

3 March 2005

## 1 The two-point correlator

The normalization of the baryon states will follow the appendix of Montvay and Münster [which differs, for example, from the choice used by Wilcox, Draper and Liu, PRD46, 1109 eqs (39) and (40)],

$$1 = \int \frac{d^3\vec{p}}{(2\pi)^3} \frac{m_n}{E_{n(\vec{p})}} \sum_s |n(\vec{p}, s)\rangle \langle n(\vec{p}, s)| \rightarrow \frac{1}{V} \sum_{\vec{p}} \frac{m_n}{E_{n(\vec{p})}} \sum_s |n(\vec{p}, s)\rangle \langle n(\vec{p}, s)|$$

where  $V$  is the spatial volume of the lattice and  $s$  sums over the possible spin states. We will consider the nucleon and  $\Delta^+$  interpolating fields (including Dirac index  $\alpha$  and Lorentz index  $\sigma$ ), such as

$$\begin{aligned}\chi_{\alpha L}^N(x) &= \epsilon^{abc} (d^{Ta}(x) C \gamma_5 u^b(x)) u_\alpha^c(x) \\ \chi_{\sigma, \alpha L}^{\Delta^+}(x) &= \epsilon^{abc} [2 (d^{Ta}(x) C \gamma_\sigma u^b(x)) u_\alpha^c(x) + (u^{Ta}(x) C \gamma_\sigma u^b(x)) d_\alpha^c(x)]\end{aligned}$$

or some smeared version of these, denoted  $\chi_{\alpha S}^N(x)$  or  $\chi_{\sigma, \alpha S}^{\Delta^+}(x)$ . In the following, the octet and decuplet baryons will be labelled by  $N$  and  $\Delta$ , respectively. However, the results may be applied to any of the octet to decuplet transitions.

The dimensionless correlator from Euclidean time  $t_i$  to Euclidean time  $t_f$  with momentum  $\vec{p}$  is

$$\begin{aligned}\Gamma_{AB}^{NN}(t_i, t_f, \vec{p}; T) &= a^9 \sum_{\vec{x}_f} e^{-i(\vec{x}_f - \vec{x}_i) \cdot \vec{p}} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x_f) \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \\ &= a^9 \sum_{n, \vec{k}, s} \sum_{\vec{x}_f} e^{-i(\vec{x}_f - \vec{x}_i) \cdot \vec{p}} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x_f) | n(\vec{k}, s) \rangle \frac{m_n}{V E_{n(\vec{k})}} \langle n(\vec{k}, s) | \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \\ &= a^9 \sum_{n, \vec{k}, s} \sum_{\vec{x}_f} e^{-i(\vec{x}_f - \vec{x}_i) \cdot \vec{p}} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x_i) e^{i(x_f - x_i) \cdot k} | n(\vec{k}, s) \rangle \frac{m_n}{V E_{n(\vec{k})}} \langle n(\vec{k}, s) | \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \\ &= a^9 \sum_{n, \vec{k}, s} \sum_{\vec{x}_f} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x_i) | n(\vec{k}, s) \rangle \frac{m_n e^{-(t_f - t_i) E_{n(\vec{k})}}}{V E_{n(\vec{k})}} \langle n(\vec{k}, s) | \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle e^{i(\vec{x}_f - \vec{x}_i) \cdot (\vec{k} - \vec{p})} \\ &= a^6 \sum_{n, \vec{k}, s} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x_i) | n(\vec{k}, s) \rangle \frac{m_n e^{-(t_f - t_i) E_{n(\vec{k})}}}{E_{n(\vec{k})}} \langle n(\vec{k}, s) | \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \delta_{\vec{k}, \vec{p}}^{(3)} e^{-i\vec{x}_i \cdot (\vec{k} - \vec{p})} \\ &= a^6 \sum_{n, s} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x_i) | n(\vec{p}, s) \rangle \langle n(\vec{p}, s) | \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \frac{m_n}{E_{n(\vec{p})}} e^{-(t_f - t_i) E_{n(\vec{p})}}\end{aligned}$$

where  $T_{\alpha\beta}$  is some generic  $4 \times 4$  matrix in Dirac spin space, and  $\alpha, \beta$  are Dirac indices. For  $t_f \gg t_i$ , the nucleon dominates and the result becomes

$$\Gamma_{AB}^{NN}(t_i, t_f, \vec{p}; T) \rightarrow a^6 \sum_s T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x_i) | N(\vec{p}, s) \rangle \langle N(\vec{p}, s) | \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \frac{m_N}{E_{N(\vec{p})}} e^{-(t_f - t_i)E_{N(\vec{p})}}$$

Similarly, for  $t_f \gg t_i$  the  $\Delta$  correlator becomes

$$\Gamma_{\sigma\tau, AB}^{\Delta\Delta}(t_i, t_f, \vec{p}; T) \rightarrow a^6 \sum_s T_{\alpha\beta} \langle 0 | \chi_{\sigma, \beta B}^\Delta(x_i) | \Delta(\vec{p}, s) \rangle \langle \Delta(\vec{p}, s) | \bar{\chi}_{\tau, \alpha A}^\Delta(x_i) | 0 \rangle \frac{m_\Delta}{E_{\Delta(\vec{p})}} e^{-(t_f - t_i)E_{\Delta(\vec{p})}}$$

where the subscripts  $\sigma, \tau$  are the Lorentz indices of the spin-3/2 interpolating fields.

