

FPGAs, HLS Tools & Runtime Systems

(Super)Advisors: Frederic Desprez, Francois Broquedis, Olivier Muller

Georgios Christodoulis

CORSE-LIG

gchristodoulis@gmail.com

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FPGA

Description

A *Field Programmable Gate Array* is an integrated circuit designed to be configured by a customer or a designer after manufacturing – hence "Field-programmable".

FPGAs are semiconductor devices that are based around a matrix of configurable logic blocks (BLEs) connected via programmable interconnects.

FPGAs Structure

LUT Example

$$y = (a + b) \cdot c$$

a	b	c	y
0	0	0	0
0	0	1	0
0	1	0	0
0	1	1	0
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

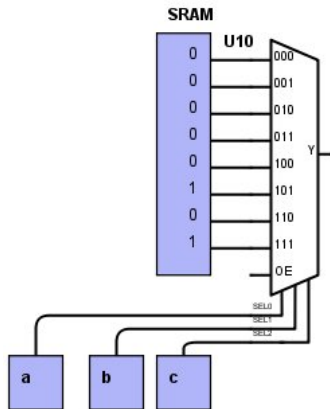


Figure: $y = (a + b) \cdot c$

FPGAs structure

BLE

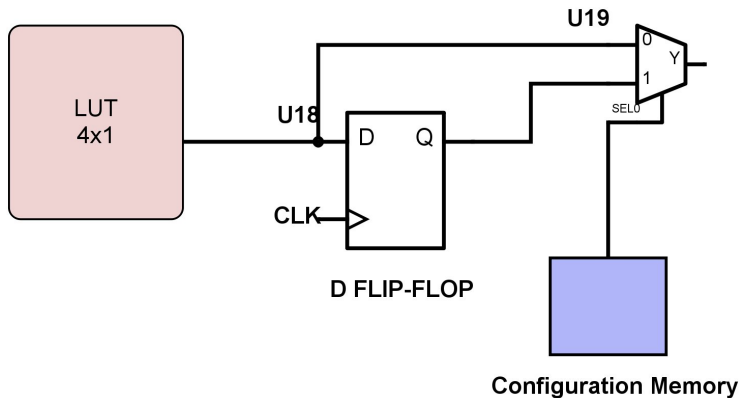


Figure: Basic Logic Element

FPGAs structure

Overview

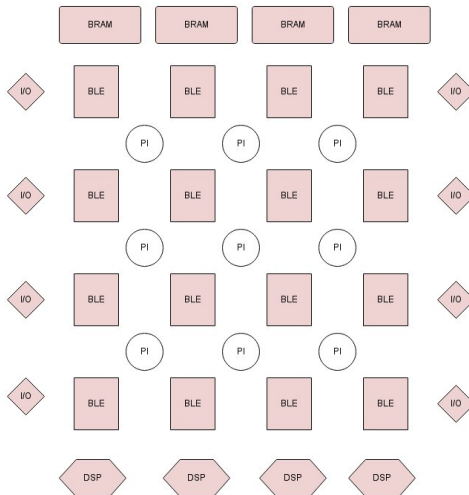


Figure: FPGAs Complete Overview

De-Motivation

```
LIBRARY ieee;  
USE ieee.std_logic_1164.ALL;
```

```
ENTITY lab4b_tb IS  
END lab4b_tb;
```

```
ARCHITECTURE behavior OF lab4b_tb IS
```

```
    signal Clk:  
std_logic    := '0';
```

```
— no reset
```

```
    signal Start:  
std_logic    := '0';
```

```
— no reset
```

```
    signal Din:  
INTEGER      := 0;
```

```
— no reset
```

```
    signal Done : std_logic;  
    signal Dout : INTEGER;
```

```
    constant Clk_period : time := 10 ns;
```

```
BEGIN
```

```
LIBRARY ieee;  
USE ieee.std_logic_1164.ALL;  
  
entity DCT_beh is  
    port (  
        Clk :  
in std_logic;  
        Start :  
in std_logic;  
        Din :  
in INTEGER;  
        Done :  
out std_logic;  
        Dout :  
out INTEGER  
    );  
  
end DCT_beh;  
  
architecture behavioral of DCT_beh is  
    type RF is array ( 0 to 7, 0 to 7 ) of INTEGER;  
    signal OutBlock:  
RF;  
    signal InBlock:  
RF;  
    signal internal_Done:  
std_logic := '0';  
    — no reset  
    signal Input_Ready:  
std_logic := '0';  
    — no reset  
