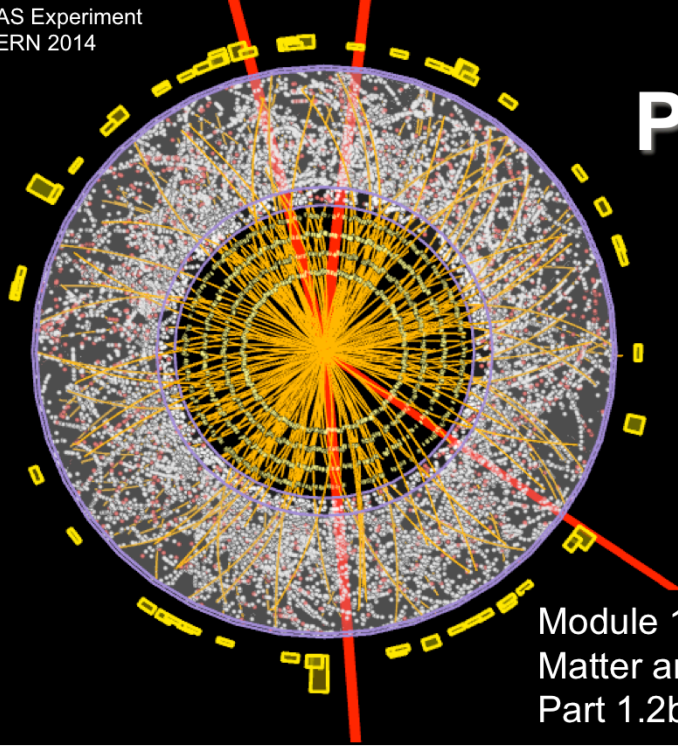


ATLAS Experiment
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Particle Physics An Introduction

Module 1:
Matter and forces, measuring and counting
Part 1.2b: Special relativity and four-vectors

For those who have forgotten about special relativity and the notation of four-vectors, we will quickly remind you about these essential tools.

A ray of light connects two events, $x_1^\mu = (ct_1, \vec{x}_1)$ et $x_2^\mu = (ct_2, \vec{x}_2)$:

$$\left((x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2\right)^{\frac{1}{2}} = c(t_1 - t_2)$$

Consequence: the length of a four-vector is independent of the inertial frame:

$$s = c^2 t^2 - x^2 - y^2 - z^2 = \text{invariant}$$

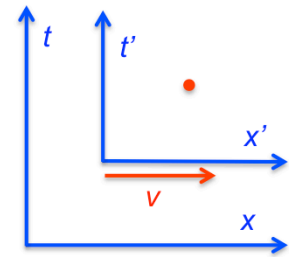
Lorentz transformations = rotations and translations in space-time which leave s invariant.

- This course deals with phenomena at high energy, i.e. at velocities which require a relativistic treatment. The fundamental principles of special relativity (based on experimental findings) are:
 - The speed of light c is the same constant in every inertial frame. This means that the Galilean way to add velocities is not valid at high speeds.
 - This way the speed of light is a maximum velocity, which cannot be exceeded in any reference frame.
- Motion is described in a four-dimensional vector space, called space-time. An event in space-time, localized by Cartesian coordinates (ct, x) is described by a four-vector x^μ .
- The metric of space-time is defined by the speed of light c , an invariant constant in every inertial frame.
- Suppose that a light ray connects two events (ct_1, x_1) and (ct_2, x_2) .
- The distance between these two points in space is always proportional to the propagation time $(t_1 - t_2)$ of the light.
- Since the proportionality constant, the speed of light, is the same in every inertial frame, it follows that the norm s of a four-vector is also constant.
- Lorentz transformations describe the rotations and translations of space-time which are compatible with these principles.

Example:

- Frame (ct', \vec{x}') moves with $\vec{v} = \beta c \hat{x}$ in direction \hat{x} with respect to the 'laboratory' (ct, \vec{x})
- Relativistic factor $\gamma = 1 / \sqrt{1 - \beta^2}$
- Coordinates in the moving frame:

$$\begin{aligned} t' &= \gamma \left(t - \frac{\beta}{c} x \right) \\ x' &= \gamma (x - \beta ct) \\ y' &= y \\ z' &= z \end{aligned}$$



Let us specify Lorentz transformations by a simple example:

- Let (ct, x) and (ct', x') be two reference frames, the first one at rest in the laboratory, the second one moving relative to the first one at constant velocity v in the direction of the x axis, which is parallel in the two frames.
- Which are the coordinates of one point (ct', x') in the moving frame expressed in the coordinates of the laboratory frame? The answer is given by the Lorentz transformation, which relates t' and x' to t and x by the relative velocity $\beta = v/c$ and the relativistic factor γ .
- The transformation corresponds to a rotation in space-time which leaves the norm of four-vectors like x_μ invariant.
- The transformation involves only the time coordinate t and the spatial coordinate x along the direction of relative motion. The coordinates orthogonal to the relative motion, y and z , are left untouched.
- In the nonrelativistic limit, $v \ll c$, i.e. $\beta \ll 1$ and $\gamma \rightarrow 1$, the Lorentz transformations reproduce the Galilei transformations, where $t = t'$ and $x' = x - vt$.

- Contravariant four-vectors transform like space-time x^μ :

$$x^\mu = (x^0, x^1, x^2, x^3) = (ct, x, y, z)$$

- Example: energy-momentum p_μ :

$$p^\mu = (p^0, p^1, p^2, p^3) = \left(\frac{E}{c}, p_x, p_y, p_z\right)$$

- Contra- and covariant four-vectors related by metric tensor:

$$x_\mu = (x_0, x_1, x_2, x_3) = (ct, -x, -y, -z) \quad ; \quad p_\mu = (p_0, p_1, p_2, p_3) = \left(\frac{E}{c}, -p_x, -p_y, -p_z\right)$$

$$x_\mu = g_{\mu\nu} x^\nu \quad ; \quad g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

- Four-vector notation unites time and space coordinates in a single vector.
- Four-vectors transforming like the four-vector x^μ of space-time under Lorentz transformations are called contravariant.
- An important example is the contravariant energy-momentum vector p^μ .
- The norm of a four-vector is defined via the scalar product between a contravariant four-vector and its covariant form. The two are related by the metric tensor $g_{\mu\nu}$ as shown.
- All scalar products between four-vectors are invariant under Lorentz transformation.

- **Scalar product** between four-vectors:

$$x_\mu x^\mu = c^2 t^2 - x^2 - y^2 - z^2 = c^2 t^2 - \vec{x}^2$$

$$p_\mu p^\mu = \frac{E^2}{c^2} - p_x^2 - p_y^2 - p_z^2 = E^2/c^2 - \vec{p}^2 = m^2 c^2$$

$$p_\mu x^\mu = Et - p_x x - p_y y - p_z z = Et - \vec{p} \cdot \vec{x}$$

- **Scalars** under Lorentz transformations, invariant when changing between inertial frames

- System of “**natural**” units:

$$\begin{aligned} x^\mu &= (x^0, x^1, x^2, x^3) = (t, x, y, z) & ; & & p^\mu &= (p^0, p^1, p^2, p^3) = (E, p_x, p_y, p_z) \\ x_\mu x^\mu &= t^2 - x^2 - y^2 - z^2 = t^2 - \vec{x}^2 & ; & & p_\mu p^\mu &= E^2 - p_x^2 - p_y^2 - p_z^2 = E^2 - \vec{p}^2 = m^2 \end{aligned}$$

- More generally, the scalar product is thus defined as the product between a co- and a contravariant four-vector. When the same Greek index shows up in the two, implicit summation over this index from 0 to 3 is assumed.
- The first example repeats the norm (squared) of the space-time four-vector. The second example shows the norm of the energy-momentum four-vector, which is the square of the invariant mass. The third example is the scalar product between the space-time and the energy-momentum four-vector. This product shows up in the wave function of particles.
- The scalar products between four-vectors are all indeed scalars under Lorentz transformation, invariant when one changes from one inertial frame to another.
- The notation simplifies tremendously when one adopts the system of natural units, since the ubiquitous speed of light disappears.

- Four-vector of electromagnetic current density:

$$j^\mu = (\rho, \vec{j})$$

- ρ : charge density
- \vec{j} : current density

- Four-vector of electromagnetic potential:

$$A^\mu = (V, \vec{A})$$

- V : scalar electric potential
- \vec{A} : magnetic vector potential

Two other important examples of four-vectors are:

- The four-vector of the electromagnetic current density j_μ , which has the charge density ρ as the time-like component, and the vector of current density j as the space-like component.
- The four-vector of the electromagnetic potential A_μ , which has the electric potential V as the time-like component and the magnetic vector potential A as the space-like component.



As an example we calculate here the total available energy in the collision of a 200 GeV electron with a proton at rest in the laboratory frame. And we confront the result with a collision in the center-of-mass frame, where a 200 GeV electron collides with a 200 GeV proton.