

# Uncertainty Principle

- We ~~claimed~~ showed that if  $G|\psi_i\rangle = g_i|\psi_i\rangle$  +

$[G, H] = 0$ , then  $H$  acting on  $|\psi_i\rangle$

~~either~~ either <sup>(1)</sup> returns  $|\psi_i\rangle$  or <sup>(2)</sup> carries  $(H|\psi_i\rangle = E_i|\psi_i\rangle)$

$|\psi_i\rangle$  to some  $|\psi_j\rangle$  where  $g_i = g_j$

- Furthermore, we claimed that basis  $|\psi_i\rangle$

~~can~~ can be chosen s.t.  $H|\psi_i\rangle = E_i|\psi_i\rangle$ ,

even if there are degeneracies in  $H$  and/or  $G$

$\Rightarrow$  i.e. ~~states~~ if  $[G, H] = 0$ , a full basis of states ~~states~~ exist

exist w/ simultaneous definite values of

$G, H$

- True in general of  $[A, B] = 0$

On the other hand, ~~conversely~~ if  $[A, B] \neq 0$ , then no states

exist with simult. def. values of  $A$  &  $B$

(Dropping  $\hbar$  now)

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- For instance  $[x, p] \neq 0$

- Obviously true:

$$[A, B]|\psi_i\rangle = (AB - BA)|\psi_i\rangle = AB|\psi_i\rangle - BA|\psi_i\rangle$$

Suppose  $A|\psi_i\rangle = a_i|\psi_i\rangle$  &  $B|\psi_i\rangle = b_i|\psi_i\rangle$

$$a_i b_i |\psi_i\rangle - b_i a_i |\psi_i\rangle = 0$$

But this is a contradiction if  $[A, B] \neq 0$

$\Rightarrow$  Cannot "simultaneously diagonalize" both operators.

~~Even stranger~~ Even stranger, cannot find a single state which has def value of both

- This leads to uncert. princ. ~~princ.~~ Let's work our way there

- Expectation value  $\langle O \rangle = \langle \psi | O | \psi \rangle$

$$\langle x \rangle = \langle \psi | x | \psi \rangle, \quad \langle p \rangle = \langle \psi | p | \psi \rangle$$

Why is this average val. of many measurements?

Probability of measuring one value given by (coef.)<sup>2</sup>

eg.  $\langle p \rangle = \frac{|c_1|^2 p_1 + |c_2|^2 p_2}{|c_1|^2 + |c_2|^2} = |c_1|^2 p_1 + |c_2|^2 p_2$

But  $\langle \psi | p | \psi \rangle = c_1 p_1 + c_2 p_2$

$\psi = c_1 |p_1\rangle + c_2 |p_2\rangle$

$\langle p \rangle$  is exp. value

- We will first prove that for any Hermitian operators  $A+B$

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$$\langle A^2 \rangle \langle B^2 \rangle \geq \frac{1}{4} |\langle [A, B] \rangle|^2$$

- For any complex  $\alpha$

$$\langle (A + \alpha B)\psi | (A + \alpha B)\psi \rangle \geq 0 \quad \text{since } H \text{ has positive norm}$$

$$\Rightarrow \langle \psi | (A + \alpha B)^\dagger (A + \alpha B) | \psi \rangle \geq 0$$

$$\langle \psi | (A + \alpha^* B) (A + \alpha B) | \psi \rangle \geq 0$$

$$\langle A^2 \rangle + \alpha^* \langle BA \rangle + \alpha \langle AB \rangle + |\alpha|^2 \langle B^2 \rangle \geq 0$$

$$\langle BA \rangle = \langle B\psi | A\psi \rangle = \langle A\psi | B\psi \rangle^* = \langle AB \rangle^*$$

(Note that although  $\langle A \rangle$  &  $\langle B \rangle$  are real,  
 $\langle AB \rangle$  is not necessarily if  $[A, B] \neq 0$ )

$$\dagger \langle B^2 \rangle^* = \langle B^2 \rangle$$

$$\Rightarrow \langle A^2 \rangle + \alpha \langle AB \rangle + \alpha^* \langle AB \rangle^* + |\alpha|^2 \langle B^2 \rangle \geq 0$$

We want to minimize the LHS wrt to  $\alpha$ .

