000, 1.000], mean action: 3.208 [0.000, 5.000], mean observation: 105.497 [87.000, 236.000], loss: 0.005935, mean_absolute_error: 0.420816, mean_q: -0.432025, mean_eps: 0.020000
  195752/1700000: episode: 164, duration: 9.930s, episode steps: 1700, steps per second: 171, episode reward: -17.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.666 [0.000, 5.000], mean observation: 105.504 [87.000, 236.000], loss: 0.005477, mean_absolute_error: 0.415277, mean_q: -0.422715, mean_eps: 0.020000
  197121/1700000: episode: 165, duration: 7.926s, episode steps: 1369, steps per second: 173, episode reward: -18.000, mean reward: -0.013 [-1.000, 1.000], mean action: 2.813 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.005365, mean_absolute_error: 0.423431, mean_q: -0.432470, mean_eps: 0.020000
  199434/1700000: episode: 166, duration: 13.392s, episode steps: 2313, steps per second: 173, episode reward: -16.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.533 [0.000, 5.000], mean observation: 105.514 [87.000, 236.000], loss: 0.005719, mean_absolute_error: 0.441629, mean_q: -0.452000, mean_eps: 0.020000
  201958/1700000: episode: 167, duration: 14.593s, episode steps: 2524, steps per second: 173, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.596 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.005872, mean_absolute_error: 0.443468, mean_q: -0.456620, mean_eps: 0.020000
  204655/1700000: episode: 168, duration: 15.565s, episode steps: 2697, steps per second: 173, episode reward: -10.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.707 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.005756, mean_absolute_error: 0.426473, mean_q: -0.431965, mean_eps: 0.020000
  206572/1700000: episode: 169, duration: 11.177s, episode steps: 1917, steps per second: 172, episode reward: -16.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.667 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.005074, mean_absolute_error: 0.405609, mean_q: -0.407333, mean_eps: 0.020000
  208815/1700000: episode: 170, duration: 12.958s, episode steps: 2243, steps per second: 173, episode reward: -13.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.819 [0.000, 5.000], mean observation: 105.553 [87.000, 236.000], loss: 0.005235, mean_absolute_error: 0.402494, mean_q: -0.401877, mean_eps: 0.020000
  210340/1700000: episode: 171, duration: 8.812s, episode steps: 1525, steps per second: 173, episode reward: -17.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.534 [0.000, 5.000], mean observation: 105.609 [87.000, 236.000], loss: 0.005122, mean_absolute_error: 0.390780, mean_q: -0.387396, mean_eps: 0.020000
  212295/1700000: episode: 172, duration: 11.334s, episode steps: 1955, steps per second: 172, episode reward: -18.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.631 [0.000, 5.000], mean observation: 105.574 [87.000, 236.000], loss: 0.004855, mean_absolute_error: 0.372168, mean_q: -0.363585, mean_eps: 0.020000
  214777/1700000: episode: 173, duration: 14.381s, episode steps: 2482, steps per second: 173, episode reward: -12.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.906 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.004530, mean_absolute_error: 0.381411, mean_q: -0.372538, mean_eps: 0.020000
  217358/1700000: episode: 174, duration: 15.239s, episode steps: 2581, steps per second: 169, episode reward: -10.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.852 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.004605, mean_absolute_error: 0.371582, mean_q: -0.359824, mean_eps: 0.020000
  219077/1700000: episode: 175, duration: 9.936s, episode steps: 1719, steps per second: 173, episode reward: -18.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.400 [0.000, 5.000], mean observation: 105.605 [87.000, 236.000], loss: 0.004659, mean_absolute_error: 0.361544, mean_q: -0.344239, mean_eps: 0.020000
  221608/1700000: episode: 176, duration: 14.766s, episode steps: 2531, steps per second: 171, episode reward: -16.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.677 [0.000, 5.000], mean observation: 105.544 [87.000, 236.000], loss: 0.004293, mean_absolute_error: 0.325850, mean_q: -0.302944, mean_eps: 0.020000
  223305/1700000: episode: 177, duration: 9.826s, episode steps: 1697, steps per second: 173, episode reward: -19.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.659 [0.000, 5.000], mean observation: 105.601 [87.000, 236.000], loss: 0.004049, mean_absolute_error: 0.316859, mean_q: -0.288668, mean_eps: 0.020000
  225764/1700000: episode: 178, duration: 14.164s, episode steps: 2459, steps per second: 174, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.526 [0.000, 5.000], mean observation: 105.549 [87.000, 236.000], loss: 0.004459, mean_absolute_error: 0.325417, mean_q: -0.305502, mean_eps: 0.020000
  227940/1700000: episode: 179, duration: 12.700s, episode steps: 2176, steps per second: 171, episode reward: -16.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.871 [0.000, 5.000], mean observation: 105.538 [87.000, 236.000], loss: 0.004370, mean_absolute_error: 0.325366, mean_q: -0.304127, mean_eps: 0.020000
  229984/1700000: episode: 180, duration: 11.782s, episode steps: 2044, steps per second: 173, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.504 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.003987, mean_absolute_error: 0.325142, mean_q: -0.307628, mean_eps: 0.020000
  231612/1700000: episode: 181, duration: 9.454s, episode steps: 1628, steps per second: 172, episode reward: -20.000, mean reward: -0.012 [-1.000, 1.000], mean action: 2.704 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.004787, mean_absolute_error: 0.313744, mean_q: -0.281602, mean_eps: 0.020000
  234895/1700000: episode: 182, duration: 18.926s, episode steps: 3283, steps per second: 173, episode reward: -8.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.642 [0.000, 5.000], mean observation: 105.586 [87.000, 236.000], loss: 0.004399, mean_absolute_error: 0.296203, mean_q: -0.259569, mean_eps: 0.020000
  236825/1700000: episode: 183, duration: 11.139s, episode steps: 1930, steps per second: 173, episode reward: -17.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.618 [0.000, 5.000], mean observation: 105.578 [87.000, 236.000], loss: 0.004087, mean_absolute_error: 0.279845, mean_q: -0.240843, mean_eps: 0.020000
  239681/1700000: episode: 184, duration: 16.620s, episode steps: 2856, steps per second: 172, episode reward: -10.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.609 [0.000, 5.000], mean observation: 105.631 [87.000, 236.000], loss: 0.004099, mean_absolute_error: 0.281510, mean_q: -0.235472, mean_eps: 0.020000
  241532/1700000: episode: 185, duration: 10.747s, episode steps: 1851, steps per second: 172, episode reward: -17.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.837 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.004564, mean_absolute_error: 0.279945, mean_q: -0.227305, mean_eps: 0.020000
  243186/1700000: episode: 186, duration: 9.555s, episode steps: 1654, steps per second: 173, episode reward: -18.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.959 [0.000, 5.000], mean observation: 105.544 [87.000, 236.000], loss: 0.004252, mean_absolute_error: 0.271980, mean_q: -0.218541, mean_eps: 0.020000
  245633/1700000: episode: 187, duration: 14.135s, episode steps: 2447, steps per second: 173, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.833 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.004547, mean_absolute_error: 0.253648, mean_q: -0.192903, mean_eps: 0.020000
  248049/1700000: episode: 188, duration: 14.033s, episode steps: 2416, steps per second: 172, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.646 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.004256, mean_absolute_error: 0.255837, mean_q: -0.207488, mean_eps: 0.020000
  250131/1700000: episode: 189, duration: 12.110s, episode steps: 2082, steps per second: 172, episode reward: -13.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.418 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.005231, mean_absolute_error: 0.269166, mean_q: -0.218274, mean_eps: 0.020000
  251856/1700000: episode: 190, duration: 9.994s, episode steps: 1725, steps per second: 173, episode reward: -14.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.708 [0.000, 5.000], mean observation: 105.468 [87.000, 236.000], loss: 0.005423, mean_absolute_error: 0.275409, mean_q: -0.225590, mean_eps: 0.020000
  254241/1700000: episode: 191, duration: 13.843s, episode steps: 2385, steps per second: 172, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.910 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.004650, mean_absolute_error: 0.265217, mean_q: -0.211864, mean_eps: 0.020000
  256622/1700000: episode: 192, duration: 13.799s, episode steps: 2381, steps per second: 173, episode reward: -18.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.781 [0.000, 5.000], mean observation: 105.541 [87.000, 236.000], loss: 0.004538, mean_absolute_error: 0.266087, mean_q: -0.210077, mean_eps: 0.020000
  258709/1700000: episode: 193, duration: 12.086s, episode steps: 2087, steps per second: 173, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.886 [0.000, 5.000], mean observation: 105.550 [87.000, 236.000], loss: 0.005174, mean_absolute_error: 0.275829, mean_q: -0.223610, mean_eps: 0.020000
  260694/1700000: episode: 194, duration: 11.551s, episode steps: 1985, steps per second: 172, episode reward: -17.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.547 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.004421, mean_absolute_error: 0.272982, mean_q: -0.226212, mean_eps: 0.020000
  262983/1700000: episode: 195, duration: 13.257s, episode steps: 2289, steps per second: 173, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.765 [0.000, 5.000], mean observation: 105.583 [87.000, 236.000], loss: 0.003972, mean_absolute_error: 0.289105, mean_q: -0.250517, mean_eps: 0.020000
  265032/1700000: episode: 196, duration: 11.883s, episode steps: 2049, steps per second: 172, episode reward: -13.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.830 [0.000, 5.000], mean observation: 105.567 [87.000, 236.000], loss: 0.004018, mean_absolute_error: 0.303868, mean_q: -0.264484, mean_eps: 0.020000
  267243/1700000: episode: 197, duration: 12.854s, episode steps: 2211, steps per second: 172, episode reward: -12.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.782 [0.000, 5.000], mean observation: 105.569 [87.000, 236.000], loss: 0.003573, mean_absolute_error: 0.303999, mean_q: -0.257956, mean_eps: 0.020000
  268943/1700000: episode: 198, duration: 10.078s, episode steps: 1700, steps per second: 169, episode reward: -18.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.941 [0.000, 5.000], mean observation: 105.551 [87.000, 236.000], loss: 0.003906, mean_absolute_error: 0.293565, mean_q: -0.231271, mean_eps: 0.020000
  270729/1700000: episode: 199, duration: 10.427s, episode steps: 1786, steps per second: 171, episode reward: -16.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.733 [0.000, 5.000], mean observation: 105.550 [87.000, 236.000], loss: 0.003950, mean_absolute_error: 0.298834, mean_q: -0.242595, mean_eps: 0.020000
  273134/1700000: episode: 200, duration: 13.951s, episode steps: 2405, steps per second: 172, episode reward: -9.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.654 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.004501, mean_absolute_error: 0.305368, mean_q: -0.242661, mean_eps: 0.020000
  275492/1700000: episode: 201, duration: 13.660s, episode steps: 2358, steps per second: 173, episode reward: -12.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.769 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.004375, mean_absolute_error: 0.299524, mean_q: -0.237122, mean_eps: 0.020000
  277294/1700000: episode: 202, duration: 10.457s, episode steps: 1802, steps per second: 172, episode reward: -16.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.511 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.004439, mean_absolute_error: 0.307296, mean_q: -0.247766, mean_eps: 0.020000
  279693/1700000: episode: 203, duration: 13.833s, episode steps: 2399, steps per second: 173, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.947 [0.000, 5.000], mean observation: 105.506 [87.000, 236.000], loss: 0.004724, mean_absolute_error: 0.307854, mean_q: -0.249694, mean_eps: 0.020000
  282292/1700000: episode: 204, duration: 15.068s, episode steps: 2599, steps per second: 172, episode reward: -14.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.702 [0.000, 5.000], mean observation: 105.502 [87.000, 236.000], loss: 0.004401, mean_absolute_error: 0.289116, mean_q: -0.231497, mean_eps: 0.020000
  284485/1700000: episode: 205, duration: 12.684s, episode steps: 2193, steps per second: 173, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.553 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.003695, mean_absolute_error: 0.275144, mean_q: -0.225990, mean_eps: 0.020000
  285928/1700000: episode: 206, duration: 8.351s, episode steps: 1443, steps per second: 173, episode reward: -17.000, mean reward: -0.012 [-1.000, 1.000], mean action: 2.414 [0.000, 5.000], mean observation: 105.467 [87.000, 236.000], loss: 0.003604, mean_absolute_error: 0.269957, mean_q: -0.223943, mean_eps: 0.020000
  288124/1700000: episode: 207, duration: 12.727s, episode steps: 2196, steps per second: 173, episode reward: -16.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.696 [0.000, 5.000], mean observation: 105.590 [87.000, 236.000], loss: 0.003504, mean_absolute_error: 0.265251, mean_q: -0.220649, mean_eps: 0.020000
  290429/1700000: episode: 208, duration: 13.358s, episode steps: 2305, steps per second: 173, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.619 [0.000, 5.000], mean observation: 105.519 [87.000, 236.000], loss: 0.003648, mean_absolute_error: 0.276265, mean_q: -0.232784, mean_eps: 0.020000
  292112/1700000: episode: 209, duration: 9.696s, episode steps: 1683, steps per second: 174, episode reward: -16.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.782 [0.000, 5.000], mean observation: 105.561 [87.000, 236.000], loss: 0.003615, mean_absolute_error: 0.286762, mean_q: -0.244744, mean_eps: 0.020000
  294547/1700000: episode: 210, duration: 14.172s, episode steps: 2435, steps per second: 172, episode reward: -11.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.881 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.003822, mean_absolute_error: 0.292134, mean_q: -0.247950, mean_eps: 0.020000
  296964/1700000: episode: 211, duration: 13.930s, episode steps: 2417, steps per second: 174, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.952 [0.000, 5.000], mean observation: 105.517 [87.000, 236.000], loss: 0.003801, mean_absolute_error: 0.296486, mean_q: -0.242207, mean_eps: 0.020000
  299386/1700000: episode: 212, duration: 14.056s, episode steps: 2422, steps per second: 172, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 3.048 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.003949, mean_absolute_error: 0.290791, mean_q: -0.228625, mean_eps: 0.020000
  301309/1700000: episode: 213, duration: 11.099s, episode steps: 1923, steps per second: 173, episode reward: -16.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.912 [0.000, 5.000], mean observation: 105.543 [87.000, 236.000], loss: 0.003611, mean_absolute_error: 0.281918, mean_q: -0.216898, mean_eps: 0.020000
  303517/1700000: episode: 214, duration: 12.791s, episode steps: 2208, steps per second: 173, episode reward: -16.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.752 [0.000, 5.000], mean observation: 105.550 [87.000, 236.000], loss: 0.004167, mean_absolute_error: 0.268611, mean_q: -0.198960, mean_eps: 0.020000
  305888/1700000: episode: 215, duration: 13.626s, episode steps: 2371, steps per second: 174, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.959 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.004241, mean_absolute_error: 0.275875, mean_q: -0.205427, mean_eps: 0.020000
  308883/1700000: episode: 216, duration: 17.333s, episode steps: 2995, steps per second: 173, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 3.095 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.003957, mean_absolute_error: 0.272406, mean_q: -0.211194, mean_eps: 0.020000
  311060/1700000: episode: 217, duration: 12.662s, episode steps: 2177, steps per second: 172, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.869 [0.000, 5.000], mean observation: 105.527 [87.000, 236.000], loss: 0.004364, mean_absolute_error: 0.265070, mean_q: -0.198323, mean_eps: 0.020000
  313180/1700000: episode: 218, duration: 12.312s, episode steps: 2120, steps per second: 172, episode reward: -13.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.966 [0.000, 5.000], mean observation: 105.546 [87.000, 236.000], loss: 0.004423, mean_absolute_error: 0.259415, mean_q: -0.177396, mean_eps: 0.020000
  315126/1700000: episode: 219, duration: 11.394s, episode steps: 1946, steps per second: 171, episode reward: -15.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.967 [0.000, 5.000], mean observation: 105.601 [87.000, 236.000], loss: 0.004289, mean_absolute_error: 0.253683, mean_q: -0.167250, mean_eps: 0.020000
  317118/1700000: episode: 220, duration: 11.477s, episode steps: 1992, steps per second: 174, episode reward: -15.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.734 [0.000, 5.000], mean observation: 105.576 [87.000, 236.000], loss: 0.004467, mean_absolute_error: 0.251519, mean_q: -0.163454, mean_eps: 0.020000
  320096/1700000: episode: 221, duration: 17.285s, episode steps: 2978, steps per second: 172, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.800 [0.000, 5.000], mean observation: 105.614 [87.000, 236.000], loss: 0.004656, mean_absolute_error: 0.254830, mean_q: -0.146668, mean_eps: 0.020000
  321859/1700000: episode: 222, duration: 10.401s, episode steps: 1763, steps per second: 170, episode reward: -17.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.738 [0.000, 5.000], mean observation: 105.609 [87.000, 236.000], loss: 0.004746, mean_absolute_error: 0.251333, mean_q: -0.137893, mean_eps: 0.020000
  324684/1700000: episode: 223, duration: 16.635s, episode steps: 2825, steps per second: 170, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.840 [0.000, 5.000], mean observation: 105.563 [87.000, 236.000], loss: 0.004440, mean_absolute_error: 0.247775, mean_q: -0.132101, mean_eps: 0.020000
  327700/1700000: episode: 224, duration: 17.536s, episode steps: 3016, steps per second: 172, episode reward: -11.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.755 [0.000, 5.000], mean observation: 105.572 [87.000, 236.000], loss: 0.004207, mean_absolute_error: 0.245717, mean_q: -0.127667, mean_eps: 0.020000
  331025/1700000: episode: 225, duration: 19.306s, episode steps: 3325, steps per second: 172, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.625 [0.000, 5.000], mean observation: 105.593 [87.000, 236.000], loss: 0.004108, mean_absolute_error: 0.238783, mean_q: -0.128455, mean_eps: 0.020000
  333570/1700000: episode: 226, duration: 14.744s, episode steps: 2545, steps per second: 173, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.792 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.004514, mean_absolute_error: 0.226687, mean_q: -0.109089, mean_eps: 0.020000
  335586/1700000: episode: 227, duration: 11.759s, episode steps: 2016, steps per second: 171, episode reward: -16.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.898 [0.000, 5.000], mean observation: 105.574 [87.000, 236.000], loss: 0.004970, mean_absolute_error: 0.228735, mean_q: -0.106080, mean_eps: 0.020000
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338222/1700000: episode: 228, duration: 15.338s, episode steps: 2636, steps per second: 172, episode reward: -12.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.658 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.004607, mean_absolute_error: 0.212101, mean_q: -0.097450, mean_eps: 0.020000
340251/1700000: episode: 229, duration: 11.820s, episode steps: 2029, steps per second: 172, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.754 [0.000, 5.000], mean observation: 105.511 [87.000, 236.000], loss: 0.004024, mean_absolute_error: 0.205641, mean_q: -0.083287, mean_eps: 0.020000
342629/1700000: episode: 230, duration: 13.877s, episode steps: 2378, steps per second: 171, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.559 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.004278, mean_absolute_error: 0.214945, mean_q: -0.105657, mean_eps: 0.020000
345603/1700000: episode: 231, duration: 17.214s, episode steps: 2974, steps per second: 173, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.770 [0.000, 5.000], mean observation: 105.594 [87.000, 236.000], loss: 0.004402, mean_absolute_error: 0.220282, mean_q: -0.115769, mean_eps: 0.020000
348216/1700000: episode: 232, duration: 15.194s, episode steps: 2613, steps per second: 172, episode reward: -17.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.889 [0.000, 5.000], mean observation: 105.586 [87.000, 236.000], loss: 0.004282, mean_absolute_error: 0.205637, mean_q: -0.106712, mean_eps: 0.020000
