

# Symbolic inductive bias for visually grounded learning of spoken language

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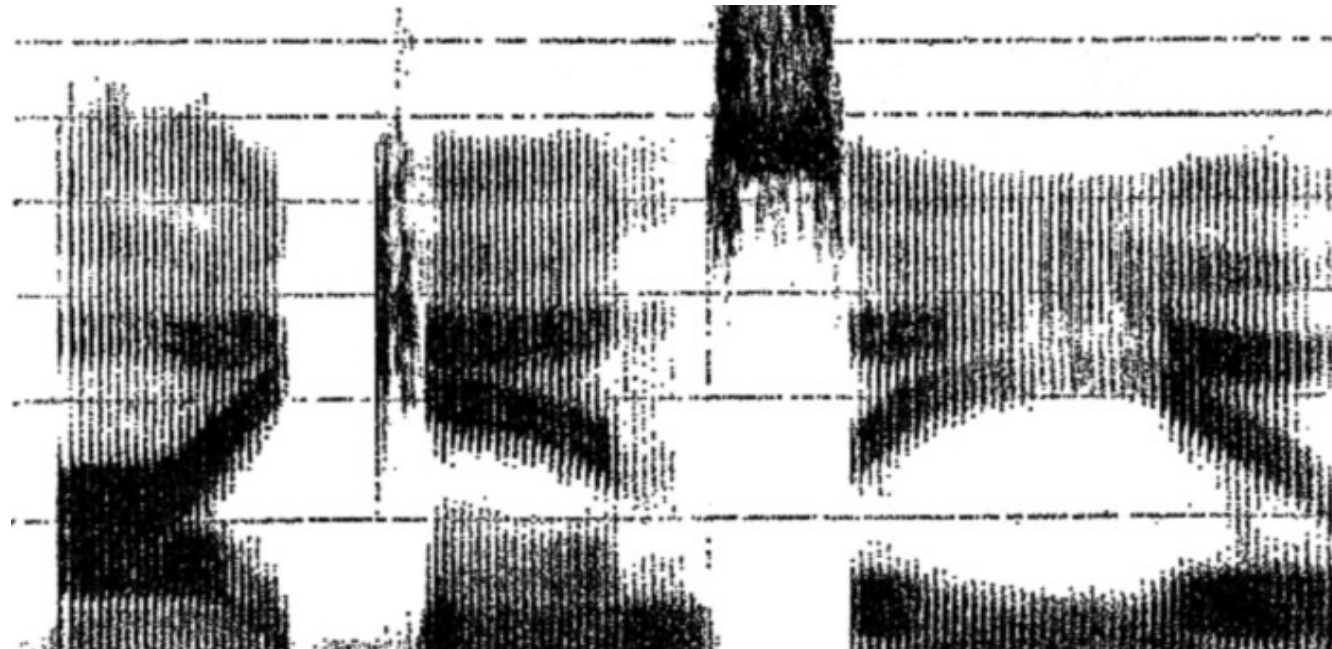


# Automatic Speech Recognition

A major commercial success story in Language Technology

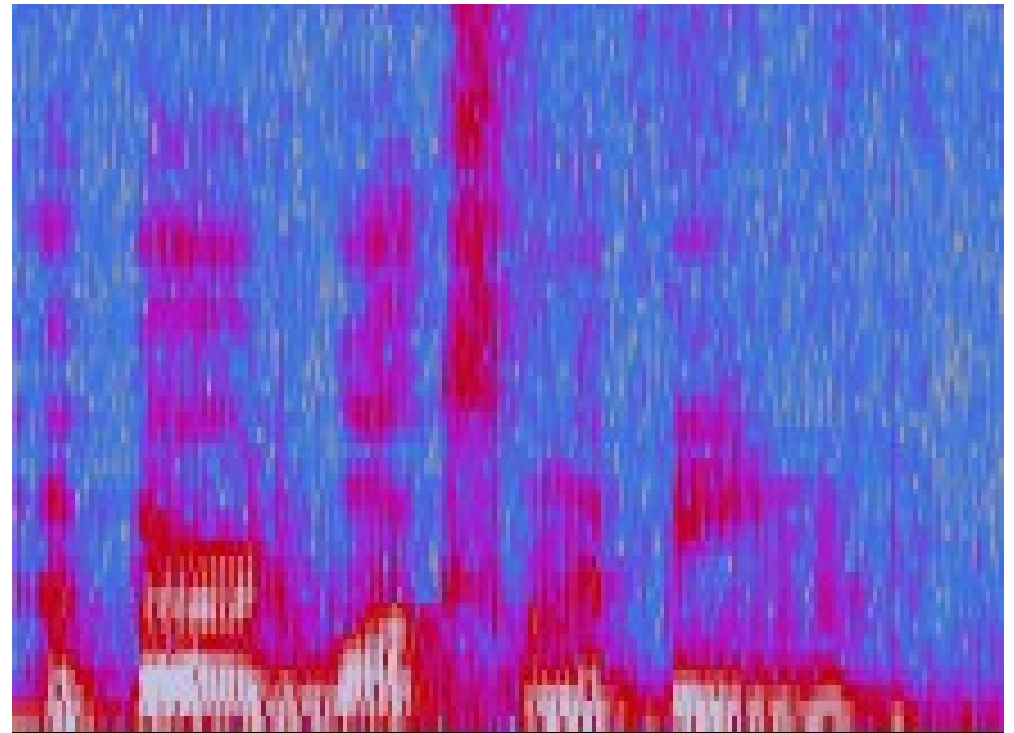


# Very strong supervision



I can see you

# Weaker supervision: Visually grounded spoken language



# Data

- Flickr8K Audio Caption Corpus  
(Harwath and Glass 2016)
  - Written captions read by crowd workers
  - 8K images, five audio captions each

# Existing models

- Convolutional neural network applied to a spectrogram
  - Harwath and Glass 2016 (NIPS)
- Multi-layer Highway recurrent network applied to Mel-frequency Cepstral Coefficient features
  - Chrupała et al 2017 (ACL)

# Learning language via visual grounding

- Closer to human language learning
- May be easier to obtain data
  - Low-resource languages
  - Languages with no standard writing system
    - Cantonese, Hokkien
- **BUT: difficult, less constrained task**

# Inductive bias

The **inductive bias** of a learning algorithm is the **set of assumptions** that the learner uses to predict outputs given inputs that it has **not encountered**.

