Model Learning, Validation, and Overfitting

June 11, 2020

Lecture 3, Applied Data Science MMCi Term 4, 2020

Matthew Engelhard



MODEL LEARNING



Learning (or training) our model means:

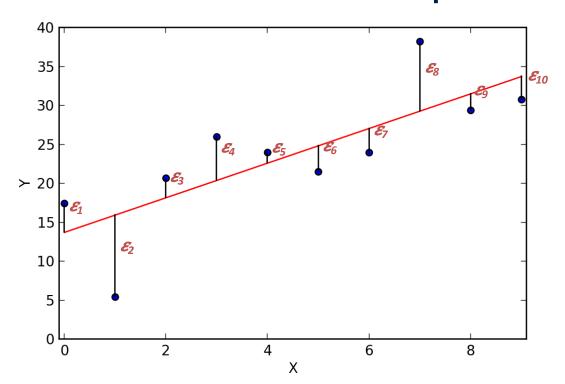
-> Setting our parameters to the specific values that are the best match for our training data

What do we mean by "best match"?

- -> We set our parameters to the values that maximize some measure of fit
- -> Alternatively, we set them to values that minimize a penalty (i.e. a *loss*) that we choose



Linear Regression Measure of Fit: Mean Squared Error



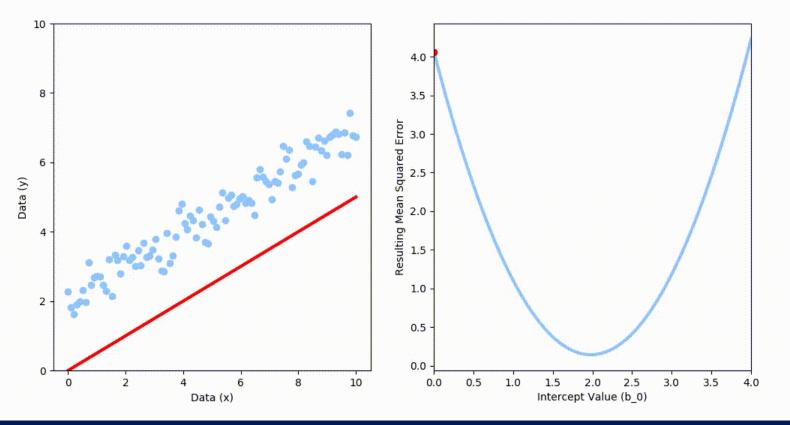
Error:

$$\varepsilon_i = y_i - \hat{y}_i$$

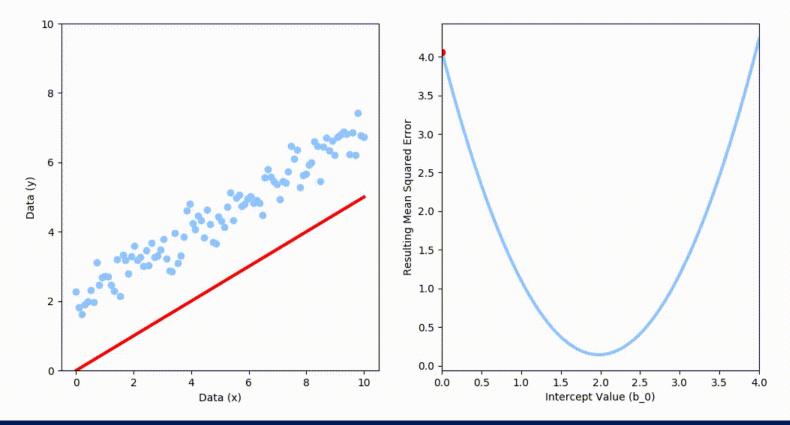
Mean square error (MSE)

$$\frac{1}{N} \sum_{i=1}^{N} \varepsilon_i^2$$

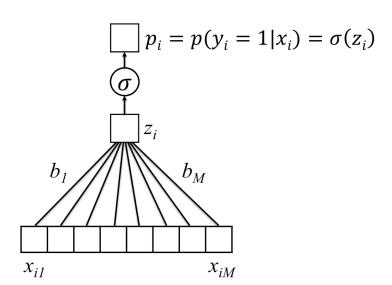
Suppose the slope is known. What happens to the MSE as we move the intercept (b_0) ?



