

## Hw 4

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$$1.) \quad ds^2 = c^2 dt^2 - dx^2 - dy^2 - dz^2$$

$$\text{Show } ds^2 = ds'^2 \quad y = y' \quad z = z'$$

$$x = \gamma(x' - vt') \quad t = \gamma(t' + \frac{vx'}{c^2})$$

$$ds^2 = c^2 \gamma^2 \left( dt' + \frac{v dx'}{c^2} \right)^2 - \gamma^2 (dx' + v dt')^2 - dy'^2 - dz'^2$$

$$= c^2 \gamma^2 \left( dt'^2 + \frac{v^2 dx'^2}{c^4} + \frac{2v dx' dt'}{c^2} \right)$$

$$- \gamma^2 (dx'^2 + v^2 dt'^2 + 2v dx' dt') - dy'^2 - dz'^2$$

$$= \gamma^2 \left( c^2 dt'^2 + \frac{v^2 dx'^2}{c^2} + \cancel{2v dx' dt'} \right)$$

$$- dx'^2 - v^2 dt'^2 - \cancel{2v dx' dt'} - dy'^2 - dz'^2$$

$$= \gamma^2 \left[ dt'^2 \left( c^2 - v^2 \right) - \frac{v^2 dx'^2}{c^2} \right] - dy'^2 - dz'^2$$

$$= 0 \quad \left[ \frac{1}{\gamma^2} \left( 1 - \frac{v^2}{c^2} \right) \right] - dy'^2 - dz'^2$$

$$= \gamma^2 \left[ \underbrace{c^2 dt'^2}_{1/\gamma^2} \left( 1 - \frac{v^2}{c^2} \right) - \underbrace{dx'^2}_{1/\gamma^2} \right] - dy'^2 - dz'^2$$

$$= c^2 dt'^2 - dx'^2 - dy'^2 - dz'^2$$


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$$2.) \quad x = \gamma(x' - vt') \quad t = \gamma\left(t' - \frac{vx'}{c^2}\right)$$

$$ct(\sigma) = \lambda \sinh(\sigma) \quad x(\sigma) = \lambda \cosh(\sigma)$$

$$i.) \quad ds^2 = c^2 dt^2 - dx^2$$

$$dct(\sigma) = \lambda \cosh(\sigma) d\sigma$$

$$dx(\sigma) = \lambda \sinh(\sigma) d\sigma$$

$$ds^2 = \lambda^2 \sinh^2(\sigma) d\sigma^2 - \lambda^2 \cosh^2(\sigma) d\sigma^2$$

$$= \lambda^2 d\sigma^2$$

$$ds^2 = c^2 d\tau^2 = \lambda^2 d\sigma^2$$

$$c d\tau = \lambda d\sigma \quad \int d\sigma = \frac{c}{\lambda} \int d\tau \quad \sigma = \frac{c\tau}{\lambda}$$

$$ii] \frac{dx}{d\tau} = \frac{dx}{d\sigma} \frac{d\sigma}{d\tau} = \lambda \sinh(\sigma) \frac{c}{\lambda}$$

$$= C \sinh\left(\frac{c\tau}{\lambda}\right) = u(\tau)$$

$$\int dx = \int c \sinh\left(\frac{c\tau}{\lambda}\right) d\tau$$

$$x = \lambda \cosh\left(\frac{c\tau}{\lambda}\right)$$

$$iii] a(\tau) = \frac{d^2 x}{d\tau^2} = \frac{d}{d\tau} \left[ c \sinh\left(\frac{c\tau}{\lambda}\right) \right]$$

$$= \frac{c^2}{\lambda} \cosh\left(\frac{c\tau}{\lambda}\right)$$

iv) This is a valid trajectory since in space-time, these look like hyperbolic motion.

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$$3.) \vec{a} = \vec{g}$$

Rindler Coordinates:

$$t' = x \sinh(at)$$

$$x' = x \cosh(at)$$

$$x = \sqrt{x'^2 - t'^2}$$

$$t = \frac{1}{a} \tanh^{-1}\left(\frac{t'}{x'}\right)$$

$$dx = \gamma(dx' - v dt')$$

$$dt = \gamma\left(dt' - \frac{v}{c^2} dx'\right)$$

$$u = \frac{u' - v}{1 - \frac{u'v}{c^2}}$$

$u' =$  velocity of rest frame

$$1 - \frac{u'^2}{c^2}$$

$u = \text{vel. of moving ref. frame}$

$$du = \frac{du' \left( 1 - \frac{u'v}{c^2} \right) + (u' - v) \frac{v du'}{c^2}}{1 - \frac{u'v}{c^2}}$$