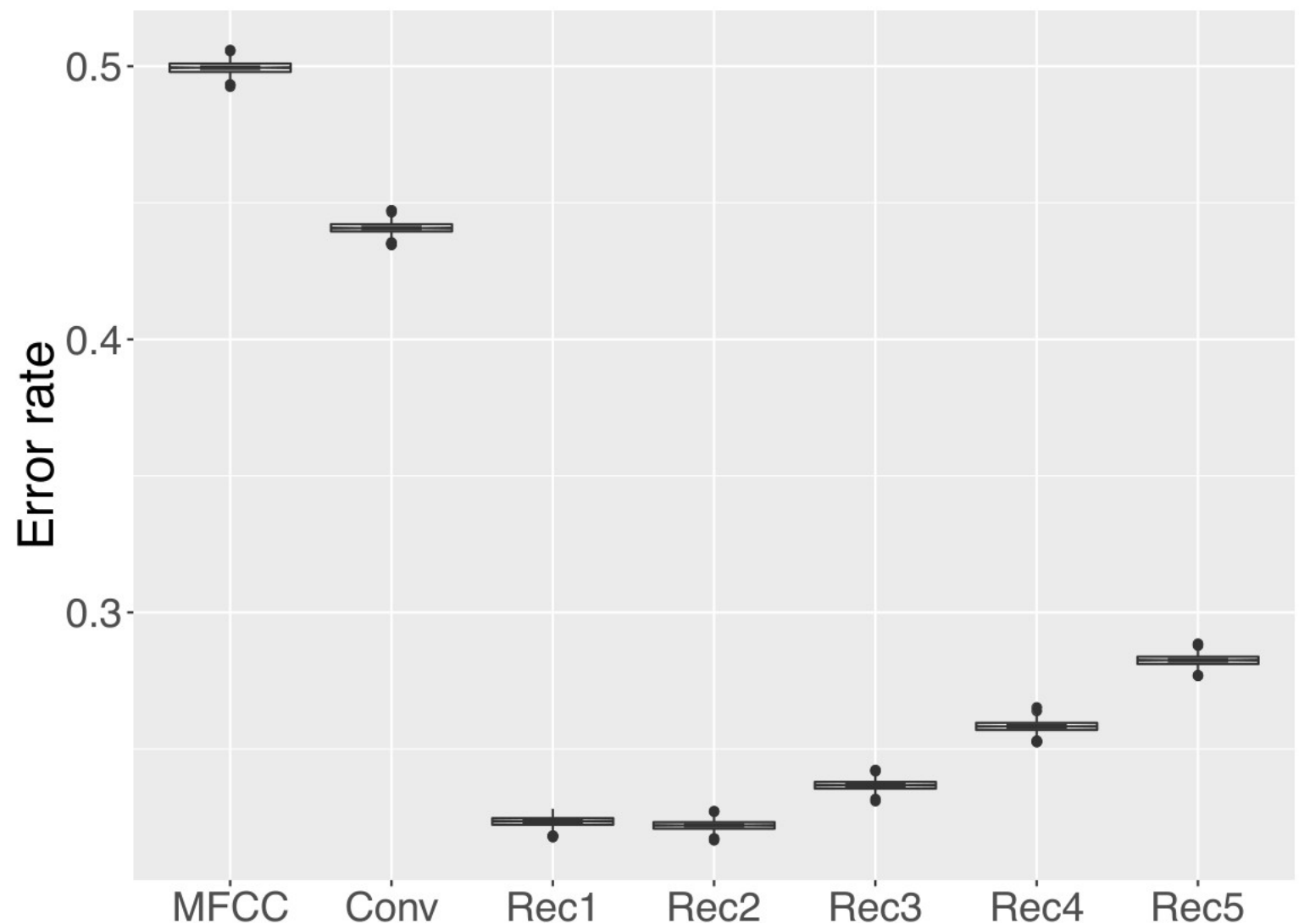


# (Recurrent) Neural Networks

- RNN: autoregressive neural nets.
- Do **not** assume any **linguistically-motivated** structure.
- They may **discover** the existence of discrete phonemes in speech, **despite** this lack of bias.

# Learned representations encode phonemes

Alishahi et al 2017  
(CoNLL)