What is the best choice of intercept (b_0) for these data, the one that minimizes the mean squared error?



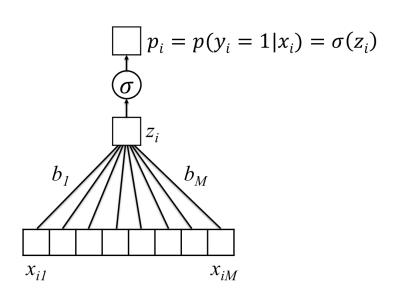
Probability that events y_1, \dots, y_N would have occurred if our model were correct



Probability that event y_i would have occurred if our model were correct:

$$(\sigma(z_i))^{y_i}(1-\sigma(z_i))^{(1-y_i)}$$

Probability that events y_1, \dots, y_N would have occurred if our model were correct

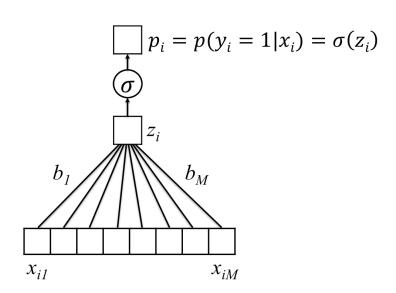


Probability that event y_i would have occurred if our model were correct:

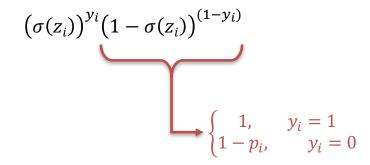
$$(\sigma(z_i))^{y_i} (1 - \sigma(z_i))^{(1-y_i)}$$

$$\begin{cases} p_i, & y_i = 1 \\ 1, & y_i = 0 \end{cases}$$

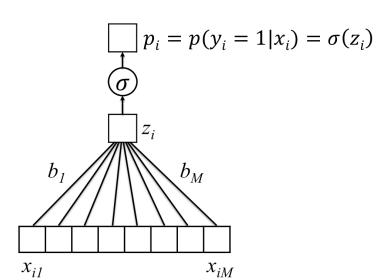
Probability that events $y_1, ..., y_N$ would have occurred if our model were correct



Probability that event y_i would have occurred if our model were correct:



Probability that events $y_1, ..., y_N$ would have occurred if our model were correct



Probability that event y_i would have occurred if our model were correct:

$$(\sigma(z_i))^{y_i}(1-\sigma(z_i))^{(1-y_i)}$$

Probability that events $y_1, ..., y_N$ would have occurred if our model were correct:

$$\prod_{i=1}^{N} (\sigma(z_i))^{y_i} (1 - \sigma(z_i))^{(1-y_i)}$$

Probability that events $y_1, ..., y_N$ would have occurred if our model were correct

Maximize the probability that events $y_1, ..., y_N$ would have occurred if our model were correct:

$$\prod_{i=1}^{N} (\sigma(z_i))^{y_i} (1 - \sigma(z_i))^{(1-y_i)}$$

Easier to maximize the log of this quantity (i.e. the log-likelihood):

$$\sum_{i=1}^{N} y_i \log \sigma(z_i) + (1 - y_i) \log (1 - \sigma(z_i))$$

Maximize the log-likelihood = minimize the "cross-entropy" loss

Log-likelihood:

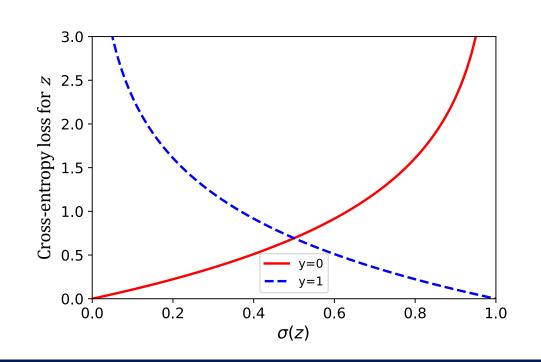
$$\sum_{i=1}^{N} y_i \log \sigma(z_i) + (1 - y_i) \log (1 - \sigma(z_i))$$

Maximize the log-likelihood = minimize the "cross-entropy" loss

Cross-entropy loss:

$$\sum_{i=1}^{N} -y_i \log \sigma(z_i) - (1-y_i) \log (1-\sigma(z_i))$$

The cross-entropy loss is also used for other classification models, including convolutional neural network classifiers for image processing.



How do we minimize the loss?

 The cross-entropy loss just tells us what quantity we should be minimizing

 In some cases (e.g. linear regression), we can solve for the minimum directly

 But, we'd like to have an approach that works even for very complex models

| MORTALITY PI | VEDICTION A | WORKSHE | <u> </u> | | | | | | | | | | |
|--------------|-------------|---------|----------------|----------|-------|--------------------------|------|-----------|--------------------|----------------|-------------|----------|-------|
| COVARIATES | | | | | | OUTCOMES AND PREDICTIONS | | | | | | | |
| patient | age | | age_normalized | female | temp | temp_normalized | | mortality | predicted_log_odds | predicted_prob | prediction | correct? | loss |
| | 0 | 30.5 | -0.5 | 0 | 105.0 | 2.4 | | 1 | 0.00 | 0.50 | 0 | 0 | 0.301 |
| | 1 | 74.0 | 1.1 | 1 | 96.7 | -0.8 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 2 | 27.4 | -0.6 | 0 | 96.1 | -1.0 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 3 | 0.1 | -1.5 | 1 | 98.5 | -0.1 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 4 | 0.7 | -1.5 | 1 | 96.5 | -0.9 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 5 | 49.9 | 0.2 | 1 | 97.1 | -0.6 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 6 | 72.9 | 1.0 | 1 | 100.1 | 0.5 | | 1 | 0.00 | 0.50 | 0 | 0 | 0.301 |
| | 7 | 29.1 | -0.5 | 1 | 99.6 | 0.3 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 8 | 83.5 | 1.4 | 1 | 100.6 | 0.7 | | 1 | 0.00 | 0.50 | 0 | 0 | 0.301 |
| | 9 | 82.3 | 1.4 | 1 | 95.2 | -1.3 | | 1 | 0.00 | 0.50 | 0 | 0 | 0.301 |
| | 10 | 23.7 | -0.7 | 0 | 99.4 | 0.2 | | 1 | 0.00 | 0.50 | 0 | 0 | 0.301 |
| | 11 | 12.9 | -1.1 | 0 | 96.6 | -0.8 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 12 | 53.9 | 0.4 | 1 | 100.3 | 0.6 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 13 | 18.8 | -0.9 | 0 | 98.6 | 0.0 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 14 | 51.8 | 0.3 | 0 | 98.5 | -0.1 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 15 | 3.3 | -1.4 | 0 | 94.6 | -1.6 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 16 | 69.7 | 0.9 | 0 | 99.1 | 0.1 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | 17 | 60.4 | 0.6 | 1 | 104.2 | 2.1 | | 1 | 0.00 | 0.50 | 0 | 0 | 0.301 |
| | 18 | 73.6 | 1.1 | 1 | 99.1 | 0.1 | | 1 | 0.00 | 0.50 | 0 | 0 | 0.301 |
| | 19 | 53.3 | 0.3 | 1 | 99.1 | 0.1 | | 0 | 0.00 | 0.50 | 0 | 1 | 0.301 |
| | | | - | | | - | | | | | | | |
| PARAMETERS | | | | b_female | | b_temp | bias | | | | PERFORMANCE | accuracy | |
| | guess | | 0.00 | 0.00 | | 0.00 | 0.00 |) | | | | 0.65 | 0.301 |
| | optimal | | | | | | | | | | | | |



