



Solver

OR-Tools

$\text{tsp}(\{c_1, \dots, c_n\}, \text{Path}, \text{Cost})$

$\text{Path}=[c, c', \dots, c], \dots, \text{Cost}=n$

**backtracking**

$\text{Path}=[d, d', \dots, d], \dots, \text{Cost}=n'$

**backtracking**

$\text{Path}=[e, e', \dots, e], \dots, \text{Cost}=n''$