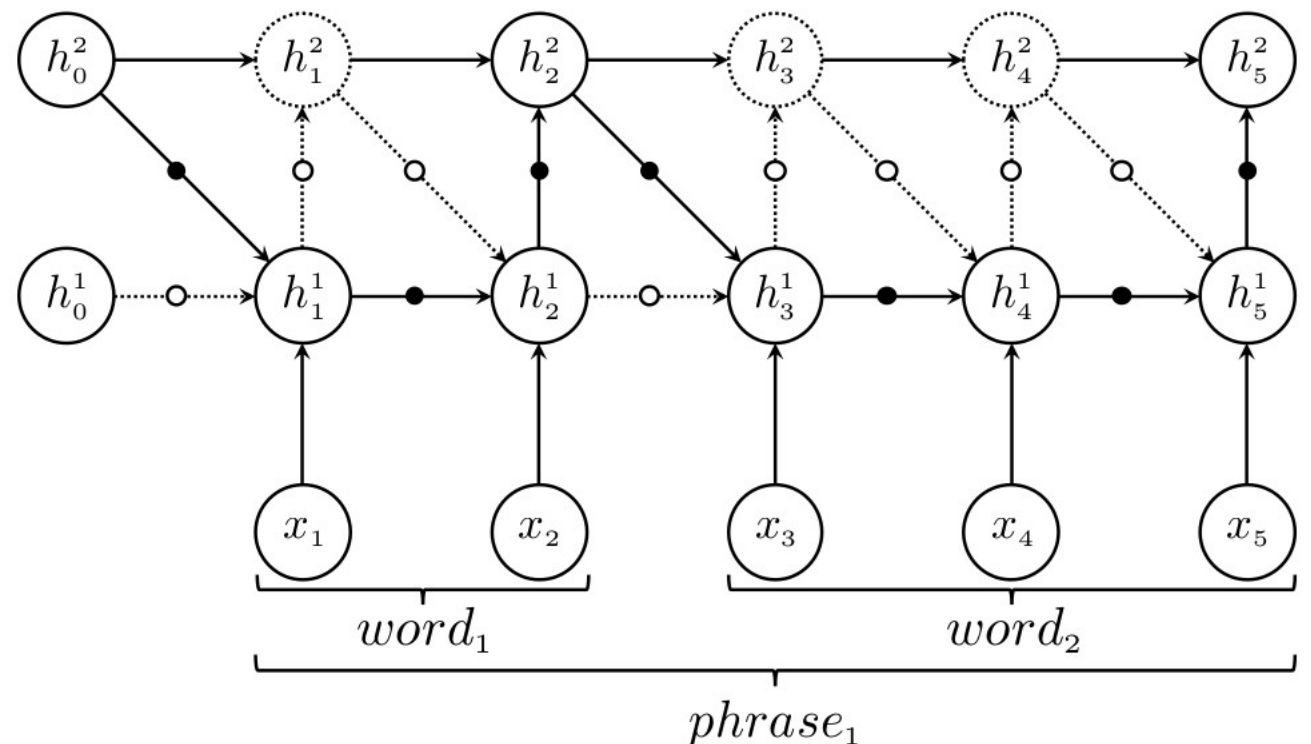


# Inject inductive bias via Multi-task learning

- Human learners – biases encoded in the genome via evolution
- ML – biases encoded via
  - Architectural design
  - Multi-task learning

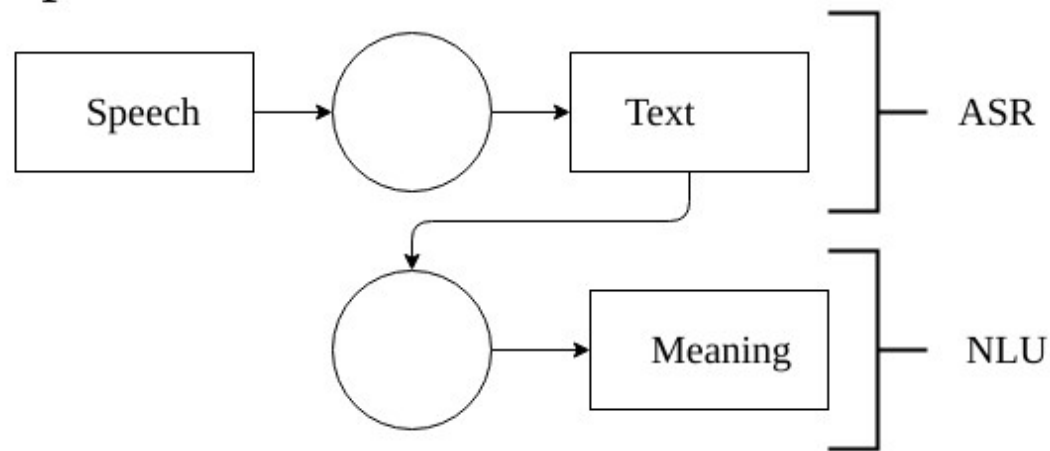
# Inductive bias via architecture

- Bias encoded as hard constraint on architecture.
- Example: Chung et al 2017 (ICLR)
- **But hard to get to work**
  - Kádár et al 2018 (COLING)