352139/1700000: episode: 233, duration: 22.798s, episode steps: 3923, steps per second: 172, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.761 [0.000, 5.000], mean observation: 105.635 [87.000, 236.000], loss: 0.004362, mean_absolute_error: 0.197339, mean_q: -0.101072, mean_eps: 0.020000
355635/1700000: episode: 234, duration: 20.267s, episode steps: 3496, steps per second: 172, episode reward: -8.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.905 [0.000, 5.000], mean observation: 105.583 [87.000, 236.000], loss: 0.004552, mean_absolute_error: 0.185691, mean_q: -0.088141, mean_eps: 0.020000
358219/1700000: episode: 235, duration: 14.939s, episode steps: 2584, steps per second: 173, episode reward: -14.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.803 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.004170, mean_absolute_error: 0.183601, mean_q: -0.091745, mean_eps: 0.020000
360459/1700000: episode: 236, duration: 12.980s, episode steps: 2240, steps per second: 173, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.555 [0.000, 5.000], mean observation: 105.569 [87.000, 236.000], loss: 0.004302, mean_absolute_error: 0.192190, mean_q: -0.102566, mean_eps: 0.020000
363279/1700000: episode: 237, duration: 16.312s, episode steps: 2820, steps per second: 173, episode reward: -15.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.786 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.003654, mean_absolute_error: 0.194080, mean_q: -0.111253, mean_eps: 0.020000
365611/1700000: episode: 238, duration: 13.547s, episode steps: 2332, steps per second: 172, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.663 [0.000, 5.000], mean observation: 105.533 [87.000, 236.000], loss: 0.003886, mean_absolute_error: 0.204331, mean_q: -0.131821, mean_eps: 0.020000
367882/1700000: episode: 239, duration: 13.155s, episode steps: 2271, steps per second: 173, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.700 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.004098, mean_absolute_error: 0.204494, mean_q: -0.131088, mean_eps: 0.020000
369778/1700000: episode: 240, duration: 10.987s, episode steps: 1896, steps per second: 173, episode reward: -20.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.354 [0.000, 5.000], mean observation: 105.496 [87.000, 236.000], loss: 0.004168, mean_absolute_error: 0.202738, mean_q: -0.129016, mean_eps: 0.020000
371639/1700000: episode: 241, duration: 10.830s, episode steps: 1861, steps per second: 172, episode reward: -15.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.655 [0.000, 5.000], mean observation: 105.508 [87.000, 236.000], loss: 0.003697, mean_absolute_error: 0.204923, mean_q: -0.142740, mean_eps: 0.020000
373897/1700000: episode: 242, duration: 13.083s, episode steps: 2258, steps per second: 173, episode reward: -17.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.640 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.003665, mean_absolute_error: 0.210808, mean_q: -0.147389, mean_eps: 0.020000
377312/1700000: episode: 243, duration: 20.173s, episode steps: 3415, steps per second: 169, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.618 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.003927, mean_absolute_error: 0.195766, mean_q: -0.132718, mean_eps: 0.020000
379383/1700000: episode: 244, duration: 12.136s, episode steps: 2071, steps per second: 171, episode reward: -19.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.838 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.004037, mean_absolute_error: 0.190651, mean_q: -0.123638, mean_eps: 0.020000
381763/1700000: episode: 245, duration: 13.750s, episode steps: 2380, steps per second: 173, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.663 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.004046, mean_absolute_error: 0.187163, mean_q: -0.117866, mean_eps: 0.020000
384176/1700000: episode: 246, duration: 13.928s, episode steps: 2413, steps per second: 173, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.376 [0.000, 5.000], mean observation: 105.617 [87.000, 236.000], loss: 0.003668, mean_absolute_error: 0.186709, mean_q: -0.109833, mean_eps: 0.020000
387381/1700000: episode: 247, duration: 18.617s, episode steps: 3205, steps per second: 172, episode reward: -7.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.400 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.003637, mean_absolute_error: 0.185157, mean_q: -0.088045, mean_eps: 0.020000
390505/1700000: episode: 248, duration: 18.051s, episode steps: 3124, steps per second: 173, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.423 [0.000, 5.000], mean observation: 105.573 [87.000, 236.000], loss: 0.004017, mean_absolute_error: 0.193671, mean_q: -0.081538, mean_eps: 0.020000
393370/1700000: episode: 249, duration: 16.655s, episode steps: 2865, steps per second: 172, episode reward: -14.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.511 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.004514, mean_absolute_error: 0.196781, mean_q: -0.066704, mean_eps: 0.020000
396256/1700000: episode: 250, duration: 16.663s, episode steps: 2886, steps per second: 173, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.353 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.004101, mean_absolute_error: 0.198989, mean_q: -0.073243, mean_eps: 0.020000
399103/1700000: episode: 251, duration: 16.418s, episode steps: 2847, steps per second: 173, episode reward: -10.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.555 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.003833, mean_absolute_error: 0.190580, mean_q: -0.077910, mean_eps: 0.020000
401145/1700000: episode: 252, duration: 12.161s, episode steps: 2042, steps per second: 168, episode reward: -17.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.508 [0.000, 5.000], mean observation: 105.567 [87.000, 236.000], loss: 0.003582, mean_absolute_error: 0.182171, mean_q: -0.075409, mean_eps: 0.020000
403549/1700000: episode: 253, duration: 14.362s, episode steps: 2404, steps per second: 167, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.306 [0.000, 5.000], mean observation: 105.608 [87.000, 236.000], loss: 0.003642, mean_absolute_error: 0.186002, mean_q: -0.084559, mean_eps: 0.020000
406195/1700000: episode: 254, duration: 15.912s, episode steps: 2646, steps per second: 166, episode reward: -14.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.291 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.003637, mean_absolute_error: 0.185060, mean_q: -0.073468, mean_eps: 0.020000
407674/1700000: episode: 255, duration: 8.883s, episode steps: 1479, steps per second: 166, episode reward: -17.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.316 [0.000, 5.000], mean observation: 105.505 [87.000, 236.000], loss: 0.004210, mean_absolute_error: 0.185668, mean_q: -0.066448, mean_eps: 0.020000
408830/1700000: episode: 256, duration: 6.939s, episode steps: 1156, steps per second: 167, episode reward: -19.000, mean reward: -0.016 [-1.000, 1.000], mean action: 2.119 [0.000, 5.000], mean observation: 105.512 [87.000, 236.000], loss: 0.004362, mean_absolute_error: 0.193691, mean_q: -0.083356, mean_eps: 0.020000
410943/1700000: episode: 257, duration: 12.659s, episode steps: 2113, steps per second: 167, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.445 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.004247, mean_absolute_error: 0.199380, mean_q: -0.090833, mean_eps: 0.020000
413535/1700000: episode: 258, duration: 15.623s, episode steps: 2592, steps per second: 166, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.497 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.004287, mean_absolute_error: 0.198014, mean_q: -0.087016, mean_eps: 0.020000
416160/1700000: episode: 259, duration: 15.733s, episode steps: 2625, steps per second: 167, episode reward: -11.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.330 [0.000, 5.000], mean observation: 105.566 [87.000, 236.000], loss: 0.003974, mean_absolute_error: 0.199292, mean_q: -0.089594, mean_eps: 0.020000
419134/1700000: episode: 260, duration: 17.848s, episode steps: 2974, steps per second: 167, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.415 [0.000, 5.000], mean observation: 105.624 [87.000, 236.000], loss: 0.003927, mean_absolute_error: 0.208275, mean_q: -0.106234, mean_eps: 0.020000
421492/1700000: episode: 261, duration: 14.181s, episode steps: 2358, steps per second: 166, episode reward: -16.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.386 [0.000, 5.000], mean observation: 105.553 [87.000, 236.000], loss: 0.004107, mean_absolute_error: 0.205641, mean_q: -0.096842, mean_eps: 0.020000
424909/1700000: episode: 262, duration: 20.558s, episode steps: 3417, steps per second: 166, episode reward: -13.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.315 [0.000, 5.000], mean observation: 105.550 [87.000, 236.000], loss: 0.004031, mean_absolute_error: 0.204740, mean_q: -0.089010, mean_eps: 0.020000
427991/1700000: episode: 263, duration: 18.830s, episode steps: 3082, steps per second: 164, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.372 [0.000, 5.000], mean observation: 105.562 [87.000, 236.000], loss: 0.004227, mean_absolute_error: 0.201171, mean_q: -0.099566, mean_eps: 0.020000
430074/1700000: episode: 264, duration: 12.166s, episode steps: 2083, steps per second: 171, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.691 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: 0.003719, mean_absolute_error: 0.195139, mean_q: -0.100350, mean_eps: 0.020000
432008/1700000: episode: 265, duration: 11.308s, episode steps: 1934, steps per second: 171, episode reward: -15.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.534 [0.000, 5.000], mean observation: 105.571 [87.000, 236.000], loss: 0.004199, mean_absolute_error: 0.197148, mean_q: -0.099886, mean_eps: 0.020000
435156/1700000: episode: 266, duration: 18.216s, episode steps: 3148, steps per second: 173, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.595 [0.000, 5.000], mean observation: 105.521 [87.000, 236.000], loss: 0.003830, mean_absolute_error: 0.202337, mean_q: -0.104262, mean_eps: 0.020000
437632/1700000: episode: 267, duration: 14.381s, episode steps: 2476, steps per second: 172, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.603 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.003748, mean_absolute_error: 0.194420, mean_q: -0.094487, mean_eps: 0.020000
441770/1700000: episode: 268, duration: 23.927s, episode steps: 4138, steps per second: 173, episode reward: -4.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.654 [0.000, 5.000], mean observation: 105.591 [87.000, 236.000], loss: 0.003970, mean_absolute_error: 0.197150, mean_q: -0.094510, mean_eps: 0.020000
445190/1700000: episode: 269, duration: 19.871s, episode steps: 3420, steps per second: 172, episode reward: -8.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.499 [0.000, 5.000], mean observation: 105.636 [87.000, 236.000], loss: 0.003867, mean_absolute_error: 0.186477, mean_q: -0.080044, mean_eps: 0.020000
447829/1700000: episode: 270, duration: 15.299s, episode steps: 2639, steps per second: 172, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.501 [0.000, 5.000], mean observation: 105.594 [87.000, 236.000], loss: 0.004027, mean_absolute_error: 0.190635, mean_q: -0.085066, mean_eps: 0.020000
450201/1700000: episode: 271, duration: 13.634s, episode steps: 2372, steps per second: 174, episode reward: -17.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.358 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.003766, mean_absolute_error: 0.181600, mean_q: -0.071177, mean_eps: 0.020000
453390/1700000: episode: 272, duration: 18.424s, episode steps: 3189, steps per second: 173, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.350 [0.000, 5.000], mean observation: 105.619 [87.000, 236.000], loss: 0.003246, mean_absolute_error: 0.174326, mean_q: -0.058747, mean_eps: 0.020000
455195/1700000: episode: 273, duration: 10.459s, episode steps: 1805, steps per second: 173, episode reward: -20.000, mean reward: -0.011 [-1.000, 1.000], mean action: 2.530 [0.000, 5.000], mean observation: 105.571 [87.000, 236.000], loss: 0.003371, mean_absolute_error: 0.173275, mean_q: -0.053555, mean_eps: 0.020000
457861/1700000: episode: 274, duration: 15.376s, episode steps: 2666, steps per second: 173, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.291 [0.000, 5.000], mean observation: 105.551 [87.000, 236.000], loss: 0.003979, mean_absolute_error: 0.176817, mean_q: -0.062587, mean_eps: 0.020000
460866/1700000: episode: 275, duration: 17.354s, episode steps: 3005, steps per second: 173, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.354 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.003653, mean_absolute_error: 0.179225, mean_q: -0.073134, mean_eps: 0.020000
464045/1700000: episode: 276, duration: 18.303s, episode steps: 3179, steps per second: 174, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.324 [0.000, 5.000], mean observation: 105.617 [87.000, 236.000], loss: 0.003801, mean_absolute_error: 0.182988, mean_q: -0.077419, mean_eps: 0.020000
466768/1700000: episode: 277, duration: 15.680s, episode steps: 2723, steps per second: 174, episode reward: -16.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.354 [0.000, 5.000], mean observation: 105.526 [87.000, 236.000], loss: 0.003726, mean_absolute_error: 0.176638, mean_q: -0.068107, mean_eps: 0.020000
469879/1700000: episode: 278, duration: 17.943s, episode steps: 3111, steps per second: 173, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.256 [0.000, 5.000], mean observation: 105.570 [87.000, 236.000], loss: 0.003694, mean_absolute_error: 0.181071, mean_q: -0.081270, mean_eps: 0.020000
473576/1700000: episode: 279, duration: 21.276s, episode steps: 3697, steps per second: 174, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.452 [0.000, 5.000], mean observation: 105.614 [87.000, 236.000], loss: 0.003470, mean_absolute_error: 0.171530, mean_q: -0.058389, mean_eps: 0.020000
476634/1700000: episode: 280, duration: 17.718s, episode steps: 3058, steps per second: 173, episode reward: -15.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.556 [0.000, 5.000], mean observation: 105.572 [87.000, 236.000], loss: 0.003041, mean_absolute_error: 0.169622, mean_q: -0.039530, mean_eps: 0.020000
479520/1700000: episode: 281, duration: 16.604s, episode steps: 2886, steps per second: 174, episode reward: -16.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.149 [0.000, 5.000], mean observation: 105.563 [87.000, 236.000], loss: 0.003336, mean_absolute_error: 0.167992, mean_q: -0.036555, mean_eps: 0.020000
483205/1700000: episode: 282, duration: 21.635s, episode steps: 3685, steps per second: 170, episode reward: -8.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.199 [0.000, 5.000], mean observation: 105.583 [87.000, 236.000], loss: 0.002715, mean_absolute_error: 0.162008, mean_q: -0.034665, mean_eps: 0.020000
484523/1700000: episode: 283, duration: 7.579s, episode steps: 1318, steps per second: 174, episode reward: -16.000, mean reward: -0.012 [-1.000, 1.000], mean action: 2.574 [0.000, 5.000], mean observation: 105.479 [87.000, 236.000], loss: 0.002740, mean_absolute_error: 0.163301, mean_q: -0.039289, mean_eps: 0.020000
486549/1700000: episode: 284, duration: 11.679s, episode steps: 2026, steps per second: 173, episode reward: -18.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.445 [0.000, 5.000], mean observation: 105.528 [87.000, 236.000], loss: 0.002652, mean_absolute_error: 0.167041, mean_q: -0.044353, mean_eps: 0.020000
488904/1700000: episode: 285, duration: 13.658s, episode steps: 2355, steps per second: 172, episode reward: -18.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.361 [0.000, 5.000], mean observation: 105.590 [87.000, 236.000], loss: 0.002783, mean_absolute_error: 0.174715, mean_q: -0.054576, mean_eps: 0.020000
492418/1700000: episode: 286, duration: 20.231s, episode steps: 3514, steps per second: 174, episode reward: -11.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.385 [0.000, 5.000], mean observation: 105.578 [87.000, 236.000], loss: 0.002939, mean_absolute_error: 0.171710, mean_q: -0.067124, mean_eps: 0.020000
495610/1700000: episode: 287, duration: 18.450s, episode steps: 3192, steps per second: 173, episode reward: -14.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.332 [0.000, 5.000], mean observation: 105.539 [87.000, 236.000], loss: 0.002864, mean_absolute_error: 0.178252, mean_q: -0.082050, mean_eps: 0.020000
498387/1700000: episode: 288, duration: 16.086s, episode steps: 2777, steps per second: 173, episode reward: -16.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.278 [0.000, 5.000], mean observation: 105.506 [87.000, 236.000], loss: 0.002651, mean_absolute_error: 0.189991, mean_q: -0.095122, mean_eps: 0.020000
500623/1700000: episode: 289, duration: 12.909s, episode steps: 2236, steps per second: 173, episode reward: -20.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.513 [0.000, 5.000], mean observation: 105.439 [87.000, 236.000], loss: 0.002634, mean_absolute_error: 0.193578, mean_q: -0.099103, mean_eps: 0.020000
503587/1700000: episode: 290, duration: 17.173s, episode steps: 2964, steps per second: 173, episode reward: -13.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.395 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.002748, mean_absolute_error: 0.205258, mean_q: -0.110465, mean_eps: 0.020000
506450/1700000: episode: 291, duration: 16.499s, episode steps: 2863, steps per second: 174, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.501 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.002531, mean_absolute_error: 0.201973, mean_q: -0.102165, mean_eps: 0.020000
509830/1700000: episode: 292, duration: 19.482s, episode steps: 3380, steps per second: 173, episode reward: -11.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.678 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.002818, mean_absolute_error: 0.198333, mean_q: -0.112949, mean_eps: 0.020000
512935/1700000: episode: 293, duration: 17.840s, episode steps: 3105, steps per second: 174, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.518 [0.000, 5.000], mean observation: 105.545 [87.000, 236.000], loss: 0.003210, mean_absolute_error: 0.197557, mean_q: -0.116870, mean_eps: 0.020000
515475/1700000: episode: 294, duration: 14.726s, episode steps: 2540, steps per second: 172, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.331 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.003405, mean_absolute_error: 0.208856, mean_q: -0.120200, mean_eps: 0.020000
518649/1700000: episode: 295, duration: 18.346s, episode steps: 3174, steps per second: 173, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.499 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.003383, mean_absolute_error: 0.217785, mean_q: -0.123329, mean_eps: 0.020000
522083/1700000: episode: 296, duration: 19.894s, episode steps: 3434, steps per second: 173, episode reward: -11.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.501 [0.000, 5.000], mean observation: 105.550 [87.000, 236.000], loss: 0.003481, mean_absolute_error: 0.224185, mean_q: -0.126665, mean_eps: 0.020000
525487/1700000: episode: 297, duration: 19.676s, episode steps: 3404, steps per second: 173, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.533 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.003447, mean_absolute_error: 0.220936, mean_q: -0.097303, mean_eps: 0.020000
527446/1700000: episode: 298, duration: 11.244s, episode steps: 1959, steps per second: 174, episode reward: -13.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.605 [0.000, 5.000], mean observation: 105.539 [87.000, 236.000], loss: 0.003509, mean_absolute_error: 0.211454, mean_q: -0.103798, mean_eps: 0.020000
529614/1700000: episode: 299, duration: 12.592s, episode steps: 2168, steps per second: 172, episode reward: -16.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.490 [0.000, 5.000], mean observation: 105.526 [87.000, 236.000], loss: 0.003595, mean_absolute_error: 0.204092, mean_q: -0.085856, mean_eps: 0.020000
531111/1700000: episode: 300, duration: 8.691s, episode steps: 1497, steps per second: 172, episode reward: -21.000, mean reward: -0.014 [-1.000, 0.000], mean action: 2.540 [0.000, 5.000], mean observation: 105.614 [87.000, 236.000], loss: 0.003343, mean_absolute_error: 0.206329, mean_q: -0.087232, mean_eps: 0.020000
532914/1700000: episode: 301, duration: 10.382s, episode steps: 1803, steps per second: 174, episode reward: -17.000, mean reward: -0.009 [-1.000, 1.000], mean action: 2.574 [0.000, 5.000], mean observation: 105.550 [87.000, 236.000], loss: 0.003876, mean_absolute_error: 0.210642, mean_q: -0.103204, mean_eps: 0.020000
534947/1700000: episode: 302, duration: 12.072s, episode steps: 2033, steps per second: 168, episode reward: -17.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.225 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.004231, mean_absolute_error: 0.213932, mean_q: -0.107359, mean_eps: 0.020000
538086/1700000: episode: 303, duration: 18.139s, episode steps: 3139, steps per second: 173, episode reward: -16.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.144 [0.000, 5.000], mean observation: 105.583 [87.000, 236.000], loss: 0.004054, mean_absolute_error: 0.220407, mean_q: -0.114303, mean_eps: 0.020000
