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## Path so far

Define generator of rotations

$$D_{\hat{n}}(\epsilon) \equiv \hat{1} - \frac{i}{\hbar} (\vec{J} \cdot \hat{n}) \epsilon$$

$\nwarrow$  defines  $\vec{J}$   
 (use  $\vec{L}$  as an analogy only)

Consider general rotation in space

$$\Rightarrow [\underbrace{J_i, J_j}] = i\hbar \epsilon_{ijk} J_k$$

N=1: cannot realize

N=2:  $S_i = \frac{1}{2}\hbar \sigma_i$  satisfy

$\nwarrow$  Pauli matrices

$$S_z \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad S_z \begin{pmatrix} 0 \\ 1 \end{pmatrix} = -\frac{\hbar}{2} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$\nwarrow$  spin  $\frac{1}{2}$

spin up

spin down

$$\vec{S}^2 = \frac{3}{4}\hbar^2 \hat{1}$$

$\nwarrow$  eigenvalue for all vectors in the  $2 \times 2$  space

N=3: consider this now

(actually consider  $N \geq 2$  all at once, i.e. including spin  $\frac{1}{2}$ )

# Eigenkets and Eigenvalues of Angular Momentum

- Use no differential equations
- Use only  $[J_i, J_j] = i\epsilon_{ijk} J_k$

$[J_i, J_j] \neq 0$  for  $i \neq j$   $\rightarrow$  cannot make simultaneous eigenkets of  $J_x, J_y$

$$\begin{aligned}
 [\vec{J}^2, J_z] &= [J_x^2 + J_y^2 + J_z^2, J_z] \\
 &= J_x J_x J_z - J_z J_x J_x + J_y J_y J_z - J_z J_y J_y + \cancel{[J_z^2, J_z]} \\
 &\quad - J_x J_z J_x + J_x J_z J_x - J_y J_z J_y + J_y J_z J_y \\
 &= J_x \underbrace{[J_x, J_z]}_{-i\hbar J_y} + \underbrace{[J_x, J_z]}_{-i\hbar J_y} J_x + J_y \underbrace{[J_y, J_z]}_{i\hbar J_x} + J_y \underbrace{[J_z, J_y]}_{i\hbar J_x} \\
 &= -i\hbar J_x J_y - i\hbar J_y J_x + i\hbar J_y J_x + i\hbar J_y J_x \\
 &= 0 \rightarrow \therefore \text{can make simultaneous eigenkets of } \vec{J}^2 \text{ and } J_z \leftarrow \text{or } J_x, J_y
 \end{aligned}$$

Make simultaneous eigenkets of  $\vec{J}^2$  and  $J_z$

$$\vec{J}^2 |a b\rangle = a |a b\rangle$$

$$J_z |a b\rangle = b |a b\rangle$$

$a, b$  real  
since  $\vec{J}^2, J_z$  are Hermitian

Ladder Operators:  $J_{\pm} = J_x \pm iJ_y$

$$\begin{aligned}
 [J_+, J_-] &= [J_x + iJ_y, J_x - iJ_y] = \\
 &= i \underbrace{[J_y, J_x]}_{-i\hbar J_z} - i \underbrace{[J_x, J_y]}_{i\hbar J_z} \\
 &= 2\hbar J_z
 \end{aligned}$$

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$$\begin{aligned}
 [J_z, J_{\pm}] &= [J_z, J_x \pm iJ_y] = \underbrace{[J_z, J_x]}_{i\hbar J_y} \pm i \underbrace{[J_z, J_y]}_{-i\hbar J_x} \\
 &= i\hbar J_y \pm \hbar J_x \\
 &= \pm \hbar [J_x \pm iJ_y] \\
 &= \pm \hbar J_{\pm}
 \end{aligned}$$

$$\begin{aligned}
 [\vec{J}^2, J_{\pm}] &= [\vec{J}^2, J_x \pm iJ_y] \\
 &= 0
 \end{aligned}$$

