

The background of the slide is a blurred image of a white robot head, likely a Pepper robot, with its ear visible on the left side.

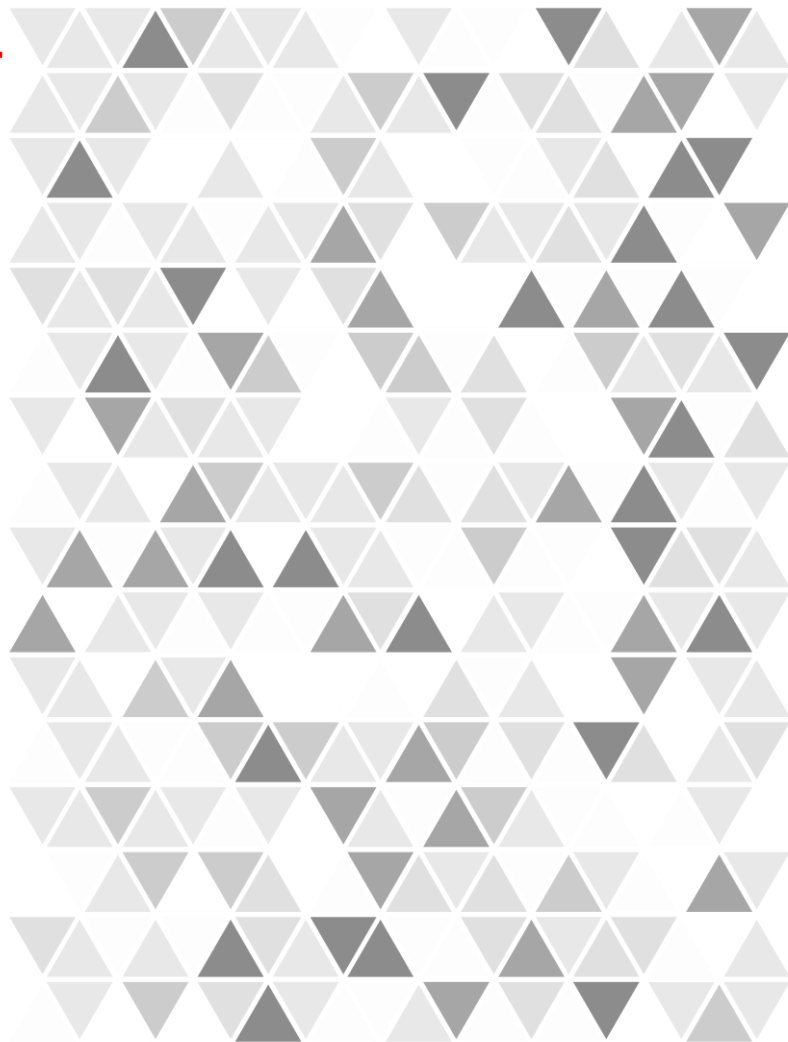
Design of an Externalized Music Player

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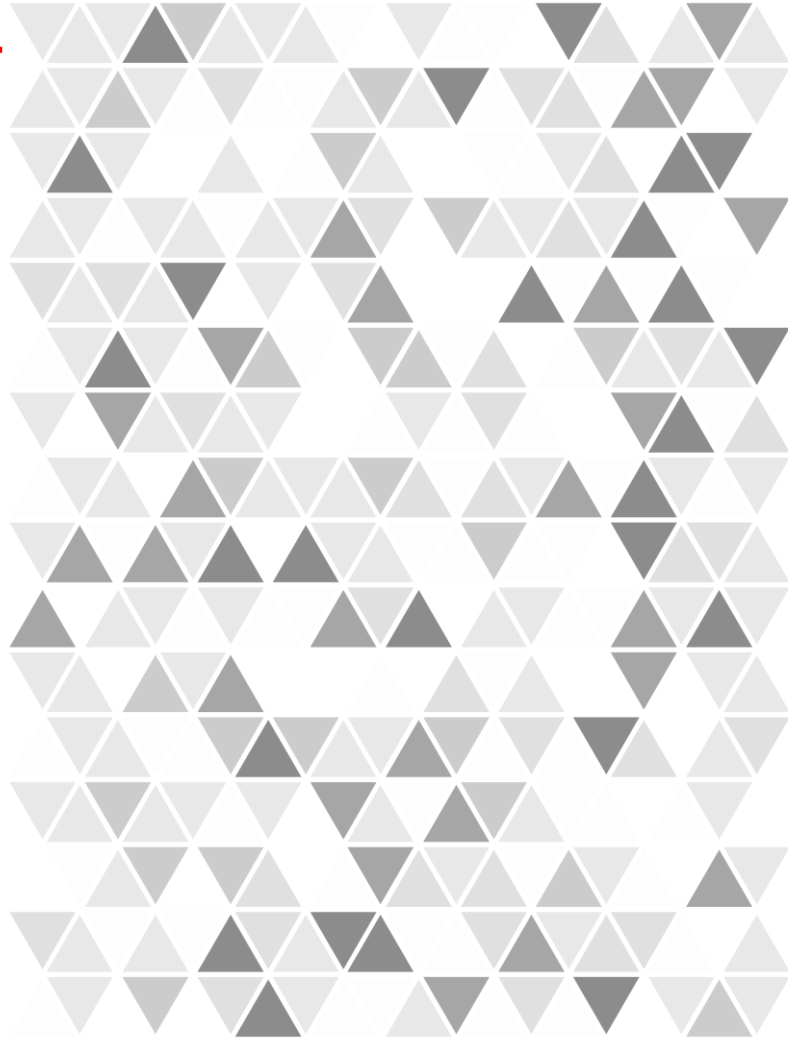
Responsible:
Prof. Dr. Hervé **LISSEK**