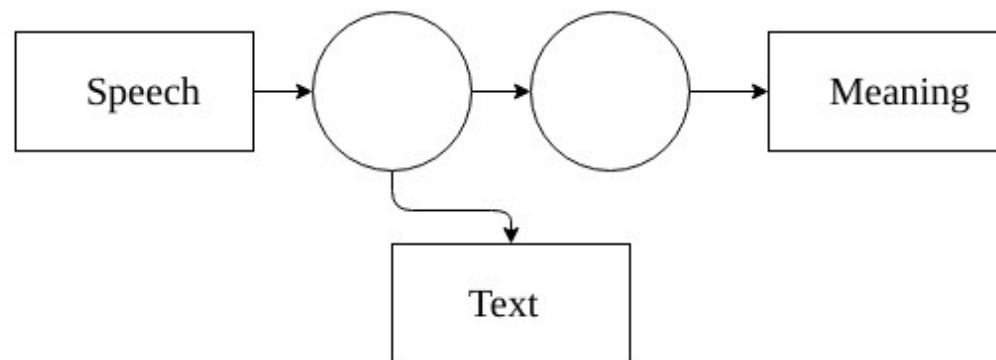


# Pipeline vs MTL

Pipeline



MTL



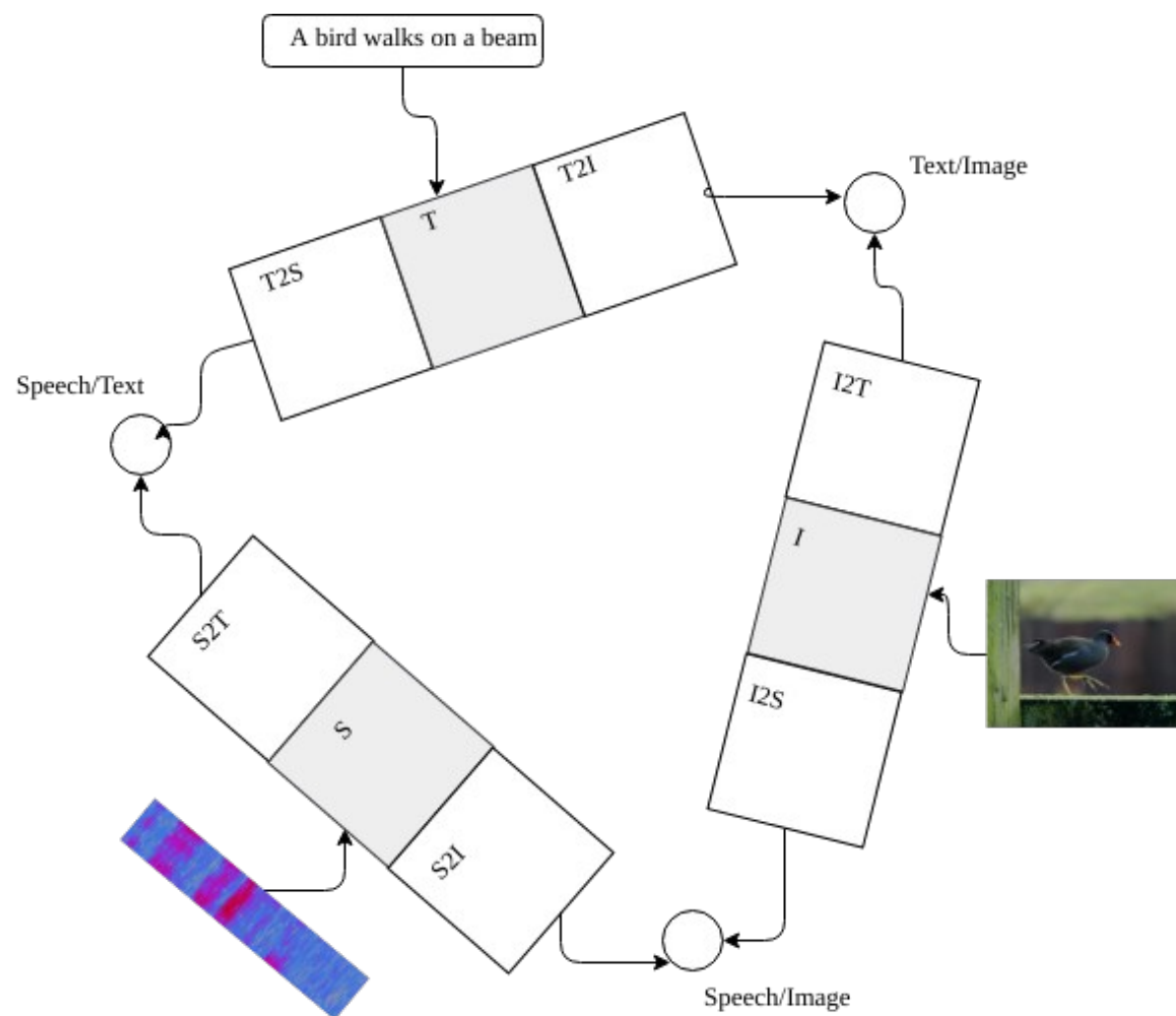
## MTL

- Text only used for training (not as input)
- Representations able to encode text, but can encode other info
- No hard constraint on representations, just a nudge.

# Questions

- Does MTL help?
  - Because of inductive bias or extra data?
- Which parameters should be shared?
- Which should be which task-specific?

# Three-task model

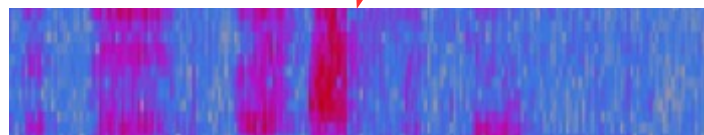
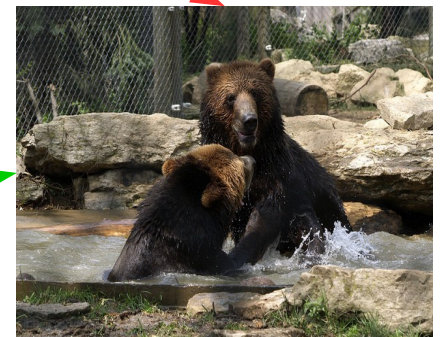
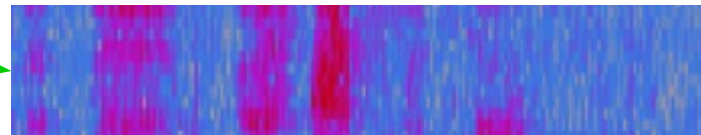


- Tasks
  - **Speech/Image**
  - Speech/Text
  - Text/Image
- Tasks share some parameters