    signal done_detected:  
std_logic := '0';  
    — no reset  
    signal input_rdy_detected:  
std_logic := '0';  
    — no reset  
    signal last_out:  
std_logic := '0';  
    — no reset  
  
begin  
    INPUT_DATA:  
    process  
    begin  
        wait until Start = '1';  
        —Read Input Data  
        for i in 0 to 7 loop  
            for j in 0 to 7 loop  
                wait until Clk = '1' and clk'event;  
                InBlock(i,j) <= Din;  
                if i=7 and j=7 then  
                    Input_Ready <= '1', '0' after 11 ns;  
                end if;  
            end loop;  
        end loop;  
    end process;  
  
    WAIT_FOR_InBlock:  
    process  
    begin  
        wait until clk = '1' and clk'event;
```


Problem Description

Matrix Multiplication

$$C = A * B$$

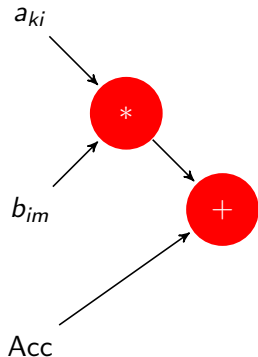
$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$$\begin{vmatrix} c_{11} & \dots & c_{1n} \\ \vdots & c_{km} & \vdots \\ c_{n1} & \dots & c_{nn} \end{vmatrix} \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{k1} & a_{k2} & \dots & a_{kn} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{vmatrix} \begin{vmatrix} b_{11} & \dots & b_{1m} & \dots & b_{1n} \\ b_{21} & \dots & b_{2m} & \dots & b_{2n} \\ \vdots & & \vdots & & \vdots \\ b_{n1} & \dots & b_{nm} & \dots & b_{nn} \end{vmatrix}$$

No Directives

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$$c_{km} = a_{k1}b_{1m} + a_{k2}b_{2m} + \cdots + a_{kn}b_{nm}$$

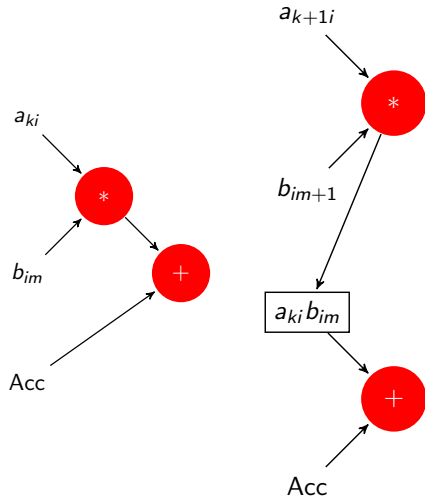


- ▶ $2n$ operations \forall element
 - ▶ n^2 elements
- $\Rightarrow 2n^3$ operations

Inner Loop Unrolling

Opt1: Sum Mul Overlapping

Our reference time interval is defined by the slowest operation which is the multiplication.

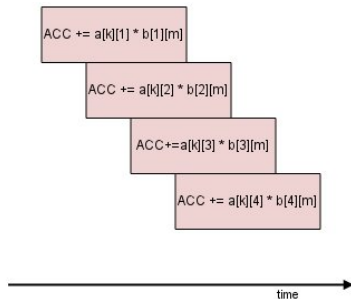
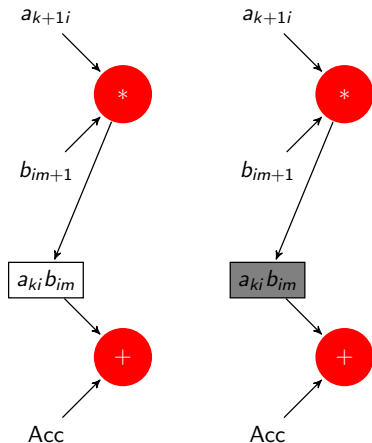


- Complete overlapping between Multiplication and addition

Pipeline

Initiation Interval is called the number of cycles between two new iterations.