540722/1700000: episode: 304, duration: 15.279s, episode steps: 2636, steps per second: 173, episode reward: -17.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.093 [0.000, 5.000], mean observation: 105.589 [87.000, 236.000], loss: 0.004129, mean_absolute_error: 0.222248, mean_q: -0.120119, mean_eps: 0.020000
544424/1700000: episode: 305, duration: 21.411s, episode steps: 3702, steps per second: 173, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.132 [0.000, 5.000], mean observation: 105.574 [87.000, 236.000], loss: 0.004632, mean_absolute_error: 0.226767, mean_q: -0.117460, mean_eps: 0.020000
547132/1700000: episode: 306, duration: 15.722s, episode steps: 2708, steps per second: 172, episode reward: -14.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.313 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.004223, mean_absolute_error: 0.226337, mean_q: -0.126096, mean_eps: 0.020000
550190/1700000: episode: 307, duration: 17.614s, episode steps: 3058, steps per second: 174, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.177 [0.000, 5.000], mean observation: 105.587 [87.000, 236.000], loss: 0.003685, mean_absolute_error: 0.214665, mean_q: -0.114639, mean_eps: 0.020000
553343/1700000: episode: 308, duration: 18.193s, episode steps: 3153, steps per second: 173, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.186 [0.000, 5.000], mean observation: 105.571 [87.000, 236.000], loss: 0.003227, mean_absolute_error: 0.206969, mean_q: -0.097083, mean_eps: 0.020000
555882/1700000: episode: 309, duration: 14.719s, episode steps: 2539, steps per second: 173, episode reward: -12.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.161 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.003243, mean_absolute_error: 0.192821, mean_q: -0.078063, mean_eps: 0.020000
558308/1700000: episode: 310, duration: 14.057s, episode steps: 2426, steps per second: 173, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.282 [0.000, 5.000], mean observation: 105.539 [87.000, 236.000], loss: 0.003587, mean_absolute_error: 0.185147, mean_q: -0.063649, mean_eps: 0.020000
561421/1700000: episode: 311, duration: 18.008s, episode steps: 3113, steps per second: 173, episode reward: -11.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.390 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.003902, mean_absolute_error: 0.193564, mean_q: -0.074662, mean_eps: 0.020000
564130/1700000: episode: 312, duration: 15.657s, episode steps: 2709, steps per second: 173, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.417 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.003963, mean_absolute_error: 0.203462, mean_q: -0.074731, mean_eps: 0.020000
566629/1700000: episode: 313, duration: 14.481s, episode steps: 2499, steps per second: 173, episode reward: -16.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.525 [0.000, 5.000], mean observation: 105.520 [87.000, 236.000], loss: 0.003826, mean_absolute_error: 0.202242, mean_q: -0.067748, mean_eps: 0.020000
569563/1700000: episode: 314, duration: 16.931s, episode steps: 2934, steps per second: 173, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.590 [0.000, 5.000], mean observation: 105.586 [87.000, 236.000], loss: 0.003686, mean_absolute_error: 0.199268, mean_q: -0.078504, mean_eps: 0.020000
571960/1700000: episode: 315, duration: 13.967s, episode steps: 2397, steps per second: 172, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.514 [0.000, 5.000], mean observation: 105.569 [87.000, 236.000], loss: 0.003787, mean_absolute_error: 0.190784, mean_q: -0.067066, mean_eps: 0.020000
574737/1700000: episode: 316, duration: 16.115s, episode steps: 2777, steps per second: 172, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.559 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.003540, mean_absolute_error: 0.186647, mean_q: -0.065272, mean_eps: 0.020000
577402/1700000: episode: 317, duration: 15.497s, episode steps: 2665, steps per second: 172, episode reward: -7.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.573 [0.000, 5.000], mean observation: 105.616 [87.000, 236.000], loss: 0.003631, mean_absolute_error: 0.182247, mean_q: -0.046415, mean_eps: 0.020000
580595/1700000: episode: 318, duration: 18.444s, episode steps: 3193, steps per second: 173, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.466 [0.000, 5.000], mean observation: 105.605 [87.000, 236.000], loss: 0.003646, mean_absolute_error: 0.175312, mean_q: -0.020041, mean_eps: 0.020000
583382/1700000: episode: 319, duration: 16.172s, episode steps: 2787, steps per second: 172, episode reward: -15.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.629 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.003791, mean_absolute_error: 0.173159, mean_q: -0.016145, mean_eps: 0.020000
585469/1700000: episode: 320, duration: 12.132s, episode steps: 2087, steps per second: 172, episode reward: -15.000, mean reward: -0.007 [-1.000, 1.000], mean action: 2.445 [0.000, 5.000], mean observation: 105.567 [87.000, 236.000], loss: 0.003685, mean_absolute_error: 0.176809, mean_q: -0.024642, mean_eps: 0.020000
587791/1700000: episode: 321, duration: 13.708s, episode steps: 2322, steps per second: 169, episode reward: -18.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.521 [0.000, 5.000], mean observation: 105.605 [87.000, 236.000], loss: 0.004031, mean_absolute_error: 0.184265, mean_q: -0.042976, mean_eps: 0.020000
590535/1700000: episode: 322, duration: 15.964s, episode steps: 2744, steps per second: 172, episode reward: -11.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.458 [0.000, 5.000], mean observation: 105.552 [87.000, 236.000], loss: 0.004031, mean_absolute_error: 0.191230, mean_q: -0.057089, mean_eps: 0.020000
592676/1700000: episode: 323, duration: 12.394s, episode steps: 2141, steps per second: 173, episode reward: -18.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.639 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.003842, mean_absolute_error: 0.191752, mean_q: -0.053574, mean_eps: 0.020000
595510/1700000: episode: 324, duration: 16.427s, episode steps: 2834, steps per second: 173, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.438 [0.000, 5.000], mean observation: 105.566 [87.000, 236.000], loss: 0.004054, mean_absolute_error: 0.187346, mean_q: -0.042376, mean_eps: 0.020000
598255/1700000: episode: 325, duration: 15.903s, episode steps: 2745, steps per second: 173, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.442 [0.000, 5.000], mean observation: 105.569 [87.000, 236.000], loss: 0.003674, mean_absolute_error: 0.182890, mean_q: -0.029328, mean_eps: 0.020000
601387/1700000: episode: 326, duration: 18.161s, episode steps: 3132, steps per second: 172, episode reward: -7.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.454 [0.000, 5.000], mean observation: 105.574 [87.000, 236.000], loss: 0.003373, mean_absolute_error: 0.179557, mean_q: -0.017574, mean_eps: 0.020000
604432/1700000: episode: 327, duration: 17.617s, episode steps: 3045, steps per second: 173, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.391 [0.000, 5.000], mean observation: 105.600 [87.000, 236.000], loss: 0.003196, mean_absolute_error: 0.183918, mean_q: 0.004200, mean_eps: 0.020000
607405/1700000: episode: 328, duration: 17.263s, episode steps: 2973, steps per second: 172, episode reward: -14.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.454 [0.000, 5.000], mean observation: 105.601 [87.000, 236.000], loss: 0.003455, mean_absolute_error: 0.197081, mean_q: 0.021343, mean_eps: 0.020000
609995/1700000: episode: 329, duration: 14.934s, episode steps: 2590, steps per second: 173, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.733 [0.000, 5.000], mean observation: 105.589 [87.000, 236.000], loss: 0.003577, mean_absolute_error: 0.197140, mean_q: 0.011956, mean_eps: 0.020000
612551/1700000: episode: 330, duration: 14.884s, episode steps: 2556, steps per second: 172, episode reward: -9.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.476 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.003588, mean_absolute_error: 0.192744, mean_q: 0.008569, mean_eps: 0.020000
615630/1700000: episode: 331, duration: 17.775s, episode steps: 3079, steps per second: 173, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.367 [0.000, 5.000], mean observation: 105.604 [87.000, 236.000], loss: 0.003091, mean_absolute_error: 0.183128, mean_q: 0.001952, mean_eps: 0.020000
617879/1700000: episode: 332, duration: 13.090s, episode steps: 2249, steps per second: 172, episode reward: -18.000, mean reward: -0.008 [-1.000, 1.000], mean action: 2.565 [0.000, 5.000], mean observation: 105.525 [87.000, 236.000], loss: 0.003661, mean_absolute_error: 0.185833, mean_q: 0.000170, mean_eps: 0.020000
620215/1700000: episode: 333, duration: 13.528s, episode steps: 2336, steps per second: 173, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.408 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.003649, mean_absolute_error: 0.190562, mean_q: -0.007894, mean_eps: 0.020000
622930/1700000: episode: 334, duration: 15.714s, episode steps: 2715, steps per second: 173, episode reward: -15.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.317 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.003422, mean_absolute_error: 0.195415, mean_q: -0.017763, mean_eps: 0.020000
626913/1700000: episode: 335, duration: 23.104s, episode steps: 3983, steps per second: 172, episode reward: -8.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.345 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.003744, mean_absolute_error: 0.200530, mean_q: -0.031565, mean_eps: 0.020000
629846/1700000: episode: 336, duration: 17.004s, episode steps: 2933, steps per second: 172, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.335 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.003283, mean_absolute_error: 0.193421, mean_q: -0.040054, mean_eps: 0.020000
633777/1700000: episode: 337, duration: 22.863s, episode steps: 3931, steps per second: 172, episode reward: -3.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.226 [0.000, 5.000], mean observation: 105.599 [87.000, 236.000], loss: 0.003026, mean_absolute_error: 0.182356, mean_q: -0.037629, mean_eps: 0.020000
635554/1700000: episode: 338, duration: 10.672s, episode steps: 1777, steps per second: 167, episode reward: -18.000, mean reward: -0.010 [-1.000, 1.000], mean action: 2.618 [0.000, 5.000], mean observation: 105.516 [87.000, 236.000], loss: 0.002892, mean_absolute_error: 0.178146, mean_q: -0.029824, mean_eps: 0.020000
638917/1700000: episode: 339, duration: 19.742s, episode steps: 3363, steps per second: 170, episode reward: -7.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.489 [0.000, 5.000], mean observation: 105.600 [87.000, 236.000], loss: 0.002793, mean_absolute_error: 0.174530, mean_q: -0.028181, mean_eps: 0.020000
642373/1700000: episode: 340, duration: 20.424s, episode steps: 3456, steps per second: 169, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.357 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.002881, mean_absolute_error: 0.177709, mean_q: -0.025821, mean_eps: 0.020000
645263/1700000: episode: 341, duration: 16.737s, episode steps: 2890, steps per second: 173, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.489 [0.000, 5.000], mean observation: 105.599 [87.000, 236.000], loss: 0.002867, mean_absolute_error: 0.173914, mean_q: -0.010542, mean_eps: 0.020000
648447/1700000: episode: 342, duration: 18.470s, episode steps: 3184, steps per second: 172, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.521 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.002990, mean_absolute_error: 0.176114, mean_q: 0.005567, mean_eps: 0.020000
652122/1700000: episode: 343, duration: 21.525s, episode steps: 3675, steps per second: 171, episode reward: -1.000, mean reward: -0.000 [-1.000, 1.000], mean action: 2.457 [0.000, 5.000], mean observation: 105.638 [87.000, 236.000], loss: 0.002979, mean_absolute_error: 0.171635, mean_q: 0.023134, mean_eps: 0.020000
654927/1700000: episode: 344, duration: 16.337s, episode steps: 2805, steps per second: 172, episode reward: -11.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.468 [0.000, 5.000], mean observation: 105.587 [87.000, 236.000], loss: 0.003242, mean_absolute_error: 0.181058, mean_q: 0.024258, mean_eps: 0.020000
657849/1700000: episode: 345, duration: 16.976s, episode steps: 2922, steps per second: 172, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.393 [0.000, 5.000], mean observation: 105.588 [87.000, 236.000], loss: 0.003368, mean_absolute_error: 0.191169, mean_q: 0.028234, mean_eps: 0.020000
660739/1700000: episode: 346, duration: 16.778s, episode steps: 2890, steps per second: 172, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.328 [0.000, 5.000], mean observation: 105.599 [87.000, 236.000], loss: 0.003291, mean_absolute_error: 0.189928, mean_q: 0.025261, mean_eps: 0.020000
663935/1700000: episode: 347, duration: 18.469s, episode steps: 3196, steps per second: 173, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.395 [0.000, 5.000], mean observation: 105.567 [87.000, 236.000], loss: 0.003832, mean_absolute_error: 0.187655, mean_q: 0.006514, mean_eps: 0.020000
666752/1700000: episode: 348, duration: 16.338s, episode steps: 2817, steps per second: 172, episode reward: -10.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.310 [0.000, 5.000], mean observation: 105.563 [87.000, 236.000], loss: 0.003758, mean_absolute_error: 0.177859, mean_q: 0.000706, mean_eps: 0.020000
669000/1700000: episode: 349, duration: 13.012s, episode steps: 2248, steps per second: 173, episode reward: -12.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.378 [0.000, 5.000], mean observation: 105.569 [87.000, 236.000], loss: 0.003948, mean_absolute_error: 0.181510, mean_q: -0.004308, mean_eps: 0.020000
672181/1700000: episode: 350, duration: 18.373s, episode steps: 3181, steps per second: 173, episode reward: -5.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.295 [0.000, 5.000], mean observation: 105.587 [87.000, 236.000], loss: 0.003832, mean_absolute_error: 0.185402, mean_q: -0.006131, mean_eps: 0.020000
675375/1700000: episode: 351, duration: 18.458s, episode steps: 3194, steps per second: 173, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.330 [0.000, 5.000], mean observation: 105.606 [87.000, 236.000], loss: 0.003573, mean_absolute_error: 0.188875, mean_q: 0.001477, mean_eps: 0.020000
678472/1700000: episode: 352, duration: 17.848s, episode steps: 3097, steps per second: 174, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.479 [0.000, 5.000], mean observation: 105.592 [87.000, 236.000], loss: 0.003645, mean_absolute_error: 0.191958, mean_q: -0.004061, mean_eps: 0.020000
681827/1700000: episode: 353, duration: 19.480s, episode steps: 3355, steps per second: 172, episode reward: -8.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.463 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.003198, mean_absolute_error: 0.186900, mean_q: -0.002246, mean_eps: 0.020000
684873/1700000: episode: 354, duration: 17.626s, episode steps: 3046, steps per second: 173, episode reward: -14.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.456 [0.000, 5.000], mean observation: 105.546 [87.000, 236.000], loss: 0.003665, mean_absolute_error: 0.183711, mean_q: -0.018161, mean_eps: 0.020000
688681/1700000: episode: 355, duration: 22.047s, episode steps: 3808, steps per second: 173, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.448 [0.000, 5.000], mean observation: 105.607 [87.000, 236.000], loss: 0.003280, mean_absolute_error: 0.179538, mean_q: -0.014609, mean_eps: 0.020000
691462/1700000: episode: 356, duration: 16.012s, episode steps: 2781, steps per second: 174, episode reward: -12.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.513 [0.000, 5.000], mean observation: 105.528 [87.000, 236.000], loss: 0.003442, mean_absolute_error: 0.174738, mean_q: -0.010463, mean_eps: 0.020000
695498/1700000: episode: 357, duration: 23.906s, episode steps: 4036, steps per second: 169, episode reward: -1.000, mean reward: -0.000 [-1.000, 1.000], mean action: 2.518 [0.000, 5.000], mean observation: 105.654 [87.000, 236.000], loss: 0.002790, mean_absolute_error: 0.172794, mean_q: 0.003714, mean_eps: 0.020000
697977/1700000: episode: 358, duration: 14.322s, episode steps: 2479, steps per second: 173, episode reward: -14.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.617 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.003255, mean_absolute_error: 0.178151, mean_q: 0.009794, mean_eps: 0.020000
701114/1700000: episode: 359, duration: 18.265s, episode steps: 3137, steps per second: 172, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.642 [0.000, 5.000], mean observation: 105.630 [87.000, 236.000], loss: 0.002921, mean_absolute_error: 0.181431, mean_q: 0.026020, mean_eps: 0.020000
704431/1700000: episode: 360, duration: 19.183s, episode steps: 3317, steps per second: 173, episode reward: -3.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.623 [0.000, 5.000], mean observation: 105.601 [87.000, 236.000], loss: 0.002741, mean_absolute_error: 0.186078, mean_q: 0.010549, mean_eps: 0.020000
707961/1700000: episode: 361, duration: 20.362s, episode steps: 3530, steps per second: 173, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.587 [0.000, 5.000], mean observation: 105.605 [87.000, 236.000], loss: 0.002832, mean_absolute_error: 0.195039, mean_q: 0.013860, mean_eps: 0.020000
711497/1700000: episode: 362, duration: 20.429s, episode steps: 3536, steps per second: 173, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.592 [0.000, 5.000], mean observation: 105.603 [87.000, 236.000], loss: 0.003154, mean_absolute_error: 0.197829, mean_q: 0.029583, mean_eps: 0.020000
714786/1700000: episode: 363, duration: 18.929s, episode steps: 3289, steps per second: 174, episode reward: -3.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.712 [0.000, 5.000], mean observation: 105.600 [87.000, 236.000], loss: 0.003259, mean_absolute_error: 0.202849, mean_q: 0.063094, mean_eps: 0.020000
718413/1700000: episode: 364, duration: 20.864s, episode steps: 3627, steps per second: 174, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.629 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.003339, mean_absolute_error: 0.210638, mean_q: 0.067739, mean_eps: 0.020000
722930/1700000: episode: 365, duration: 26.718s, episode steps: 4517, steps per second: 169, episode reward: -4.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.621 [0.000, 5.000], mean observation: 105.597 [87.000, 236.000], loss: 0.003079, mean_absolute_error: 0.203365, mean_q: 0.060770, mean_eps: 0.020000
725480/1700000: episode: 366, duration: 15.187s, episode steps: 2550, steps per second: 168, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.770 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.003343, mean_absolute_error: 0.198504, mean_q: 0.061452, mean_eps: 0.020000
728586/1700000: episode: 367, duration: 18.456s, episode steps: 3106, steps per second: 168, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.447 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: 0.003312, mean_absolute_error: 0.196567, mean_q: 0.051755, mean_eps: 0.020000
732125/1700000: episode: 368, duration: 21.045s, episode steps: 3539, steps per second: 168, episode reward: -5.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.528 [0.000, 5.000], mean observation: 105.606 [87.000, 236.000], loss: 0.003331, mean_absolute_error: 0.201572, mean_q: 0.086708, mean_eps: 0.020000
734836/1700000: episode: 369, duration: 16.043s, episode steps: 2711, steps per second: 169, episode reward: -11.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.723 [0.000, 5.000], mean observation: 105.541 [87.000, 236.000], loss: 0.003194, mean_absolute_error: 0.203066, mean_q: 0.086532, mean_eps: 0.020000
737742/1700000: episode: 370, duration: 17.329s, episode steps: 2906, steps per second: 168, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.586 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.003555, mean_absolute_error: 0.212492, mean_q: 0.078257, mean_eps: 0.020000
740980/1700000: episode: 371, duration: 19.102s, episode steps: 3238, steps per second: 170, episode reward: -1.000, mean reward: -0.000 [-1.000, 1.000], mean action: 2.399 [0.000, 5.000], mean observation: 105.639 [87.000, 236.000], loss: 0.003132, mean_absolute_error: 0.212354, mean_q: 0.067080, mean_eps: 0.020000
744274/1700000: episode: 372, duration: 19.547s, episode steps: 3294, steps per second: 169, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.284 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.003461, mean_absolute_error: 0.216445, mean_q: 0.078044, mean_eps: 0.020000
747302/1700000: episode: 373, duration: 18.178s, episode steps: 3028, steps per second: 167, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.526 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.003632, mean_absolute_error: 0.223679, mean_q: 0.113510, mean_eps: 0.020000
749739/1700000: episode: 374, duration: 14.309s, episode steps: 2437, steps per second: 170, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.291 [0.000, 5.000], mean observation: 105.542 [87.000, 236.000], loss: 0.003319, mean_absolute_error: 0.230453, mean_q: 0.140660, mean_eps: 0.020000