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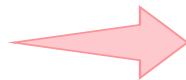
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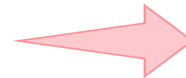
1. Introduction

Introduction: Sound Externalization

- Sounds from the real-world are perceived **externalized** and the source can be **localized**
- Sounds from headphones are perceived **inside-the-head**
- Headphones **sound externalization** recreates the perception of an externalized sound source
- Applications in hearing aids technologies, augmented and virtual reality, ...



Localization



Lateralization

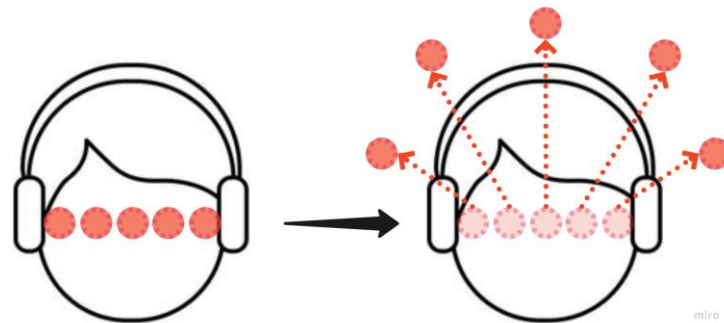


Figure 1: Concept of Sound Externalization

Introduction: Scope of the Project

- Sound reproduction systems over headphones may lead to **mental fatigue** which can be reduced with externalized sounds.
- The scope of the project is to design of a **music player capable of externalizing audio** tracks according to a specific environment
 - Based on **convolutional artificial reverberation**
 - Adjustable in real-time according to an **head tracking system**

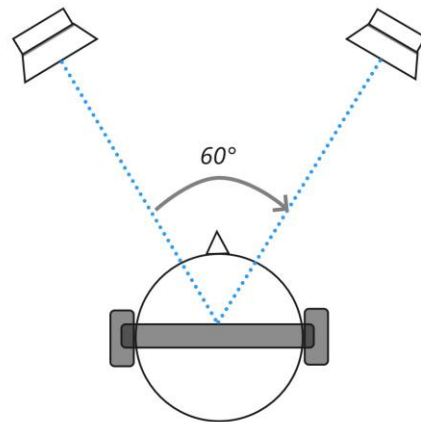


Figure 2: Simulated loudspeaker setup

- Artificial Reverberation Algorithms simulate the **psychoacoustic impact** of reverberation impulse response features
 - Input 'dry' **signal convolved with BRIR**
 - For real-time application, **partitioned convolution** is the most valid alternative to regular convolution
 - Partitioned convolutions guarantee a latency as short as the partition size (**ex: 64 samples at 44100 Hz \rightarrow 1.45 ms**)

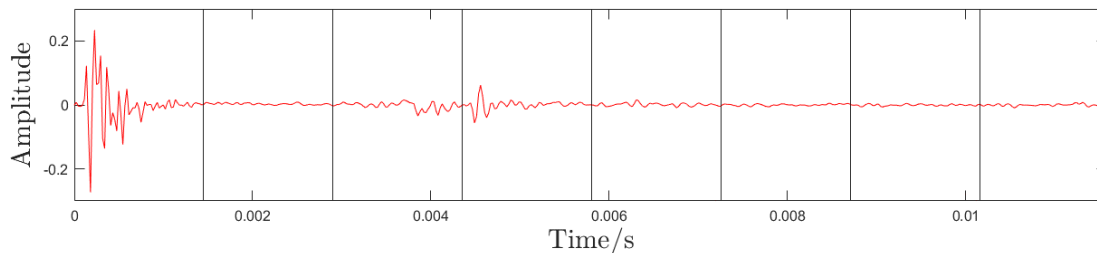
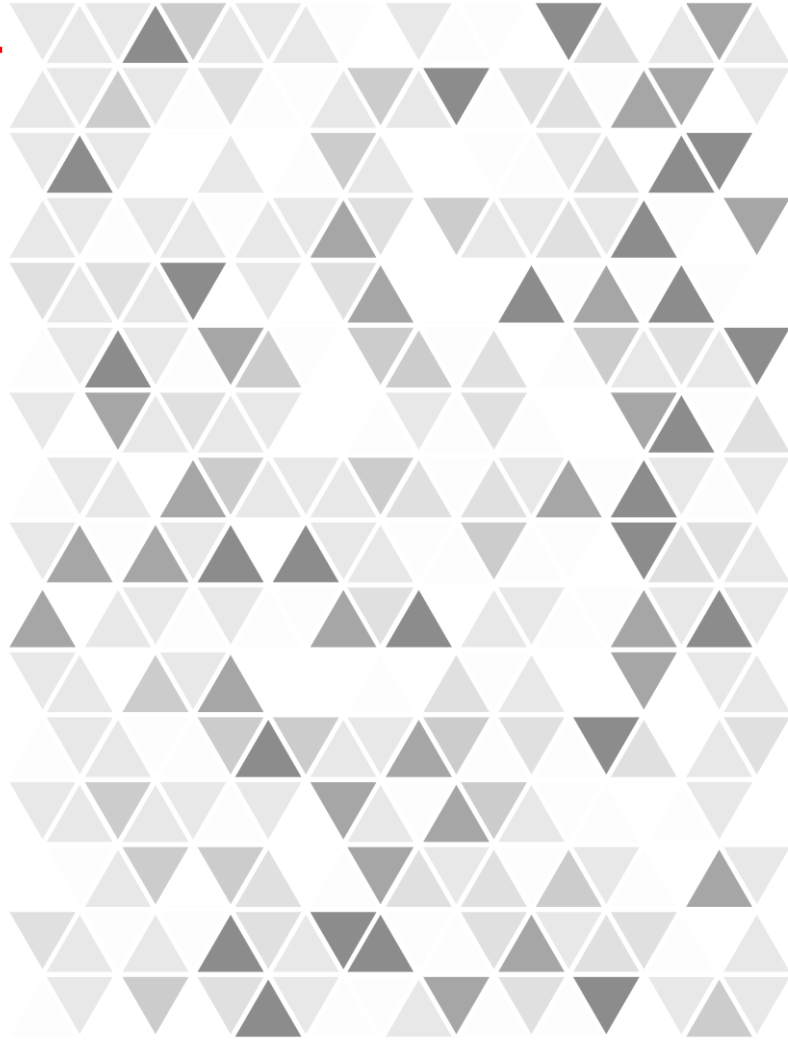
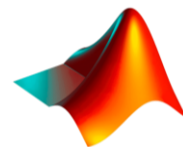