The dimensionless matrix elements are given by [see, eg, UKQCD Collaboration, PRD57, 6948 (1998), equation (A4)],

$$\begin{aligned} a^3 \langle 0 | \chi_{\beta B}^N(x) | N(\vec{p}, s) \rangle &= \left[ \left( Z_B^{(1)}(|\vec{p}|) + \gamma_4 Z_B^{(2)}(|\vec{p}|) \right) u(\vec{p}, s) \right]_\beta e^{ix \cdot p} \\ a^3 \langle 0 | \chi_{\sigma, \beta B}^\Delta(x) | \Delta(\vec{p}, s) \rangle &= \left[ \left( Z_B^{(1)}(|\vec{p}|) + \gamma_4 Z_B^{(2)}(|\vec{p}|) \right) u_\sigma(\vec{p}, s) \right]_\beta e^{ix \cdot p} \end{aligned}$$

and its adjoint.  $x$  and  $p$  are Euclidean. (These equations implicitly define  $u(\vec{p}, s)$  and  $u_\sigma(\vec{p}, s)$ . Note in particular that they are implicitly chosen to be dimensionless.) Notice that we are assuming that any smearing is spatially-democratic. If there is no smearing at all, then we will use  $Z_L^{(1)}(|\vec{p}|) = 1$  and  $Z_L^{(2)}(|\vec{p}|) = 0$ . In either case, for the nucleon and  $\Delta$  we have

$$\begin{aligned} \Gamma_{AB}^{NN}(t_i, t_f, \vec{p}; T) &\rightarrow \sum_s T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}|) + \gamma_4 Z_B^{(2)}(|\vec{p}|) \right) u(\vec{p}, s) \bar{u}(\vec{p}, s) \left( Z_A^{(1)*}(|\vec{p}|) + \gamma_4 Z_A^{(2)*}(|\vec{p}|) \right) \right]_{\beta\alpha} \\ &\quad \frac{m_N}{E_{N(\vec{p})}} e^{-(t_f - t_i)E_{N(\vec{p})}} \\ \Gamma_{\sigma\tau, AB}^{\Delta\Delta}(t_i, t_f, \vec{p}; T) &\rightarrow \sum_s T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}|) + \gamma_4 Z_B^{(2)}(|\vec{p}|) \right) u_\sigma(\vec{p}, s) \bar{u}_\tau(\vec{p}, s) \left( Z_A^{(1)*}(|\vec{p}|) + \gamma_4 Z_A^{(2)*}(|\vec{p}|) \right) \right]_{\beta\alpha} \\ &\quad \frac{m_\Delta}{E_{\Delta(\vec{p})}} e^{-(t_f - t_i)E_{\Delta(\vec{p})}} \end{aligned}$$

In the following, we will consider the spin projection matrices defined as

$$T_i = \begin{pmatrix} \sigma_i & 0 \\ 0 & 0 \end{pmatrix}, \quad T_4 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

The gamma matrix basis used is

$$\gamma_i = \begin{pmatrix} 0 & \sigma_i \\ \sigma_i & 0 \end{pmatrix}, \quad \gamma_4 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Note that the Pauli spin matrices are

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

For the nucleon, the Dirac spin sum is

$$\sum_s u(\vec{p}, s) \bar{u}(\vec{p}, s) = \frac{i\not{p} + m_N}{2m_N}$$

so we arrive at

$$\Gamma_{AB}^{NN}(t_i, t_f, \vec{p}; T) \rightarrow T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}|) + \gamma_4 Z_B^{(2)}(|\vec{p}|) \right) \left( \frac{i\not{p} + m_N}{2E_{N(\vec{p})}} \right) \left( Z_A^{(1)*}(|\vec{p}|) + \gamma_4 Z_A^{(2)*}(|\vec{p}|) \right) \right]_{\beta\alpha} e^{-(t_f - t_i)E_{N(\vec{p})}}$$

For  $\beta = \alpha$  our result becomes

$$\Gamma_{\alpha\alpha, AB}^{NN}(t_i, t_f, \vec{p}) \rightarrow \left( Z_B^{(1)}(|\vec{p}|) + c_\alpha Z_B^{(2)}(|\vec{p}|) \right) \left( Z_A^{(1)*}(|\vec{p}|) + c_\alpha Z_A^{(2)*}(|\vec{p}|) \right) \left( \frac{E_{N(\vec{p})} + c_\alpha m_N}{2E_{N(\vec{p})}} \right) e^{-(t_f - t_i)E_{N(\vec{p})}} \quad (1)$$

where the repeated Dirac index  $\alpha$  is *not* summed. Also, we have defined  $c_1 = c_2 = 1$  and  $c_3 = c_4 = -1$ . Thus, for the standard projector  $T_4$ , we have

$$\Gamma_{AB}^{NN}(t_i, t_f, \vec{p}; T_4) \rightarrow 2 \left( Z_B^{(1)}(|\vec{p}|) + Z_B^{(2)}(|\vec{p}|) \right) \left( Z_A^{(1)*}(|\vec{p}|) + Z_A^{(2)*}(|\vec{p}|) \right) \left( \frac{E_{N(\vec{p})} + m_N}{2E_{N(\vec{p})}} \right) e^{-(t_f - t_i)E_{N(\vec{p})}} \quad (2)$$

