

The Wave Equation

In vacuum, with no sources ($\rho=0, \vec{j}=0$), Maxwell's equations for the electromagnetic field are:

$$\vec{\nabla} \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{H}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{H} = 0$$

$$\vec{\nabla} \times \vec{H} = \frac{1}{c} \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{E} = 0$$

We also recall that:

$$\vec{H} = \vec{\nabla} \times \vec{A}$$

$$\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} - \vec{\nabla} \phi$$

ϕ is scalar potential, \vec{A} is vector potential

To simplify the equations, we can make the choice of gauge:

$$\phi = 0 \quad \text{and} \quad \vec{\nabla} \cdot \vec{A} = 0 \quad (\text{Coulomb gauge})$$

Then:

$$\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t}$$

$$\frac{\partial \vec{E}}{\partial t} = -\frac{1}{c} \frac{\partial^2 \vec{A}}{\partial t^2}$$

Plug into equation for $\vec{\nabla} \times \vec{H}$:

$$c \vec{\nabla} \times \vec{H} = -\frac{1}{c} \frac{\partial^2 \vec{A}}{\partial t^2}$$

Also:

$$\vec{\nabla} \times \vec{H} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \vec{\nabla}^2 \vec{A} = -\vec{\nabla}^2 \vec{A} \quad \rightarrow 0 \text{ by choice of gauge}$$

so:
$$\boxed{\vec{\nabla}^2 \vec{A} - \frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} = 0}$$

To get an equation for \vec{E} , take another time derivative:

$$\vec{\nabla}^2 \frac{\partial \vec{A}}{\partial t} - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \left(\frac{\partial \vec{A}}{\partial t} \right) = 0 \quad (\text{recall } \vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t})$$

$$\Rightarrow \boxed{\vec{\nabla}^2 \vec{E} - \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} = 0}$$

To get an equation for \vec{H} , take the curl:

$$\vec{\nabla} \times (\vec{\nabla}^2 \vec{A}) - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} (\vec{\nabla} \times \vec{A}) = 0$$

From above, $\vec{\nabla}^2 \vec{A} = -\vec{\nabla} \times \vec{H}$, so: From Maxwell's equations

$$\vec{\nabla} \times (\vec{\nabla}^2 \vec{A}) = -\vec{\nabla} \times (\vec{\nabla} \times \vec{H}) = -[\vec{\nabla} (\vec{\nabla} \cdot \vec{H}) - \vec{\nabla}^2 \vec{H}] = \vec{\nabla}^2 \vec{H}$$

$$\Rightarrow \boxed{\vec{\nabla}^2 \vec{H} - \frac{1}{c^2} \frac{\partial^2 \vec{H}}{\partial t^2} = 0}$$

The wave equations for \vec{E} and \vec{H} have some resemblance to the 1D scalar wave equation:

$$\frac{\partial^2 f}{\partial t^2} - c^2 \frac{\partial^2 f}{\partial z^2} = 0$$

where z is chosen as the one spatial dimension to consider. It is instructive to examine solutions to this equation. Note that:

$$\begin{aligned} \left(\frac{\partial}{\partial t} - c \frac{\partial}{\partial z} \right) \left(\frac{\partial}{\partial t} + c \frac{\partial}{\partial z} \right) f &= \\ &= \frac{\partial^2 f}{\partial t^2} - c \frac{\partial f}{\partial t \partial z} + c \frac{\partial f}{\partial t \partial z} - c^2 \frac{\partial^2 f}{\partial z^2} = \frac{\partial^2 f}{\partial t^2} - c^2 \frac{\partial^2 f}{\partial z^2} = 0 \end{aligned}$$

The 1D scalar wave equation can therefore be written as:

$$\left(\frac{\partial}{\partial t} - c \frac{\partial}{\partial z} \right) \left(\frac{\partial}{\partial t} + c \frac{\partial}{\partial z} \right) f = 0$$

Let us consider functions of the form

$$f = f_1\left(t - \frac{z}{c}\right) + f_2\left(t + \frac{z}{c}\right)$$

for arbitrary functions f_1 and f_2 . Let $\alpha = t - \frac{z}{c}$.