752291/1700000: episode: 375, duration: 14.691s, episode steps: 2552, steps per second: 174, episode reward: -8.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.556 [0.000, 5.000], mean observation: 105.604 [87.000, 236.000], loss: 0.003128, mean_absolute_error: 0.238824, mean_q: 0.165704, mean_eps: 0.020000
755994/1700000: episode: 376, duration: 21.079s, episode steps: 3703, steps per second: 176, episode reward: -2.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.412 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.003309, mean_absolute_error: 0.245868, mean_q: 0.161356, mean_eps: 0.020000
758887/1700000: episode: 377, duration: 16.394s, episode steps: 2893, steps per second: 176, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.375 [0.000, 5.000], mean observation: 105.527 [87.000, 236.000], loss: 0.003451, mean_absolute_error: 0.258150, mean_q: 0.165588, mean_eps: 0.020000
762343/1700000: episode: 378, duration: 19.662s, episode steps: 3456, steps per second: 176, episode reward: -3.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.616 [0.000, 5.000], mean observation: 105.588 [87.000, 236.000], loss: 0.003169, mean_absolute_error: 0.254713, mean_q: 0.161610, mean_eps: 0.020000
765180/1700000: episode: 379, duration: 16.091s, episode steps: 2837, steps per second: 176, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.416 [0.000, 5.000], mean observation: 105.571 [87.000, 236.000], loss: 0.003314, mean_absolute_error: 0.266549, mean_q: 0.196183, mean_eps: 0.020000
768194/1700000: episode: 380, duration: 16.996s, episode steps: 3014, steps per second: 177, episode reward: -11.000, mean reward: -0.004 [-1.000, 1.000], mean action: 2.683 [0.000, 5.000], mean observation: 105.587 [87.000, 236.000], loss: 0.003029, mean_absolute_error: 0.273010, mean_q: 0.223864, mean_eps: 0.020000
770966/1700000: episode: 381, duration: 15.564s, episode steps: 2772, steps per second: 178, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.762 [0.000, 5.000], mean observation: 105.610 [87.000, 236.000], loss: 0.003292, mean_absolute_error: 0.269766, mean_q: 0.198664, mean_eps: 0.020000
773613/1700000: episode: 382, duration: 14.955s, episode steps: 2647, steps per second: 177, episode reward: -9.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.649 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.003532, mean_absolute_error: 0.275280, mean_q: 0.193173, mean_eps: 0.020000
776278/1700000: episode: 383, duration: 14.918s, episode steps: 2665, steps per second: 179, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.690 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.003835, mean_absolute_error: 0.279339, mean_q: 0.192831, mean_eps: 0.020000
778948/1700000: episode: 384, duration: 15.067s, episode steps: 2670, steps per second: 177, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.657 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.003756, mean_absolute_error: 0.298000, mean_q: 0.219906, mean_eps: 0.020000
781977/1700000: episode: 385, duration: 16.895s, episode steps: 3029, steps per second: 179, episode reward: -7.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.692 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.003799, mean_absolute_error: 0.307149, mean_q: 0.243348, mean_eps: 0.020000
785272/1700000: episode: 386, duration: 18.299s, episode steps: 3295, steps per second: 180, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.483 [0.000, 5.000], mean observation: 105.625 [87.000, 236.000], loss: 0.003924, mean_absolute_error: 0.310178, mean_q: 0.257227, mean_eps: 0.020000
788812/1700000: episode: 387, duration: 19.679s, episode steps: 3540, steps per second: 180, episode reward: 1.000, mean reward: 0.000 [-1.000, 1.000], mean action: 2.512 [0.000, 5.000], mean observation: 105.607 [87.000, 236.000], loss: 0.004075, mean_absolute_error: 0.302388, mean_q: 0.251512, mean_eps: 0.020000
791795/1700000: episode: 388, duration: 16.626s, episode steps: 2983, steps per second: 179, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.502 [0.000, 5.000], mean observation: 105.608 [87.000, 236.000], loss: 0.003854, mean_absolute_error: 0.300581, mean_q: 0.254545, mean_eps: 0.020000
794804/1700000: episode: 389, duration: 16.848s, episode steps: 3009, steps per second: 179, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.417 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.003482, mean_absolute_error: 0.305191, mean_q: 0.277212, mean_eps: 0.020000
798021/1700000: episode: 390, duration: 17.940s, episode steps: 3217, steps per second: 179, episode reward: 2.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.396 [0.000, 5.000], mean observation: 105.606 [87.000, 236.000], loss: 0.003406, mean_absolute_error: 0.318900, mean_q: 0.302626, mean_eps: 0.020000
800131/1700000: episode: 391, duration: 11.663s, episode steps: 2110, steps per second: 181, episode reward: -12.000, mean reward: -0.006 [-1.000, 1.000], mean action: 2.518 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.004376, mean_absolute_error: 0.313644, mean_q: 0.308116, mean_eps: 0.020000
803549/1700000: episode: 392, duration: 19.163s, episode steps: 3418, steps per second: 178, episode reward: -10.000, mean reward: -0.003 [-1.000, 1.000], mean action: 2.360 [0.000, 5.000], mean observation: 105.530 [87.000, 236.000], loss: 0.004686, mean_absolute_error: 0.300494, mean_q: 0.274721, mean_eps: 0.020000
806393/1700000: episode: 393, duration: 15.667s, episode steps: 2844, steps per second: 182, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.295 [0.000, 5.000], mean observation: 105.593 [87.000, 236.000], loss: 0.003760, mean_absolute_error: 0.298432, mean_q: 0.265676, mean_eps: 0.020000
809633/1700000: episode: 394, duration: 17.871s, episode steps: 3240, steps per second: 181, episode reward: -7.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.666 [0.000, 5.000], mean observation: 105.599 [87.000, 236.000], loss: 0.003297, mean_absolute_error: 0.285543, mean_q: 0.251509, mean_eps: 0.020000
813095/1700000: episode: 395, duration: 18.948s, episode steps: 3462, steps per second: 183, episode reward: -1.000, mean reward: -0.000 [-1.000, 1.000], mean action: 2.533 [0.000, 5.000], mean observation: 105.634 [87.000, 236.000], loss: 0.003411, mean_absolute_error: 0.280976, mean_q: 0.257824, mean_eps: 0.020000
817354/1700000: episode: 396, duration: 23.353s, episode steps: 4259, steps per second: 182, episode reward: 2.000, mean reward: 0.000 [-1.000, 1.000], mean action: 2.520 [0.000, 5.000], mean observation: 105.625 [87.000, 236.000], loss: 0.003576, mean_absolute_error: 0.280276, mean_q: 0.256357, mean_eps: 0.020000
819923/1700000: episode: 397, duration: 14.200s, episode steps: 2569, steps per second: 181, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.447 [0.000, 5.000], mean observation: 105.568 [87.000, 236.000], loss: 0.003299, mean_absolute_error: 0.273969, mean_q: 0.247216, mean_eps: 0.020000
823290/1700000: episode: 398, duration: 18.543s, episode steps: 3367, steps per second: 182, episode reward: -4.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.626 [0.000, 5.000], mean observation: 105.614 [87.000, 236.000], loss: 0.003201, mean_absolute_error: 0.272672, mean_q: 0.248422, mean_eps: 0.020000
827276/1700000: episode: 399, duration: 21.785s, episode steps: 3986, steps per second: 183, episode reward: -3.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.504 [0.000, 5.000], mean observation: 105.600 [87.000, 236.000], loss: 0.003408, mean_absolute_error: 0.273334, mean_q: 0.259596, mean_eps: 0.020000
829863/1700000: episode: 400, duration: 14.167s, episode steps: 2587, steps per second: 183, episode reward: 7.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.412 [0.000, 5.000], mean observation: 105.576 [87.000, 236.000], loss: 0.003654, mean_absolute_error: 0.279570, mean_q: 0.273751, mean_eps: 0.020000
832819/1700000: episode: 401, duration: 16.199s, episode steps: 2956, steps per second: 182, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.151 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.003473, mean_absolute_error: 0.284339, mean_q: 0.293217, mean_eps: 0.020000
836469/1700000: episode: 402, duration: 20.022s, episode steps: 3650, steps per second: 182, episode reward: -4.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.438 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.003280, mean_absolute_error: 0.285596, mean_q: 0.301923, mean_eps: 0.020000
839166/1700000: episode: 403, duration: 14.684s, episode steps: 2697, steps per second: 184, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.519 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.003645, mean_absolute_error: 0.286701, mean_q: 0.303149, mean_eps: 0.020000
842481/1700000: episode: 404, duration: 18.126s, episode steps: 3315, steps per second: 183, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.665 [0.000, 5.000], mean observation: 105.626 [87.000, 236.000], loss: 0.003705, mean_absolute_error: 0.283671, mean_q: 0.285582, mean_eps: 0.020000
846050/1700000: episode: 405, duration: 19.525s, episode steps: 3569, steps per second: 183, episode reward: -4.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.823 [0.000, 5.000], mean observation: 105.574 [87.000, 236.000], loss: 0.003619, mean_absolute_error: 0.292346, mean_q: 0.291195, mean_eps: 0.020000
848930/1700000: episode: 406, duration: 15.804s, episode steps: 2880, steps per second: 182, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.587 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.003170, mean_absolute_error: 0.298763, mean_q: 0.298146, mean_eps: 0.020000
851935/1700000: episode: 407, duration: 16.380s, episode steps: 3005, steps per second: 183, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.869 [0.000, 5.000], mean observation: 105.591 [87.000, 236.000], loss: 0.003047, mean_absolute_error: 0.292194, mean_q: 0.290486, mean_eps: 0.020000
854672/1700000: episode: 408, duration: 15.163s, episode steps: 2737, steps per second: 181, episode reward: 14.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.578 [0.000, 5.000], mean observation: 105.527 [87.000, 236.000], loss: 0.003343, mean_absolute_error: 0.289875, mean_q: 0.296975, mean_eps: 0.020000
857023/1700000: episode: 409, duration: 12.847s, episode steps: 2351, steps per second: 183, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.615 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.003055, mean_absolute_error: 0.301583, mean_q: 0.332353, mean_eps: 0.020000
861615/1700000: episode: 410, duration: 25.451s, episode steps: 4592, steps per second: 180, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.506 [0.000, 5.000], mean observation: 105.617 [87.000, 236.000], loss: 0.003241, mean_absolute_error: 0.301284, mean_q: 0.342279, mean_eps: 0.020000
865610/1700000: episode: 411, duration: 21.916s, episode steps: 3995, steps per second: 182, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.534 [0.000, 5.000], mean observation: 105.616 [87.000, 236.000], loss: 0.002633, mean_absolute_error: 0.296438, mean_q: 0.343884, mean_eps: 0.020000
868944/1700000: episode: 412, duration: 18.212s, episode steps: 3334, steps per second: 183, episode reward: 11.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.406 [0.000, 5.000], mean observation: 105.589 [87.000, 236.000], loss: 0.002647, mean_absolute_error: 0.290886, mean_q: 0.326330, mean_eps: 0.020000
871740/1700000: episode: 413, duration: 15.417s, episode steps: 2796, steps per second: 181, episode reward: 15.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.382 [0.000, 5.000], mean observation: 105.545 [87.000, 236.000], loss: 0.002402, mean_absolute_error: 0.284490, mean_q: 0.331056, mean_eps: 0.020000
874923/1700000: episode: 414, duration: 17.617s, episode steps: 3183, steps per second: 181, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.427 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.002524, mean_absolute_error: 0.286661, mean_q: 0.335748, mean_eps: 0.020000
877711/1700000: episode: 415, duration: 15.426s, episode steps: 2788, steps per second: 181, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.412 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.002480, mean_absolute_error: 0.296639, mean_q: 0.351769, mean_eps: 0.020000
880583/1700000: episode: 416, duration: 16.003s, episode steps: 2872, steps per second: 179, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.363 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.002681, mean_absolute_error: 0.308827, mean_q: 0.367775, mean_eps: 0.020000
883740/1700000: episode: 417, duration: 17.377s, episode steps: 3157, steps per second: 182, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.288 [0.000, 5.000], mean observation: 105.582 [87.000, 236.000], loss: 0.002774, mean_absolute_error: 0.323599, mean_q: 0.380198, mean_eps: 0.020000
886236/1700000: episode: 418, duration: 13.715s, episode steps: 2496, steps per second: 182, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.446 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.002735, mean_absolute_error: 0.335456, mean_q: 0.396690, mean_eps: 0.020000
889950/1700000: episode: 419, duration: 20.393s, episode steps: 3714, steps per second: 182, episode reward: -6.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.393 [0.000, 5.000], mean observation: 105.611 [87.000, 236.000], loss: 0.002647, mean_absolute_error: 0.330472, mean_q: 0.389358, mean_eps: 0.020000
893782/1700000: episode: 420, duration: 20.848s, episode steps: 3832, steps per second: 184, episode reward: -7.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.384 [0.000, 5.000], mean observation: 105.574 [87.000, 236.000], loss: 0.002689, mean_absolute_error: 0.307250, mean_q: 0.341136, mean_eps: 0.020000
896806/1700000: episode: 421, duration: 16.487s, episode steps: 3024, steps per second: 183, episode reward: -7.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.569 [0.000, 5.000], mean observation: 105.591 [87.000, 236.000], loss: 0.002730, mean_absolute_error: 0.297415, mean_q: 0.323612, mean_eps: 0.020000
899695/1700000: episode: 422, duration: 15.663s, episode steps: 2889, steps per second: 184, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.498 [0.000, 5.000], mean observation: 105.534 [87.000, 236.000], loss: 0.002684, mean_absolute_error: 0.299719, mean_q: 0.319949, mean_eps: 0.020000
902057/1700000: episode: 423, duration: 12.838s, episode steps: 2362, steps per second: 184, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.362 [0.000, 5.000], mean observation: 105.533 [87.000, 236.000], loss: 0.002525, mean_absolute_error: 0.330127, mean_q: 0.368294, mean_eps: 0.020000
904986/1700000: episode: 424, duration: 15.883s, episode steps: 2929, steps per second: 184, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.449 [0.000, 5.000], mean observation: 105.606 [87.000, 236.000], loss: 0.002839, mean_absolute_error: 0.352216, mean_q: 0.405818, mean_eps: 0.020000
908411/1700000: episode: 425, duration: 18.752s, episode steps: 3425, steps per second: 183, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.385 [0.000, 5.000], mean observation: 105.642 [87.000, 236.000], loss: 0.003869, mean_absolute_error: 0.366149, mean_q: 0.430477, mean_eps: 0.020000
912022/1700000: episode: 426, duration: 19.805s, episode steps: 3611, steps per second: 182, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.353 [0.000, 5.000], mean observation: 105.594 [87.000, 236.000], loss: 0.003548, mean_absolute_error: 0.365099, mean_q: 0.422259, mean_eps: 0.020000
914873/1700000: episode: 427, duration: 15.806s, episode steps: 2851, steps per second: 180, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.104 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.003159, mean_absolute_error: 0.344036, mean_q: 0.390117, mean_eps: 0.020000
917334/1700000: episode: 428, duration: 13.397s, episode steps: 2461, steps per second: 184, episode reward: -13.000, mean reward: -0.005 [-1.000, 1.000], mean action: 2.359 [0.000, 5.000], mean observation: 105.535 [87.000, 236.000], loss: 0.003475, mean_absolute_error: 0.347757, mean_q: 0.395670, mean_eps: 0.020000
920112/1700000: episode: 429, duration: 15.078s, episode steps: 2778, steps per second: 184, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.500 [0.000, 5.000], mean observation: 105.588 [87.000, 236.000], loss: 0.003061, mean_absolute_error: 0.343963, mean_q: 0.391572, mean_eps: 0.020000
923341/1700000: episode: 430, duration: 17.683s, episode steps: 3229, steps per second: 183, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.498 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: 0.003264, mean_absolute_error: 0.356124, mean_q: 0.401942, mean_eps: 0.020000
926074/1700000: episode: 431, duration: 14.859s, episode steps: 2733, steps per second: 184, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.412 [0.000, 5.000], mean observation: 105.538 [87.000, 236.000], loss: 0.003317, mean_absolute_error: 0.346931, mean_q: 0.394206, mean_eps: 0.020000
928597/1700000: episode: 432, duration: 13.687s, episode steps: 2523, steps per second: 184, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.458 [0.000, 5.000], mean observation: 105.515 [87.000, 236.000], loss: 0.002674, mean_absolute_error: 0.357793, mean_q: 0.427372, mean_eps: 0.020000
933016/1700000: episode: 433, duration: 23.893s, episode steps: 4419, steps per second: 185, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.482 [0.000, 5.000], mean observation: 105.643 [87.000, 236.000], loss: 0.002695, mean_absolute_error: 0.360005, mean_q: 0.429494, mean_eps: 0.020000
936009/1700000: episode: 434, duration: 16.147s, episode steps: 2993, steps per second: 185, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.536 [0.000, 5.000], mean observation: 105.525 [87.000, 236.000], loss: 0.002692, mean_absolute_error: 0.359714, mean_q: 0.440509, mean_eps: 0.020000
939027/1700000: episode: 435, duration: 16.308s, episode steps: 3018, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.193 [0.000, 5.000], mean observation: 105.599 [87.000, 236.000], loss: 0.002646, mean_absolute_error: 0.350146, mean_q: 0.424072, mean_eps: 0.020000
941938/1700000: episode: 436, duration: 15.628s, episode steps: 2911, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.188 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.002745, mean_absolute_error: 0.357860, mean_q: 0.435971, mean_eps: 0.020000
946185/1700000: episode: 437, duration: 22.919s, episode steps: 4247, steps per second: 185, episode reward: 1.000, mean reward: 0.000 [-1.000, 1.000], mean action: 2.427 [0.000, 5.000], mean observation: 105.618 [87.000, 236.000], loss: 0.002967, mean_absolute_error: 0.360544, mean_q: 0.432138, mean_eps: 0.020000
949068/1700000: episode: 438, duration: 15.498s, episode steps: 2883, steps per second: 186, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.522 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.002905, mean_absolute_error: 0.342504, mean_q: 0.405649, mean_eps: 0.020000
952974/1700000: episode: 439, duration: 21.131s, episode steps: 3906, steps per second: 185, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.563 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.003041, mean_absolute_error: 0.327654, mean_q: 0.383797, mean_eps: 0.020000
955864/1700000: episode: 440, duration: 15.566s, episode steps: 2890, steps per second: 186, episode reward: 14.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.526 [0.000, 5.000], mean observation: 105.509 [87.000, 236.000], loss: 0.003268, mean_absolute_error: 0.333681, mean_q: 0.392034, mean_eps: 0.020000
957927/1700000: episode: 441, duration: 11.131s, episode steps: 2063, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.173 [0.000, 5.000], mean observation: 105.601 [87.000, 236.000], loss: 0.002910, mean_absolute_error: 0.351150, mean_q: 0.422032, mean_eps: 0.020000
961038/1700000: episode: 442, duration: 16.642s, episode steps: 3111, steps per second: 187, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.500 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.002919, mean_absolute_error: 0.357177, mean_q: 0.442568, mean_eps: 0.020000
964033/1700000: episode: 443, duration: 16.087s, episode steps: 2995, steps per second: 186, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.623 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.002898, mean_absolute_error: 0.367960, mean_q: 0.458818, mean_eps: 0.020000
967519/1700000: episode: 444, duration: 18.888s, episode steps: 3486, steps per second: 185, episode reward: 1.000, mean reward: 0.000 [-1.000, 1.000], mean action: 2.723 [0.000, 5.000], mean observation: 105.650 [87.000, 236.000], loss: 0.002928, mean_absolute_error: 0.377129, mean_q: 0.463577, mean_eps: 0.020000
970216/1700000: episode: 445, duration: 14.519s, episode steps: 2697, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.624 [0.000, 5.000], mean observation: 105.508 [87.000, 236.000], loss: 0.002903, mean_absolute_error: 0.366942, mean_q: 0.441259, mean_eps: 0.020000
973075/1700000: episode: 446, duration: 15.765s, episode steps: 2859, steps per second: 181, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.587 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.003237, mean_absolute_error: 0.370623, mean_q: 0.451451, mean_eps: 0.020000
