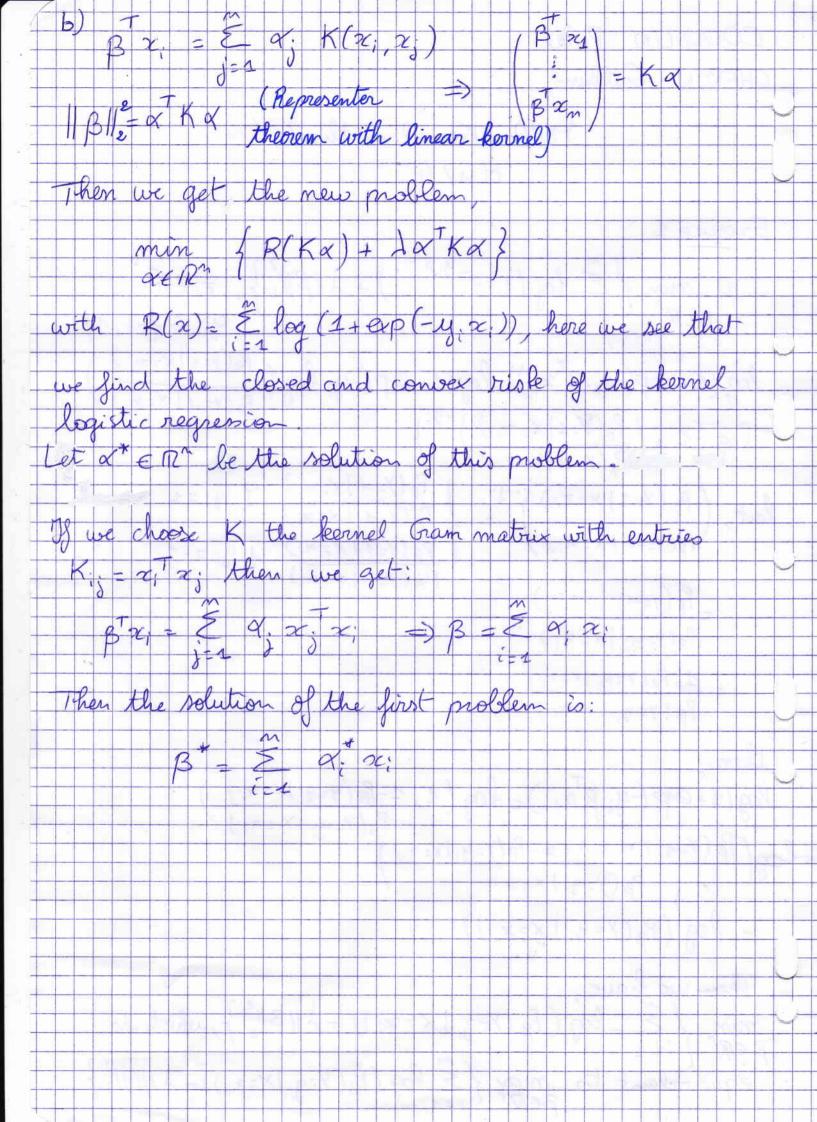
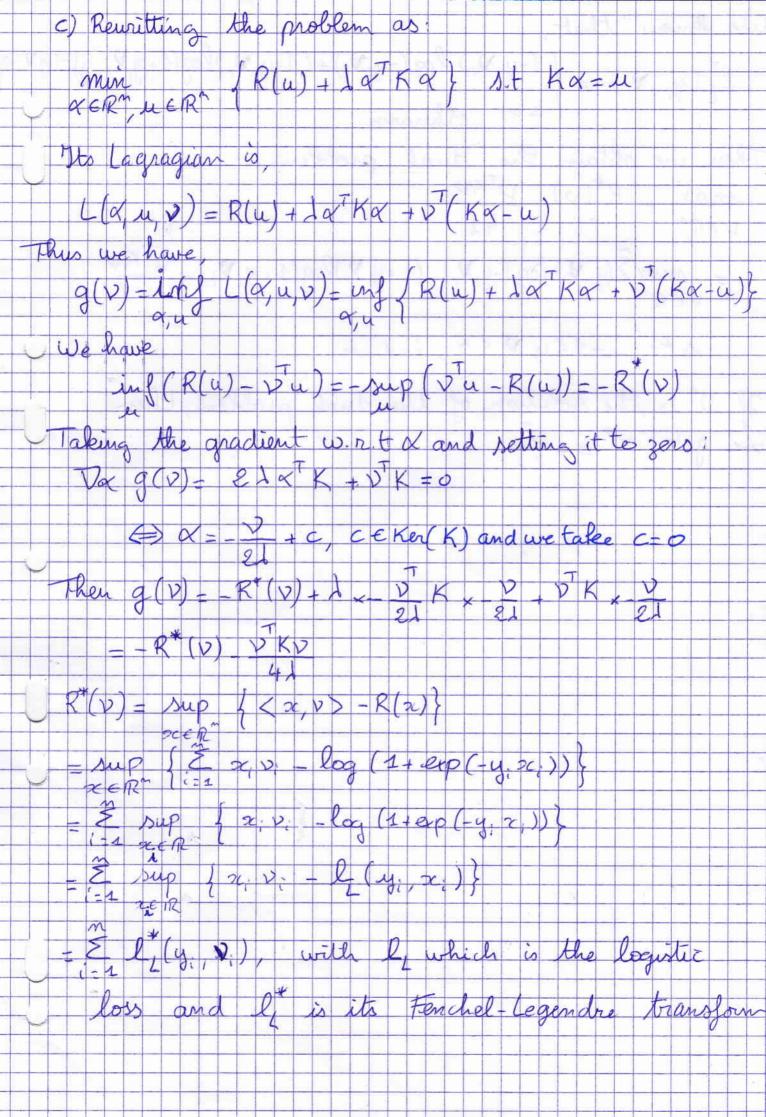
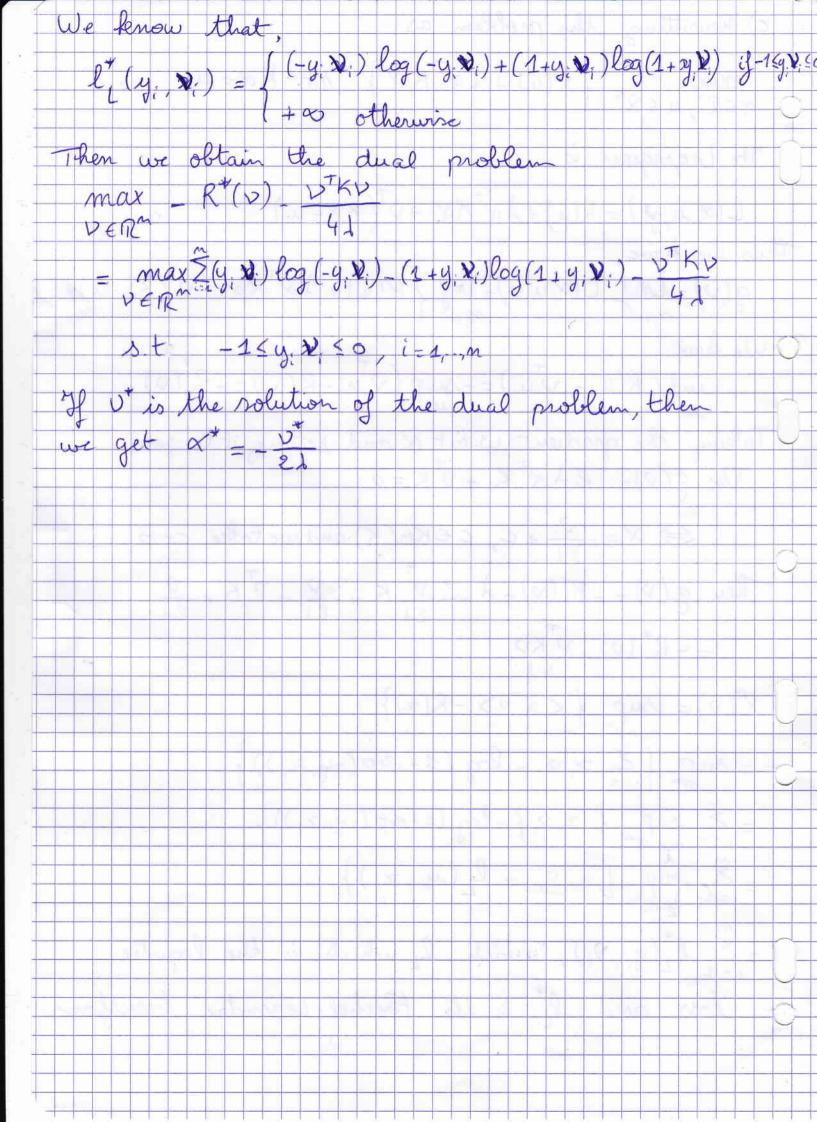
Pierre COQUELIN CHERON Guillem YVA Kernel methods HW 4 Exercice 1 min { E log (1+e) + 1 | B | 2 }, z, ER 9: 6 1-1,1} log (1+ exp(-y; B x;))=log (1+ exp(-y; log (PB (Y=1 | X=n; $= \log \left(1 + \left(\frac{P_{\beta}(\mathbf{Y}=1 \mid \mathbf{X}=\mathbf{x}_{:})}{P_{\beta}(\mathbf{Y}=1 \mid \mathbf{X}=\mathbf{x}_{:})}\right)^{-g_{:}}\right)$ PB (Y=-1 | X= >2;) but, (Ps (Y=11x=x;))-y: if y = 1 PB(Y=1 | X=x;) PB(Y=-1 1 x=21:) PB (Y=1) X=n:) ig ig: = -1 PB (4-11 X=2) - PB (Y=-4) (X= 961) PB(Y= 4) | X= 2(1) 1- PB (Y=4; X=x;) PB (Y= y: 1 x= 21) then, log (1+exp (-y; B, 7;)= log (1, 1-Pp (y=y; 1x=x;) log (PB (Y=y; 1 x=x;) + 1-PB (Y=y; 1x=x;)