Figure 3: Impulse Response Partitioning



2. Method

- Implementation on **Pure Data**
- Auxiliary scripts on **MATLAB** and **C** language
- BRIRs recorded at EPFL listening room using **KEMAR** manikin by **G.R.A.S.**
- HRTFs from the compact dataset made available by **MIT Media Lab**
- **IMU** sensor produced by **x-io Technologies**



MATLAB®



G.R.A.S. Sound
& Vibration



- **Open source** visual programming environment for interactive **computer music** and multimedia works
- Equipped with hundreds of objects optimized for real-time multimedia application
- Can interact with multiple devices (e.g. Raspberry board, Arduino board, MIDI devices) and allows transfer of data over WiFi

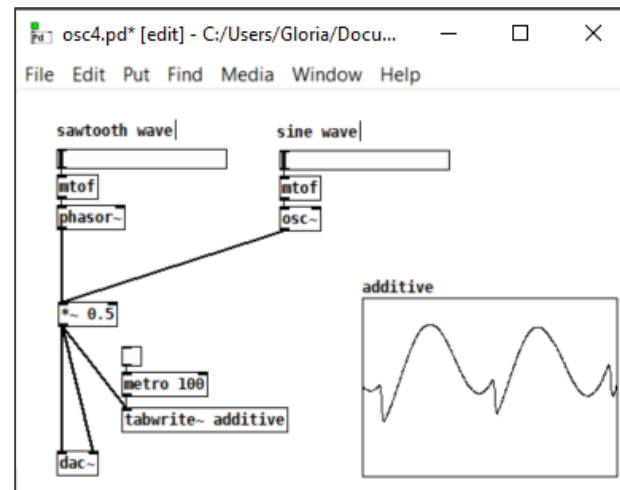


Figure 4: Example of a Pure Data patch

- No objects available for partitioned convolution that allow to change on the fly the set of BRIRs without producing artifacts
- The available objects for partitioned convolution
 - **Clear the buffers** when a new set of BRIRs are loaded
 - Works on a **heavy use of FFTs** that may cause spikes in the CPU usage which in turns interrupt the audio stream
- Lack of an intuitive tool for debugging custom objects and patches

