

FPGAs, HLS Tools & Runtime Systems

(Super)Advisors: Frederic Desprez, Francois Broquedis, Olivier Muller

Georgios Christodoulis

CORSE-LIG

gchristodoulis@gmail.com

Overview

FPGAs structure

- Look-Up Table

- Basic Logic Element

- Overview

Optimization Using HLS tools

- Problem Description

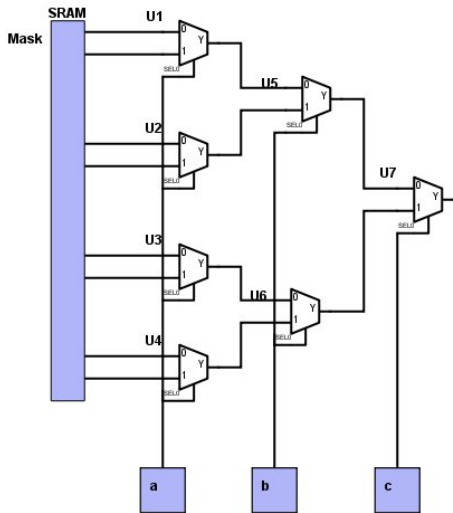
- Serial Version

- Opt1: Inner Loop Unrolling

- Pipeline

FPGAs Structure

LUT



- ▶ It is a **table** that determines what the output is for any given input
- ▶ A **state-less** interconnection of any number of gates (no feedback loops)
- ▶ Implemented *multiplexing* a combination of SRAM bits

Figure: 3 stages of 2x1 MUX

FPGAs Structure

LUT Example

$$y = (a + b) \cdot c$$

a	b	c	y
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	0
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

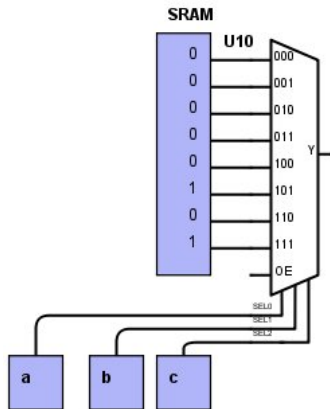


Figure: $y = (a + b) \cdot c$

FPGAs structure

BLE

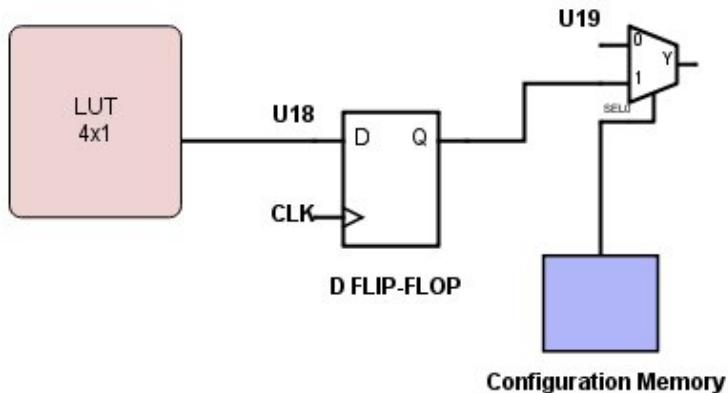


Figure: Basic Logic Element

FPGAs structure

Overview

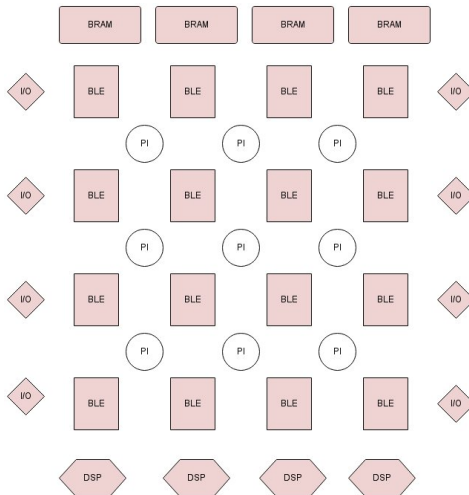


Figure: FPGAs Complete Overview

Problem Description

Matrix Multiplication

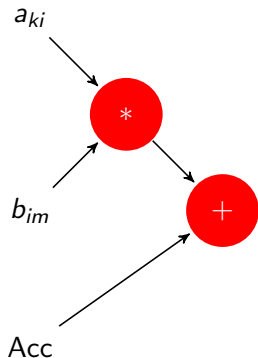
$$C = A * B$$

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$$\begin{vmatrix} c_{11} & \dots & c_{1n} \\ \vdots & c_{km} & \vdots \\ c_{n1} & \dots & c_{nn} \end{vmatrix} \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{k1} & a_{k2} & \dots & a_{kn} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{vmatrix} \begin{vmatrix} b_{11} & \dots & b_{1m} & \dots & b_{1n} \\ b_{21} & \dots & b_{2m} & \dots & b_{2n} \\ \vdots & & \vdots & & \vdots \\ b_{n1} & \dots & b_{nm} & \dots & b_{nn} \end{vmatrix}$$

No Directives

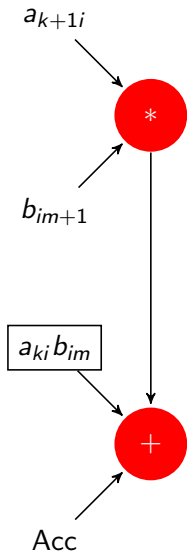
$$c_{km} = a_{k1}b_{1m} + a_{k2}b_{2m} + \cdots + a_{kn}b_{nm}$$



- ▶ $2n$ operations \forall element
- ▶ n^2 elements
- $\Rightarrow 2n^3$ operations
- ▶ 19MFLOPS on the tested platform

Opt1: Sum Mul Overlapping

In the scope of this paper it is considered that the clock cycle is adjusted to the execution depth of the multiplication.



- ▶ Complete overlapping between Multiplication and addition
- ▶ 35MFLOPS on the given machine

Pipeline

Initiation Interval is called the number of cycles between two new iterations.

In this case it is indicated by the time that the addition register is occupied.