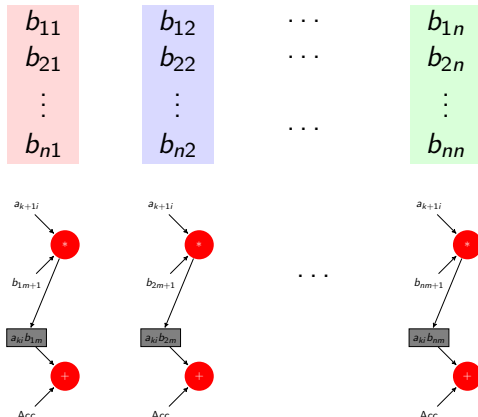
In this case it is indicated by the time that the addition register is occupied.



J-loop unrolling

$a_{k1} \quad a_{k2} \quad \dots \quad a_{kn}$

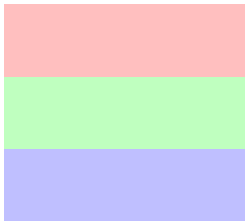
- ▶ Extra Hardware
- ▶ Real Parallelism (Superscalar CPU architectures)
- ▶ Expected scaling: $\times n$
- ▶ Actual scaling: $\times 2$



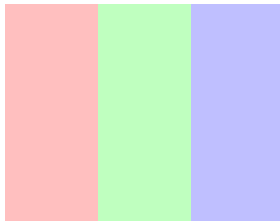
Memory Bounds: Dual Channeled memory \implies only 2 concurrent operations.

Row / Col Partitioning

A



B



- Distributing arrays into different BRAMs increases scaling proportionally to hardware addition

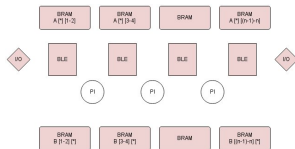


Figure: Distribute the array into multiple BRAMS

Maximize Resource Use

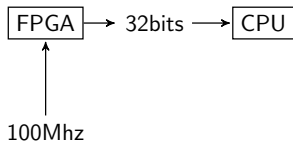
Maximize DSP use

- ▶ Since we have succeeded $II=1$ we increase n in order to maximize DSP usage
- ▶ In our case $n=32 \implies 72\%$ usage while $n=43 \implies 98\%$ usage

Maximize BRAM use

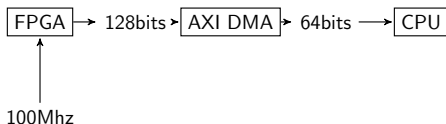
- ▶ Increasing n increases BRAM usage too

Improve I/O



- ▶ $100Mhz \times 32bits = 400MB/s$
- ▶ So the default communication speed is 400MB/s

Bottomline: We increased our communication bandwidth from 400MB/s to 1.2GB/s



- ▶ $100Mhz \times 128bits = 1.6GB/s$
- ▶ AXI DMA's limit is 1.2GB/s at 64bits channel width

Block Computation

$$c_{ij} = \sum_{k=0}^{m-1} A_{ik} B_{kj}$$

CPU FPGA

- ▶ Multiplications on FPGA
- ▶ Additions on CPU

This optimization is suitable much larger matrixes than the previous, more significantly when n exceeds 2000 entries.

Optimizations Review

Naive Implementation 0.019GFLOPS

- ▶ Inner Loop Unrolling 0.035 GFLOPS
- ▶ Pipeline Inner Loop 0.044 GFLOPS
- ▶ Unrol Loop J 0.188 GFLOPS
- ▶ Row/Col Partitioning 0.33 GFLOPS
- ▶ Maximize DSPs 1.247 GFLOPS
- ▶ Maximize Resource Usage 2.886 GFLOPS
- ▶ Improve I/O 3.573 GFLOPS
- ▶ Block Computation 4.107 GFLOPS
- ▶ Optimize Communication 4.695 GFLOPS

Thank You!