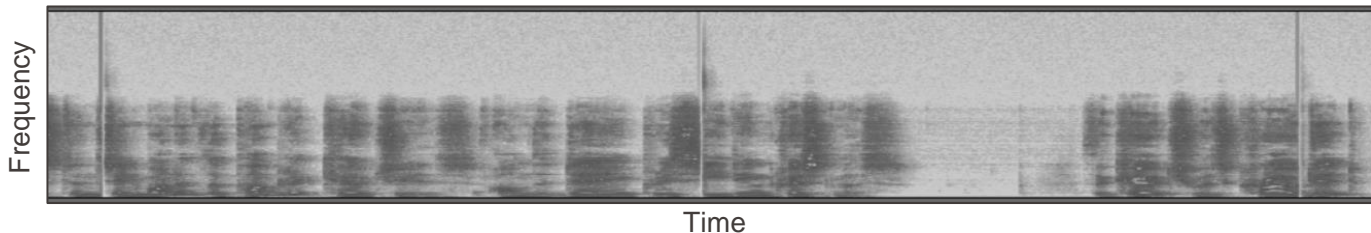
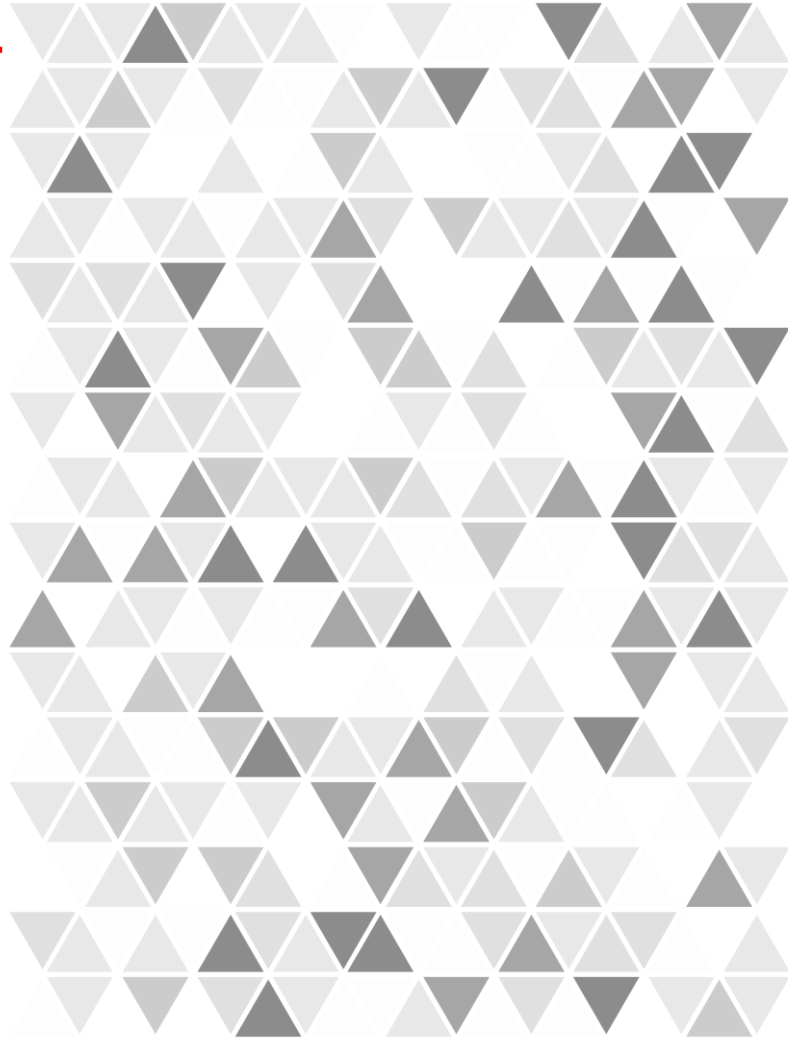


Figure 5: Spectrogram of the output of a convolution object in Pd



3. Concept

Design 1

- Improve the source code of the available objects
 - Modified buffer management
 - Import the BRIR dataset at initialization

Conclusions

- The deadtime reduced slightly but not enough
- The code requires a more drastic re-design to get acceptable results

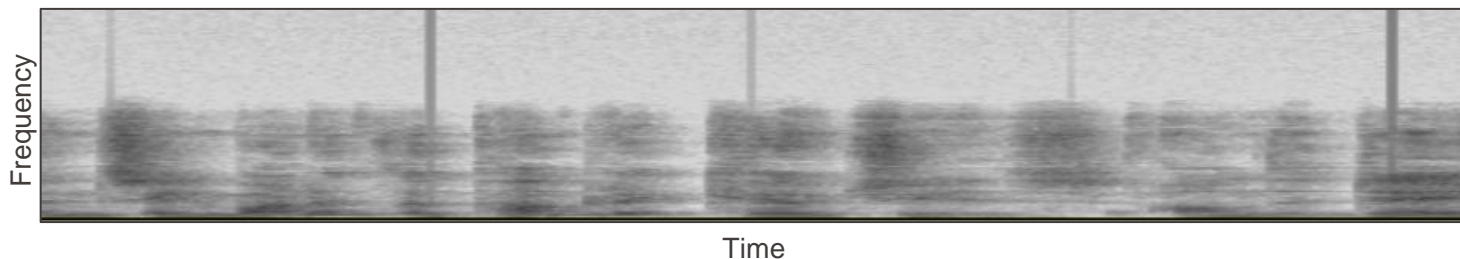


Figure 6: Spectrogram of the output of the modified convolution object in Pd

Concept: Initial Designs

Design 2

- Circular chain of 5 partitioned convolution objects per channel whose output is controlled by a multiplexer
 - The output of the multiplexer never coincides with the newly updated partitioned convolution object
- Expected high usage of the CPU