PB (Y=y; 1 x=x;) = log (PB (Y= 4: 1 x= x;)) Then we have, log (Pg (Y=y: | X=x;)) + 2 | 3 | 2 }, which is equivalent to may { 5 log (PB(Y=y, |X=x;)) - 2 / |B|)2}







d. *The objective of problem (1) is: C1(B) = \$ log(1+e-Y; B'x;) + > 11B112 = - Elogis (y: B =) + 2 /1/B/1/2 With g(x) = 1+expl-x) the signoid function. VB (103 3(x, BTx;)) = 1 3(x, BTx;) (1-9(x, BTx;))(1-9(x, BTx;))(1/2) Because $\frac{\partial g(x)}{\partial x} = g(x)(1-g(x))$. Thus the gradient of Ca(B) is VBC1(B) = - 27, x; (1-9(Y; Bx;)) + 22B We have 2 y·x; g(y; β^Tx;) = x; (p) (g(y; β^Tx;)(1-g(y; β²x;)) x; (κ) y;² Thus the Hessiah of C1(B) is (VBC1(B))pk = \(\int \x; (p) \x; (k) (g/y, B\(\int \)) (1-g/y, B\(\int \)) +27 1/5p=k3

The objective of problem (2) is

$$C_{2}(x) = \underbrace{\underbrace{8}}_{103} \underbrace{(1 + \exp(-y; \underbrace{\$a}_{1}, K_{1}) + 2x^{*}Kx}$$

$$= -\underbrace{\$lo_{3}}_{103} \underbrace{(9, y; \underbrace{\$a}_{1}, K_{1}) + 2x^{*}Kx}$$

We have
$$\underbrace{8lo_{3}}_{103} \underbrace{(y; \underbrace{\$a}_{1}, K_{1})}_{103} = \underbrace{(1 - 9, y; \underbrace{\$a}_{1}, K_{1}) + y; K_{1}}_{103} \underbrace{(Ka)_{1}}_{103}$$

Thus the godient is
$$\underbrace{(\nabla_{1} C_{2}(x))_{k}}_{103} = -\underbrace{\underbrace{5}_{103}}_{103} \underbrace{(1 - 9, y; \underbrace{\$a}_{1}, K_{1}) + y; K_{1}}_{103} \underbrace{(Ka)_{1}}_{103} \underbrace{(Ka)_{1}}_{103}$$

And the Hessian is
$$\underbrace{(\nabla_{1}^{2} C_{2}(x))_{kp}}_{103} = \underbrace{\underbrace{8}_{103}}_{103} \underbrace{(y; \underbrace{\$a}_{1}, K_{1}) + y; K_{1}}_{103} \underbrace{(1 + y; F_{1}) + y; K_{2}}_{103} \underbrace{(1 + y; F_{1}) + y; K_{2}}_{103$$

We implemented a simple Newton-Raphson algorithm and the gradient and Hessian matrix of each problem in MATLAB.

Data is generated randomly using Gaussian distributions with random covariance matrix generated using Wishart distribution. The data is split into a train set and a test set.

The parameter λ is determined using a 5-fold cross validation on the training set. For optimization problems (2) and (3) we used both a linear kernel and a Gaussian kernel with $\sigma = 10$.

Problem (3) is the only one with constraints. After a Newton-Raphson iteration, we set the variables v_i that don't respect these constraints at the closest frontier of the constraint set.

The figures below display the objective function and prediction error in function of Newton-Raphson iterations. Each figure display the results obtained with the various methods, for given values of n and p.

We observe the following points:

- As expected, results obtained with problem (1) and (2) are the same when using a linear kernel (red and yellow curves on the figures below are superimposed).
- Optimization problem (2) needs fewer iterations to converge than problem (3)
- The highest computation cost source is the inversion of the Hessian matrix. Thus, when the number of points n is superior to the dimension p, problem (2) and (3) have a higher computation cost than problem (1). Indeed hessians of problems (2) and (3) have the same size as the Gram matrix (number of points) while hessian of problem (1) size's is p x p.

