Hidden Markov Models (I)

Natural Language Processing

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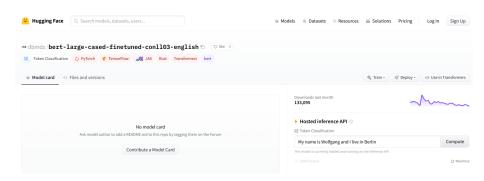
Sequential Labelling

- Many problems in NLP require text to be labelled:
 - Part-of-Speech Tagging (POS): Find lexical terms in a sentence.
 - Input: 'red', 'flower'
 - Output: 'adjective', 'noun'
 - Named Entity Recognition (NER): Find 'Entities' in a sentence.
 - Input: 'Bill', 'Gates', 'founded', 'Microsoft', 'decades', 'ago'
 - Output: 'Person', 'Person', '-', 'Company', 'O', 'O'

Sequential Labelling

- Example: 'Bill', 'Gates', 'founded', 'Microsoft', 'decades', 'ago'
- We would like to know that 'Bill Gates' is a person, not consider 'Bill' and 'Gates' as two different people
- Inside-Outside-Beginning Tagging (IOB Tagging) uses B
 (Beginning) and I (Inside) tags to change the class label of a word to
 allow multiple words to belong to a single concept
 - Input: 'Bill', 'Gates', 'founded', 'Microsoft', 'decades', 'ago'
 - Output: 'B-Per', 'I-Per', 'O', 'B-COMP', 'O', 'O'
 - Input: Angelina Jolie was born in Los Angeles.
 - Output: 'B-PER', 'I-PER', 'O', 'O', 'O', 'B-LOC', 'I-LOC'

https://huggingface.co/dbmdz/bert-large-cased-finetuned-conll03-english



→ Hosted inference API ③

🚟 Token Classification

My name is Robert Paulson and I live in Wilmington, Delaware

Compute

Computation time on cpu: 0.2724 s

My name is Robert Paulson PER and I live in Wilmington Loc, Delaware Loc



 Image: Following the properties of the properties of

Han Xiao did not like Hugging Face much, that is why he built Jina

Compute

Computation time on cpu: 0.42 s

Han Xiao PER did not like Hugging MISC Face PER much, that is why he built

Jin ORE a MISC

→ Hosted inference API ③

🚟 Token Classification

I love that Julia replaces standard classes by multiple dispatch

Compute

Computation time on cpu: 0.2135999999999998 s

I love that Julia PER replaces standard classes by multiple dispatch

Sequential Labelling: Notation

- Let $\Sigma := w_1, ..., w_J$ be a set of words
- Let $\Lambda := c_1, ..., c_K$ be a set of labels
- ullet A sentence is an element from Σ^* which is the Kleene closure of Σ
 - The Kleene closure of a set Σ is defined as the set containing all possible strings of arbitrary length made up with elements in Σ , ϵ is used for the empty string
 - $\Sigma = a, b$ then $\Sigma^* = \epsilon, a, b, aa, ab, ba, bb, aaa, aab, bab, bba, ...$
 - $\Sigma = ab, c$ then $\Sigma^* = \epsilon, ab, c, abab, abc, cab, cc, ababab, ababc, ...$

Sequential Labelling: Notation

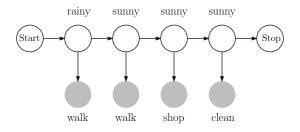
• A Hidden Markov Model (HMM) is a probabilistic model that defines a probability distribution over input/output pairs as follows:

$$\begin{split} P(X_{1} = x_{1},...,X_{N} = x_{N},Y_{1} = y_{1},...,Y_{N} = y_{N}) = & P_{\text{init}}(y_{1} | \text{start}) \cdot \prod_{i=1}^{N-1} P_{\text{trans}}(y_{i+1} | y_{i}) \cdot \\ & P_{\text{final}}(\text{stop} | y_{N}) \cdot \prod_{i=1}^{N} P_{\text{emiss}}(x_{i} | y_{i}) \end{split}$$

 The previous formula tells us how to compute the probability of a pair if we have the initial, transition, final and emission probabilities, but how do we find such probabilities?