$$\frac{\partial f_1(\alpha)}{\partial t} = \frac{\partial f_1(\alpha)}{\partial \alpha} \frac{\partial \alpha}{\partial t} = \frac{\partial f_1(\alpha)}{\partial \alpha}$$

$$c \frac{\partial f_1(\alpha)}{\partial z} = c \frac{\partial f_1(\alpha)}{\partial \alpha} \frac{\partial \alpha}{\partial z} = c \frac{\partial f_1(\alpha)}{\partial \alpha} \left(-\frac{1}{c} \right) = -\frac{\partial f_1(\alpha)}{\partial \alpha} = -\frac{\partial f_1(\alpha)}{\partial t}$$

so $\left(\frac{\partial}{\partial t} + c \frac{\partial}{\partial z} \right) f_1\left(t - \frac{z}{c}\right) = 0$, so $f_1\left(t - \frac{z}{c}\right)$ satisfies

the wave equation. A similar argument shows that $f_2\left(t + \frac{z}{c}\right)$ also satisfies the wave equation, because $\left(\frac{\partial}{\partial t} - c \frac{\partial}{\partial z} \right) f_2\left(t + \frac{z}{c}\right) = 0$.

The sum $f = f_1(t - \frac{z}{c}) + f_2(t + \frac{z}{c})$ is also a solution

Example: Consider the case where $f_2 = 0$. Then our solution is $f_1(t - \frac{z}{c})$. This solution means that the field f_1 has the same value each time the argument $t - \frac{z}{c} = A$, for some constant A .

This corresponds to:

$$z = \text{constant} + ct$$

\Rightarrow the values of the field propagate in space along the positive direction of z at the speed of light c .

Similarly, in the case where $f_1 = 0$, the solution $f_2(t + \frac{z}{c})$ corresponds to a wave traveling along the negative direction of z with speed c .

Plane Waves

Plane waves are a special case in which the fields depend on only one spatial coordinate and on time.

Let us choose this spatial coordinate to be z for the moment. The wave equation for \vec{A} then is:

$$\vec{\nabla}^2 \vec{A}(z, t) - \frac{1}{c^2} \frac{\partial^2 \vec{A}(z, t)}{\partial t^2} = 0$$

Since there is no dependence of \vec{A} on x or y , this reduces to:

$$\frac{\partial^2 A_i(z, t)}{\partial z^2} - \frac{1}{c^2} \frac{\partial^2 A_i(z, t)}{\partial t^2} = 0$$

$$\Rightarrow \frac{\partial^2 A_i(z, t)}{\partial t^2} - c^2 \frac{\partial^2 A_i(z, t)}{\partial z^2} = 0$$

For $i = x, y, z$. That is, we get a 1D wave equation for each of the three components A_x , A_y , and A_z of \vec{A} .

Recall that we chose our gauge so that

$$\phi = 0, \quad \vec{\nabla} \cdot \vec{A} = 0$$

In this case, where \vec{A} only depends on z and t ,

$$\vec{\nabla} \cdot \vec{A} = 0 \Rightarrow \frac{\partial A_z}{\partial z} = 0$$

Therefore, the wave equation for A_z reduces to

$$\frac{\partial^2 A_z}{\partial t^2} = 0 \Rightarrow \frac{\partial A_z}{\partial t} = \text{constant}$$

In our gauge, $\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t}$, so $E_z = \text{constant}$.

A constant background field has no relation to the electromagnetic wave. In this case, a nonzero A_z can just give a constant background E_z component, so for the purpose of considering plane waves we set $A_z = 0$. Since A_z has no dependence on x or y , it will not contribute to the curl $\vec{\nabla} \times \vec{A} = \vec{H}$, so it will not influence the magnetic field.

We consider solutions to the wave equation that move in the positive z direction, so

$$\vec{A} = \vec{A}(t - \frac{z}{c}) = \vec{A}(\alpha) \quad \text{where } \alpha = t - \frac{z}{c}$$

$$\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial \alpha} \underbrace{\frac{\partial \alpha}{\partial t}}_{=1} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial \alpha}$$

$$\begin{aligned} \vec{H} = \vec{\nabla} \times \vec{A} &= \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \times \vec{A} = \left(\overset{0}{\frac{\partial \alpha}{\partial x} \frac{\partial}{\partial \alpha}}, \overset{0}{\frac{\partial \alpha}{\partial y} \frac{\partial}{\partial \alpha}}, \frac{\partial \alpha}{\partial z} \frac{\partial}{\partial \alpha} \right) \times \vec{A} \\ &= \left(0, 0, -\frac{1}{c} \frac{\partial}{\partial \alpha} \right) \times \vec{A} = -\frac{1}{c} \hat{z} \times \frac{\partial \vec{A}}{\partial \alpha} \quad (\hat{z} \text{ is unit vector in } +z \text{ direction}) \end{aligned}$$