Consider the state vectors  $J_{\pm} |a b\rangle$

operator makes one state vector from another

$$\begin{aligned}
 J_z \{ J_{\pm} |a b\rangle \} &= (J_z J_{\pm} + \underbrace{[J_z, J_{\pm}]}_{\pm \hbar J_{\pm}}) |a b\rangle \\
 &= J_{\pm} b |a b\rangle \pm \hbar J_{\pm} |a b\rangle \\
 &= (b \pm \hbar) \{ J_{\pm} |a b\rangle \}
 \end{aligned}$$

$J_z$  eigenvalue increased by  $\hbar$

$$\begin{aligned}
 \vec{J}^2 \{ J_{\pm} |a b\rangle \} &= J_{\pm} \vec{J}^2 |a b\rangle \\
 &= a \{ J_{\pm} |a b\rangle \}
 \end{aligned}$$

$\vec{J}^2$  eigenvalue unchanged

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For any state vector:  $\langle \phi | \phi \rangle \geq 0 \leftarrow$  postulate of Q.M.

Use  $|\phi_{\pm}\rangle = J_{\pm}^{\dagger} |a b\rangle \leadsto \langle \phi_{\pm} | = \langle a b | J_{\pm}$

$$\therefore \langle a b | J_{\pm} J_{\pm}^{\dagger} | a b \rangle \geq 0$$

$$\therefore \langle a b | \underbrace{J_{+} J_{+}^{\dagger} + J_{-} J_{-}^{\dagger}} | a b \rangle \geq 0$$

$$\begin{aligned} J_{+} J_{+}^{\dagger} + J_{-} J_{-}^{\dagger} &= (J_x + iJ_y)(J_x - iJ_y) + (J_x - iJ_y)(J_x + iJ_y) \\ &= 2(J_x^2 + J_y^2) + i(\cancel{J_y J_x} - \cancel{J_x J_y} - \cancel{J_y J_x} + \cancel{J_x J_y}) \\ &= 2(\vec{J}^2 - J_z^2) \end{aligned}$$

$$\langle a b | \cancel{2}(\vec{J}^2 - J_z^2) | a b \rangle \geq 0$$

$$a - b^2 \geq 0$$

$$\underline{b^2 \leq a} \leadsto a \text{ is non-neg.}$$

Since  $b^2 \leq a \rightarrow$  cannot raise or lower  $b$  forever

$$J_{+} |a b_{\max}\rangle = 0 \quad \text{and} \quad J_{-} |a b_{\min}\rangle = 0$$

$$\underbrace{J_{-} J_{+}} |a b_{\max}\rangle = 0$$

$$\underbrace{J_{+} J_{-}} |a b_{\min}\rangle = 0$$

$$\begin{aligned} J_{-} J_{+} &= (J_x - iJ_y)(J_x + iJ_y) = J_x^2 + J_y^2 + i \underbrace{[J_x, J_y]}_{i\hbar J_z} = J_x^2 + J_y^2 - \hbar J_z \\ &= \vec{J}^2 - J_z^2 - \hbar J_z \end{aligned}$$

$$\begin{aligned} J_{+} J_{-} &= (J_x + iJ_y)(J_x - iJ_y) = J_x^2 + J_y^2 + i \underbrace{[J_y, J_x]}_{-i\hbar J_z} \\ &= \vec{J}^2 - J_z^2 + \hbar J_z \end{aligned}$$

$$(\vec{J}^2 - J_z^2 - \hbar J_z) |a b_{\max}\rangle = 0 \quad | \quad (\vec{J}^2 - J_z^2 + \hbar J_z) |a b_{\min}\rangle = 0$$

$$a = b_{\max}(b_{\max} + \hbar)$$

$$a = b_{\min}(b_{\min} - \hbar) = (-b_{\min})(-b_{\min} + \hbar)$$

$$b_{\max} = -b_{\min}$$

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Repeatedly raise  $|a_{b_{\min}}\rangle$  with  $J_+$