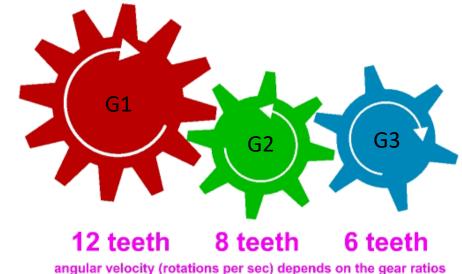
We know:

- If we rotate G1 by 1 radian, G2 will rotate by -12/8 radians.
- If G2 rotates by 1 radian, G3 will rotate by -8/6 radians.

How do we determine the effect of G1 on G3?

Multiply the effects.

$$\left(-\frac{12}{8} \right) * \left(-\frac{8}{6} \right) = \frac{12}{6} = 2$$

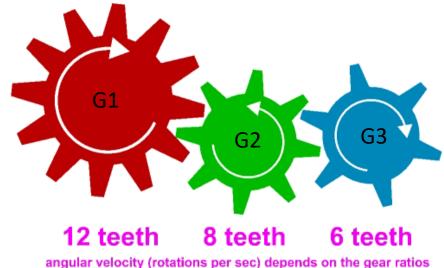


We know:

- If we rotate G1 by 1 radian, G2 will rotate by -12/8 radians.
- If G2 rotates by 1 radian, G3 will rotate by -8/6 radians.

How do we determine the effect of G1 on G3?

- Multiply the effects.
- $\left(-\frac{12}{9}\right)*\left(-\frac{8}{6}\right) = \frac{12}{6} = 2$

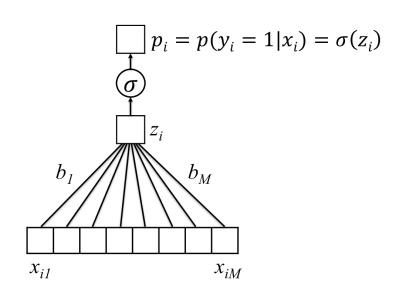


We know:

- If we increase b_1 by a small amount ε , then z_i will increase by $\varepsilon * x_{i1}$
- If we increase z_i by a small amount ε , then p_i will increase by $\varepsilon*\frac{d\sigma(z_i)}{dz_i}$ (depends on z_i)

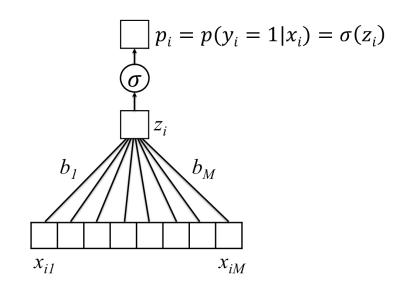
How do we determine the effect b_1 on the cross-entropy loss (which depends on p_i)?

Multiply the effects.



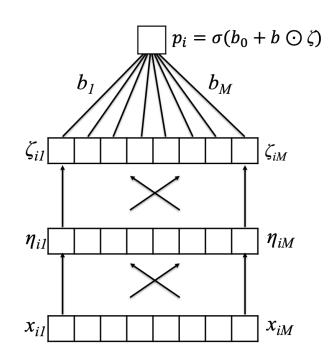
This is called the *chain rule* (calc 101)

- We use it to see how small changes in parameters affect the loss
- Could be a very long chain...
- Some parameters have a greater effect than others
- We change all parameters at once, with each change proportional to that parameter's effect on the loss
 - This is gradient descent



It could be a very long (and complex) chain...