Conclusions

- Same artifacts as in Design 1

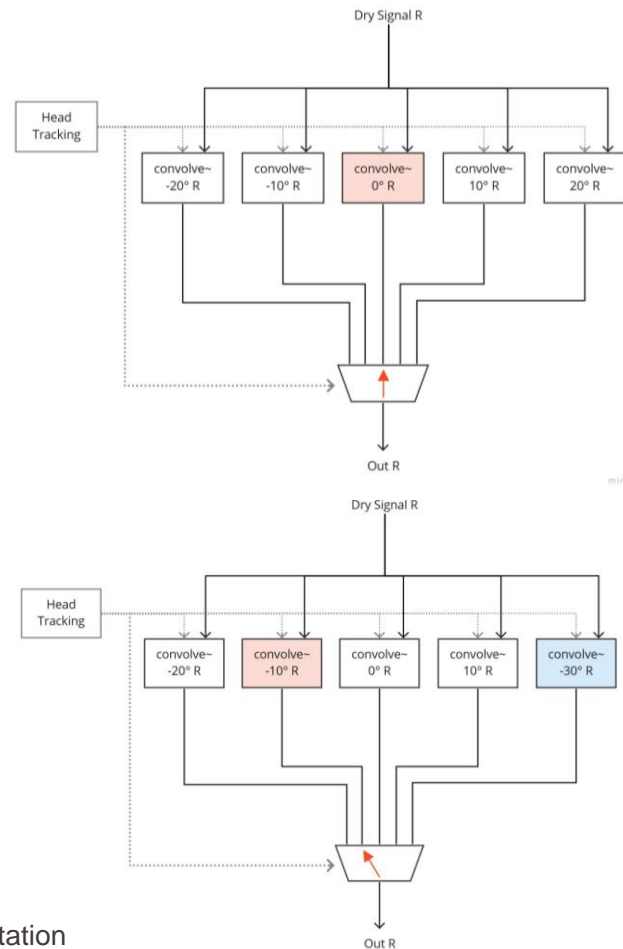


Figure 7: Two subsequent instances of [part of] the second implementation

- Direct sound and reflections treated separately and combined together after processing
 - **Direct Sound:** dry sound convolved in time domain with the HRTFs
 - **Early Reflections (ER)** and **Late Reverberation (LR):** dry sound convolved in frequency domain with modified BRIRs
- HRTFs are linearly interpolated
- The location of the ER and LR is fixed to avoid artifacts

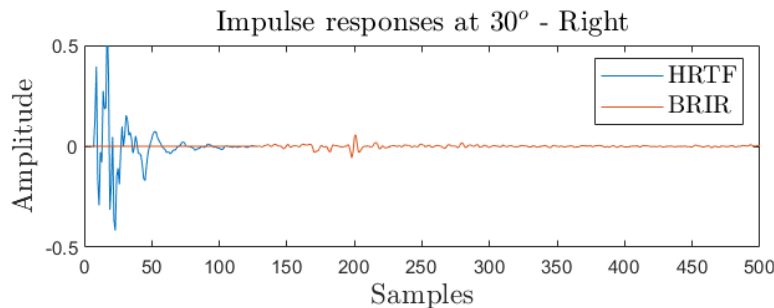
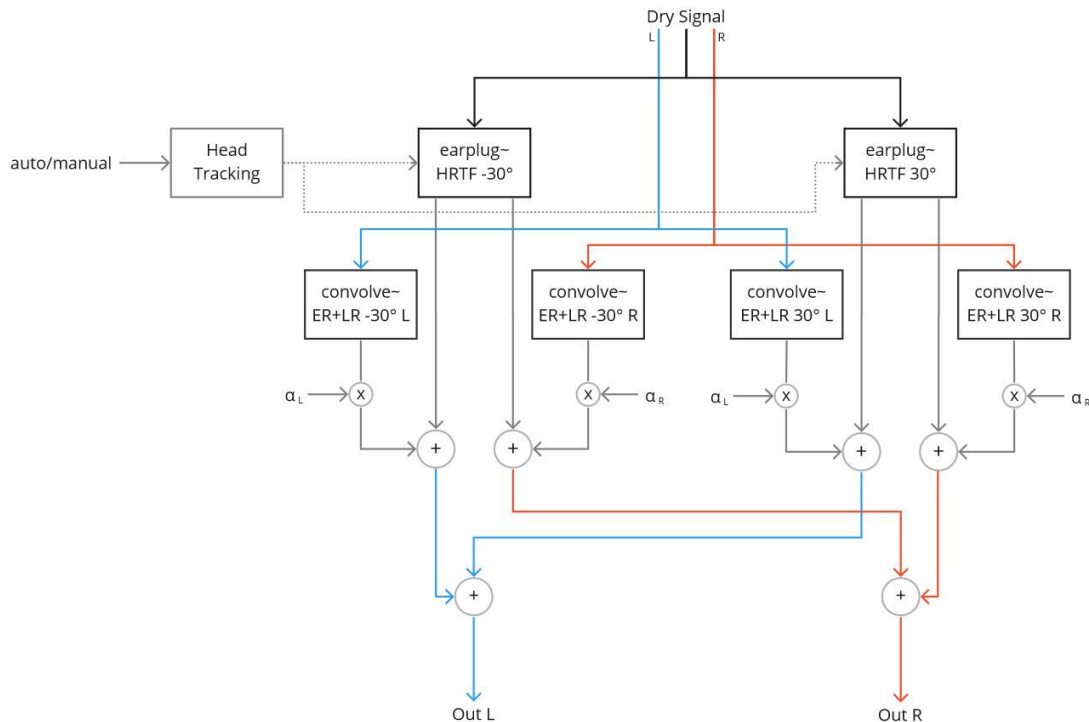