$$b_{\min} \rightarrow b_{\min} \rightarrow b_{\min} + \hbar \rightarrow \dots$$

To stop from raising forever need  $b_{\max} = b_{\min} + n\hbar$   
 $b_{\max} = -b_{\max} + n\hbar$

pos.  
integer  
↓

$$\boxed{b_{\max} = \frac{1}{2}n\hbar}$$

$$\boxed{b_{\min} = -\frac{1}{2}n\hbar}$$

$$n = 0, 1, 2, \dots \quad \uparrow$$

Let  $j \equiv \frac{1}{2}n$   $\longrightarrow$  possible  $j$  values  
 $j = 0, \frac{1}{2}, 1, \frac{3}{2}, 2, \dots$

$$\begin{aligned} a &= b_{\max} (b_{\max} + \hbar) \\ &= \frac{1}{2}n\hbar \left( \frac{1}{2}n\hbar + \hbar \right) \\ &= j\hbar (j\hbar + \hbar) \\ &= \hbar^2 j(j+1) \leftarrow \text{eigenvalue of } \vec{J}^2 \end{aligned}$$

Let  $b \equiv m\hbar$  :  $b_{\min} \leq b \leq b_{\max}$

$$-j\hbar \leq m\hbar \leq j\hbar$$

$$-j \leq m \leq j$$

$$\therefore m = -j, -j+1, \dots, j$$

Normal notation:

$$\vec{J}^2 |jm\rangle = \hbar^2 j(j+1) |jm\rangle$$

$$J_z |jm\rangle = \hbar m |jm\rangle$$

$$j = 0, \frac{1}{2}, 1, \dots \quad m = -j, -j+1, \dots, j$$

## Normalization for $J_{\pm}$ Matrix Elements

$$J_{\pm} |jm\rangle = C_{jm}^{(\pm)} |j, m\pm 1\rangle \leadsto \underline{C_{jm}^{\pm} = \langle j, m\pm 1 | J_{\pm} | jm \rangle}$$

the  
Get/constant  $C_{jm}^{(\pm)}$

$$J_{+} |jm\rangle = C_{jm}^{(+)} |j, m+1\rangle \leadsto \langle jm | J_{+}^{\dagger} = C_{jm}^{(+)*} \langle j, m+1 |$$

$$\langle jm | \underbrace{J_{+}^{\dagger} J_{+}} | jm \rangle = |C_{jm}^{(+)}|^2$$

$$\underline{J^2 - J_z^2 - \hbar J_z} \text{ (showed earlier)}$$

$$\hbar^2 j(j+1) - \hbar^2 m^2 - \hbar \hbar m$$

$$|C_{jm}^{(+)}|^2 = \hbar^2 [j(j+1) - m(m+1)]$$

$$= \hbar^2 [(j-m)(j+m+1)]$$

Free to choose phase,  $\therefore$  choose simple  $C_{jm}^{+} = \hbar \sqrt{(j-m)(j+m+1)}$

$$J_{+} |jm\rangle = \hbar \sqrt{(j-m)(j+m+1)} |j, m+1\rangle$$

Relate to  $C_{jm}^{+}$

$$\begin{aligned}
 &= \langle j, m-1 | J_{-} | jm \rangle \\
 &= \langle jm | J_{-}^{\dagger} | j, m-1 \rangle^{*} \\
 &= \langle jm | J_{+} | j, m-1 \rangle^{*} \\
 &= (C_{j, m-1}^{+})^{*}
 \end{aligned}$$

$$\begin{aligned}
 &= \hbar \sqrt{(j-(m-1))(j+(m-1)+1)} \\
 &= \hbar \sqrt{(j-m+1)(j+m)}
 \end{aligned}$$

Together

$$J_{\pm} |jm\rangle = \hbar \sqrt{(j\mp m)(j\pm m+1)} |j, m\pm 1\rangle$$