# Project two modalities to joint space



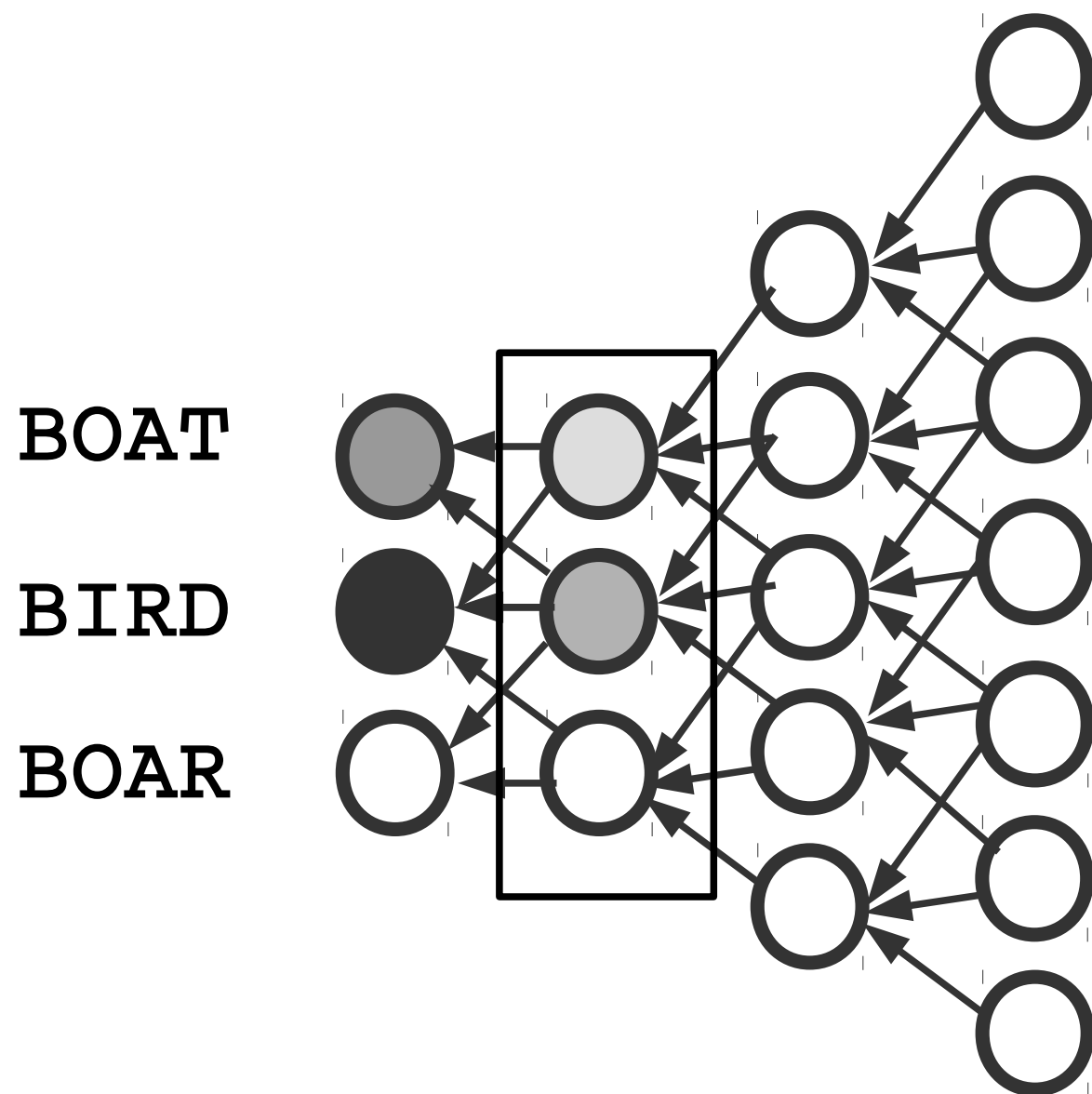
a bird walks on a beam



bears play in water

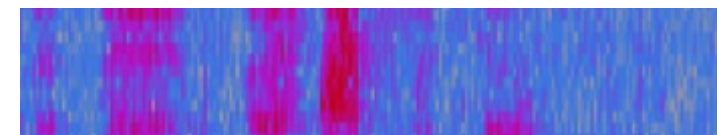
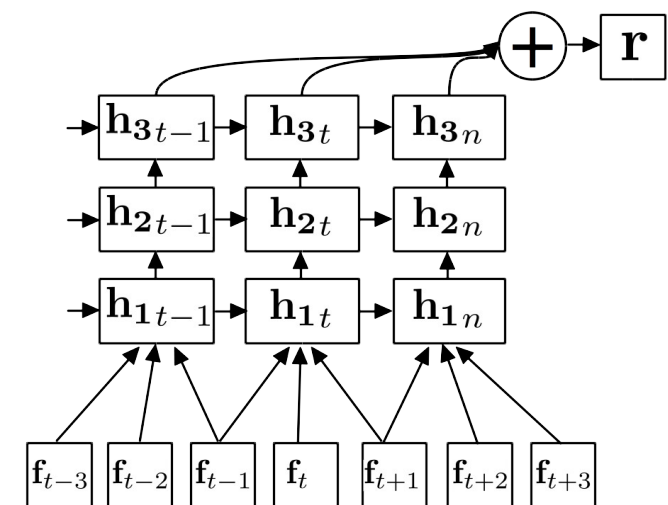
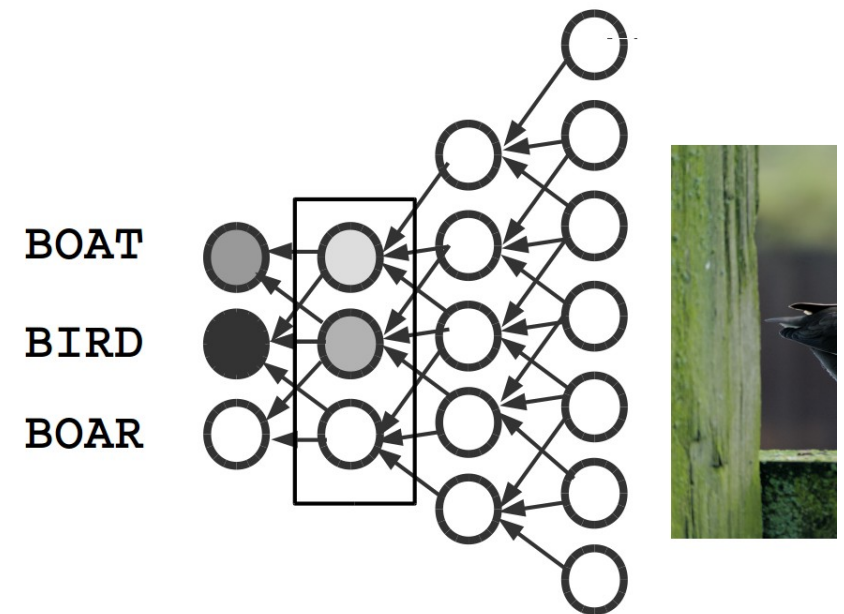