975977/1700000: episode: 447, duration: 15.580s, episode steps: 2902, steps per second: 186, episode reward: 15.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.790 [0.000, 5.000], mean observation: 105.484 [87.000, 236.000], loss: 0.002913, mean_absolute_error: 0.379445, mean_q: 0.470330, mean_eps: 0.020000
979577/1700000: episode: 448, duration: 19.401s, episode steps: 3600, steps per second: 186, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.817 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.003235, mean_absolute_error: 0.391659, mean_q: 0.491675, mean_eps: 0.020000
982856/1700000: episode: 449, duration: 17.684s, episode steps: 3279, steps per second: 185, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.694 [0.000, 5.000], mean observation: 105.615 [87.000, 236.000], loss: 0.002710, mean_absolute_error: 0.391971, mean_q: 0.496988, mean_eps: 0.020000
985327/1700000: episode: 450, duration: 13.321s, episode steps: 2471, steps per second: 185, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.738 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.002323, mean_absolute_error: 0.393438, mean_q: 0.500365, mean_eps: 0.020000
987496/1700000: episode: 451, duration: 11.586s, episode steps: 2169, steps per second: 187, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.617 [0.000, 5.000], mean observation: 105.534 [87.000, 236.000], loss: 0.002759, mean_absolute_error: 0.420223, mean_q: 0.532602, mean_eps: 0.020000
990760/1700000: episode: 452, duration: 17.629s, episode steps: 3264, steps per second: 185, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.562 [0.000, 5.000], mean observation: 105.633 [87.000, 236.000], loss: 0.002704, mean_absolute_error: 0.433994, mean_q: 0.557169, mean_eps: 0.020000
994835/1700000: episode: 453, duration: 21.841s, episode steps: 4075, steps per second: 187, episode reward: -1.000, mean reward: -0.000 [-1.000, 1.000], mean action: 2.654 [0.000, 5.000], mean observation: 105.653 [87.000, 236.000], loss: 0.002916, mean_absolute_error: 0.435687, mean_q: 0.553293, mean_eps: 0.020000
997736/1700000: episode: 454, duration: 15.671s, episode steps: 2901, steps per second: 185, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.800 [0.000, 5.000], mean observation: 105.588 [87.000, 236.000], loss: 0.002679, mean_absolute_error: 0.409741, mean_q: 0.507919, mean_eps: 0.020000
1001268/1700000: episode: 455, duration: 18.956s, episode steps: 3532, steps per second: 186, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.518 [0.000, 5.000], mean observation: 105.623 [87.000, 236.000], loss: 0.002942, mean_absolute_error: 0.398591, mean_q: 0.481332, mean_eps: 0.020000
1003638/1700000: episode: 456, duration: 12.728s, episode steps: 2370, steps per second: 186, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.754 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.002992, mean_absolute_error: 0.391121, mean_q: 0.466451, mean_eps: 0.020000
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1007173/1700000: episode: 457, duration: 18.901s, episode steps: 3535, steps per second: 187, episode reward: 8.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.796 [0.000, 5.000], mean observation: 105.578 [87.000, 236.000], loss: 0.002653, mean_absolute_error: 0.422974, mean_q: 0.509628, mean_eps: 0.020000
1011102/1700000: episode: 458, duration: 21.027s, episode steps: 3929, steps per second: 187, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.516 [0.000, 5.000], mean observation: 105.597 [87.000, 236.000], loss: 0.002702, mean_absolute_error: 0.399924, mean_q: 0.492160, mean_eps: 0.020000
1013854/1700000: episode: 459, duration: 14.821s, episode steps: 2752, steps per second: 186, episode reward: 14.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.564 [0.000, 5.000], mean observation: 105.527 [87.000, 236.000], loss: 0.002680, mean_absolute_error: 0.392016, mean_q: 0.484923, mean_eps: 0.020000
1016811/1700000: episode: 460, duration: 15.865s, episode steps: 2957, steps per second: 186, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.618 [0.000, 5.000], mean observation: 105.614 [87.000, 236.000], loss: 0.002966, mean_absolute_error: 0.388642, mean_q: 0.485505, mean_eps: 0.020000
1020297/1700000: episode: 461, duration: 18.733s, episode steps: 3486, steps per second: 186, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.497 [0.000, 5.000], mean observation: 105.588 [87.000, 236.000], loss: 0.003288, mean_absolute_error: 0.404256, mean_q: 0.499487, mean_eps: 0.020000
1022724/1700000: episode: 462, duration: 13.215s, episode steps: 2427, steps per second: 184, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.522 [0.000, 5.000], mean observation: 105.520 [87.000, 236.000], loss: 0.003889, mean_absolute_error: 0.426644, mean_q: 0.523069, mean_eps: 0.020000
1024883/1700000: episode: 463, duration: 11.623s, episode steps: 2159, steps per second: 186, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.390 [0.000, 5.000], mean observation: 105.506 [87.000, 236.000], loss: 0.003679, mean_absolute_error: 0.439311, mean_q: 0.534494, mean_eps: 0.020000
1028257/1700000: episode: 464, duration: 18.326s, episode steps: 3374, steps per second: 184, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.472 [0.000, 5.000], mean observation: 105.612 [87.000, 236.000], loss: 0.003386, mean_absolute_error: 0.455554, mean_q: 0.565464, mean_eps: 0.020000
1031310/1700000: episode: 465, duration: 16.780s, episode steps: 3053, steps per second: 182, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.631 [0.000, 5.000], mean observation: 105.602 [87.000, 236.000], loss: 0.003341, mean_absolute_error: 0.454405, mean_q: 0.557191, mean_eps: 0.020000
1033671/1700000: episode: 466, duration: 13.162s, episode steps: 2361, steps per second: 179, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.653 [0.000, 5.000], mean observation: 105.504 [87.000, 236.000], loss: 0.003154, mean_absolute_error: 0.457011, mean_q: 0.562085, mean_eps: 0.020000
1036321/1700000: episode: 467, duration: 14.730s, episode steps: 2650, steps per second: 180, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.612 [0.000, 5.000], mean observation: 105.534 [87.000, 236.000], loss: 0.003533, mean_absolute_error: 0.459961, mean_q: 0.569365, mean_eps: 0.020000
1038675/1700000: episode: 468, duration: 13.064s, episode steps: 2354, steps per second: 180, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.735 [0.000, 5.000], mean observation: 105.522 [87.000, 236.000], loss: 0.002920, mean_absolute_error: 0.459404, mean_q: 0.577310, mean_eps: 0.020000
1041191/1700000: episode: 469, duration: 14.042s, episode steps: 2516, steps per second: 179, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.810 [0.000, 5.000], mean observation: 105.524 [87.000, 236.000], loss: 0.002880, mean_absolute_error: 0.489510, mean_q: 0.626116, mean_eps: 0.020000
1044535/1700000: episode: 470, duration: 18.688s, episode steps: 3344, steps per second: 179, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.643 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: 0.003190, mean_absolute_error: 0.490085, mean_q: 0.621585, mean_eps: 0.020000
1046510/1700000: episode: 471, duration: 10.970s, episode steps: 1975, steps per second: 180, episode reward: 20.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.457 [0.000, 5.000], mean observation: 105.484 [87.000, 236.000], loss: 0.003160, mean_absolute_error: 0.472882, mean_q: 0.598918, mean_eps: 0.020000
1049183/1700000: episode: 472, duration: 14.650s, episode steps: 2673, steps per second: 182, episode reward: 14.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.892 [0.000, 5.000], mean observation: 105.479 [87.000, 236.000], loss: 0.002892, mean_absolute_error: 0.481194, mean_q: 0.612120, mean_eps: 0.020000
1051455/1700000: episode: 473, duration: 12.426s, episode steps: 2272, steps per second: 183, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.388 [0.000, 5.000], mean observation: 105.549 [87.000, 236.000], loss: 0.002904, mean_absolute_error: 0.487760, mean_q: 0.619796, mean_eps: 0.020000
1053909/1700000: episode: 474, duration: 13.447s, episode steps: 2454, steps per second: 182, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.812 [0.000, 5.000], mean observation: 105.534 [87.000, 236.000], loss: 0.002567, mean_absolute_error: 0.514157, mean_q: 0.649575, mean_eps: 0.020000
1056321/1700000: episode: 475, duration: 13.286s, episode steps: 2412, steps per second: 182, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.590 [0.000, 5.000], mean observation: 105.517 [87.000, 236.000], loss: 0.002760, mean_absolute_error: 0.520725, mean_q: 0.660282, mean_eps: 0.020000
1058332/1700000: episode: 476, duration: 10.823s, episode steps: 2011, steps per second: 186, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.492 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.002661, mean_absolute_error: 0.537884, mean_q: 0.680725, mean_eps: 0.020000
1061081/1700000: episode: 477, duration: 14.978s, episode steps: 2749, steps per second: 184, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.494 [0.000, 5.000], mean observation: 105.528 [87.000, 236.000], loss: 0.002567, mean_absolute_error: 0.545326, mean_q: 0.694394, mean_eps: 0.020000
1064054/1700000: episode: 478, duration: 15.993s, episode steps: 2973, steps per second: 186, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.677 [0.000, 5.000], mean observation: 105.566 [87.000, 236.000], loss: 0.002923, mean_absolute_error: 0.530837, mean_q: 0.671445, mean_eps: 0.020000
1066290/1700000: episode: 479, duration: 12.034s, episode steps: 2236, steps per second: 186, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.514 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.003170, mean_absolute_error: 0.531181, mean_q: 0.671597, mean_eps: 0.020000
1068609/1700000: episode: 480, duration: 12.452s, episode steps: 2319, steps per second: 186, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.457 [0.000, 5.000], mean observation: 105.545 [87.000, 236.000], loss: 0.003184, mean_absolute_error: 0.521186, mean_q: 0.654230, mean_eps: 0.020000
1071810/1700000: episode: 481, duration: 17.250s, episode steps: 3201, steps per second: 186, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.535 [0.000, 5.000], mean observation: 105.695 [87.000, 236.000], loss: 0.003571, mean_absolute_error: 0.501644, mean_q: 0.625686, mean_eps: 0.020000
1074382/1700000: episode: 482, duration: 13.856s, episode steps: 2572, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.774 [0.000, 5.000], mean observation: 105.549 [87.000, 236.000], loss: 0.003189, mean_absolute_error: 0.507576, mean_q: 0.637289, mean_eps: 0.020000
1076576/1700000: episode: 483, duration: 11.859s, episode steps: 2194, steps per second: 185, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.603 [0.000, 5.000], mean observation: 105.485 [87.000, 236.000], loss: 0.003038, mean_absolute_error: 0.518931, mean_q: 0.652341, mean_eps: 0.020000
1078789/1700000: episode: 484, duration: 12.031s, episode steps: 2213, steps per second: 184, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.500 [0.000, 5.000], mean observation: 105.519 [87.000, 236.000], loss: 0.002836, mean_absolute_error: 0.521224, mean_q: 0.661534, mean_eps: 0.020000
1081603/1700000: episode: 485, duration: 15.061s, episode steps: 2814, steps per second: 187, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.486 [0.000, 5.000], mean observation: 105.549 [87.000, 236.000], loss: 0.002557, mean_absolute_error: 0.533200, mean_q: 0.678446, mean_eps: 0.020000
1083822/1700000: episode: 486, duration: 11.937s, episode steps: 2219, steps per second: 186, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.657 [0.000, 5.000], mean observation: 105.505 [87.000, 236.000], loss: 0.002298, mean_absolute_error: 0.554415, mean_q: 0.706715, mean_eps: 0.020000
1086155/1700000: episode: 487, duration: 12.907s, episode steps: 2333, steps per second: 181, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.498 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.002342, mean_absolute_error: 0.561751, mean_q: 0.715842, mean_eps: 0.020000
1089294/1700000: episode: 488, duration: 16.936s, episode steps: 3139, steps per second: 185, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.537 [0.000, 5.000], mean observation: 105.542 [87.000, 236.000], loss: 0.002450, mean_absolute_error: 0.554257, mean_q: 0.707333, mean_eps: 0.020000
1091416/1700000: episode: 489, duration: 11.382s, episode steps: 2122, steps per second: 186, episode reward: 18.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.404 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.002463, mean_absolute_error: 0.554272, mean_q: 0.706991, mean_eps: 0.020000
1093546/1700000: episode: 490, duration: 11.438s, episode steps: 2130, steps per second: 186, episode reward: 16.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.360 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.002500, mean_absolute_error: 0.559907, mean_q: 0.717800, mean_eps: 0.020000
1096509/1700000: episode: 491, duration: 15.877s, episode steps: 2963, steps per second: 187, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.452 [0.000, 5.000], mean observation: 105.537 [87.000, 236.000], loss: 0.002503, mean_absolute_error: 0.552946, mean_q: 0.707070, mean_eps: 0.020000
1098581/1700000: episode: 492, duration: 11.096s, episode steps: 2072, steps per second: 187, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.455 [0.000, 5.000], mean observation: 105.518 [87.000, 236.000], loss: 0.002433, mean_absolute_error: 0.546362, mean_q: 0.698895, mean_eps: 0.020000
1100921/1700000: episode: 493, duration: 12.617s, episode steps: 2340, steps per second: 185, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.418 [0.000, 5.000], mean observation: 105.542 [87.000, 236.000], loss: 0.002276, mean_absolute_error: 0.558506, mean_q: 0.717502, mean_eps: 0.020000
1102997/1700000: episode: 494, duration: 11.080s, episode steps: 2076, steps per second: 187, episode reward: 12.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.718 [0.000, 5.000], mean observation: 105.526 [87.000, 236.000], loss: 0.002788, mean_absolute_error: 0.565025, mean_q: 0.721333, mean_eps: 0.020000
1104763/1700000: episode: 495, duration: 9.444s, episode steps: 1766, steps per second: 187, episode reward: 19.000, mean reward: 0.011 [-1.000, 1.000], mean action: 2.668 [0.000, 5.000], mean observation: 105.468 [87.000, 236.000], loss: 0.002403, mean_absolute_error: 0.595723, mean_q: 0.758265, mean_eps: 0.020000
1107803/1700000: episode: 496, duration: 16.373s, episode steps: 3040, steps per second: 186, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.390 [0.000, 5.000], mean observation: 105.544 [87.000, 236.000], loss: 0.002542, mean_absolute_error: 0.608883, mean_q: 0.772155, mean_eps: 0.020000
1110201/1700000: episode: 497, duration: 12.887s, episode steps: 2398, steps per second: 186, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.389 [0.000, 5.000], mean observation: 105.525 [87.000, 236.000], loss: 0.002534, mean_absolute_error: 0.607426, mean_q: 0.769015, mean_eps: 0.020000
1112510/1700000: episode: 498, duration: 12.467s, episode steps: 2309, steps per second: 185, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.527 [0.000, 5.000], mean observation: 105.538 [87.000, 236.000], loss: 0.002303, mean_absolute_error: 0.624706, mean_q: 0.791063, mean_eps: 0.020000
1115559/1700000: episode: 499, duration: 16.403s, episode steps: 3049, steps per second: 186, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.583 [0.000, 5.000], mean observation: 105.604 [87.000, 236.000], loss: 0.003179, mean_absolute_error: 0.595648, mean_q: 0.752019, mean_eps: 0.020000
1118056/1700000: episode: 500, duration: 13.451s, episode steps: 2497, steps per second: 186, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.506 [0.000, 5.000], mean observation: 105.573 [87.000, 236.000], loss: 0.003073, mean_absolute_error: 0.602526, mean_q: 0.761203, mean_eps: 0.020000
1120631/1700000: episode: 501, duration: 13.862s, episode steps: 2575, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.585 [0.000, 5.000], mean observation: 105.521 [87.000, 236.000], loss: 0.003117, mean_absolute_error: 0.585469, mean_q: 0.733672, mean_eps: 0.020000
1123439/1700000: episode: 502, duration: 15.135s, episode steps: 2808, steps per second: 186, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.504 [0.000, 5.000], mean observation: 105.545 [87.000, 236.000], loss: 0.003047, mean_absolute_error: 0.574161, mean_q: 0.719194, mean_eps: 0.020000
1125506/1700000: episode: 503, duration: 11.063s, episode steps: 2067, steps per second: 187, episode reward: 16.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.540 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.002736, mean_absolute_error: 0.578701, mean_q: 0.728412, mean_eps: 0.020000
1127423/1700000: episode: 504, duration: 10.294s, episode steps: 1917, steps per second: 186, episode reward: 19.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.409 [0.000, 5.000], mean observation: 105.464 [87.000, 236.000], loss: 0.002722, mean_absolute_error: 0.600629, mean_q: 0.757995, mean_eps: 0.020000
1130647/1700000: episode: 505, duration: 17.471s, episode steps: 3224, steps per second: 185, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.575 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.002783, mean_absolute_error: 0.609981, mean_q: 0.771659, mean_eps: 0.020000
1133361/1700000: episode: 506, duration: 14.783s, episode steps: 2714, steps per second: 184, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.537 [0.000, 5.000], mean observation: 105.591 [87.000, 236.000], loss: 0.003099, mean_absolute_error: 0.593752, mean_q: 0.749502, mean_eps: 0.020000
1136004/1700000: episode: 507, duration: 14.264s, episode steps: 2643, steps per second: 185, episode reward: 7.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.622 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.003109, mean_absolute_error: 0.609542, mean_q: 0.770434, mean_eps: 0.020000
1139323/1700000: episode: 508, duration: 17.830s, episode steps: 3319, steps per second: 186, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.477 [0.000, 5.000], mean observation: 105.602 [87.000, 236.000], loss: 0.003660, mean_absolute_error: 0.572348, mean_q: 0.721881, mean_eps: 0.020000
1141529/1700000: episode: 509, duration: 11.905s, episode steps: 2206, steps per second: 185, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.738 [0.000, 5.000], mean observation: 105.517 [87.000, 236.000], loss: 0.003501, mean_absolute_error: 0.588349, mean_q: 0.739741, mean_eps: 0.020000
1144346/1700000: episode: 510, duration: 15.610s, episode steps: 2817, steps per second: 180, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.608 [0.000, 5.000], mean observation: 105.568 [87.000, 236.000], loss: 0.003440, mean_absolute_error: 0.595984, mean_q: 0.751979, mean_eps: 0.020000
1146642/1700000: episode: 511, duration: 12.377s, episode steps: 2296, steps per second: 186, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.539 [0.000, 5.000], mean observation: 105.533 [87.000, 236.000], loss: 0.003660, mean_absolute_error: 0.585672, mean_q: 0.739952, mean_eps: 0.020000
1149810/1700000: episode: 512, duration: 17.174s, episode steps: 3168, steps per second: 184, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.565 [0.000, 5.000], mean observation: 105.594 [87.000, 236.000], loss: 0.003618, mean_absolute_error: 0.606449, mean_q: 0.769858, mean_eps: 0.020000
1151807/1700000: episode: 513, duration: 10.731s, episode steps: 1997, steps per second: 186, episode reward: 17.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.756 [0.000, 5.000], mean observation: 105.492 [87.000, 236.000], loss: 0.003397, mean_absolute_error: 0.592128, mean_q: 0.750345, mean_eps: 0.020000
1155132/1700000: episode: 514, duration: 17.855s, episode steps: 3325, steps per second: 186, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.765 [0.000, 5.000], mean observation: 105.627 [87.000, 236.000], loss: 0.003397, mean_absolute_error: 0.614978, mean_q: 0.774222, mean_eps: 0.020000
1157660/1700000: episode: 515, duration: 13.610s, episode steps: 2528, steps per second: 186, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.738 [0.000, 5.000], mean observation: 105.572 [87.000, 236.000], loss: 0.003424, mean_absolute_error: 0.581585, mean_q: 0.729440, mean_eps: 0.020000
1160748/1700000: episode: 516, duration: 16.657s, episode steps: 3088, steps per second: 185, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.879 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.003138, mean_absolute_error: 0.590839, mean_q: 0.740570, mean_eps: 0.020000
1164199/1700000: episode: 517, duration: 18.500s, episode steps: 3451, steps per second: 187, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.794 [0.000, 5.000], mean observation: 105.603 [87.000, 236.000], loss: 0.003160, mean_absolute_error: 0.535353, mean_q: 0.670841, mean_eps: 0.020000
1166951/1700000: episode: 518, duration: 14.852s, episode steps: 2752, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.648 [0.000, 5.000], mean observation: 105.588 [87.000, 236.000], loss: 0.003119, mean_absolute_error: 0.548876, mean_q: 0.693652, mean_eps: 0.020000