The Rarita-Schwinger spin sum for the  $\Delta$  in Euclidean space is

$$\sum_s u_\sigma(\vec{p}, s) \bar{u}_\tau(\vec{p}, s) = \frac{i\not{p} + m_\Delta}{2m_\Delta} \left[ \delta_{\sigma\tau} + \frac{2p_\sigma p_\tau}{3m_\Delta^2} + i \frac{p_\sigma \gamma_\tau - p_\tau \gamma_\sigma}{3m_\Delta} - \frac{1}{3} \gamma_\sigma \gamma_\tau \right]$$

which results in

$$\Gamma_{\sigma\tau, AB}^{\Delta\Delta}(t_i, t_f, \vec{p}; T) \rightarrow \text{Tr} \left[ T \left( Z_B^{(1)}(|\vec{p}|) + \gamma_4 Z_B^{(2)}(|\vec{p}|) \right) \left( \frac{i\not{p} + m_\Delta}{2E_{\Delta(\vec{p})}} \right) \left( \delta_{\sigma\tau} + \frac{2p_\sigma p_\tau}{3m_\Delta^2} + i \frac{p_\sigma \gamma_\tau - p_\tau \gamma_\sigma}{3m_\Delta} - \frac{1}{3} \gamma_\sigma \gamma_\tau \right) \left( Z_A^{(1)*}(|\vec{p}|) + \gamma_4 Z_A^{(2)*}(|\vec{p}|) \right) \right] e^{-(t_f - t_i)E_{\Delta(\vec{p})}}$$

where  $\sigma$  and  $\tau$  are Lorentz indices. In the case  $\sigma = \tau$  and the projector  $T_4$ , we find (with no implied sum over  $\sigma$ )

$$\Gamma_{\sigma\sigma, AB}^{\Delta\Delta}(t_i, t_f, \vec{p}; T_4) \rightarrow \left( Z_B^{(1)}(|\vec{p}|) + Z_B^{(2)}(|\vec{p}|) \right) \left( Z_A^{(1)*}(|\vec{p}|) + Z_A^{(2)*}(|\vec{p}|) \right) \frac{2}{3} \left( 1 + \frac{p_\sigma^2}{m_\Delta^2} \right) \left( \frac{E_{\Delta(\vec{p})} + m_\Delta}{2E_{\Delta(\vec{p})}} \right) e^{-(t_f - t_i)E_{\Delta(\vec{p})}} \quad (3)$$

## 2 The three-point correlator

The dimensionless correlator from Euclidean time  $t_i$  (incoming momentum  $\vec{p}_i$ ) to Euclidean time  $t_f$  (outgoing momentum  $\vec{p}_f$ ) with a vector insertion at Euclidean time  $t$  is

$$\begin{aligned}
& \Gamma_{\mu,AB}^{NN}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) \\
&= a^{12} \sum_{\vec{x}_i, \vec{x}_f} T_{\alpha\beta} e^{-i(\vec{x}_f - \vec{x}) \cdot \vec{p}_f} e^{-i(\vec{x} - \vec{x}_i) \cdot \vec{p}_i} \langle 0 | \chi_{\beta B}^N(x_f) V_\mu(x) \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \\
&= a^{12} \sum_{n, \vec{k}, s} \sum_{m, \vec{l}, s'} \sum_{\vec{x}_i, \vec{x}_f} T_{\alpha\beta} e^{-i(\vec{x}_f - \vec{x}) \cdot \vec{p}_f} e^{-i(\vec{x} - \vec{x}_i) \cdot \vec{p}_i} \langle 0 | \chi_{\beta B}^N(x_f) | m(\vec{l}, s') \rangle \frac{m_m}{V E_{m(\vec{l})}} \\
&\quad \langle m(\vec{l}, s') | V_\mu(x) | n(\vec{k}, s) \rangle \frac{m_n}{V E_{n(\vec{k})}} \langle n(\vec{k}, s) | \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \\
&= a^{12} \sum_{n, \vec{k}, s} \sum_{m, \vec{l}, s'} \sum_{\vec{x}_i, \vec{x}_f} T_{\alpha\beta} e^{-i(\vec{x}_f - \vec{x}) \cdot \vec{p}_f} e^{-i(\vec{x} - \vec{x}_i) \cdot \vec{p}_i} \langle 0 | \chi_{\beta B}^N(x) e^{i(x_f - x) \cdot l} | m(\vec{l}, s') \rangle \\
&\quad \frac{m_m}{V E_{m(\vec{l})}} \langle m(\vec{l}, s') | V_\mu(x) | n(\vec{k}, s) \rangle \frac{m_n}{V E_{n(\vec{k})}} \langle n(\vec{k}, s) | e^{-i(x_i - x) \cdot k} \bar{\chi}_{\alpha A}^N(x) | 0 \rangle \\
&= a^{12} \sum_{n, \vec{k}, s} \sum_{m, \vec{l}, s'} \sum_{\vec{x}_i, \vec{x}_f} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x) | m(\vec{l}, s') \rangle \frac{m_m}{V E_{m(\vec{l})}} e^{-(t_f - t) E_{m(\vec{l})}} e^{i(\vec{x}_f - \vec{x}) \cdot (\vec{l} - \vec{p}_f)} \\
&\quad \langle m(\vec{l}, s') | V_\mu(x) | n(\vec{k}, s) \rangle \frac{m_n}{V E_{n(\vec{k})}} e^{-(t - t_i) E_{n(\vec{k})}} e^{i(\vec{x} - \vec{x}_i) \cdot (\vec{k} - \vec{p}_i)} \langle n(\vec{k}, s) | \bar{\chi}_{\alpha A}^N(x) | 0 \rangle \\
&= a^6 \sum_{n, \vec{k}, s} \sum_{m, \vec{l}, s'} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x) | m(\vec{l}, s') \rangle \delta_{\vec{l}, \vec{p}_f}^{(3)} \frac{m_m}{E_{m(\vec{l})}} e^{-(t_f - t) E_{m(\vec{l})}} e^{-i\vec{x} \cdot (\vec{l} - \vec{p}_f)} \\
&\quad \langle m(\vec{l}, s') | V_\mu(x) | n(\vec{k}, s) \rangle \delta_{\vec{k}, \vec{p}_i}^{(3)} \frac{m_n}{E_{n(\vec{k})}} e^{-(t - t_i) E_{n(\vec{k})}} e^{i\vec{x} \cdot (\vec{k} - \vec{p}_i)} \langle n(\vec{k}, s) | \bar{\chi}_{\alpha A}^N(x) | 0 \rangle \\
&= a^6 \sum_{n, s} \sum_{m, s'} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x) | m(\vec{p}_f, s') \rangle \frac{m_m}{E_{m(\vec{p}_f)}} e^{-(t_f - t) E_{m(\vec{p}_f)}} \langle m(\vec{p}_f, s') | V_\mu(x) | n(\vec{p}_i, s) \rangle \\
&\quad \frac{m_n}{E_{n(\vec{p}_i)}} e^{-(t - t_i) E_{n(\vec{p}_i)}} \langle n(\vec{p}_i, s) | \bar{\chi}_{\alpha A}^N(x) | 0 \rangle
\end{aligned}$$