# Image encoder



# Encoders

- Image
  - Fixed CNN
  - Linear projection
- Speech
  - CNN layer
  - GRU RNN layers



# Text encoder

- Text
  - Embedding layer (symbol lookup)
  - GRU RNN layers
- Text = sequence of characters

# Evaluation metrics

- Image retrieval
  - Encode an image into joint speech/image space
  - Rank images by distance
  - Check how good the ranking is
    - Recall@K (higher better)
    - Median rank of correct image (lower better)
- Speaker identity decodability (lower better)
  - Logistic regression model on encoded speech

# Experimental conditions

- Vary number of tasks (1-3)
- Vary which layers are shared
- Vary whether tasks are trained on same or different data
  - Flickr8K – speech, text, image
  - Libri – speech, text

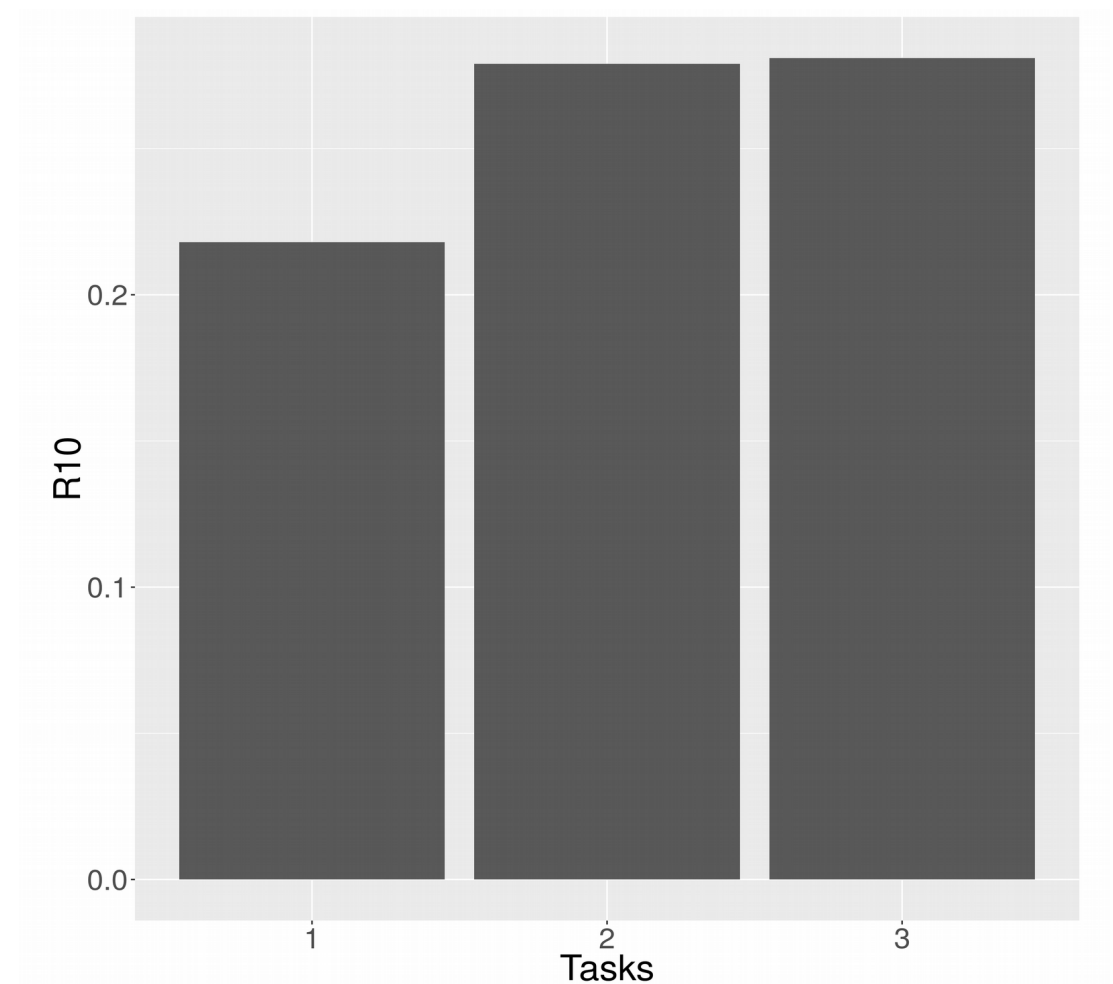
# Results on validation data

Data	Tasks	S	T	S2I	S2T	T2S	T2I	R@10	Medr	Spkr
NA	1	2	.	2	.	.	.	0.218	63.8	0.297
Joint	2	2	1	2	0	0	.	0.279	42.3	0.101
Disjoint	2	2	1	2	0	0	.	0.280	41.3	0.177
Joint	3	2	1	2	0	0	1	<b>0.281</b>	<b>39.7</b>	<b>0.085</b>
Joint	3	4	1	0	0	0	0	0.248	46.3	0.211
Disjoint	3	2	1	2	0	0	1	<b>0.280</b>	<b>41.7</b>	<b>0.177</b>
Disjoint	3	4	1	0	0	0	0	0.223	59.3	0.282

# 1-task vs 2-task vs 3-task

Speech/Text helps.  
Quite a bit.