1169477/1700000: episode: 519, duration: 13.576s, episode steps: 2526, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.536 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.003644, mean_absolute_error: 0.552877, mean_q: 0.697222, mean_eps: 0.020000
1172208/1700000: episode: 520, duration: 14.711s, episode steps: 2731, steps per second: 186, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.676 [0.000, 5.000], mean observation: 105.538 [87.000, 236.000], loss: 0.003249, mean_absolute_error: 0.561754, mean_q: 0.714022, mean_eps: 0.020000
1175050/1700000: episode: 521, duration: 15.315s, episode steps: 2842, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.817 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.002972, mean_absolute_error: 0.586027, mean_q: 0.750514, mean_eps: 0.020000
1177128/1700000: episode: 522, duration: 11.261s, episode steps: 2078, steps per second: 185, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.658 [0.000, 5.000], mean observation: 105.516 [87.000, 236.000], loss: 0.002930, mean_absolute_error: 0.583613, mean_q: 0.754041, mean_eps: 0.020000
1179893/1700000: episode: 523, duration: 14.856s, episode steps: 2765, steps per second: 186, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.471 [0.000, 5.000], mean observation: 105.539 [87.000, 236.000], loss: 0.002553, mean_absolute_error: 0.600994, mean_q: 0.775750, mean_eps: 0.020000
1182148/1700000: episode: 524, duration: 12.084s, episode steps: 2255, steps per second: 187, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.655 [0.000, 5.000], mean observation: 105.539 [87.000, 236.000], loss: 0.002772, mean_absolute_error: 0.619414, mean_q: 0.797962, mean_eps: 0.020000
1185275/1700000: episode: 525, duration: 16.775s, episode steps: 3127, steps per second: 186, episode reward: -4.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.590 [0.000, 5.000], mean observation: 105.621 [87.000, 236.000], loss: 0.002919, mean_absolute_error: 0.626430, mean_q: 0.797738, mean_eps: 0.020000
1187938/1700000: episode: 526, duration: 14.285s, episode steps: 2663, steps per second: 186, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.751 [0.000, 5.000], mean observation: 105.598 [87.000, 236.000], loss: 0.003179, mean_absolute_error: 0.606583, mean_q: 0.763611, mean_eps: 0.020000
1190713/1700000: episode: 527, duration: 15.190s, episode steps: 2775, steps per second: 183, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.578 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.003329, mean_absolute_error: 0.602610, mean_q: 0.754264, mean_eps: 0.020000
1193431/1700000: episode: 528, duration: 14.514s, episode steps: 2718, steps per second: 187, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.493 [0.000, 5.000], mean observation: 105.535 [87.000, 236.000], loss: 0.003302, mean_absolute_error: 0.587870, mean_q: 0.740379, mean_eps: 0.020000
1196666/1700000: episode: 529, duration: 17.414s, episode steps: 3235, steps per second: 186, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.520 [0.000, 5.000], mean observation: 105.624 [87.000, 236.000], loss: 0.003096, mean_absolute_error: 0.598211, mean_q: 0.759915, mean_eps: 0.020000
1199249/1700000: episode: 530, duration: 13.891s, episode steps: 2583, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.700 [0.000, 5.000], mean observation: 105.568 [87.000, 236.000], loss: 0.002825, mean_absolute_error: 0.590800, mean_q: 0.749810, mean_eps: 0.020000
1202628/1700000: episode: 531, duration: 18.536s, episode steps: 3379, steps per second: 182, episode reward: 11.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.510 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.003179, mean_absolute_error: 0.575008, mean_q: 0.729671, mean_eps: 0.020000
1205295/1700000: episode: 532, duration: 14.450s, episode steps: 2667, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.642 [0.000, 5.000], mean observation: 105.607 [87.000, 236.000], loss: 0.003073, mean_absolute_error: 0.552029, mean_q: 0.700457, mean_eps: 0.020000
1207813/1700000: episode: 533, duration: 13.483s, episode steps: 2518, steps per second: 187, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.869 [0.000, 5.000], mean observation: 105.567 [87.000, 236.000], loss: 0.002402, mean_absolute_error: 0.565250, mean_q: 0.721087, mean_eps: 0.020000
1210239/1700000: episode: 534, duration: 13.046s, episode steps: 2426, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.669 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.002706, mean_absolute_error: 0.554671, mean_q: 0.706794, mean_eps: 0.020000
1213386/1700000: episode: 535, duration: 16.925s, episode steps: 3147, steps per second: 186, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.683 [0.000, 5.000], mean observation: 105.533 [87.000, 236.000], loss: 0.002585, mean_absolute_error: 0.565498, mean_q: 0.714752, mean_eps: 0.020000
1215522/1700000: episode: 536, duration: 11.401s, episode steps: 2136, steps per second: 187, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.788 [0.000, 5.000], mean observation: 105.518 [87.000, 236.000], loss: 0.002347, mean_absolute_error: 0.570626, mean_q: 0.725713, mean_eps: 0.020000
1218274/1700000: episode: 537, duration: 14.822s, episode steps: 2752, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.599 [0.000, 5.000], mean observation: 105.522 [87.000, 236.000], loss: 0.002290, mean_absolute_error: 0.568054, mean_q: 0.722556, mean_eps: 0.020000
1221199/1700000: episode: 538, duration: 15.728s, episode steps: 2925, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.728 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.002716, mean_absolute_error: 0.565944, mean_q: 0.723546, mean_eps: 0.020000
1223593/1700000: episode: 539, duration: 12.946s, episode steps: 2394, steps per second: 185, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.572 [0.000, 5.000], mean observation: 105.526 [87.000, 236.000], loss: 0.002602, mean_absolute_error: 0.563635, mean_q: 0.718889, mean_eps: 0.020000
1226081/1700000: episode: 540, duration: 13.313s, episode steps: 2488, steps per second: 187, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.715 [0.000, 5.000], mean observation: 105.510 [87.000, 236.000], loss: 0.002494, mean_absolute_error: 0.567778, mean_q: 0.726917, mean_eps: 0.020000
1228936/1700000: episode: 541, duration: 15.352s, episode steps: 2855, steps per second: 186, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.808 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.002844, mean_absolute_error: 0.570974, mean_q: 0.728913, mean_eps: 0.020000
1231783/1700000: episode: 542, duration: 15.305s, episode steps: 2847, steps per second: 186, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.619 [0.000, 5.000], mean observation: 105.576 [87.000, 236.000], loss: 0.002657, mean_absolute_error: 0.569930, mean_q: 0.728721, mean_eps: 0.020000
1233863/1700000: episode: 543, duration: 11.287s, episode steps: 2080, steps per second: 184, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.585 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.002919, mean_absolute_error: 0.572798, mean_q: 0.729351, mean_eps: 0.020000
1236328/1700000: episode: 544, duration: 13.362s, episode steps: 2465, steps per second: 184, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.694 [0.000, 5.000], mean observation: 105.520 [87.000, 236.000], loss: 0.002239, mean_absolute_error: 0.584044, mean_q: 0.738274, mean_eps: 0.020000
1238592/1700000: episode: 545, duration: 12.235s, episode steps: 2264, steps per second: 185, episode reward: 11.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.805 [0.000, 5.000], mean observation: 105.537 [87.000, 236.000], loss: 0.002440, mean_absolute_error: 0.606053, mean_q: 0.760396, mean_eps: 0.020000
1240537/1700000: episode: 546, duration: 10.485s, episode steps: 1945, steps per second: 186, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.863 [0.000, 5.000], mean observation: 105.503 [87.000, 236.000], loss: 0.002333, mean_absolute_error: 0.621353, mean_q: 0.782585, mean_eps: 0.020000
1242690/1700000: episode: 547, duration: 11.623s, episode steps: 2153, steps per second: 185, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.608 [0.000, 5.000], mean observation: 105.526 [87.000, 236.000], loss: 0.002011, mean_absolute_error: 0.646653, mean_q: 0.814353, mean_eps: 0.020000
1244882/1700000: episode: 548, duration: 11.942s, episode steps: 2192, steps per second: 184, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.596 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.002353, mean_absolute_error: 0.636115, mean_q: 0.801468, mean_eps: 0.020000
1247513/1700000: episode: 549, duration: 14.363s, episode steps: 2631, steps per second: 183, episode reward: -5.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.648 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.002599, mean_absolute_error: 0.612399, mean_q: 0.773137, mean_eps: 0.020000
1249958/1700000: episode: 550, duration: 13.228s, episode steps: 2445, steps per second: 185, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.604 [0.000, 5.000], mean observation: 105.552 [87.000, 236.000], loss: 0.002898, mean_absolute_error: 0.604094, mean_q: 0.765394, mean_eps: 0.020000
1253159/1700000: episode: 551, duration: 17.271s, episode steps: 3201, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.676 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.003166, mean_absolute_error: 0.580281, mean_q: 0.740322, mean_eps: 0.020000
1255771/1700000: episode: 552, duration: 14.153s, episode steps: 2612, steps per second: 185, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.766 [0.000, 5.000], mean observation: 105.552 [87.000, 236.000], loss: 0.003643, mean_absolute_error: 0.555060, mean_q: 0.712656, mean_eps: 0.020000
1259045/1700000: episode: 553, duration: 17.994s, episode steps: 3274, steps per second: 182, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.522 [0.000, 5.000], mean observation: 105.620 [87.000, 236.000], loss: 0.002953, mean_absolute_error: 0.571719, mean_q: 0.739202, mean_eps: 0.020000
1261108/1700000: episode: 554, duration: 11.137s, episode steps: 2063, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.712 [0.000, 5.000], mean observation: 105.529 [87.000, 236.000], loss: 0.003226, mean_absolute_error: 0.574641, mean_q: 0.738486, mean_eps: 0.020000
1264112/1700000: episode: 555, duration: 16.396s, episode steps: 3004, steps per second: 183, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.846 [0.000, 5.000], mean observation: 105.576 [87.000, 236.000], loss: 0.002908, mean_absolute_error: 0.593068, mean_q: 0.762302, mean_eps: 0.020000
1266135/1700000: episode: 556, duration: 10.993s, episode steps: 2023, steps per second: 184, episode reward: 16.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.766 [0.000, 5.000], mean observation: 105.546 [87.000, 236.000], loss: 0.002515, mean_absolute_error: 0.614124, mean_q: 0.790847, mean_eps: 0.020000
1268157/1700000: episode: 557, duration: 10.910s, episode steps: 2022, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.744 [0.000, 5.000], mean observation: 105.487 [87.000, 236.000], loss: 0.002647, mean_absolute_error: 0.637506, mean_q: 0.820162, mean_eps: 0.020000
1270856/1700000: episode: 558, duration: 14.579s, episode steps: 2699, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.705 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.002417, mean_absolute_error: 0.666980, mean_q: 0.856301, mean_eps: 0.020000
1273000/1700000: episode: 559, duration: 11.578s, episode steps: 2144, steps per second: 185, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.596 [0.000, 5.000], mean observation: 105.506 [87.000, 236.000], loss: 0.002639, mean_absolute_error: 0.675916, mean_q: 0.864402, mean_eps: 0.020000
1276189/1700000: episode: 560, duration: 17.205s, episode steps: 3189, steps per second: 185, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.699 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.003098, mean_absolute_error: 0.665781, mean_q: 0.846632, mean_eps: 0.020000
1279279/1700000: episode: 561, duration: 16.720s, episode steps: 3090, steps per second: 185, episode reward: 3.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.454 [0.000, 5.000], mean observation: 105.529 [87.000, 236.000], loss: 0.003252, mean_absolute_error: 0.639124, mean_q: 0.811861, mean_eps: 0.020000
1281225/1700000: episode: 562, duration: 10.504s, episode steps: 1946, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.594 [0.000, 5.000], mean observation: 105.542 [87.000, 236.000], loss: 0.003355, mean_absolute_error: 0.627453, mean_q: 0.795744, mean_eps: 0.020000
1283341/1700000: episode: 563, duration: 11.387s, episode steps: 2116, steps per second: 186, episode reward: 12.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.655 [0.000, 5.000], mean observation: 105.510 [87.000, 236.000], loss: 0.002878, mean_absolute_error: 0.637983, mean_q: 0.806621, mean_eps: 0.020000
1285834/1700000: episode: 564, duration: 13.441s, episode steps: 2493, steps per second: 185, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.602 [0.000, 5.000], mean observation: 105.543 [87.000, 236.000], loss: 0.002539, mean_absolute_error: 0.654179, mean_q: 0.825874, mean_eps: 0.020000
1287813/1700000: episode: 565, duration: 10.719s, episode steps: 1979, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.420 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.002279, mean_absolute_error: 0.664171, mean_q: 0.835483, mean_eps: 0.020000
1290086/1700000: episode: 566, duration: 12.309s, episode steps: 2273, steps per second: 185, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.450 [0.000, 5.000], mean observation: 105.502 [87.000, 236.000], loss: 0.002107, mean_absolute_error: 0.686106, mean_q: 0.868915, mean_eps: 0.020000
1293549/1700000: episode: 567, duration: 18.753s, episode steps: 3463, steps per second: 185, episode reward: -2.000, mean reward: -0.001 [-1.000, 1.000], mean action: 2.712 [0.000, 5.000], mean observation: 105.610 [87.000, 236.000], loss: 0.002588, mean_absolute_error: 0.658756, mean_q: 0.834676, mean_eps: 0.020000
1296297/1700000: episode: 568, duration: 14.778s, episode steps: 2748, steps per second: 186, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.527 [0.000, 5.000], mean observation: 105.567 [87.000, 236.000], loss: 0.002592, mean_absolute_error: 0.621805, mean_q: 0.791577, mean_eps: 0.020000
1299085/1700000: episode: 569, duration: 15.048s, episode steps: 2788, steps per second: 185, episode reward: -5.000, mean reward: -0.002 [-1.000, 1.000], mean action: 2.496 [0.000, 5.000], mean observation: 105.627 [87.000, 236.000], loss: 0.002719, mean_absolute_error: 0.579885, mean_q: 0.737550, mean_eps: 0.020000
1301840/1700000: episode: 570, duration: 14.915s, episode steps: 2755, steps per second: 185, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.486 [0.000, 5.000], mean observation: 105.569 [87.000, 236.000], loss: 0.002647, mean_absolute_error: 0.565492, mean_q: 0.718508, mean_eps: 0.020000
1304209/1700000: episode: 571, duration: 12.905s, episode steps: 2369, steps per second: 184, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.445 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.002901, mean_absolute_error: 0.586660, mean_q: 0.743745, mean_eps: 0.020000
1306686/1700000: episode: 572, duration: 13.370s, episode steps: 2477, steps per second: 185, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.616 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.003111, mean_absolute_error: 0.588465, mean_q: 0.743879, mean_eps: 0.020000
1308834/1700000: episode: 573, duration: 11.750s, episode steps: 2148, steps per second: 183, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.487 [0.000, 5.000], mean observation: 105.534 [87.000, 236.000], loss: 0.003311, mean_absolute_error: 0.621437, mean_q: 0.788330, mean_eps: 0.020000
1312397/1700000: episode: 574, duration: 19.272s, episode steps: 3563, steps per second: 185, episode reward: 8.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.560 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: 0.003076, mean_absolute_error: 0.618689, mean_q: 0.793770, mean_eps: 0.020000
1315352/1700000: episode: 575, duration: 16.291s, episode steps: 2955, steps per second: 181, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.606 [0.000, 5.000], mean observation: 105.568 [87.000, 236.000], loss: 0.002951, mean_absolute_error: 0.578085, mean_q: 0.742263, mean_eps: 0.020000
1319002/1700000: episode: 576, duration: 19.674s, episode steps: 3650, steps per second: 186, episode reward: 1.000, mean reward: 0.000 [-1.000, 1.000], mean action: 2.687 [0.000, 5.000], mean observation: 105.640 [87.000, 236.000], loss: 0.003027, mean_absolute_error: 0.552693, mean_q: 0.712175, mean_eps: 0.020000
1321713/1700000: episode: 577, duration: 14.579s, episode steps: 2711, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.427 [0.000, 5.000], mean observation: 105.552 [87.000, 236.000], loss: 0.003209, mean_absolute_error: 0.518182, mean_q: 0.668097, mean_eps: 0.020000
1323874/1700000: episode: 578, duration: 11.739s, episode steps: 2161, steps per second: 184, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.185 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.003043, mean_absolute_error: 0.554896, mean_q: 0.711638, mean_eps: 0.020000
1326647/1700000: episode: 579, duration: 14.913s, episode steps: 2773, steps per second: 186, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.410 [0.000, 5.000], mean observation: 105.578 [87.000, 236.000], loss: 0.003002, mean_absolute_error: 0.561071, mean_q: 0.719857, mean_eps: 0.020000
1329096/1700000: episode: 580, duration: 13.202s, episode steps: 2449, steps per second: 186, episode reward: 7.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.256 [0.000, 5.000], mean observation: 105.617 [87.000, 236.000], loss: 0.003072, mean_absolute_error: 0.603273, mean_q: 0.769144, mean_eps: 0.020000
1330896/1700000: episode: 581, duration: 9.728s, episode steps: 1800, steps per second: 185, episode reward: 20.000, mean reward: 0.011 [-1.000, 1.000], mean action: 2.374 [0.000, 5.000], mean observation: 105.475 [87.000, 236.000], loss: 0.002966, mean_absolute_error: 0.622213, mean_q: 0.792371, mean_eps: 0.020000
1333544/1700000: episode: 582, duration: 14.347s, episode steps: 2648, steps per second: 185, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.506 [0.000, 5.000], mean observation: 105.527 [87.000, 236.000], loss: 0.002874, mean_absolute_error: 0.631349, mean_q: 0.803855, mean_eps: 0.020000
1335385/1700000: episode: 583, duration: 9.941s, episode steps: 1841, steps per second: 185, episode reward: 20.000, mean reward: 0.011 [-1.000, 1.000], mean action: 2.404 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.002196, mean_absolute_error: 0.630046, mean_q: 0.802026, mean_eps: 0.020000
1337973/1700000: episode: 584, duration: 14.033s, episode steps: 2588, steps per second: 184, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.619 [0.000, 5.000], mean observation: 105.532 [87.000, 236.000], loss: 0.002264, mean_absolute_error: 0.622934, mean_q: 0.797761, mean_eps: 0.020000
1339978/1700000: episode: 585, duration: 10.843s, episode steps: 2005, steps per second: 185, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.683 [0.000, 5.000], mean observation: 105.546 [87.000, 236.000], loss: 0.002309, mean_absolute_error: 0.630562, mean_q: 0.814032, mean_eps: 0.020000
1342108/1700000: episode: 586, duration: 11.497s, episode steps: 2130, steps per second: 185, episode reward: 16.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.311 [0.000, 5.000], mean observation: 105.521 [87.000, 236.000], loss: 0.002676, mean_absolute_error: 0.636296, mean_q: 0.820554, mean_eps: 0.020000
1344737/1700000: episode: 587, duration: 14.241s, episode steps: 2629, steps per second: 185, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.688 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.002567, mean_absolute_error: 0.642984, mean_q: 0.830638, mean_eps: 0.020000
1347136/1700000: episode: 588, duration: 12.942s, episode steps: 2399, steps per second: 185, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.558 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.002704, mean_absolute_error: 0.650287, mean_q: 0.833362, mean_eps: 0.020000
1349126/1700000: episode: 589, duration: 10.751s, episode steps: 1990, steps per second: 185, episode reward: 17.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.533 [0.000, 5.000], mean observation: 105.480 [87.000, 236.000], loss: 0.003189, mean_absolute_error: 0.657138, mean_q: 0.839051, mean_eps: 0.020000
1351123/1700000: episode: 590, duration: 10.831s, episode steps: 1997, steps per second: 184, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.757 [0.000, 5.000], mean observation: 105.504 [87.000, 236.000], loss: 0.002619, mean_absolute_error: 0.661667, mean_q: 0.846634, mean_eps: 0.020000
1354353/1700000: episode: 591, duration: 17.550s, episode steps: 3230, steps per second: 184, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.770 [0.000, 5.000], mean observation: 105.692 [87.000, 236.000], loss: 0.002900, mean_absolute_error: 0.661880, mean_q: 0.843494, mean_eps: 0.020000
1356719/1700000: episode: 592, duration: 12.814s, episode steps: 2366, steps per second: 185, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.702 [0.000, 5.000], mean observation: 105.511 [87.000, 236.000], loss: 0.003001, mean_absolute_error: 0.632190, mean_q: 0.807615, mean_eps: 0.020000