For  $t_f \gg t \gg t_i$ , the nucleon dominates and the result becomes

$$\begin{aligned}
\Gamma_{\mu,AB}^{NN}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) &\rightarrow \\
&a^6 \sum_s \sum_{s'} T_{\alpha\beta} \langle 0 | \chi_{\beta B}^N(x) | N(\vec{p}_f, s') \rangle \langle N(\vec{p}_f, s') | V_\mu(x) | N(\vec{p}_i, s) \rangle \\
&\langle N(\vec{p}_i, s) | \bar{\chi}_{\alpha A}^N(x) | 0 \rangle \frac{m_N^2}{E_{N(\vec{p}_f)} E_{N(\vec{p}_i)}} e^{-(t_f-t)E_{N(\vec{p}_f)}} e^{-(t-t_i)E_{N(\vec{p}_i)}} \\
&= e^{ix \cdot (p_f - p_i)} \frac{m_N^2}{E_{N(\vec{p}_f)} E_{N(\vec{p}_i)}} e^{-(t_f-t)E_{N(\vec{p}_f)}} e^{-(t-t_i)E_{N(\vec{p}_i)}} \\
&\sum_{s,s'} T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) u(\vec{p}_f, s') \right]_\beta \\
&\langle N(\vec{p}_f, s') | V_\mu(x) | N(\vec{p}_i, s) \rangle \left[ \bar{u}(\vec{p}_i, s) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right]_\alpha \\
&= \frac{m_N^2}{E_{N(\vec{p}_f)} E_{N(\vec{p}_i)}} e^{-(t_f-t)E_{N(\vec{p}_f)}} e^{-(t-t_i)E_{N(\vec{p}_i)}} \\
&\sum_{s,s'} T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) u(\vec{p}_f, s') \right]_\beta \\
&\langle N(\vec{p}_f, s') | V_\mu(0) | N(\vec{p}_i, s) \rangle \left[ \bar{u}(\vec{p}_i, s) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right]_\alpha \\
&\quad (4)
\end{aligned}$$

Similarly, for  $t_f \gg t \gg t_i$ , the result for the  $\Delta$  becomes

$$\begin{aligned}
\Gamma_{\sigma\tau,\mu,AB}^{\Delta\Delta}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) &= a^{12} \sum_{\vec{x}_i, \vec{x}_f} T_{\alpha\beta} e^{-i(\vec{x}_f - \vec{x}) \cdot \vec{p}_f} e^{-i(\vec{x} - \vec{x}_i) \cdot \vec{p}_i} \langle 0 | \chi_{\sigma,\beta B}^\Delta(x_f) V_\mu(x) \bar{\chi}_{\tau,\alpha A}^\Delta(x_i) | 0 \rangle \\
&\rightarrow \frac{m_\Delta^2}{E_{\Delta(\vec{p}_f)} E_{\Delta(\vec{p}_i)}} e^{-(t_f-t)E_{\Delta(\vec{p}_f)}} e^{-(t-t_i)E_{\Delta(\vec{p}_i)}} \\
&\sum_{s,s'} T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) u_\sigma(\vec{p}_f, s') \right]_\beta \\
&\langle \Delta(\vec{p}_f, s') | V_\mu(0) | \Delta(\vec{p}_i, s) \rangle \left[ \bar{u}_\tau(\vec{p}_i, s) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right]_\alpha \\
&\quad (5)
\end{aligned}$$