Comparing the equations for \vec{E} and \vec{H} , we see that:

$$\boxed{\vec{H} = \hat{z} \times \vec{E}}$$

and we assume $\boxed{\vec{E} \perp \hat{z}}$ from above

\vec{E} , \hat{z} , and \vec{H} are mutually perpendicular
 \vec{E} and \vec{H} point in x - y plane

This implies that the electric field, the magnetic field, and the direction of propagation point in mutually perpendicular directions.

The energy flux is given by the Poynting vector:

$$\begin{aligned}\vec{S} &= \frac{c}{4\pi} \vec{E} \times \vec{H} = \frac{c}{4\pi} \vec{E} \times (\hat{z} \times \vec{E}) = \left[(\vec{E} \cdot \vec{E}) \hat{z} - \underbrace{(\vec{E} \cdot \hat{z}) \vec{E}}_0 \right] \frac{c}{4\pi} \\ &= \frac{c}{4\pi} E^2 \hat{z}\end{aligned}$$

As expected, energy flows along the propagation direction \hat{z} .

Monochromatic Plane Waves and Polarization

In many experimentally relevant situations, we are interested in waves that oscillate in time at a single frequency ω .

For a plane wave propagating in the \hat{z} direction, we are therefore interested in solutions of the form

$$\vec{A} \propto \cos(kz - \omega t - \theta), \quad \text{where } k = \frac{\omega}{c} \text{ and } \theta \text{ is a constant representing the phase offset of the oscillation}$$

It is mathematically nicer to work with complex exponentials and take the real part at the end. Note that:

$$e^{i(kz - \omega t - \theta)} = \cos(kz - \omega t - \theta) + i \sin(kz - \omega t - \theta)$$

When we take the real part, we get

$$\text{Re}[e^{i(kz - \omega t - \theta)}] = \cos(kz - \omega t - \theta)$$

Using the complex exponential approach, our solution for \vec{A} takes the form

$$\vec{A} = \vec{A}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)} \quad ; \quad \vec{r} = (x, y, z); \quad \vec{k} = \frac{\omega}{c} \hat{n}$$

\vec{A}_0 is a complex valued constant. Here, we have absorbed the factor $e^{-i\theta}$ into \vec{A}_0 and generalized to the case of propagation along a direction \hat{n} :

\hat{n} is a unit vector pointing in the direction of propagation

Note also that $\hat{n} = \hat{k}$.

$$\vec{E} = -\frac{1}{c} \frac{\partial \vec{A}}{\partial t} = i \frac{\omega}{c} \vec{A} = i k \vec{A}$$

$$\vec{H} = \vec{\nabla} \times \vec{A} = i \vec{k} \times \vec{A}$$

For the electric field, we can write

$$\vec{E} = \vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

\vec{E}_0 is a complex vector with amplitude and phase. In general, we note that \vec{E}^2 is also complex.

We will write \vec{E}_0 as

$$\vec{E}_0 = (\vec{E}_{0r} + i \vec{E}_{0i}) e^{-i\theta}$$

The ultimate goal is to get a convenient picture of direction which \vec{E} points as a function of time

where \vec{E}_{0r} and \vec{E}_{0i} are real vectors, and θ is real.

We will choose θ so that \vec{E}_{0r} and \vec{E}_{0i} are mutually orthogonal. Let \vec{a} and \vec{b} denote the real and imaginary parts of \vec{E}_0 :

$$\vec{a} \equiv \text{Re}[\vec{E}_0], \quad \vec{b} \equiv \text{Im}[\vec{E}_0]$$

$$\text{Since } \vec{E}_{0r} + i \vec{E}_{0i} = \vec{E}_0 e^{i\theta} = (\vec{a} + i \vec{b}) e^{i\theta};$$

$$\vec{E}_{0r} = \vec{a} \cos \theta - \vec{b} \sin \theta$$

$$e^{i\theta} = \cos \theta + i \sin \theta$$

$$\vec{E}_{0i} = \vec{a} \sin \theta + \vec{b} \cos \theta$$