1358999/1700000: episode: 593, duration: 12.380s, episode steps: 2280, steps per second: 184, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.729 [0.000, 5.000], mean observation: 105.517 [87.000, 236.000], loss: 0.002939, mean_absolute_error: 0.644038, mean_q: 0.823975, mean_eps: 0.020000
1361690/1700000: episode: 594, duration: 14.517s, episode steps: 2691, steps per second: 185, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.894 [0.000, 5.000], mean observation: 105.603 [87.000, 236.000], loss: 0.003159, mean_absolute_error: 0.640273, mean_q: 0.814058, mean_eps: 0.020000
1363798/1700000: episode: 595, duration: 11.373s, episode steps: 2108, steps per second: 185, episode reward: 16.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.726 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.002429, mean_absolute_error: 0.645410, mean_q: 0.818478, mean_eps: 0.020000
1366998/1700000: episode: 596, duration: 17.354s, episode steps: 3200, steps per second: 184, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.760 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.003004, mean_absolute_error: 0.660325, mean_q: 0.840486, mean_eps: 0.020000
1369931/1700000: episode: 597, duration: 15.835s, episode steps: 2933, steps per second: 185, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.733 [0.000, 5.000], mean observation: 105.609 [87.000, 236.000], loss: 0.003115, mean_absolute_error: 0.653058, mean_q: 0.832670, mean_eps: 0.020000
1371998/1700000: episode: 598, duration: 11.414s, episode steps: 2067, steps per second: 181, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.820 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.002483, mean_absolute_error: 0.656575, mean_q: 0.837340, mean_eps: 0.020000
1374880/1700000: episode: 599, duration: 15.928s, episode steps: 2882, steps per second: 181, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.779 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.002545, mean_absolute_error: 0.648956, mean_q: 0.829011, mean_eps: 0.020000
1377209/1700000: episode: 600, duration: 12.856s, episode steps: 2329, steps per second: 181, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.768 [0.000, 5.000], mean observation: 105.526 [87.000, 236.000], loss: 0.002697, mean_absolute_error: 0.656972, mean_q: 0.837757, mean_eps: 0.020000
1380232/1700000: episode: 601, duration: 16.524s, episode steps: 3023, steps per second: 183, episode reward: 7.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.772 [0.000, 5.000], mean observation: 105.611 [87.000, 236.000], loss: 0.003009, mean_absolute_error: 0.654115, mean_q: 0.835514, mean_eps: 0.020000
1382927/1700000: episode: 602, duration: 14.746s, episode steps: 2695, steps per second: 183, episode reward: 7.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.669 [0.000, 5.000], mean observation: 105.606 [87.000, 236.000], loss: 0.003115, mean_absolute_error: 0.649585, mean_q: 0.828573, mean_eps: 0.020000
1384967/1700000: episode: 603, duration: 10.977s, episode steps: 2040, steps per second: 186, episode reward: 19.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.452 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.002769, mean_absolute_error: 0.646901, mean_q: 0.828237, mean_eps: 0.020000
1387360/1700000: episode: 604, duration: 13.025s, episode steps: 2393, steps per second: 184, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.782 [0.000, 5.000], mean observation: 105.527 [87.000, 236.000], loss: 0.002310, mean_absolute_error: 0.651251, mean_q: 0.835673, mean_eps: 0.020000
1389834/1700000: episode: 605, duration: 13.342s, episode steps: 2474, steps per second: 185, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.484 [0.000, 5.000], mean observation: 105.570 [87.000, 236.000], loss: 0.002048, mean_absolute_error: 0.666410, mean_q: 0.853076, mean_eps: 0.020000
1392519/1700000: episode: 606, duration: 14.603s, episode steps: 2685, steps per second: 184, episode reward: 7.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.699 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.002376, mean_absolute_error: 0.664010, mean_q: 0.852342, mean_eps: 0.020000
1395387/1700000: episode: 607, duration: 15.498s, episode steps: 2868, steps per second: 185, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.555 [0.000, 5.000], mean observation: 105.596 [87.000, 236.000], loss: 0.002692, mean_absolute_error: 0.668033, mean_q: 0.854872, mean_eps: 0.020000
1398327/1700000: episode: 608, duration: 16.271s, episode steps: 2940, steps per second: 181, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.629 [0.000, 5.000], mean observation: 105.621 [87.000, 236.000], loss: 0.002680, mean_absolute_error: 0.635898, mean_q: 0.813207, mean_eps: 0.020000
1400574/1700000: episode: 609, duration: 12.260s, episode steps: 2247, steps per second: 183, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.431 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.002671, mean_absolute_error: 0.634683, mean_q: 0.812101, mean_eps: 0.020000
1402678/1700000: episode: 610, duration: 11.407s, episode steps: 2104, steps per second: 184, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.565 [0.000, 5.000], mean observation: 105.479 [87.000, 236.000], loss: 0.002353, mean_absolute_error: 0.649944, mean_q: 0.831562, mean_eps: 0.020000
1405199/1700000: episode: 611, duration: 13.571s, episode steps: 2521, steps per second: 186, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.465 [0.000, 5.000], mean observation: 105.521 [87.000, 236.000], loss: 0.002268, mean_absolute_error: 0.652118, mean_q: 0.835584, mean_eps: 0.020000
1407023/1700000: episode: 612, duration: 9.846s, episode steps: 1824, steps per second: 185, episode reward: 19.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.312 [0.000, 5.000], mean observation: 105.589 [87.000, 236.000], loss: 0.001921, mean_absolute_error: 0.685122, mean_q: 0.880290, mean_eps: 0.020000
1409593/1700000: episode: 613, duration: 13.913s, episode steps: 2570, steps per second: 185, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.602 [0.000, 5.000], mean observation: 105.570 [87.000, 236.000], loss: 0.001824, mean_absolute_error: 0.698188, mean_q: 0.897581, mean_eps: 0.020000
1411937/1700000: episode: 614, duration: 12.773s, episode steps: 2344, steps per second: 184, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.617 [0.000, 5.000], mean observation: 105.561 [87.000, 236.000], loss: 0.002003, mean_absolute_error: 0.685403, mean_q: 0.880856, mean_eps: 0.020000
1414730/1700000: episode: 615, duration: 15.214s, episode steps: 2793, steps per second: 184, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.394 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.002363, mean_absolute_error: 0.678820, mean_q: 0.871459, mean_eps: 0.020000
1416752/1700000: episode: 616, duration: 11.062s, episode steps: 2022, steps per second: 183, episode reward: 19.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.567 [0.000, 5.000], mean observation: 105.466 [87.000, 236.000], loss: 0.002172, mean_absolute_error: 0.658040, mean_q: 0.850581, mean_eps: 0.020000
1418845/1700000: episode: 617, duration: 11.533s, episode steps: 2093, steps per second: 181, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.698 [0.000, 5.000], mean observation: 105.516 [87.000, 236.000], loss: 0.002378, mean_absolute_error: 0.650601, mean_q: 0.842630, mean_eps: 0.020000
1420712/1700000: episode: 618, duration: 10.348s, episode steps: 1867, steps per second: 180, episode reward: 18.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.516 [0.000, 5.000], mean observation: 105.537 [87.000, 236.000], loss: 0.002009, mean_absolute_error: 0.667849, mean_q: 0.864213, mean_eps: 0.020000
1424001/1700000: episode: 619, duration: 17.815s, episode steps: 3289, steps per second: 185, episode reward: 8.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.744 [0.000, 5.000], mean observation: 105.612 [87.000, 236.000], loss: 0.002185, mean_absolute_error: 0.678176, mean_q: 0.876019, mean_eps: 0.020000
1425929/1700000: episode: 620, duration: 10.479s, episode steps: 1928, steps per second: 184, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.518 [0.000, 5.000], mean observation: 105.512 [87.000, 236.000], loss: 0.002241, mean_absolute_error: 0.682182, mean_q: 0.879525, mean_eps: 0.020000
1428207/1700000: episode: 621, duration: 12.423s, episode steps: 2278, steps per second: 183, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.574 [0.000, 5.000], mean observation: 105.585 [87.000, 236.000], loss: 0.002293, mean_absolute_error: 0.690304, mean_q: 0.889093, mean_eps: 0.020000
1431096/1700000: episode: 622, duration: 15.798s, episode steps: 2889, steps per second: 183, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.749 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.002348, mean_absolute_error: 0.683089, mean_q: 0.878522, mean_eps: 0.020000
1433260/1700000: episode: 623, duration: 11.679s, episode steps: 2164, steps per second: 185, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.701 [0.000, 5.000], mean observation: 105.518 [87.000, 236.000], loss: 0.003278, mean_absolute_error: 0.672530, mean_q: 0.862247, mean_eps: 0.020000
1436288/1700000: episode: 624, duration: 16.304s, episode steps: 3028, steps per second: 186, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.700 [0.000, 5.000], mean observation: 105.591 [87.000, 236.000], loss: 0.003382, mean_absolute_error: 0.681904, mean_q: 0.875718, mean_eps: 0.020000
1438564/1700000: episode: 625, duration: 12.249s, episode steps: 2276, steps per second: 186, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.655 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.003218, mean_absolute_error: 0.654740, mean_q: 0.840206, mean_eps: 0.020000
1441644/1700000: episode: 626, duration: 16.626s, episode steps: 3080, steps per second: 185, episode reward: 4.000, mean reward: 0.001 [-1.000, 1.000], mean action: 2.748 [0.000, 5.000], mean observation: 105.620 [87.000, 236.000], loss: 0.003812, mean_absolute_error: 0.641622, mean_q: 0.818168, mean_eps: 0.020000
1444437/1700000: episode: 627, duration: 15.079s, episode steps: 2793, steps per second: 185, episode reward: 5.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.586 [0.000, 5.000], mean observation: 105.587 [87.000, 236.000], loss: 0.003077, mean_absolute_error: 0.638781, mean_q: 0.814357, mean_eps: 0.020000
1446630/1700000: episode: 628, duration: 11.779s, episode steps: 2193, steps per second: 186, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.549 [0.000, 5.000], mean observation: 105.530 [87.000, 236.000], loss: 0.002833, mean_absolute_error: 0.629525, mean_q: 0.801490, mean_eps: 0.020000
1449200/1700000: episode: 629, duration: 13.864s, episode steps: 2570, steps per second: 185, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.552 [0.000, 5.000], mean observation: 105.537 [87.000, 236.000], loss: 0.002574, mean_absolute_error: 0.637968, mean_q: 0.810030, mean_eps: 0.020000
1451504/1700000: episode: 630, duration: 12.447s, episode steps: 2304, steps per second: 185, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.516 [0.000, 5.000], mean observation: 105.524 [87.000, 236.000], loss: 0.002074, mean_absolute_error: 0.662097, mean_q: 0.843164, mean_eps: 0.020000
1454277/1700000: episode: 631, duration: 14.949s, episode steps: 2773, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.650 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.002313, mean_absolute_error: 0.672711, mean_q: 0.858250, mean_eps: 0.020000
1457140/1700000: episode: 632, duration: 15.474s, episode steps: 2863, steps per second: 185, episode reward: 14.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.582 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.002335, mean_absolute_error: 0.660574, mean_q: 0.845731, mean_eps: 0.020000
1459284/1700000: episode: 633, duration: 11.557s, episode steps: 2144, steps per second: 186, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.439 [0.000, 5.000], mean observation: 105.514 [87.000, 236.000], loss: 0.002647, mean_absolute_error: 0.645404, mean_q: 0.823075, mean_eps: 0.020000
1461962/1700000: episode: 634, duration: 14.405s, episode steps: 2678, steps per second: 186, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.741 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.002558, mean_absolute_error: 0.644777, mean_q: 0.828206, mean_eps: 0.020000
1464744/1700000: episode: 635, duration: 15.054s, episode steps: 2782, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.891 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.002689, mean_absolute_error: 0.638996, mean_q: 0.820453, mean_eps: 0.020000
1467416/1700000: episode: 636, duration: 14.442s, episode steps: 2672, steps per second: 185, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.702 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.002674, mean_absolute_error: 0.642490, mean_q: 0.828441, mean_eps: 0.020000
1469948/1700000: episode: 637, duration: 13.722s, episode steps: 2532, steps per second: 185, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.823 [0.000, 5.000], mean observation: 105.553 [87.000, 236.000], loss: 0.002459, mean_absolute_error: 0.643549, mean_q: 0.827999, mean_eps: 0.020000
1472303/1700000: episode: 638, duration: 12.763s, episode steps: 2355, steps per second: 185, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.658 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.002449, mean_absolute_error: 0.648410, mean_q: 0.833118, mean_eps: 0.020000
1475048/1700000: episode: 639, duration: 14.843s, episode steps: 2745, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.648 [0.000, 5.000], mean observation: 105.558 [87.000, 236.000], loss: 0.002535, mean_absolute_error: 0.663832, mean_q: 0.852889, mean_eps: 0.020000
1477449/1700000: episode: 640, duration: 12.936s, episode steps: 2401, steps per second: 186, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.679 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.002940, mean_absolute_error: 0.665198, mean_q: 0.850560, mean_eps: 0.020000
1479544/1700000: episode: 641, duration: 11.288s, episode steps: 2095, steps per second: 186, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.453 [0.000, 5.000], mean observation: 105.500 [87.000, 236.000], loss: 0.002618, mean_absolute_error: 0.677506, mean_q: 0.867663, mean_eps: 0.020000
1481580/1700000: episode: 642, duration: 10.985s, episode steps: 2036, steps per second: 185, episode reward: 19.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.751 [0.000, 5.000], mean observation: 105.520 [87.000, 236.000], loss: 0.002081, mean_absolute_error: 0.680434, mean_q: 0.871843, mean_eps: 0.020000
1484266/1700000: episode: 643, duration: 14.485s, episode steps: 2686, steps per second: 185, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.810 [0.000, 5.000], mean observation: 105.537 [87.000, 236.000], loss: 0.001931, mean_absolute_error: 0.689949, mean_q: 0.882503, mean_eps: 0.020000
1487152/1700000: episode: 644, duration: 16.036s, episode steps: 2886, steps per second: 180, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.722 [0.000, 5.000], mean observation: 105.551 [87.000, 236.000], loss: 0.002086, mean_absolute_error: 0.682278, mean_q: 0.877363, mean_eps: 0.020000
1488797/1700000: episode: 645, duration: 8.894s, episode steps: 1645, steps per second: 185, episode reward: 21.000, mean reward: 0.013 [0.000, 1.000], mean action: 2.889 [0.000, 5.000], mean observation: 105.598 [87.000, 236.000], loss: 0.001901, mean_absolute_error: 0.681625, mean_q: 0.875332, mean_eps: 0.020000
1490778/1700000: episode: 646, duration: 10.713s, episode steps: 1981, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.751 [0.000, 5.000], mean observation: 105.507 [87.000, 236.000], loss: 0.002122, mean_absolute_error: 0.688411, mean_q: 0.885246, mean_eps: 0.020000
1492861/1700000: episode: 647, duration: 11.187s, episode steps: 2083, steps per second: 186, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.792 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.001979, mean_absolute_error: 0.691761, mean_q: 0.889591, mean_eps: 0.020000
1494801/1700000: episode: 648, duration: 10.433s, episode steps: 1940, steps per second: 186, episode reward: 15.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.730 [0.000, 5.000], mean observation: 105.577 [87.000, 236.000], loss: 0.001611, mean_absolute_error: 0.726762, mean_q: 0.932183, mean_eps: 0.020000
1497466/1700000: episode: 649, duration: 14.405s, episode steps: 2665, steps per second: 185, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.682 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.001747, mean_absolute_error: 0.750094, mean_q: 0.958073, mean_eps: 0.020000
1499241/1700000: episode: 650, duration: 9.621s, episode steps: 1775, steps per second: 184, episode reward: 20.000, mean reward: 0.011 [-1.000, 1.000], mean action: 2.653 [0.000, 5.000], mean observation: 105.546 [87.000, 236.000], loss: 0.001915, mean_absolute_error: 0.741383, mean_q: 0.951618, mean_eps: 0.020000
1501413/1700000: episode: 651, duration: 11.791s, episode steps: 2172, steps per second: 184, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.597 [0.000, 5.000], mean observation: 105.501 [87.000, 236.000], loss: 0.001856, mean_absolute_error: 0.743423, mean_q: 0.950468, mean_eps: 0.020000
1503722/1700000: episode: 652, duration: 12.445s, episode steps: 2309, steps per second: 186, episode reward: 17.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.752 [0.000, 5.000], mean observation: 105.552 [87.000, 236.000], loss: 0.001669, mean_absolute_error: 0.734679, mean_q: 0.938996, mean_eps: 0.020000
1505623/1700000: episode: 653, duration: 10.219s, episode steps: 1901, steps per second: 186, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.660 [0.000, 5.000], mean observation: 105.465 [87.000, 236.000], loss: 0.001884, mean_absolute_error: 0.729090, mean_q: 0.930724, mean_eps: 0.020000
1507880/1700000: episode: 654, duration: 12.125s, episode steps: 2257, steps per second: 186, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.864 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.001882, mean_absolute_error: 0.737604, mean_q: 0.940521, mean_eps: 0.020000
1510265/1700000: episode: 655, duration: 12.886s, episode steps: 2385, steps per second: 185, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.743 [0.000, 5.000], mean observation: 105.560 [87.000, 236.000], loss: 0.001663, mean_absolute_error: 0.763013, mean_q: 0.973829, mean_eps: 0.020000
1512598/1700000: episode: 656, duration: 12.548s, episode steps: 2333, steps per second: 186, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.638 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.001891, mean_absolute_error: 0.756813, mean_q: 0.961831, mean_eps: 0.020000
1514532/1700000: episode: 657, duration: 10.525s, episode steps: 1934, steps per second: 184, episode reward: 17.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.511 [0.000, 5.000], mean observation: 105.505 [87.000, 236.000], loss: 0.002023, mean_absolute_error: 0.752527, mean_q: 0.955959, mean_eps: 0.020000
1516412/1700000: episode: 658, duration: 10.152s, episode steps: 1880, steps per second: 185, episode reward: 19.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.794 [0.000, 5.000], mean observation: 105.541 [87.000, 236.000], loss: 0.002123, mean_absolute_error: 0.764790, mean_q: 0.972307, mean_eps: 0.020000
1518690/1700000: episode: 659, duration: 12.232s, episode steps: 2278, steps per second: 186, episode reward: 17.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.680 [0.000, 5.000], mean observation: 105.536 [87.000, 236.000], loss: 0.001626, mean_absolute_error: 0.774758, mean_q: 0.984355, mean_eps: 0.020000
1521241/1700000: episode: 660, duration: 13.728s, episode steps: 2551, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.623 [0.000, 5.000], mean observation: 105.541 [87.000, 236.000], loss: 0.001830, mean_absolute_error: 0.770596, mean_q: 0.981672, mean_eps: 0.020000
1523728/1700000: episode: 661, duration: 13.331s, episode steps: 2487, steps per second: 187, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.809 [0.000, 5.000], mean observation: 105.544 [87.000, 236.000], loss: 0.002085, mean_absolute_error: 0.774275, mean_q: 0.983484, mean_eps: 0.020000
1525539/1700000: episode: 662, duration: 9.707s, episode steps: 1811, steps per second: 187, episode reward: 18.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.421 [0.000, 5.000], mean observation: 105.448 [87.000, 236.000], loss: 0.002146, mean_absolute_error: 0.757838, mean_q: 0.964181, mean_eps: 0.020000
1528739/1700000: episode: 663, duration: 17.310s, episode steps: 3200, steps per second: 185, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.577 [0.000, 5.000], mean observation: 105.624 [87.000, 236.000], loss: 0.002273, mean_absolute_error: 0.733916, mean_q: 0.932952, mean_eps: 0.020000
1531033/1700000: episode: 664, duration: 12.435s, episode steps: 2294, steps per second: 184, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.679 [0.000, 5.000], mean observation: 105.538 [87.000, 236.000], loss: 0.002583, mean_absolute_error: 0.704486, mean_q: 0.898186, mean_eps: 0.020000