Nothing is conceptually different for the transition form-factors, thus for  $t_f \gg t \gg t_i$  the result for the  $\Delta \rightarrow N$  (the  $\Delta$  has incoming momentum  $\vec{p}_i$  and the nucleon has outgoing

momentum  $\vec{p}_f$ ) becomes

$$\begin{aligned}
\Gamma_{\sigma,\mu,AB}^{\Delta N}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) &= a^{12} \sum_{\vec{x}_i, \vec{x}_f} T_{\alpha\beta} e^{-i(\vec{x}_f - \vec{x}) \cdot \vec{p}_f} e^{-i(\vec{x} - \vec{x}_i) \cdot \vec{p}_i} \langle 0 | \chi_{\beta B}^N(x_f) V_\mu(x) \bar{\chi}_{\sigma, \alpha A}^\Delta(x_i) | 0 \rangle \\
&\rightarrow \frac{m_\Delta m_N}{E_N(\vec{p}_f) E_\Delta(\vec{p}_i)} e^{-(t_f - t) E_N(\vec{p}_f)} e^{-(t - t_i) E_\Delta(\vec{p}_i)} \\
&\quad \sum_{s, s'} T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) u(\vec{p}_f, s') \right]_\beta \\
&\quad \langle N(\vec{p}_f, s') | V_\mu(0) | \Delta(\vec{p}_i, s) \rangle \left[ \bar{u}_\sigma(\vec{p}_i, s) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right]_\alpha
\end{aligned} \tag{6}$$

and the result for the  $N \rightarrow \Delta$  (the nucleon has incoming momentum  $\vec{p}_i$  and the  $\Delta$  has outgoing momentum  $\vec{p}_f$ )

$$\begin{aligned}
\Gamma_{\sigma,\mu,AB}^{N\Delta}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) &= a^{12} \sum_{\vec{x}_i, \vec{x}_f} T_{\alpha\beta} e^{-i(\vec{x}_f - \vec{x}) \cdot \vec{p}_f} e^{-i(\vec{x} - \vec{x}_i) \cdot \vec{p}_i} \langle 0 | \chi_{\sigma, \beta B}^\Delta(x_f) V_\mu(x) \bar{\chi}_{\alpha A}^N(x_i) | 0 \rangle \\
&\rightarrow \frac{m_\Delta m_N}{E_\Delta(\vec{p}_f) E_N(\vec{p}_i)} e^{-(t_f - t) E_\Delta(\vec{p}_f)} e^{-(t - t_i) E_N(\vec{p}_i)} \\
&\quad \sum_{s, s'} T_{\alpha\beta} \left[ \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) u_\sigma(\vec{p}_f, s') \right]_\beta \\
&\quad \langle \Delta(\vec{p}_f, s') | V_\mu(0) | N(\vec{p}_i, s) \rangle \left[ \bar{u}(\vec{p}_i, s) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right]_\alpha
\end{aligned} \tag{7}$$

### 3 The nucleon electromagnetic form factors

In conventional (but Euclidean) notation, the matrix element of interest is

$$\begin{aligned}
\langle N(\vec{p}_f, s') | V_\mu(0) | N(\vec{p}_i, s) \rangle_{\text{continuum}} &= Z_V \langle N(\vec{p}_f, s') | V_\mu(0) | N(\vec{p}_i, s) \rangle \\
&= \bar{u}(\vec{p}_f, s') \left[ \gamma_\mu F_1(q^2) - \frac{\sigma_{\mu\nu} q_\nu}{2m_N} F_2(q^2) \right] u(\vec{p}_i, s) \tag{8}
\end{aligned}$$

where  $Z_V$  is the renormalization factor ( $Z_V = 1$  for a conserved current),  $q = p_f - p_i$  and the electric and magnetic form factors are

$$G_E(q^2) = F_1(q^2) - \frac{q^2}{4m_N^2} F_2(q^2) \tag{9}$$

$$G_M(q^2) = F_1(q^2) + F_2(q^2) \tag{10}$$

This allows the three-point correlator with  $t_f \gg t \gg t_i$  to be written as

$$\Gamma_{\mu,AB}^{NN}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) = \frac{e^{-(t_f-t)E_{N(\vec{p}_f)}} e^{-(t-t_i)E_{N(\vec{p}_i)}}}{4Z_V E_{N(\vec{p}_f)} E_{N(\vec{p}_i)}} [\text{Tr}(T M_\mu^{(1)}) F_1(q^2) + \text{Tr}(T M_\mu^{(2)}) F_2(q^2)]$$

where

$$\begin{aligned} M_\mu^{(1)} &= \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) (i\not{p}_f + m_N) \gamma_\mu (i\not{p}_i + m_N) \\ &\quad \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \\ M_\mu^{(2)} &= \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) (i\not{p}_f + m_N) \left( \frac{-\sigma_{\mu\nu} q_\nu}{2m_N} \right) (i\not{p}_i + m_N) \\ &\quad \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \end{aligned}$$

