HW2

Sunday, April 17, 2022 11:28 PM

 $\frac{dx}{dt} = f(x, m)$

- \(\chi \) \(\chi \)

f(x, M)

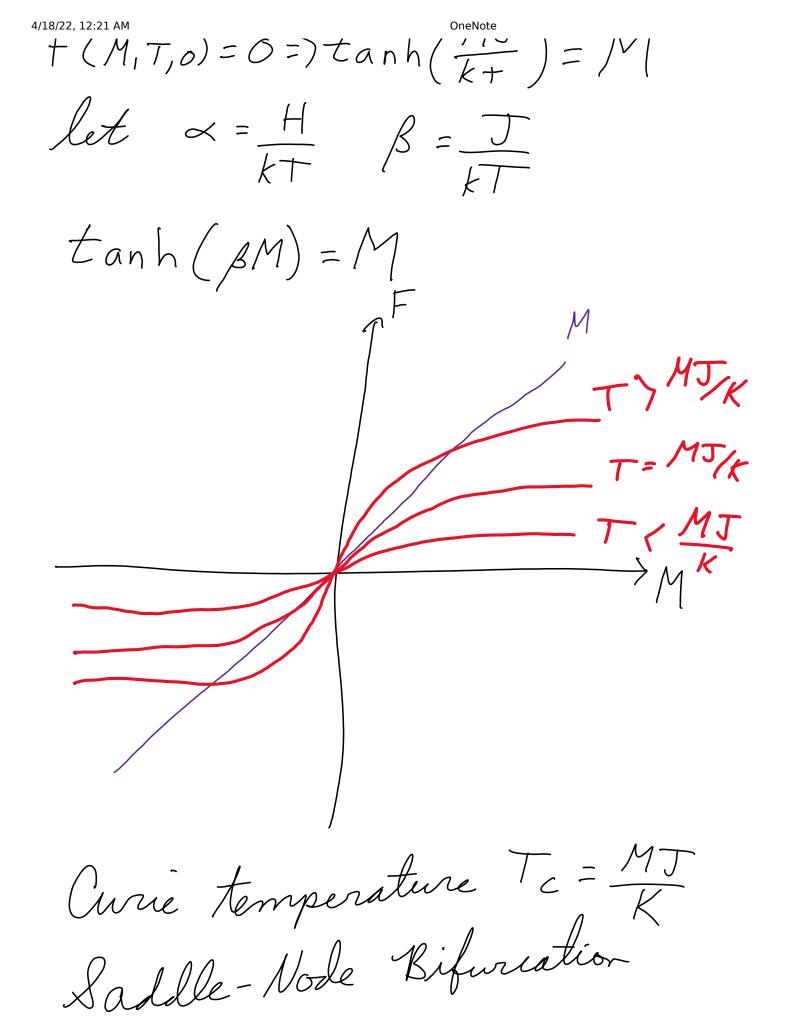
(f(o,o)=0?