HMM Example

(x, y) = ([walk, walk, shop, clean], [rainy, sunny, sunny, sunny])



 $P([\text{walk, walk, shop, clean}], [\text{rainy, sunny, sunny, sunny}]) = \\ P_{\text{init}}(\text{rainy}|\text{start}) \cdot P_{\text{trans}}(\text{sunny}|\text{rainy}) \cdot P_{\text{trans}}(\text{sunny}|\text{sunny}) \cdot P_{\text{trans}}(\text{sunny}|\text{sunny}) \cdot P_{\text{final}}(\text{stop}|\text{sunny}) \cdot \\ P_{\text{emiss}}(\text{walk}|\text{rainy}) \cdot P_{\text{emiss}}(\text{walk}|\text{sunny}) \cdot P_{\text{emiss}}(\text{shop}|\text{sunny}) \cdot P_{\text{emiss}}(\text{clean}|\text{sunny}) \cdot \\ P_{\text{emiss}}(\text{walk}|\text{rainy}) \cdot P_{\text{emiss}}(\text{walk}|\text{rainy}) \cdot P_{\text{emiss}}(\text{shop}|\text{sunny}) \cdot P_{\text{emiss}}(\text{clean}|\text{sunny}) \cdot \\ P_{\text{emiss}}(\text{shop}|\text{sunny}) \cdot P_{\text{emiss}}(\text{sh$

HMM Parameters in memory

Parameter	#Floats
$P_{\mathrm{init}}(c \mathrm{start})$	\ \ \
$P_{ m trans}(c \hat{c})$	$ \Lambda ^2$
$P_{\mathrm{final}}(\mathrm{stop} c)$	\[\ \
$P_{ m emiss}(w c)$	$ \Sigma \cdot \Lambda $

HMM Properties

• Independence of Previous States: the probability of being in a given state at position i only depends on the state of the previous position i-1 (this defines a first order Markov chain)

$$P(Y_i = y_i | Y_{i-1} = y_{i-1}, Y_{i-2} = y_{i-2}, ..., Y_1 = y_1) = P(Y_i = y_i | Y_{i-1} = y_{i-1})$$

• Homogeneus Transition: the probability of making a transition from state c_l to state c_k is independent of the particular sequence position

$$P(Y_i = c_k | Y_{i-1} = c_l) = P(Y_t = c_k | Y_{t-1} = c_l)$$

• Observation Independence: the probability of observing $X_i = x_i$ at position i is fully determined by the state Y_i at that position. The probability is also independent of the particular position

$$P(X_i = x_i | Y_1 = y_1, ..., Y_i = y_i, ..., Y_N = y_N) = P(X_i = x_i | Y_i = y_i)$$

$$P(X_i = w_j | Y_i = c_k) = P(X_t = w_j | Y_t = c_k)$$

Decoding Problems in HMM

• Posterior decoding

$$y_i^* = \arg\max_{y_i \in \Lambda} P(Y_i = y_i | X_1 = x_1, ..., X_N = x_N)$$

Viterbi decoding

$$y^* = \underset{y \in \Lambda^N}{\text{arg max }} P(Y_1 = y_1, ..., Y_N = y_N | X_1 = x_1, ..., X_N = x_N)$$

Learning the Parameters of an HMM

 HMM parameters can be learnt by counting the different events we encounter in the training data*

Parameter	Value
$c_{\text{init}}(c_k)$	$\sum_{m=1}^{M} 1_{(y_1^m = c_k)}$
$P_{\text{init}}(c_k \text{start})$	$\frac{c_{\text{init}}(c_k)}{\sum_{l=1}^{L}c_{\text{init}}(c_l)}$
$c_{\mathrm{trans}}(c_k,c_l)$	$\sum_{m=1}^{M} \sum_{i=1}^{N} 1_{(y_i^m = c_k \land y_{i-1}^m = c_l)}$
$P_{\mathrm{trans}}(c_I c_k)$	$\frac{c_{\text{trans}}(c_k, c_l)}{\sum_{p=1}^{P} c_{\text{trans}}(c_k, c_p) + c_{\text{final}}(c_k)}$
$c_{\text{final}}(c_k)$	$\sum_{m=1}^{M} 1_{(y_N^m = c_k)}$
$P_{\text{final}}(\text{stop} c_I)$	$\frac{c_{\text{final}}(c_l)}{\sum_{p=1}^{P} c_{\text{trans}}(c_l, c_p) + c_{\text{final}}(c_l)}$
$c_{\mathrm{emiss}}(w_j, c_k)$	$\sum_{m=1}^{M} \sum_{i=1}^{N} 1_{(x_i^m = w_j \wedge y_i^m = c_k)}$
$P_{\mathrm{emiss}}(w_j c_k)$	$\frac{c_{\mathrm{emiss}}(w_j, c_k)}{\sum_{q=1}^{J} c_{\mathrm{emiss}}(w_q, c_k)}$