and

$$\sigma_{\mu\nu} = \frac{i}{2} [\gamma_\mu, \gamma_\nu]$$

### 3.1 The result for $\mu = 4$

The  $\mu = 4$  matrices are

$$\begin{aligned} M_4^{(1)} &= \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) [\gamma_4 (E_{N(\vec{p}_f)} + \gamma_4 m) (E_{N(\vec{p}_i)} + \gamma_4 m) - 2\gamma_4 i\sigma_{jk} p_{fj} p_{ik} \\ &\quad + \gamma_4 \vec{p}_i \cdot \vec{p}_f - i (E_{N(\vec{p}_i)} - \gamma_4 m) \vec{p}_f \cdot \vec{\gamma} - i (E_{N(\vec{p}_f)} + \gamma_4 m) \vec{p}_i \cdot \vec{\gamma}] \\ &\quad \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \\ M_4^{(2)} &= \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) \frac{\gamma_4}{2m} [- (E_{N(\vec{p}_f)} + \gamma_4 m) i\vec{\gamma} \cdot \vec{q} (E_{N(\vec{p}_i)} + \gamma_4 m) \\ &\quad - \vec{q}^2 \gamma_4 (E_{N(\vec{p}_i)} + \gamma_4 m) - \vec{p}_i \cdot \vec{q} \gamma_4 (E_{N(\vec{p}_i)} - E_{N(\vec{p}_f)}) + (\vec{p}_i + \vec{p}_f) \cdot \vec{q} i\vec{\gamma} \cdot \vec{p}_i \\ &\quad + \vec{p}_i^2 i\vec{\gamma} \cdot \vec{q} + 2i\sigma_{jk} p_{ij} q_k \gamma_4 (E_{N(\vec{p}_i)} + E_{N(\vec{p}_f)} + 2\gamma_4 m)] \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \end{aligned}$$

Thus, for  $T_4$  the result is

$$\begin{aligned}
\text{Tr} \left( T_4 M_4^{(1)} \right) &= 2 \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \\
&\quad \left[ 2E_{N(\vec{p}_i)} E_{N(\vec{p}_f)} + m_N (E_{N(\vec{p}_i)} + E_{N(\vec{p}_f)}) - \frac{q^2}{2} \right] \\
&\quad \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right) \\
\text{Tr} \left( T_4 M_4^{(2)} \right) &= 2 \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \\
&\quad \left[ \frac{-q^2}{4m_N^2} (m_N E_{N(\vec{p}_i)} + m_N E_{N(\vec{p}_f)} + 2m_N^2) - \frac{1}{2} (E_{N(\vec{p}_f)} - E_{N(\vec{p}_i)})^2 \right] \\
&\quad \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right)
\end{aligned} \tag{11}$$

Consider the ratio

$$R_4 = \frac{Z_V \Gamma_{4,AB}^{NN}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T_4) \Gamma_{CL}^{NN}(t_i, t, \vec{p}_f; T_4)}{\Gamma_{AL}^{NN}(t_i, t, \vec{p}_i; T_4) \Gamma_{CB}^{NN}(t_i, t_f, \vec{p}_f; T_4)} \tag{12}$$

$$\begin{aligned}
&= \frac{1}{2E_{N(\vec{p}_f)} (E_{N(\vec{p}_i)} + m_N)} \left[ \left( 2E_{N(\vec{p}_i)} E_{N(\vec{p}_f)} + m_N (E_{N(\vec{p}_i)} + E_{N(\vec{p}_f)}) - \frac{q^2}{2} \right) F_1(q^2) \right. \\
&\quad \left. + \left( \frac{-q^2}{4m_N} (E_{N(\vec{p}_i)} + E_{N(\vec{p}_f)} + 2m_N) - \frac{1}{2} (E_{N(\vec{p}_f)} - E_{N(\vec{p}_i)})^2 \right) F_2(q^2) \right]
\end{aligned} \tag{13}$$

For the special case of  $\vec{p}_f = \vec{0}$ , we have  $q^2 = 2m_N (E_{N(\vec{p}_i)} - m_N)$  and we arrive at

$$R_4 = G_E(q^2)$$

### 3.2 The result for $\mu \neq 4$

We now consider other projection matrices  $T_k$

$$\begin{aligned}
\text{Tr} \left[ M_j^{(1)} T_k \right] &= 2 \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \epsilon_{jkl} \left[ p_{fl} (E_{N(\vec{p}_i)} + m_N) \right. \\
&\quad \left. - p_{il} (E_{N(\vec{p}_f)} + m_N) \right] \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right) \\
\text{Tr} \left[ M_j^{(2)} T_k \right] &= \frac{1}{m_N} \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \left[ \epsilon_{jkl} p_{fl} (E_{N(\vec{p}_i)} + m_N)^2 \right. \\
&\quad \left. - \epsilon_{jkl} p_{il} (2m_N (E_{N(\vec{p}_f)} + m_N) + \vec{p}_i \cdot \vec{p}_f) - p_{ik} \epsilon_{jlm} p_{il} p_{fm} \right. \\
&\quad \left. - p_{fj} \epsilon_{klm} p_{il} p_{fm} \right] \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right)
\end{aligned}$$



Consider the ratio

$$R_{jk} = \frac{Z_V (E_{N(\vec{p}_i)} + m_N)}{(-\epsilon_{jkl} p_{il})} \frac{\Gamma_{j,AB}^{NN}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T_k) \Gamma_{CL}^{NN}(t_i, t, \vec{p}_f; T_4)}{\Gamma_{AL}^{NN}(t_i, t, \vec{p}_i; T_4) \Gamma_{CB}^{NN}(t_i, t_f, \vec{p}_f; T_4)} \quad (14)$$

$$= \frac{-1}{4E_{N(\vec{p}_f)} \epsilon_{jkl} p_{il}} \left[ 2\epsilon_{jkl} \{p_{fl} (E_{N(\vec{p}_i)} + m_N) - p_{il} (E_{N(\vec{p}_f)} + m_N)\} F_1(q^2) \right. \\ \left. + \left\{ \epsilon_{jkl} p_{fl} (E_{N(\vec{p}_i)} + m_N)^2 - \epsilon_{jkl} p_{il} (2m_N (E_{N(\vec{p}_f)} + m_N) + \vec{p}_i \cdot \vec{p}_f) \right. \right. \\ \left. \left. - p_{ik} \epsilon_{jlm} p_{il} p_{fm} - p_{fj} \epsilon_{klm} p_{il} p_{fm} \right\} \frac{F_2(q^2)}{m_N} \right] \quad (15)$$

For the special case of  $\vec{p}_f = \vec{0}$ , the expression simplifies to

$$R_{jk} = G_M(q^2)$$

In the general case, Eqs. (13) and (15) can be used to determine  $G_E(q^2)$  and  $G_M(q^2)$ .