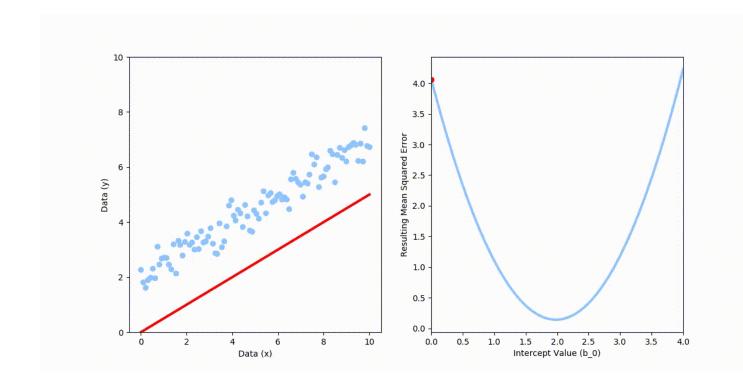
- If we increase x_{i1} by ε , it changes all of the η_{ij} ...
- ...each of which changes \emph{all} of the ζ_{ij}
- ...each of which changes p_i
- Machine learning software like TensorFlow allows us to keep track, even for very complicated models



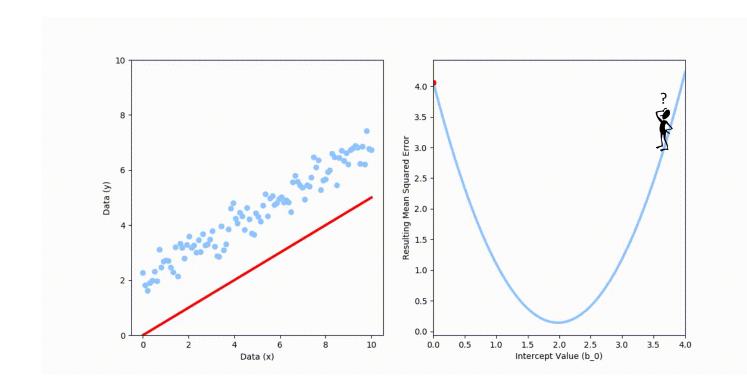
Let's begin by finding the value of a *single* parameter that minimizes the loss. We'll consider the intercept b_0 of a linear regression model.

$$y_i = bx_i + b_0 + \varepsilon_i$$

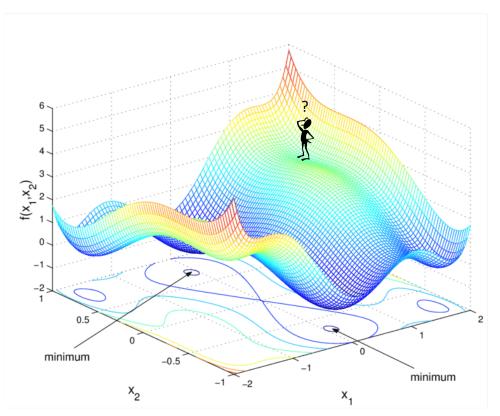
Easy!!



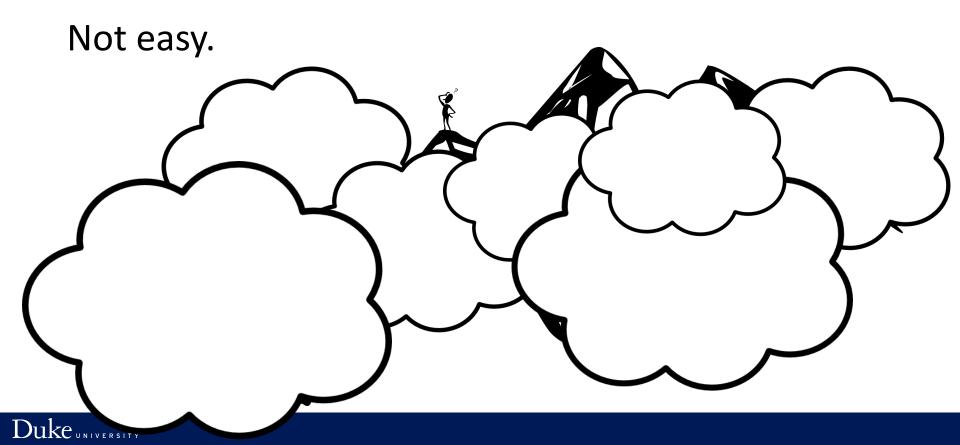
Easy!!