^{*} M: number of samples

Forward Backward Algorithm

• Forward quantity

$$f(i,x,c) := P(X_1 = x_1,...,X_i = x_i,Y_i = c)$$

• Backward quantity

$$b(i,x,c) := P(X_{i+1} = x_{i+1},...,X_N = x_N | Y_i = c)$$

Efficient Forward Quantity Computations

• If we define $f(i, x, c) := P(X_1 = x_1, ..., X_i = x_i, Y_i = c)$ then, the forward quantity at position i can be written as:

$$f(i, x, c) = P_{\text{emiss}}(x_i|c) \cdot \left(\sum_{\tilde{c} \in \Lambda} P_{\text{trans}}(c|\tilde{c}) \cdot f(i-1, x, \tilde{c})\right)$$

Recurrence Rule for the Forward Quantities

$$f(i, x, c) := P(X_{1} = x_{1}, ..., X_{i} = x_{i}, Y_{i} = c)$$

$$P(y_{i}, x_{1:i}) = \sum_{y_{i-1} \in \Lambda} P(y_{i}, y_{i-1}, x_{1:i}) = \sum_{y_{i-1} \in \Lambda} P(y_{i}, y_{i-1}, x_{1:i-1}, x_{i}) = \sum_{y_{i-1} \in \Lambda} P(x_{i}|y_{i}, y_{i-1}, x_{1:i-1}) \cdot P(y_{i}, y_{i-1}, x_{1:i-1}) = \sum_{y_{i-1} \in \Lambda} P(x_{i}|y_{i}, y_{i-1}, x_{1:i-1}) \cdot P(y_{i}|y_{i-1}, x_{1:i-1}) \cdot P(y_{i-1}, x_{1:i-1}) \approx \sum_{y_{i-1} \in \Lambda} P(x_{i}|y_{i}) \cdot P(y_{i}|y_{i-1}) \cdot P(y_{i-1}, x_{1:i-1}) = P(x_{i}|y_{i}) \cdot \sum_{y_{i-1} \in \Lambda} P(y_{i}|y_{i-1}) \cdot P(y_{i-1}, x_{1:i-1})$$

Forward Quantities Definition

- Let us consider a sequence x with N words
- For every state c let us define:

$$f(1,x,c) = P_{\text{init}}(c_k|\text{start}) \cdot P_{\text{emiss}}(x_1|c_k)$$

• For every position i = 2 up to N

$$f(i,x,c) = P_{\mathrm{emiss}}(x_i|c) \cdot \left(\sum_{\tilde{c} \in \Lambda} P_{\mathrm{trans}}(c|\tilde{c}) \cdot f(i-1,x,\tilde{c})\right)$$

• For position N+1

$$f(N+1, \text{stop}) = \sum_{c_l \in \Lambda} P_{\text{final}}(\text{stop}|c) \cdot f(N, x, c)$$

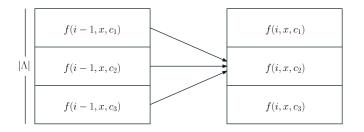
Forward Quantities

$$f(i, x, c) = P_{\text{emiss}}(x_i|c) \cdot \left(\sum_{\tilde{c} \in \Lambda} P_{\text{trans}}(c|\tilde{c}) \cdot f(i-1, x, \tilde{c})\right)$$