$$= \frac{du'}{\gamma^2 \left( 1 - \frac{u'v}{c^2} \right)^2}$$

$$\frac{du}{dt} = a = \frac{\frac{du'}{dt}}{\gamma^3 \left( 1 - \frac{u'v}{c^2} \right)^3} = \frac{a'}{\gamma^3 \left( 1 - \frac{u'v}{c^2} \right)^3}$$

in 1-D motion:  $u' = v$

$$a = \gamma^3 a' = \frac{d(\gamma v)}{dt'} = v \frac{d\gamma}{dt'} + \gamma \frac{dv}{dt'}$$

$$= \gamma a' \left( 1 + \frac{\gamma^2 v^2}{c^2} \right)$$

$$\int c d(\gamma v) = \int a dt'$$

$$\boxed{\gamma v = at'}$$

$$\gamma = \sqrt{\frac{1}{1 - \frac{v^2}{c^2}}} = \sqrt{1 + \frac{a^2 t'^2}{c^2}}$$

$$t' = \frac{\gamma v}{a} = \frac{v}{g} \sqrt{\frac{1}{1 - \frac{v^2}{c^2}}}$$

$\boxed{c}$

$$\boxed{ii} \quad \frac{v}{c} = \tanh\left(\frac{gt'}{c}\right)$$

$$\frac{gt'}{c} = \tanh^{-1}\left(\frac{v}{c}\right)$$

$$t' = \frac{c}{g} \tanh^{-1}\left(\frac{v}{c}\right)$$

$\boxed{iii}$

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$$t = \frac{v}{g} \sqrt{\frac{1}{1 - \frac{v^2}{c^2}}} = \frac{c}{4g} \sqrt{1 - \frac{c^2}{4^2 c^2}}$$

$$= \frac{c}{4g} \sqrt{\frac{1}{1 - \frac{1}{16}}} = \frac{c}{4g} \sqrt{\frac{1}{15/16}}$$

$$= \frac{c}{4g} \sqrt{\frac{16}{15}} = \frac{c}{g\sqrt{15}} = 7.9 \times 10^6 \text{ s}$$

$$t' = \frac{c}{g} \tanh^{-1}\left(\frac{1}{4}\right) = 7.8 \times 10^6 \text{ s}$$

4.)

$$\therefore F_{\mu\nu} F^{\mu\nu} =$$

$$\text{tr} \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -E_z & E_y \\ E_y & E_z & 0 & -E_x \\ -E_z & -E_y & E_x & 0 \end{bmatrix} \begin{bmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -E_z & E_y \\ E_y & E_z & 0 & -E_x \\ -E_z & -E_y & E_x & 0 \end{bmatrix}$$

$$\left\{ \begin{bmatrix} E_x & 0 & 0 & 0 \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{bmatrix} \begin{bmatrix} E_x & 0 & 0 & 0 \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{bmatrix} \right\}$$

$$= (E_x^2 + E_y^2 + E_z^2) + (E_x^2 + B_z^2 + B_y^2)$$

$$+ (E_y^2 + B_z^2 + B_x^2) + (E_z^2 + B_y^2 + B_x^2)$$

$$= 2\vec{E}^2 + 2\vec{B}^2 = 2(E^2 + B^2)$$

$$(i) F_{\mu\nu} F^{\mu\nu}$$

$$= \text{tr} \left\{ \begin{bmatrix} 0 & B_x & B_y & B_z \\ -B_x & 0 & E_z & -E_y \\ -B_y & -E_z & 0 & E_x \\ -B_z & E_y & -E_x & 0 \end{bmatrix} \begin{bmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{bmatrix} \right\}$$



$$\begin{aligned}
 &= (B_x E_x + B_y E_y + B_z E_z) + (B_x E_x + B_z E_z + B_y E_y) \\
 &+ (B_y E_y + B_z E_z + B_x E_x) + (B_z E_z + B_y E_y + B_x E_x) \\
 &= 4(B_x E_x + B_y E_y + B_z E_z) = 4 \vec{B} \cdot \vec{E}
 \end{aligned}$$

iii) A purely electric field in one inertial frame will not be seen as a purely magnetic field because the electromagnetic field is an invariant, as shown in part i.

iv) A progressive EM wave cannot be seen as purely electric + because of their

or magnetic field, it is invariant in orthogonality; it is invariant in any inertial reference frame and also in geometry.