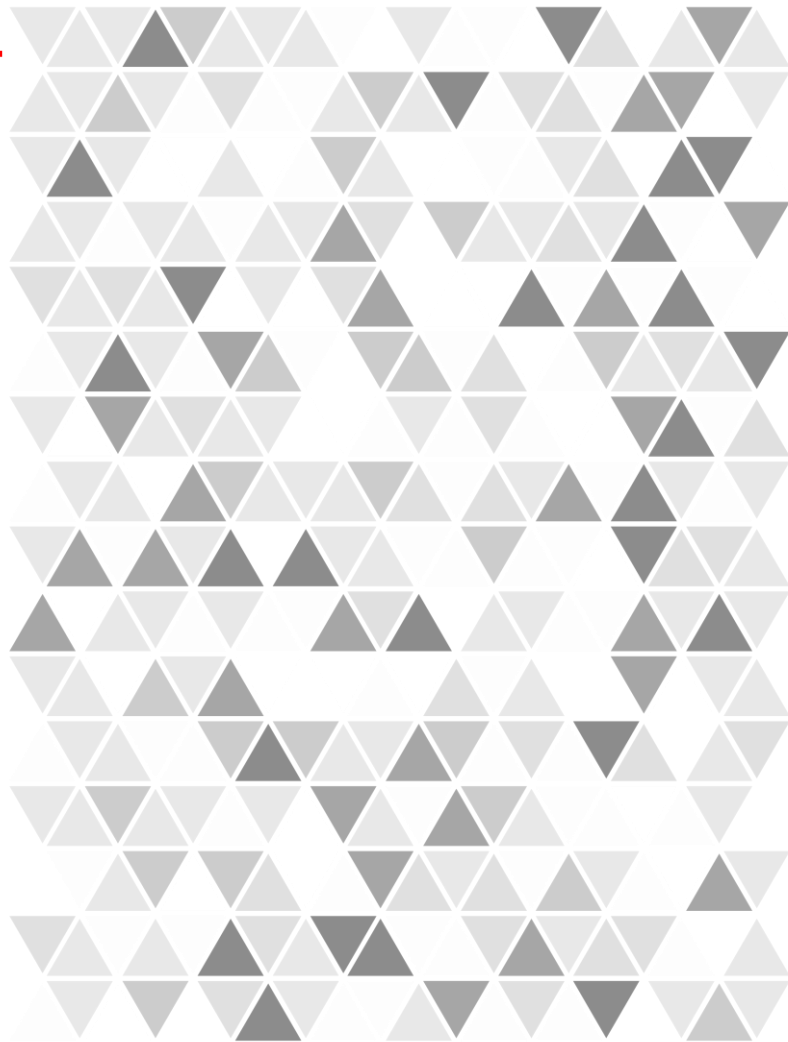
Figure 8: HRTF and modified BRIR at 30°



Pure Data objects:

- **earplug:** convolution with the HRTFs
- **convolve:** convolution with the BRIRs

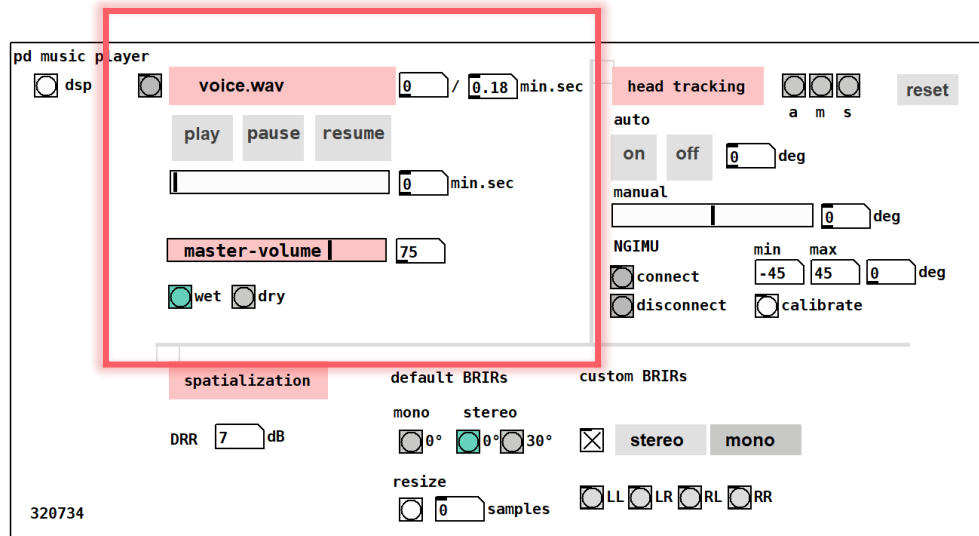
Figure 9: Diagram of the sound externalization block



4. User Interface of the Music Player

Music Player

- Load from file explorer
- Play/pause/resume the audio file
- Scroll bar to play from a specific point
- Master volume control bar
- Toggle between wet (externalized) and dry sound



Head Tracking System

Three modes available

- **auto:** simulation of the rotation of the head from -45° to 45°
- **manual:** user can set the desired angle of the head
- **sensor:** connects the patch to the IMU tracking device to retrieve the rotation of the head