## 4 The $\gamma N \rightarrow \Delta$ electromagnetic form factors

In conventional (but Euclidean) notation, the matrix element of interest is

$$\begin{aligned} \langle \Delta(\vec{p}_f, s') | V_\mu(0) | N(\vec{p}_i, s) \rangle_{\text{continuum}} &= Z_V \langle \Delta(\vec{p}_f, s') | V_\mu(0) | N(\vec{p}_i, s) \rangle \\ &= i\sqrt{\frac{2}{3}} \bar{u}_\tau(\vec{p}_f, s') \mathcal{O}^{\tau\mu} u(\vec{p}_i, s) \end{aligned} \quad (16)$$

where  $Z_V$  is the renormalization factor ( $Z_V = 1$  for a conserved current),  $q = p_f - p_i$ ,  $u_\tau(\vec{p}, s)$  is a spin-vector in the Rarita-Schwinger formalism, and  $u(\vec{p}, s)$  is a Dirac spin vector. The operator  $\mathcal{O}^{\tau\mu}$  can be decomposed into

$$\mathcal{O}^{\tau\mu} = G_{M1}(q^2) K_{M1}^{\tau\mu} + G_{E2}(q^2) K_{E2}^{\tau\mu} + G_{C2}(q^2) K_{C2}^{\tau\mu},$$

where the form-factors  $G_{M1}(q^2)$ ,  $G_{E2}(q^2)$ , and  $G_{C2}(q^2)$  are referred to as the magnetic dipole  $M1$ , the electric quadrupole  $E2$  and the electric charge or scalar quadrupole  $C2$  transition form factors. Definitions come from Leinweber PRD48, and Alexandrou. The kinematical factors are, in Euclidean notation,

$$K_{M1}^{\tau\mu} = -\frac{3}{(m_\Delta + m_N)^2 + q^2} \frac{(m_\Delta + m_N)}{2m_N} i\epsilon^{\tau\mu\alpha\beta} P_\alpha q_\beta \quad (17)$$

$$K_{E2}^{\tau\mu} = -K_{M1}^{\tau\mu} + 6\Omega^{-1}(q^2) \frac{(m_\Delta + m_N)}{2m_N} i\gamma_5 \epsilon^{\tau\lambda\alpha\beta} P_\alpha q_\beta \epsilon^{\mu\lambda\gamma\delta} (2P_\gamma + q_\gamma) q_\delta \quad (18)$$

$$K_{C2}^{\tau\mu} = -6\Omega^{-1}(q^2) \frac{(m_\Delta + m_N)}{2m_N} i\gamma_5 q_\tau (q^2 P_\mu - q \cdot P q_\mu) \quad (19)$$

with  $\Omega(q^2) = [(m_\Delta + m_N)^2 + q^2][(m_\Delta - m_N)^2 + q^2]$ . Recall the momenta are Euclidean, so  $q_4$  is imaginary. The  $P^\mu = (p_f^\mu + p_i^\mu)/2$ . This allows the three-point correlator with  $t_f \gg t \gg t_i$  to be written as

$$\begin{aligned} \Gamma_{\sigma,\mu,AB}^{N\Delta}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) &= i\sqrt{\frac{2}{3}} \frac{e^{-(t_f-t)E_{\Delta}(\vec{p}_f)} e^{-(t-t_i)E_N(\vec{p}_i)}}{4Z_V E_{\Delta}(\vec{p}_f) E_N(\vec{p}_i)} \\ &\quad [M_{\sigma\mu}^{(1)} G_{M1}(q^2) + M_{\sigma\mu}^{(2)} G_{E2}(q^2) + M_{\sigma\mu}^{(3)} G_{C2}(q^2)] \end{aligned} \quad (20)$$

where

$$\begin{aligned}
M_{\sigma\mu}^{(1)} &= \text{Tr} \left( T \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) (i\not{p}_f + m_\Delta) \left[ \delta_{\sigma\tau} + \frac{2p_{f\sigma}p_{f\tau}}{3m_\Delta^2} + i\frac{p_{f\sigma}\gamma_\tau - p_{f\tau}\gamma_\sigma}{3m_\Delta} - \frac{1}{3}\gamma_\sigma\gamma_\tau \right] \right. \\
&\quad \left. K_{M1}^{\tau\mu} (i\not{p}_i + m_N) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right) \\
M_{\sigma\mu}^{(2)} &= \text{Tr} \left( T \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) (i\not{p}_f + m_\Delta) \left[ \delta_{\sigma\tau} + \frac{2p_{f\sigma}p_{f\tau}}{3m_\Delta^2} + i\frac{p_{f\sigma}\gamma_\tau - p_{f\tau}\gamma_\sigma}{3m_\Delta} - \frac{1}{3}\gamma_\sigma\gamma_\tau \right] \right. \\
&\quad \left. K_{E2}^{\tau\mu} (i\not{p}_i + m_N) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right) \\
M_{\sigma\mu}^{(3)} &= \text{Tr} \left( T \left( Z_B^{(1)}(|\vec{p}_f|) + \gamma_4 Z_B^{(2)}(|\vec{p}_f|) \right) (i\not{p}_f + m_\Delta) \left[ \delta_{\sigma\tau} + \frac{2p_{f\sigma}p_{f\tau}}{3m_\Delta^2} + i\frac{p_{f\sigma}\gamma_\tau - p_{f\tau}\gamma_\sigma}{3m_\Delta} - \frac{1}{3}\gamma_\sigma\gamma_\tau \right] \right. \\
&\quad \left. K_{C2}^{\tau\mu} (i\not{p}_i + m_N) \left( Z_A^{(1)*}(|\vec{p}_i|) + \gamma_4 Z_A^{(2)*}(|\vec{p}_i|) \right) \right)
\end{aligned}$$