~~But~~ You get the right result if you take  $\frac{\partial}{\partial \alpha} (\dots)$  and pretend that  $\alpha^*$  is independent, as but we will use a more simple-minded approach. ~~but I don't understand why that has to work.~~

~~So, I'll do it a longer way ...~~

$$\alpha = a + ib$$

$$\langle AB \rangle = c + id \quad \text{where those 4 coefficients are real}$$

$$\Rightarrow \langle A^2 \rangle + 2ac - 2bd + (a^2 + b^2) \langle B^2 \rangle \geq 0$$

$$\frac{\partial}{\partial a}(\dots) = 2c + 2a \langle B^2 \rangle = 0 \Rightarrow a = \frac{-\text{Re} \langle AB \rangle}{\langle B^2 \rangle}$$

$$\frac{\partial}{\partial b}(\dots) = -2d + 2b \langle B^2 \rangle = 0 \Rightarrow b = \frac{\text{Im} \langle AB \rangle}{\langle B^2 \rangle}$$

$$\Rightarrow \alpha = \frac{-\langle AB \rangle^*}{\langle B^2 \rangle}$$

(From inequality in original form)

$$\langle A^2 \rangle - \frac{\langle AB \rangle \langle AB \rangle^*}{\langle B^2 \rangle} - \frac{\langle AB \rangle^* \langle AB \rangle}{\langle B^2 \rangle} + \frac{\langle AB \rangle^* \langle AB \rangle}{\langle B^2 \rangle} \geq 0$$

$$\Rightarrow \boxed{\langle A^2 \rangle \langle B^2 \rangle \geq |\langle AB \rangle|^2}$$

Now  $\langle AB \rangle = \frac{1}{2} \langle AB - BA \rangle + \frac{1}{2} \langle AB + BA \rangle$  (This is a trick to get the commutator to appear)

$$\Rightarrow |\langle AB \rangle|^2 = \frac{1}{4} |\langle AB - BA \rangle|^2 + \frac{1}{4} |\langle AB + BA \rangle|^2 + \frac{1}{4} [\langle AB - BA \rangle^* \langle AB + BA \rangle + \langle AB - BA \rangle \langle AB + BA \rangle^*]$$

So 2nd line vanishes

$$\Rightarrow \langle A^2 \rangle \langle B^2 \rangle \geq \frac{1}{4} |\langle AB - BA \rangle|^2$$

- Since  $|\langle AB + BA \rangle|^2 \geq 0$ , we finally have  
(taking only the first term converting to inequality)




~~But a commutator is 0~~  
~~also. why not label inequality~~  
~~for anticommutator of R's?~~  
~~Just not useful later in some way?~~  
 but that is not as interesting. Doesn't carry  
 } - difference obtained by reversing measurements.

- Now put  $A = x - c$ ,  $B = p - d$

where  $c$  &  $d$  are any constants

- In particular, take  $c = \langle x \rangle$ ,  $d = \langle p \rangle$

$\langle x \rangle = 0$   
~~Handwritten scribbles~~  
 $\langle x \rangle > 0$   


(Deviation of given measurement from mean value)  $\propto$  width of a distribution

~~by  $\langle \Delta x \rangle^2$  describes~~

~~Correct this to RMS as is. Maybe just for Gaussian?~~

$\Rightarrow \langle \Delta x \rangle^2 \langle \Delta p \rangle^2$  are positive quantities describing square of

\* width of distribution variance  
These are the ~~standard deviation~~ of measurements of  $x + p$

$$\Rightarrow \langle \Delta x \rangle^2 \langle \Delta p \rangle^2 \geq \frac{1}{4} \hbar^2$$

$$\Delta x_{SD} \Delta p_{SD} \geq \frac{\hbar}{2}$$

(just dist width  $\hbar^2$ )

(Often a different def is used:  $\Delta x = \sqrt{\langle \Delta x^2 \rangle}$ )

(common  $\leftarrow$  standard deviation)

$\Rightarrow$  Similar uncert. princ., just w/ different RHS deviation

for any non-commuting observables

$\Rightarrow$  Spread in  $x \rightarrow \infty$  as spread in  $p \rightarrow 0$  &

vice versa.