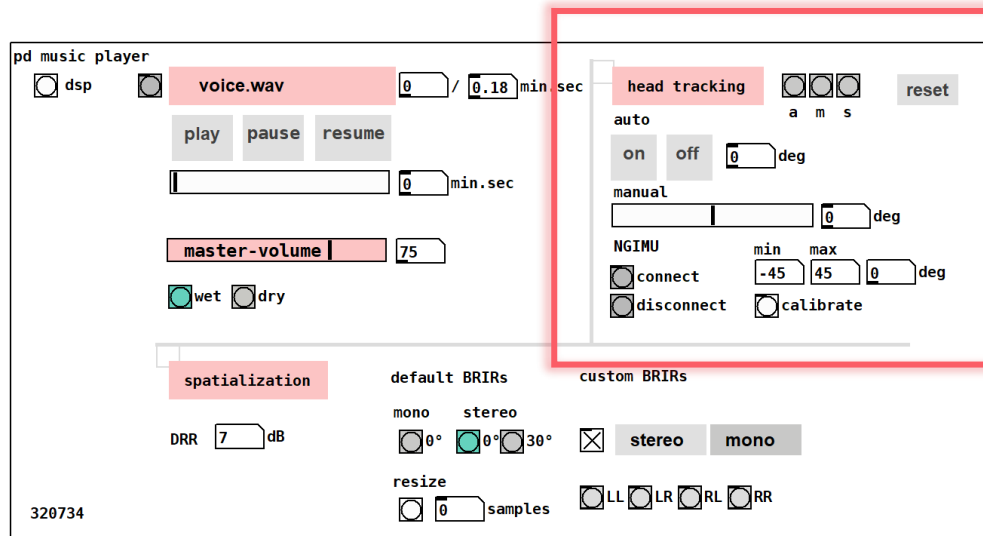
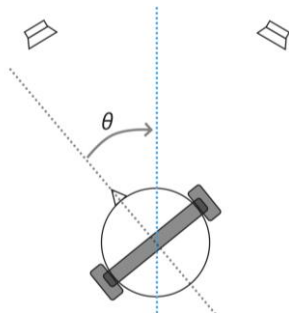


Figure 10: Head tracking system angle convention

Artificial Reverb

- Custom **DRR**
- Simulation of mono or stereo loudspeaker set up
- Custom length of the BRIRs
- The user can load his own set of ER+LR both in mono and stereo mode

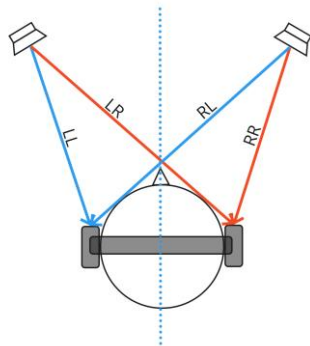
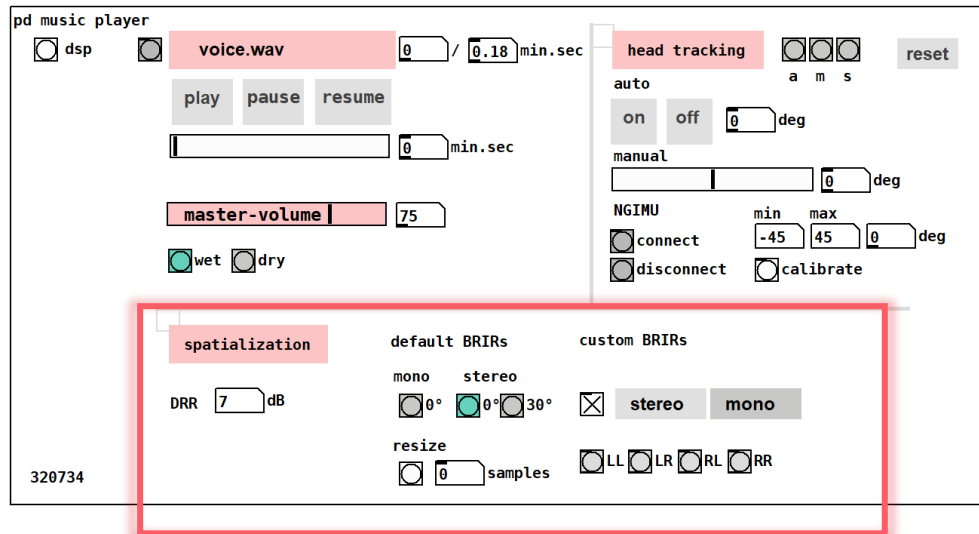
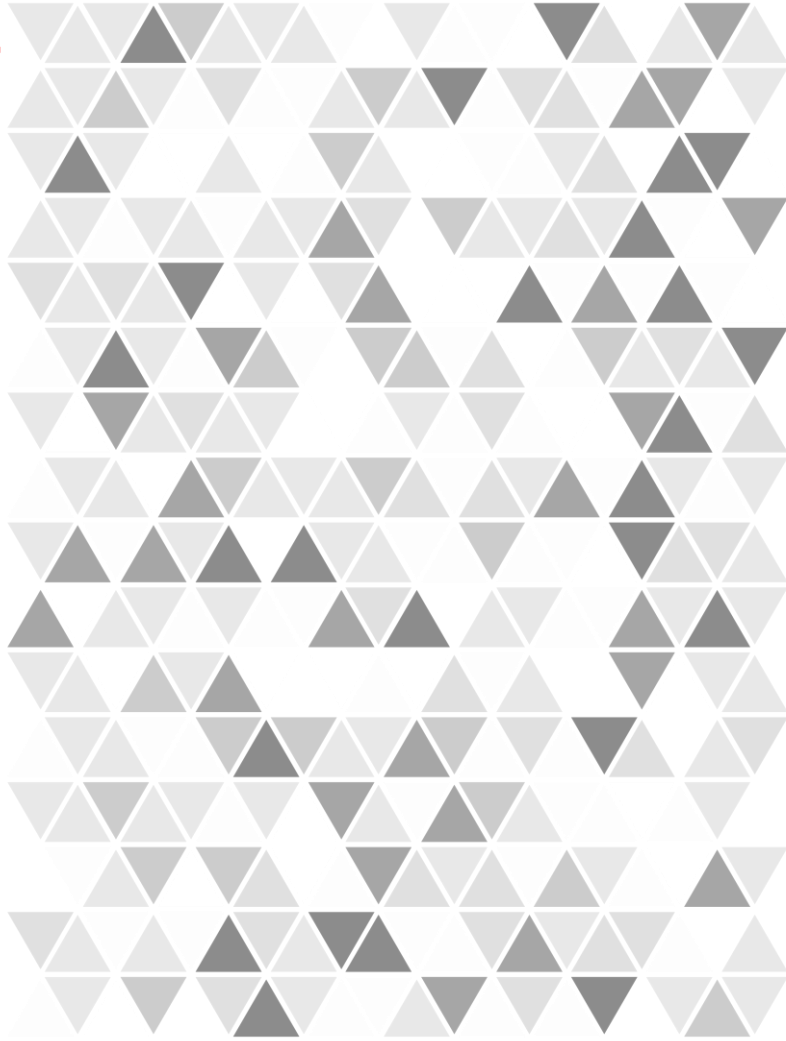