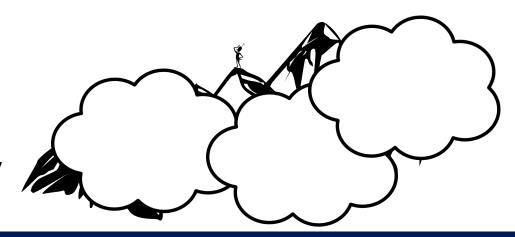
Easy?







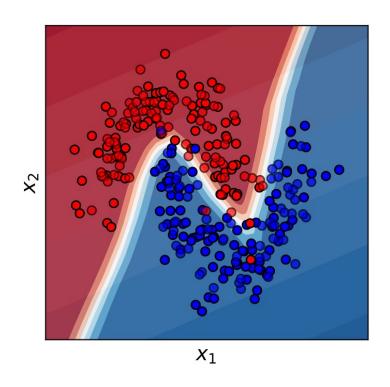
- With deep learning models, we are trying to minimize a function of many variables
- Can't visualize it
- Can't solve for the minimum directly
- So, we follow the slope and hope for the best (i.e. gradient descent)
- May end up in a low point that isn't the lowest, i.e. local minimum
- But, if we have lots of data, things usually work out OK



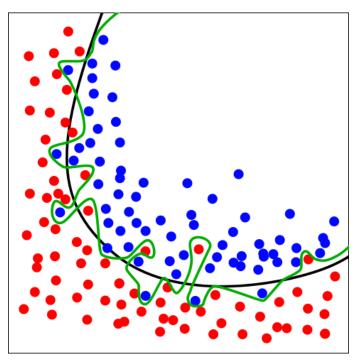
OVERFITTING



We like flexible, non-linear decision boundaries...



But some models can be *too* flexible.



Green boundary:

- This is overfitting

Black boundary:

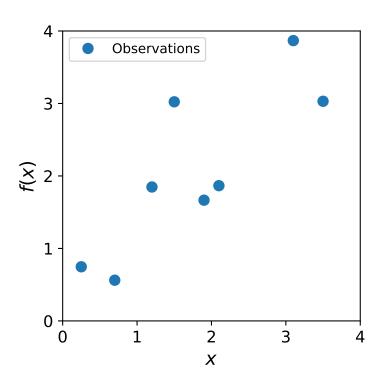
- Balance between fit and model complexity
 - -> The black boundary is likely to perform better on new data

By Chabacano - Own work, CC BY-SA 4.0,

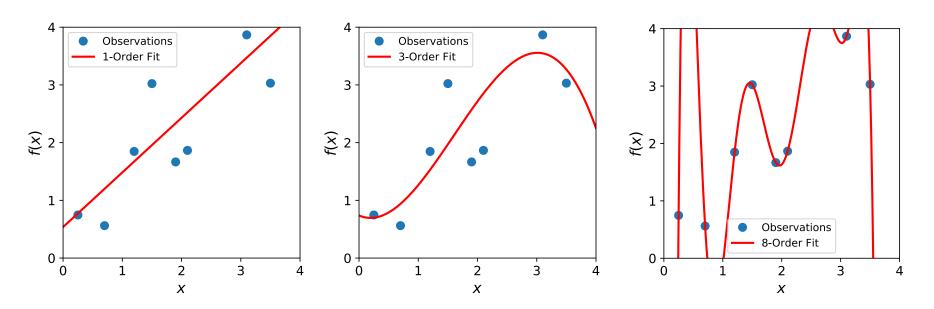
Overfitting

"Overfitting" happens when the learned model increases complexity to fit the observed training data *too well* – will not work to predict future data!