- Heisenberg uncertainty ~~principle~~ principle.

- For  $x + p$  in position space, already argued qualitatively based on Fourier compositions. But more general than that.

- We made a gaussian wavepacket earlier where

$\sqrt{\langle \Delta x \rangle^2} \sqrt{\langle \Delta p \rangle^2} = \frac{\hbar}{2}$ . So condition can be saturated but not violated.

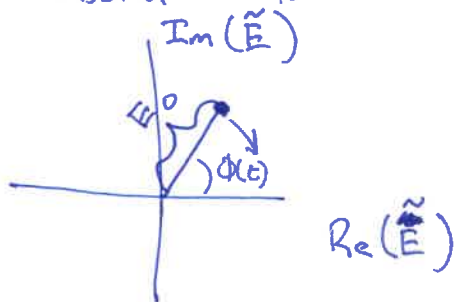


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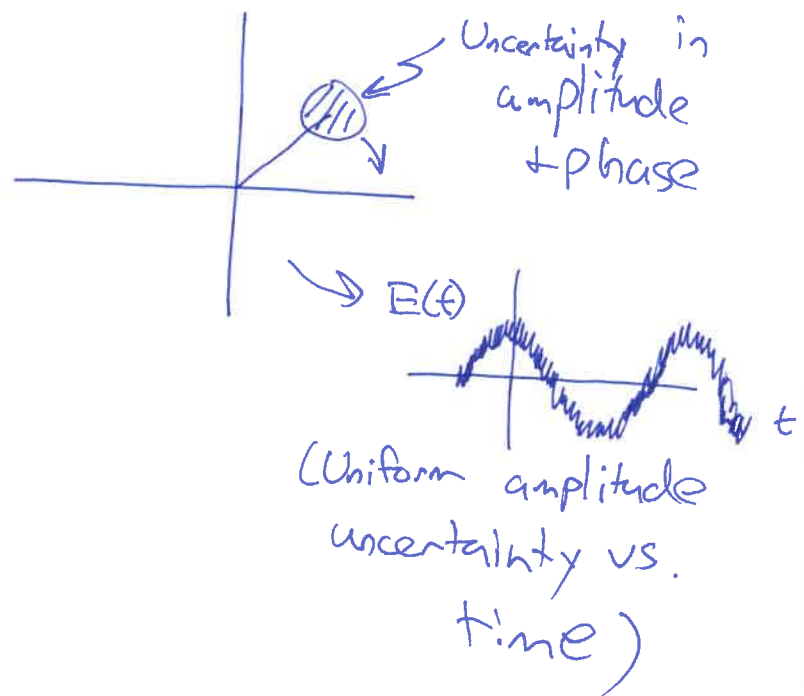
This goes for any non-commuting observables. Consider the amplitude & phase of an electromagnetic wave. From Quantum Electrodynamics, it can be shown that  $[\Phi, n] \neq 0$ , where  $\Phi$  is the operator for phase measurements &  $n$  is the photon number (i.e. amplitude) operator.  $\vec{E} = \text{Re } \tilde{\vec{E}}(t)$

$$\vec{E} = E_0 \text{Re}(e^{-i(\omega t + \Phi)}) = E_0 \text{Re}(e^{-i\Phi(t)})$$