1533319/1700000: episode: 665, duration: 12.243s, episode steps: 2286, steps per second: 187, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.523 [0.000, 5.000], mean observation: 105.535 [87.000, 236.000], loss: 0.002251, mean_absolute_error: 0.711206, mean_q: 0.904115, mean_eps: 0.020000
1535710/1700000: episode: 666, duration: 12.832s, episode steps: 2391, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.513 [0.000, 5.000], mean observation: 105.586 [87.000, 236.000], loss: 0.002615, mean_absolute_error: 0.699667, mean_q: 0.888194, mean_eps: 0.020000
1537741/1700000: episode: 667, duration: 10.965s, episode steps: 2031, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.315 [0.000, 5.000], mean observation: 105.551 [87.000, 236.000], loss: 0.002225, mean_absolute_error: 0.706509, mean_q: 0.895304, mean_eps: 0.020000
1540633/1700000: episode: 668, duration: 15.546s, episode steps: 2892, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.557 [0.000, 5.000], mean observation: 105.563 [87.000, 236.000], loss: 0.002130, mean_absolute_error: 0.741050, mean_q: 0.942989, mean_eps: 0.020000
1543124/1700000: episode: 669, duration: 13.695s, episode steps: 2491, steps per second: 182, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.583 [0.000, 5.000], mean observation: 105.557 [87.000, 236.000], loss: 0.001946, mean_absolute_error: 0.721941, mean_q: 0.919706, mean_eps: 0.020000
1545362/1700000: episode: 670, duration: 12.206s, episode steps: 2238, steps per second: 183, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.625 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.002452, mean_absolute_error: 0.721526, mean_q: 0.920923, mean_eps: 0.020000
1547612/1700000: episode: 671, duration: 12.066s, episode steps: 2250, steps per second: 186, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.515 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.002547, mean_absolute_error: 0.714640, mean_q: 0.911165, mean_eps: 0.020000
1549642/1700000: episode: 672, duration: 10.934s, episode steps: 2030, steps per second: 186, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.525 [0.000, 5.000], mean observation: 105.579 [87.000, 236.000], loss: 0.002252, mean_absolute_error: 0.697963, mean_q: 0.891132, mean_eps: 0.020000
1551673/1700000: episode: 673, duration: 10.874s, episode steps: 2031, steps per second: 187, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.694 [0.000, 5.000], mean observation: 105.529 [87.000, 236.000], loss: 0.002757, mean_absolute_error: 0.719848, mean_q: 0.919698, mean_eps: 0.020000
1553701/1700000: episode: 674, duration: 10.916s, episode steps: 2028, steps per second: 186, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.749 [0.000, 5.000], mean observation: 105.478 [87.000, 236.000], loss: 0.002588, mean_absolute_error: 0.733805, mean_q: 0.940421, mean_eps: 0.020000
1556041/1700000: episode: 675, duration: 12.542s, episode steps: 2340, steps per second: 187, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.650 [0.000, 5.000], mean observation: 105.548 [87.000, 236.000], loss: 0.002147, mean_absolute_error: 0.737289, mean_q: 0.948391, mean_eps: 0.020000
1557961/1700000: episode: 676, duration: 10.297s, episode steps: 1920, steps per second: 186, episode reward: 17.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.809 [0.000, 5.000], mean observation: 105.477 [87.000, 236.000], loss: 0.001985, mean_absolute_error: 0.750603, mean_q: 0.963206, mean_eps: 0.020000
1560615/1700000: episode: 677, duration: 14.336s, episode steps: 2654, steps per second: 185, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.810 [0.000, 5.000], mean observation: 105.584 [87.000, 236.000], loss: 0.002386, mean_absolute_error: 0.751759, mean_q: 0.962612, mean_eps: 0.020000
1562613/1700000: episode: 678, duration: 10.694s, episode steps: 1998, steps per second: 187, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.471 [0.000, 5.000], mean observation: 105.514 [87.000, 236.000], loss: 0.002218, mean_absolute_error: 0.746420, mean_q: 0.955576, mean_eps: 0.020000
1565467/1700000: episode: 679, duration: 15.337s, episode steps: 2854, steps per second: 186, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.616 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.002183, mean_absolute_error: 0.745190, mean_q: 0.953528, mean_eps: 0.020000
1568363/1700000: episode: 680, duration: 15.486s, episode steps: 2896, steps per second: 187, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.544 [0.000, 5.000], mean observation: 105.547 [87.000, 236.000], loss: 0.002580, mean_absolute_error: 0.697793, mean_q: 0.892904, mean_eps: 0.020000
1570465/1700000: episode: 681, duration: 11.252s, episode steps: 2102, steps per second: 187, episode reward: 16.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.487 [0.000, 5.000], mean observation: 105.502 [87.000, 236.000], loss: 0.002341, mean_absolute_error: 0.681218, mean_q: 0.871832, mean_eps: 0.020000
1573765/1700000: episode: 682, duration: 17.739s, episode steps: 3300, steps per second: 186, episode reward: 8.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.691 [0.000, 5.000], mean observation: 105.581 [87.000, 236.000], loss: 0.002125, mean_absolute_error: 0.672051, mean_q: 0.861712, mean_eps: 0.020000
1575871/1700000: episode: 683, duration: 11.409s, episode steps: 2106, steps per second: 185, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.840 [0.000, 5.000], mean observation: 105.541 [87.000, 236.000], loss: 0.002326, mean_absolute_error: 0.677172, mean_q: 0.866810, mean_eps: 0.020000
1578071/1700000: episode: 684, duration: 11.884s, episode steps: 2200, steps per second: 185, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.385 [0.000, 5.000], mean observation: 105.523 [87.000, 236.000], loss: 0.002125, mean_absolute_error: 0.721105, mean_q: 0.921304, mean_eps: 0.020000
1580102/1700000: episode: 685, duration: 10.934s, episode steps: 2031, steps per second: 186, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.473 [0.000, 5.000], mean observation: 105.507 [87.000, 236.000], loss: 0.002011, mean_absolute_error: 0.724511, mean_q: 0.927251, mean_eps: 0.020000
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 1582677/1700000: episode: 686, duration: 13.882s, episode steps: 2575, steps per second: 185, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.526 [0.000, 5.000], mean observation: 105.569 [87.000, 236.000], loss: 0.002245, mean_absolute_error: 0.732920, mean_q: 0.939551, mean_eps: 0.020000
 1584712/1700000: episode: 687, duration: 11.003s, episode steps: 2035, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.679 [0.000, 5.000], mean observation: 105.487 [87.000, 236.000], loss: 0.002396, mean_absolute_error: 0.750276, mean_q: 0.959373, mean_eps: 0.020000
 1587222/1700000: episode: 688, duration: 13.555s, episode steps: 2510, steps per second: 185, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.456 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.002177, mean_absolute_error: 0.748544, mean_q: 0.959628, mean_eps: 0.020000
 1589387/1700000: episode: 689, duration: 11.726s, episode steps: 2165, steps per second: 185, episode reward: 18.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.921 [0.000, 5.000], mean observation: 105.531 [87.000, 236.000], loss: 0.002016, mean_absolute_error: 0.741995, mean_q: 0.949879, mean_eps: 0.020000
 1591933/1700000: episode: 690, duration: 13.710s, episode steps: 2546, steps per second: 186, episode reward: 14.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.444 [0.000, 5.000], mean observation: 105.565 [87.000, 236.000], loss: 0.002043, mean_absolute_error: 0.746178, mean_q: 0.958449, mean_eps: 0.020000
 1594045/1700000: episode: 691, duration: 11.349s, episode steps: 2112, steps per second: 186, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.224 [0.000, 5.000], mean observation: 105.517 [87.000, 236.000], loss: 0.002366, mean_absolute_error: 0.746649, mean_q: 0.956278, mean_eps: 0.020000
 1595815/1700000: episode: 692, duration: 9.498s, episode steps: 1770, steps per second: 186, episode reward: 19.000, mean reward: 0.011 [-1.000, 1.000], mean action: 2.873 [0.000, 5.000], mean observation: 105.559 [87.000, 236.000], loss: 0.001917, mean_absolute_error: 0.744665, mean_q: 0.954384, mean_eps: 0.020000
 1598357/1700000: episode: 693, duration: 13.672s, episode steps: 2542, steps per second: 186, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.398 [0.000, 5.000], mean observation: 105.538 [87.000, 236.000], loss: 0.001987, mean_absolute_error: 0.753823, mean_q: 0.968359, mean_eps: 0.020000
 1600289/1700000: episode: 694, duration: 10.584s, episode steps: 1932, steps per second: 183, episode reward: 19.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.367 [0.000, 5.000], mean observation: 105.556 [87.000, 236.000], loss: 0.001829, mean_absolute_error: 0.757327, mean_q: 0.971834, mean_eps: 0.020000
 1603008/1700000: episode: 695, duration: 14.787s, episode steps: 2719, steps per second: 184, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.656 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: 0.001837, mean_absolute_error: 0.756310, mean_q: 0.969152, mean_eps: 0.020000
 1605247/1700000: episode: 696, duration: 12.076s, episode steps: 2239, steps per second: 185, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.662 [0.000, 5.000], mean observation: 105.554 [87.000, 236.000], loss: 0.001721, mean_absolute_error: 0.772679, mean_q: 0.990959, mean_eps: 0.020000
 1608121/1700000: episode: 697, duration: 15.457s, episode steps: 2874, steps per second: 186, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.699 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.002027, mean_absolute_error: 0.735385, mean_q: 0.939972, mean_eps: 0.020000
 1610083/1700000: episode: 698, duration: 10.593s, episode steps: 1962, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.638 [0.000, 5.000], mean observation: 105.549 [87.000, 236.000], loss: 0.001959, mean_absolute_error: 0.736245, mean_q: 0.938066, mean_eps: 0.020000
 1612377/1700000: episode: 699, duration: 12.306s, episode steps: 2294, steps per second: 186, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.532 [0.000, 5.000], mean observation: 105.517 [87.000, 236.000], loss: 0.001956, mean_absolute_error: 0.749410, mean_q: 0.956166, mean_eps: 0.020000
 1615433/1700000: episode: 700, duration: 16.435s, episode steps: 3056, steps per second: 186, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.827 [0.000, 5.000], mean observation: 105.611 [87.000, 236.000], loss: 0.001946, mean_absolute_error: 0.720026, mean_q: 0.923075, mean_eps: 0.020000
 1617605/1700000: episode: 701, duration: 11.622s, episode steps: 2172, steps per second: 187, episode reward: 18.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.709 [0.000, 5.000], mean observation: 105.591 [87.000, 236.000], loss: 0.001942, mean_absolute_error: 0.710069, mean_q: 0.909967, mean_eps: 0.020000
 1619844/1700000: episode: 702, duration: 12.134s, episode steps: 2239, steps per second: 185, episode reward: 13.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.467 [0.000, 5.000], mean observation: 105.524 [87.000, 236.000], loss: 0.001783, mean_absolute_error: 0.715786, mean_q: 0.920215, mean_eps: 0.020000
 1622062/1700000: episode: 703, duration: 11.963s, episode steps: 2218, steps per second: 185, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.784 [0.000, 5.000], mean observation: 105.543 [87.000, 236.000], loss: 0.001837, mean_absolute_error: 0.704487, mean_q: 0.906228, mean_eps: 0.020000
 1624418/1700000: episode: 704, duration: 12.628s, episode steps: 2356, steps per second: 187, episode reward: 12.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.893 [0.000, 5.000], mean observation: 105.538 [87.000, 236.000], loss: 0.002106, mean_absolute_error: 0.713443, mean_q: 0.913733, mean_eps: 0.020000
 1626811/1700000: episode: 705, duration: 12.835s, episode steps: 2393, steps per second: 186, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.719 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.002372, mean_absolute_error: 0.727846, mean_q: 0.931127, mean_eps: 0.020000
 1629281/1700000: episode: 706, duration: 13.255s, episode steps: 2470, steps per second: 186, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.574 [0.000, 5.000], mean observation: 105.521 [87.000, 236.000], loss: 0.002481, mean_absolute_error: 0.725384, mean_q: 0.923843, mean_eps: 0.020000
 1631807/1700000: episode: 707, duration: 13.646s, episode steps: 2526, steps per second: 185, episode reward: 9.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.754 [0.000, 5.000], mean observation: 105.561 [87.000, 236.000], loss: 0.002822, mean_absolute_error: 0.714042, mean_q: 0.908801, mean_eps: 0.020000
 1634426/1700000: episode: 708, duration: 14.151s, episode steps: 2619, steps per second: 185, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.806 [0.000, 5.000], mean observation: 105.608 [87.000, 236.000], loss: 0.003007, mean_absolute_error: 0.701107, mean_q: 0.895471, mean_eps: 0.020000
 1637131/1700000: episode: 709, duration: 14.494s, episode steps: 2705, steps per second: 187, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.837 [0.000, 5.000], mean observation: 105.564 [87.000, 236.000], loss: 0.002486, mean_absolute_error: 0.697053, mean_q: 0.890870, mean_eps: 0.020000
 1638817/1700000: episode: 710, duration: 9.030s, episode steps: 1686, steps per second: 187, episode reward: 21.000, mean reward: 0.012 [0.000, 1.000], mean action: 2.466 [0.000, 5.000], mean observation: 105.612 [87.000, 236.000], loss: 0.002280, mean_absolute_error: 0.705369, mean_q: 0.901099, mean_eps: 0.020000
 1640964/1700000: episode: 711, duration: 11.663s, episode steps: 2147, steps per second: 184, episode reward: 15.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.968 [0.000, 5.000], mean observation: 105.555 [87.000, 236.000], loss: 0.002135, mean_absolute_error: 0.710843, mean_q: 0.914715, mean_eps: 0.020000
 1643980/1700000: episode: 712, duration: 16.275s, episode steps: 3016, steps per second: 185, episode reward: 9.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.864 [0.000, 5.000], mean observation: 105.595 [87.000, 236.000], loss: 0.002556, mean_absolute_error: 0.708290, mean_q: 0.906006, mean_eps: 0.020000
 1646760/1700000: episode: 713, duration: 14.944s, episode steps: 2780, steps per second: 186, episode reward: 12.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.760 [0.000, 5.000], mean observation: 105.550 [87.000, 236.000], loss: 0.002961, mean_absolute_error: 0.693238, mean_q: 0.887457, mean_eps: 0.020000
 1649480/1700000: episode: 714, duration: 14.674s, episode steps: 2720, steps per second: 185, episode reward: 6.000, mean reward: 0.002 [-1.000, 1.000], mean action: 2.904 [0.000, 5.000], mean observation: 105.638 [87.000, 236.000], loss: 0.002868, mean_absolute_error: 0.679110, mean_q: 0.868242, mean_eps: 0.020000
 1651903/1700000: episode: 715, duration: 13.027s, episode steps: 2423, steps per second: 186, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.962 [0.000, 5.000], mean observation: 105.515 [87.000, 236.000], loss: 0.002256, mean_absolute_error: 0.670662, mean_q: 0.859017, mean_eps: 0.020000
 1654121/1700000: episode: 716, duration: 11.966s, episode steps: 2218, steps per second: 185, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.556 [0.000, 5.000], mean observation: 105.513 [87.000, 236.000], loss: 0.001710, mean_absolute_error: 0.686740, mean_q: 0.884458, mean_eps: 0.020000
 1656667/1700000: episode: 717, duration: 13.572s, episode steps: 2546, steps per second: 188, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.830 [0.000, 5.000], mean observation: 105.575 [87.000, 236.000], loss: 0.002122, mean_absolute_error: 0.704341, mean_q: 0.902027, mean_eps: 0.020000
 1658616/1700000: episode: 718, duration: 10.803s, episode steps: 1949, steps per second: 180, episode reward: 19.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.625 [0.000, 5.000], mean observation: 105.442 [87.000, 236.000], loss: 0.001913, mean_absolute_error: 0.725746, mean_q: 0.935326, mean_eps: 0.020000
 1661065/1700000: episode: 719, duration: 13.147s, episode steps: 2449, steps per second: 186, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.555 [0.000, 5.000], mean observation: 105.502 [87.000, 236.000], loss: 0.002115, mean_absolute_error: 0.735295, mean_q: 0.949140, mean_eps: 0.020000
 1663401/1700000: episode: 720, duration: 12.630s, episode steps: 2336, steps per second: 185, episode reward: 18.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.669 [0.000, 5.000], mean observation: 105.566 [87.000, 236.000], loss: 0.002029, mean_absolute_error: 0.738631, mean_q: 0.951632, mean_eps: 0.020000
 1666088/1700000: episode: 721, duration: 14.464s, episode steps: 2687, steps per second: 186, episode reward: 10.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.836 [0.000, 5.000], mean observation: 105.539 [87.000, 236.000], loss: 0.002071, mean_absolute_error: 0.751494, mean_q: 0.966659, mean_eps: 0.020000
 1668961/1700000: episode: 722, duration: 15.446s, episode steps: 2873, steps per second: 186, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.497 [0.000, 5.000], mean observation: 105.621 [87.000, 236.000], loss: 0.001954, mean_absolute_error: 0.750044, mean_q: 0.964713, mean_eps: 0.020000
 1671341/1700000: episode: 723, duration: 12.767s, episode steps: 2380, steps per second: 186, episode reward: 15.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.744 [0.000, 5.000], mean observation: 105.545 [87.000, 236.000], loss: 0.002060, mean_absolute_error: 0.725265, mean_q: 0.933309, mean_eps: 0.020000
 1673309/1700000: episode: 724, duration: 10.668s, episode steps: 1968, steps per second: 184, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.652 [0.000, 5.000], mean observation: 105.477 [87.000, 236.000], loss: 0.001804, mean_absolute_error: 0.736335, mean_q: 0.945183, mean_eps: 0.020000
 1675146/1700000: episode: 725, duration: 9.891s, episode steps: 1837, steps per second: 186, episode reward: 19.000, mean reward: 0.010 [-1.000, 1.000], mean action: 2.575 [0.000, 5.000], mean observation: 105.514 [87.000, 236.000], loss: 0.001649, mean_absolute_error: 0.747534, mean_q: 0.957982, mean_eps: 0.020000
 1678287/1700000: episode: 726, duration: 16.928s, episode steps: 3141, steps per second: 186, episode reward: 8.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.843 [0.000, 5.000], mean observation: 105.601 [87.000, 236.000], loss: 0.002031, mean_absolute_error: 0.754493, mean_q: 0.968018, mean_eps: 0.020000
 1680312/1700000: episode: 727, duration: 10.931s, episode steps: 2025, steps per second: 185, episode reward: 18.000, mean reward: 0.009 [-1.000, 1.000], mean action: 2.577 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.002447, mean_absolute_error: 0.759673, mean_q: 0.974201, mean_eps: 0.020000
 1682354/1700000: episode: 728, duration: 10.965s, episode steps: 2042, steps per second: 186, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.689 [0.000, 5.000], mean observation: 105.535 [87.000, 236.000], loss: 0.002145, mean_absolute_error: 0.762101, mean_q: 0.976582, mean_eps: 0.020000
 1684185/1700000: episode: 729, duration: 9.816s, episode steps: 1831, steps per second: 187, episode reward: 20.000, mean reward: 0.011 [-1.000, 1.000], mean action: 2.596 [0.000, 5.000], mean observation: 105.449 [87.000, 236.000], loss: 0.002023, mean_absolute_error: 0.765898, mean_q: 0.978219, mean_eps: 0.020000
 1686271/1700000: episode: 730, duration: 11.271s, episode steps: 2086, steps per second: 185, episode reward: 17.000, mean reward: 0.008 [-1.000, 1.000], mean action: 2.641 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.002069, mean_absolute_error: 0.758632, mean_q: 0.965869, mean_eps: 0.020000
 1689133/1700000: episode: 731, duration: 15.447s, episode steps: 2862, steps per second: 185, episode reward: 11.000, mean reward: 0.004 [-1.000, 1.000], mean action: 2.665 [0.000, 5.000], mean observation: 105.580 [87.000, 236.000], loss: 0.002407, mean_absolute_error: 0.770648, mean_q: 0.980888, mean_eps: 0.020000
 1692424/1700000: episode: 732, duration: 17.698s, episode steps: 3291, steps per second: 186, episode reward: 10.000, mean reward: 0.003 [-1.000, 1.000], mean action: 2.654 [0.000, 5.000], mean observation: 105.517 [87.000, 236.000], loss: 0.002387, mean_absolute_error: 0.740107, mean_q: 0.944140, mean_eps: 0.020000
 1694761/1700000: episode: 733, duration: 12.695s, episode steps: 2337, steps per second: 184, episode reward: 14.000, mean reward: 0.006 [-1.000, 1.000], mean action: 2.559 [0.000, 5.000], mean observation: 105.486 [87.000, 236.000], loss: 0.002366, mean_absolute_error: 0.691903, mean_q: 0.885508, mean_eps: 0.020000
 1697255/1700000: episode: 734, duration: 13.738s, episode steps: 2494, steps per second: 182, episode reward: 13.000, mean reward: 0.005 [-1.000, 1.000], mean action: 2.541 [0.000, 5.000], mean observation: 105.540 [87.000, 236.000], loss: 0.002197, mean_absolute_error: 0.687410, mean_q: 0.880595, mean_eps: 0.020000
 1699583/1700000: episode: 735, duration: 12.789s, episode steps: 2328, steps per second: 182, episode reward: 16.000, mean reward: 0.007 [-1.000, 1.000], mean action: 2.578 [0.000, 5.000], mean observation: 105.496 [87.000, 236.000], loss: 0.002175, mean_absolute_error: 0.709629, mean_q: 0.911238, mean_eps: 0.020000
done, took 9537.960 seconds
```