	$f(1,x,\cdot)$	$f(2,x,\cdot)$		$f(i-1,x,\cdot)$	$f(i,x,\cdot)$		$f(N,x,\cdot)$
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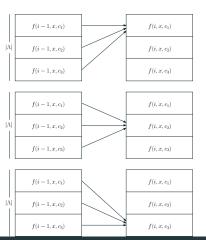
Forward Quantities

$$f(i, x, c) = P_{\text{emiss}}(x_i|c) \cdot \left(\sum_{\tilde{c} \in \Lambda} P_{\text{trans}}(c|\tilde{c}) \cdot f(i-1, x, \tilde{c})\right)$$



Forward Quantity Given the Previous Forward Quantity

$$f(i, x, c) = P_{\text{emiss}}(x_i|c) \cdot \left(\sum_{\tilde{c} \in \Lambda} P_{\text{trans}}(c|\tilde{c}) \cdot f(i-1, x, \tilde{c})\right)$$



Recurrence Rule for the Backward Quantities

$$b(i,x,c) := P(X_{i+1} = x_{i+1},...,X_N = x_N | Y_i = c)$$

Exercise!

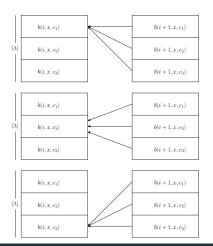
Backward Quantities

$$b(i,x,c) := \sum_{\tilde{c} \in \Lambda} P_{\mathrm{trans}}(\tilde{c}|c) \cdot P_{\mathrm{emiss}}(x_{i+1}|\tilde{c}) \cdot b(i+1,x,\tilde{c})$$

	$b(1,x,\cdot)$	$b(2,x,\cdot)$		$b(i-1,x,\cdot)$	$b(i,x,\cdot)$		$b(N,x,\cdot)$
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Backward Quantities

$$b(i,x,c) := \sum_{\tilde{c} \in \Lambda} P_{\mathrm{trans}}(\tilde{c}|c) \cdot P_{\mathrm{emiss}}(x_{i+1}|\tilde{c}) \cdot b(i+1,x,\tilde{c})$$



Forward Backward Algorithm

- Proposition I: $P(X = x_{1:N}, Y_i = c) = f(i, x, c) \cdot b(i, x, c)$
- Proposition II: $P(X = x_{1:N}) = \sum_{c \in \Lambda} f(i, x, c) \cdot b(i, x, c)$
- Proposition III: $P(Y_i = c | X = x_{1:N}) = \frac{f(i,x,c) \cdot b(i,x,c)}{P(X=x)}$
- Proposition IV (Posterior decoding):

$$y^* = \arg\max_{c \in \Lambda} P(Y_i = c | X_1 = x_1, ..., X_N = x_N) = \arg\max_{c \in \Lambda} f(i, x, c) \cdot b(i, x, c)$$

Forward Backward Algorithm

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\begin{split} & \text{forward\_backward}(x, \Lambda, P_{\text{init}}, P_{\text{trans}}, P_{\text{final}}, P_{\text{emiss}}) \\ & \text{\# Forward pass} \\ & \text{for } c_k \in \Lambda: \\ & \text{forward}(1, x, c_k) = P_{\text{init}}(c_k | \text{start}) \cdot P_{\text{emiss}}(x_1 | c_k) \\ & \text{for } i = 1 \text{ to } N: \\ & \text{for } \tilde{c} \in \Lambda: \\ & \text{forward}(i, x, \tilde{c}) = \left(\sum_{c_k \in \Lambda} P_{\text{trans}}(\tilde{c} | c_k) \cdot \text{forward}(i - 1, x, c_k)\right) P_{\text{emiss}}(x_i | \tilde{c}) \\ & \text{\# Backward pass} \\ & \text{for } c_k \in \Lambda: \\ & \text{backward}(N, x, c_k) = P_{\text{final}}(\text{stop} | c_k) \\ & \text{for } i = N - 1 \text{ to } 1: \\ & \text{for } \tilde{c} \in \Lambda: \\ & \text{backward}(i, x, \tilde{c}) = \sum_{c_k \in \Lambda} P_{\text{trans}}(c_k | \tilde{c}) \cdot P_{\text{emiss}}(x_{i+1} | c_k) \cdot \text{backward}(i + 1, x, c_k) \end{split}
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