Classical Field

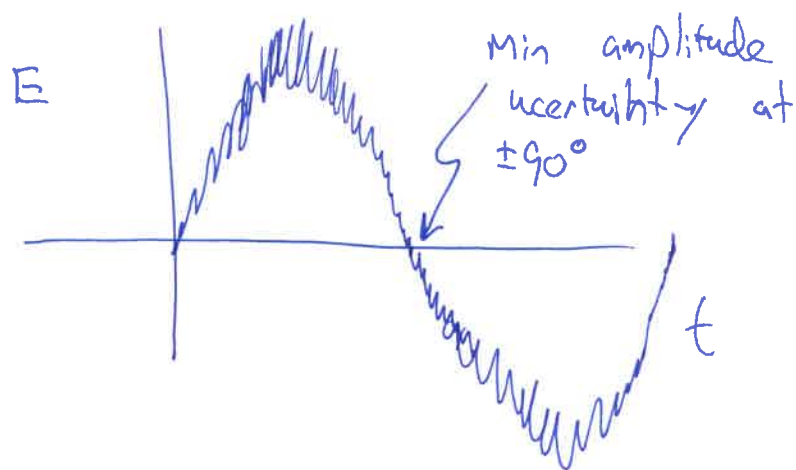
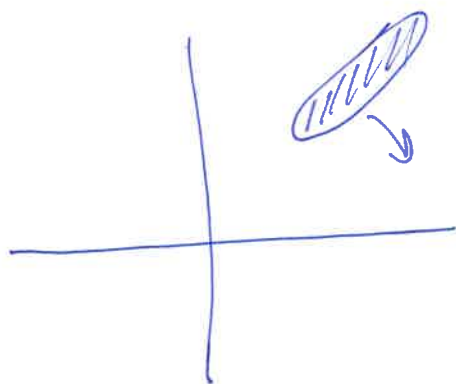


Quantum Coherent State

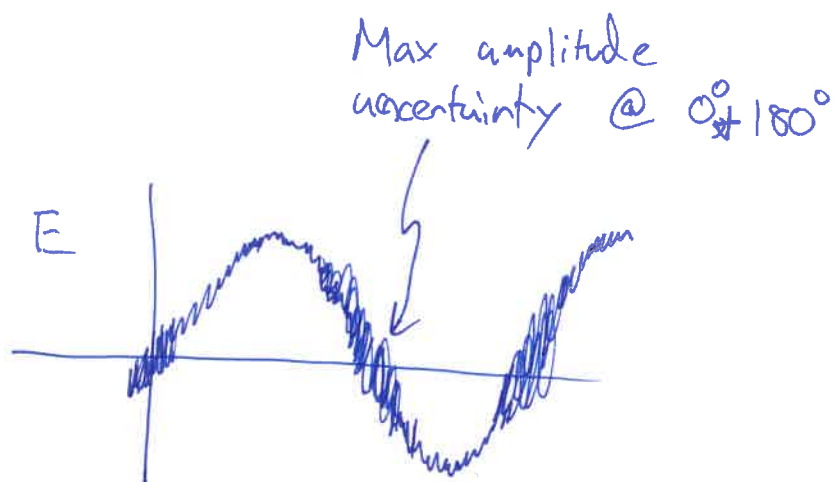
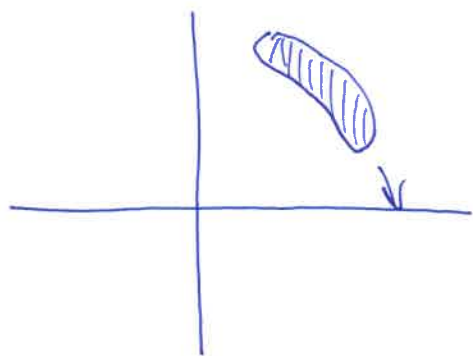


But we are allowed to squeeze the uncertainty 8 into one or the other observable, just as we do for  $x + p$ .

## Phase-squeezed State



## Amplitude-squeezed State



So, for instance the amplitude-squeezed state still has amplitude uncertainty, particularly at some phases. But because its uncertainty is around  $E=0$ , the  $\langle \Delta E^2 \rangle$  is reduced relative to the coherent state case.