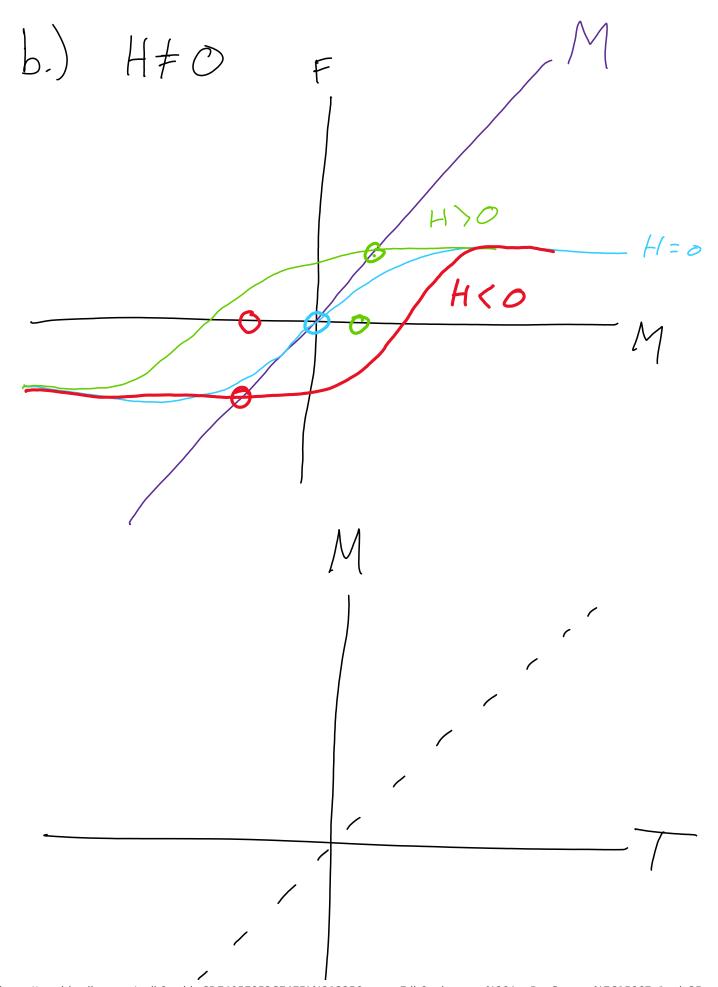
No ((0,0) is not a fixed point

(0,0) is a fixed point

Qualitative changed at fixed point? (Created, destroyed, or stability change)

100 bifurcation)





C.

1 point

J point

3.) $dg = \dot{g} = k_1 s_0 - k_2 g + k_3 g^2 \frac{1}{k_4^2 + g^2}$

= 1,5,- 1, 6,92

$$\left(\frac{dg}{dt}\right)\frac{k_{4}}{k_{4}k_{3}} = \frac{k_{1}k_{4}}{k_{4}k_{3}} - \frac{k_{2}k_{4}g}{k_{3}} + \frac{k_{3}g^{2}/k_{4}}{k_{4}} + \frac{k_{3}g^{2}/k_{4}}{(1+\frac{g^{2}}{k_{4}^{2}})} + \frac{k_{4}k_{3}g^{2}}{k_{4}k_{3}}$$

$$\left(\frac{d(\frac{9}{k_4})}{dt}\right) \frac{k_4}{k_4 k_3} = \frac{k_1}{k_3} s_0 - \frac{k_2 k_4}{k_3} \frac{9}{k_4} + \frac{9^2 k_4^2}{1 + 9^2 k_4^2}$$

$$\frac{9}{k_{4}} = x \qquad \frac{k_{2}k_{4}}{k_{3}} = r \qquad \frac{k_{1}s_{0}}{k_{3}} = s \qquad \frac{k_{4}k_{3}}{k_{4}} = r = r$$

$$\frac{dx}{d\tau} = S - rx + \frac{x^2}{1 + x^2}$$

b.)
$$S = 0$$
 $\frac{dx}{d\tau} = 0 - (x + \frac{x^2}{1 + x^2}) = 0$

$$\frac{7}{11 \times 2} \qquad 7x + 7x^3 = x^2$$

$$X = 0, 1 \pm \sqrt{1 - 4r^2}$$

$$C.) \quad g(6) = 0 \longrightarrow X(0) = 0$$

For high valves of r, g(t) will revert to the x*=0 stable point. Lower ralves will make

g(t) go towards one of the ther nonzero stable points.

$$\frac{dA}{dx} = 0 = 7 S - rx + \frac{x^2}{1+x^2}$$

$$\frac{d}{dx}\left(\frac{dx}{dz}\right) = 0 \qquad x^2(1+x^2)^{-1}$$

$$0 - (1 + \frac{2x}{1 + x^2} + \frac{-x^2}{(1 + x^2)^2} = 0$$

$$r = \frac{2x}{(1+x^2)^2}$$

$$S - \frac{2x^2}{(1+x^2)^2} + \frac{x^2}{(1+x^2)^2}$$

$$S - \frac{2x^{2}}{(1+x^{2})^{2}} + \frac{x^{2}(1+x^{2})}{(1+x^{2})^{2}} = 0$$

$$S = \frac{\chi^2(1-\chi^2)}{(\chi^2-1)^2}$$
Saddle Mode
$$S = \frac{\chi^2(1-\chi^2)}{(\chi^2-1)^2}$$
Soddle Saddle Sadd