Text/Image doesn't.

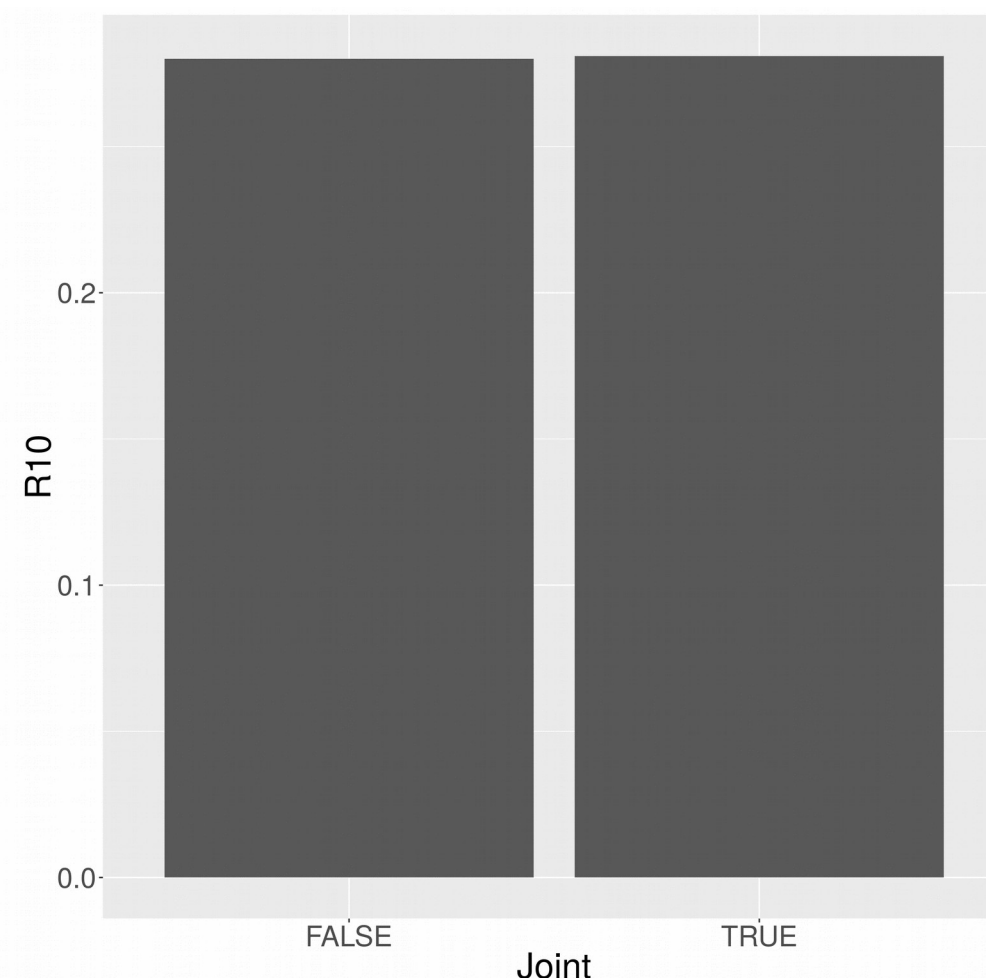


(joint)