Figure 11: BRIRs naming convention





5. Conclusions

Strengths

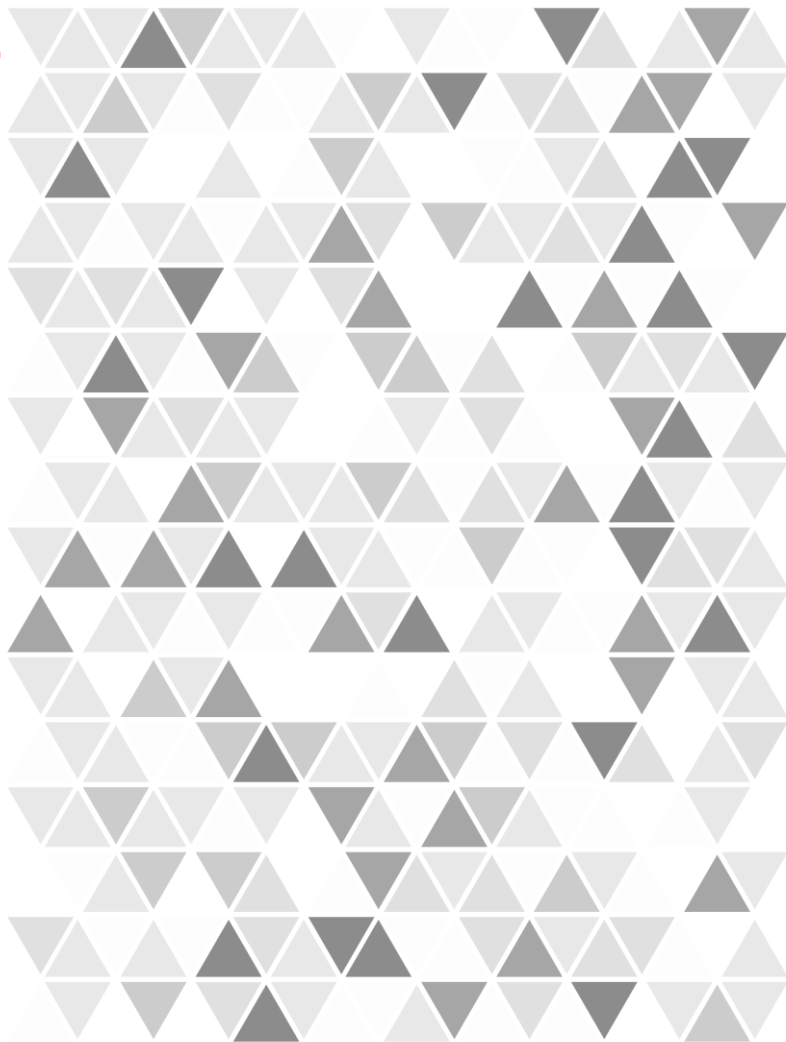
- Control over several parameters
 - It can be used to investigate the effects on perceived externalization of different configuration
- Artifact-free and low computational expensive implementation
- Modular architecture, easy to be modified

Limitations

- It cannot be distributed as a standalone application
- Lack of a Pure Data object that allows to change the set of BRIRs in real-time

Future Work

- Conduct a formal psychoacoustic test to assess the efficacy of the sound externalization algorithm and on the effect of externalized sounds on mental fatigue



**Thank you for your
attention!**



Questions?

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