What would we want to use to fit these example data points?



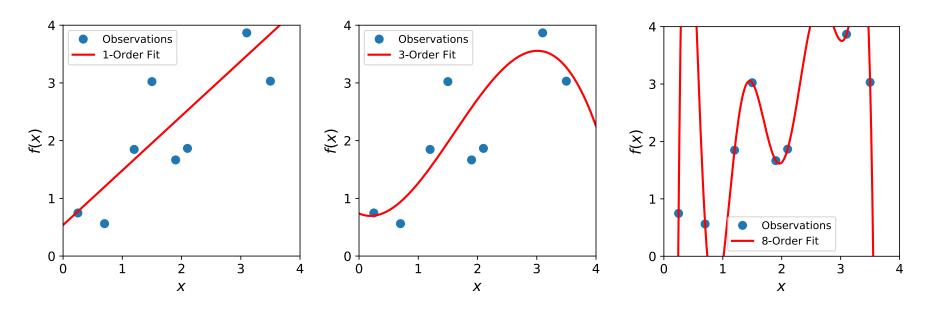
Classic Example: Increasing Polynomial Order



Increasing complexity does not seem appropriate...

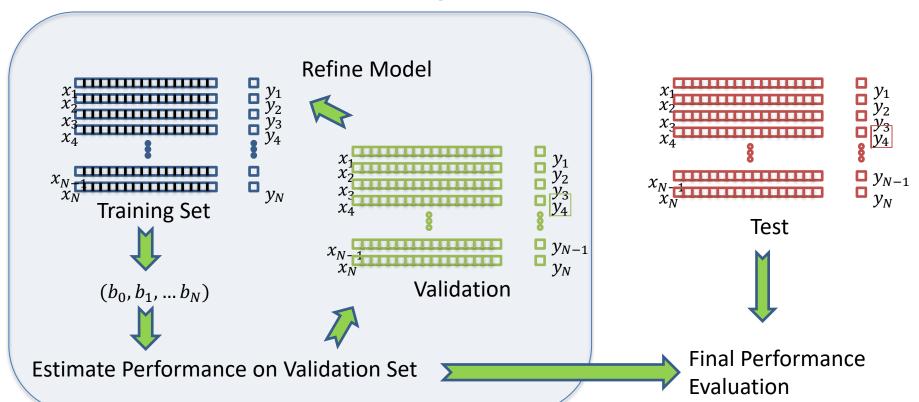


With a flexible enough model, we can typically reach 100% accuracy on our training set



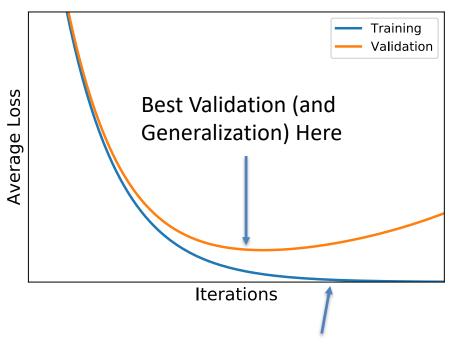
Increasing complexity does not seem appropriate...

Using a Test Set Protects Against Overfitting: See how the model performs on *new* data



Early Stopping

- During optimization, we can check the validation loss as we go.
- Instead of optimizing to convergence, we can optimize until the *validation* loss stops improving
 - Saves computational cost
 - Performs better on validation (and test) sets
- Widely used technique in the field



Training Loss Keeps Improving

Other Ways to Use the Validation Set

- Choosing between models (e.g. MLP, LR)
- Choosing how strongly to regularize the model, i.e. penalize parameters
- Choosing network depth, width, etc.
- Many other "hyperparameters" we might tune



Conclusions

- Learning consists in setting model parameters to maximize some measure of fit (or equivalently, minimize some loss)
- This sounds easy, but is difficult in practice when working with complex models
- Greater model complexity is often, but not always, advantageous
- Proper model validation is critical to estimate real-world performance and prevent overfitting