# Joint vs disjoint

Same/different data makes no difference →

MTL helps because of inductive bias

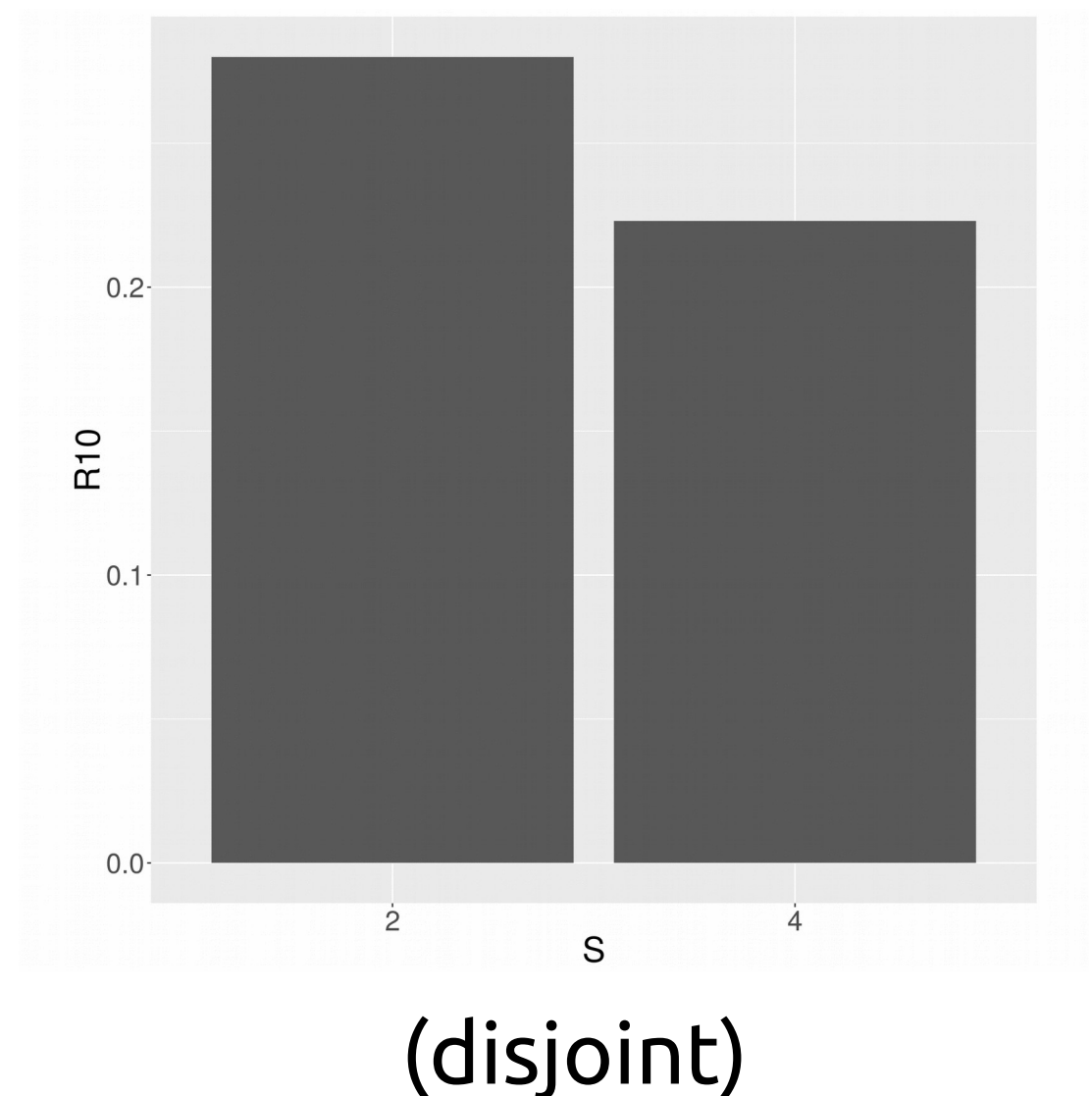


(3-task)



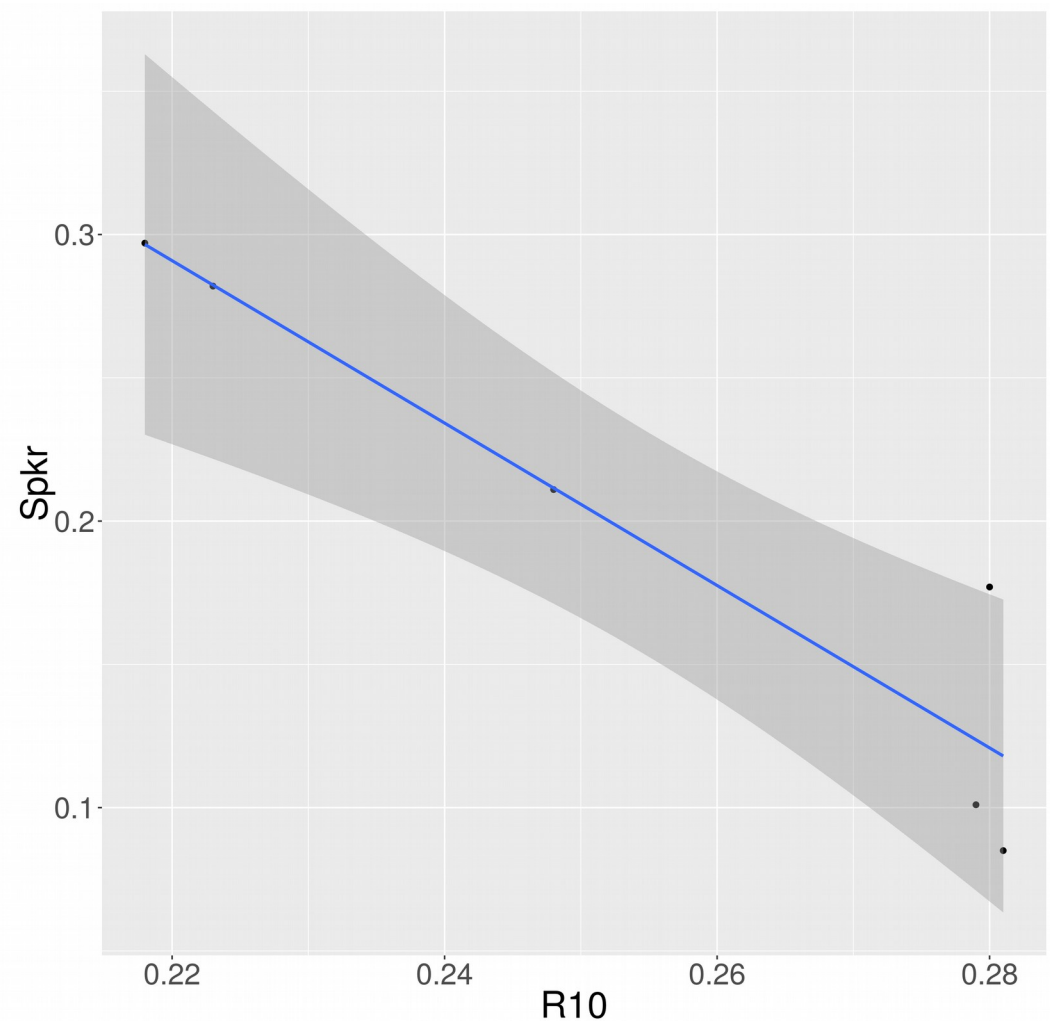
# Full vs partial sharing

Sharing 2 bottom layers of speech encoder works better than sharing all 4 layers.



# Speaker decodability

Better models:  
more speaker-  
invariant.



# Compared to previous work

Compared to previous single task approaches

Data	Tasks	S	T	S2I	S2T	T2S	T2I	R@10	Medr	Spkr
NA	1	Harwath and Glass 2015						0.179	-	-
NA	1	Chrupała et al 2017						0.253	48	-
NA	1	2	.	2	.	.	.	0.244	51	0.312
Joint	3	2	1	2	0	0	1	0.296	34	0.096

(test set)

# Current and future work

- Speech transcription in addition to current Speech/Text task
- Compare against pipeline architecture in a controlled fashion
- Evaluate with varying data size for auxiliary task