Consider the ratio

$$R_{\sigma\mu j} = \frac{Z_V^2 \Gamma_{\sigma,\mu,AB}^{N\Delta}(t_i, t, t_f, \vec{p}_i, \vec{p}_f; T) \Gamma_{\sigma,\mu,DC}^{\Delta N}(t_i, t, t_f, -\vec{p}_f, -\vec{p}_i; T)}{\Gamma_{AC}^{NN}(t_i, t_f, -\vec{p}_i; T_4) \sum_{j=1}^3 \Gamma_{BD}^{\Delta\Delta}(t_i, t_f, \vec{p}_f; T_4)} \quad (21)$$

It can be used to obtain the three form factors,  $G_{M1}(q^2)$ ,  $G_{E2}(q^2)$  and  $G_{C2}(q^2)$ . All  $Z$  factors and exponentials cancel. Three different choices for the indices  $\sigma$ ,  $\mu$  and  $j$  will suffice to determine the three form factors for any given momenta. Technically, Eq. (21) only gives their magnitudes since  $R_{\sigma\mu j}$  is quadratic in the form factors. This same type of ratio is used by Alexandrou et al, PRD69,114506 (2004), eq 12.

## 4.1 The $M_{\sigma\mu}^{(n)}$ for $T = T_4$

In these expressions, Greek indices run from 1 to 4 and Roman indices run from 1 to 3.

$$\begin{aligned}
M_{\sigma\mu}^{(1)} = & \frac{-(m_N + m_\Delta)p_{i\alpha}p_{f\beta}}{m_N((m_N + m_\Delta)^2 + q^2)} \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right) \\
& \left[ (E_\Delta + m_\Delta)(E_N + m_N) \left( 2i\epsilon_{\sigma\mu\alpha\beta} - \frac{p_{f\sigma}}{m_\Delta}\epsilon_{4\mu\alpha\beta} \right) \right. \\
& + (E_\Delta + m_\Delta) \left( \frac{-ip_{f\sigma}}{m_\Delta}\epsilon_{j\mu\alpha\beta}p_{ij} + \epsilon_{j\mu\alpha\beta}p_{ij}\delta_{4\sigma} - \epsilon_{4\mu\alpha\beta}p_{i\sigma}(1 - \delta_{4\sigma}) \right) \\
& + (E_N + m_N) \left( \frac{-ip_{f\sigma}}{m_\Delta}\epsilon_{j\mu\alpha\beta}p_{fj} - \epsilon_{j\mu\alpha\beta}p_{fj}\delta_{4\sigma} + \epsilon_{4\mu\alpha\beta}p_{f\sigma}(1 - \delta_{4\sigma}) \right) \\
& \left. - 2i\epsilon_{\sigma\mu\alpha\beta}\vec{p}_i \cdot \vec{p}_f + \frac{p_{f\sigma}}{m_\Delta}\epsilon_{4\mu\alpha\beta}\vec{p}_i \cdot \vec{p}_f + i\epsilon_{j\mu\alpha\beta}(p_{ij}p_{f\sigma} - p_{i\sigma}p_{fj})(1 - \delta_{4\sigma}) \right] \quad (22)
\end{aligned}$$

$$\begin{aligned}
M_{\sigma\mu}^{(2)} = & -M_{\sigma\mu}^{(1)} + \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right) \mathcal{K}_{\tau\mu} \left[ \right. \\
& \left( (m_\Delta + E_\Delta)p_{ik} - (m_N + E_N)p_{fk} \right) (1 - \delta_{4\sigma})(1 - \delta_{4\tau})\epsilon_{\sigma\tau k} \\
& \left. + ip_{fk}p_{il}\delta_{4\tau}(1 - \delta_{4\sigma})\epsilon_{k\sigma l} - ip_{fk}p_{il} \left( \delta_{4\sigma} + \frac{ip_{f\sigma}}{m_\Delta} \right) (1 - \delta_{4\tau})\epsilon_{k\tau l} \right] \quad (23)
\end{aligned}$$

$$M_{\sigma\mu}^{(3)} = 0 \quad (24)$$

where

$$\mathcal{K}_{\alpha\mu} = \frac{4(m_N + m_\Delta)}{m_N\Omega(q^2)} \left( m_N^2 m_\Delta^2 \delta_{\alpha\mu} + m_N^2 p_{f\alpha} p_{f\mu} + m_\Delta^2 p_{i\alpha} p_{i\mu} + p_i \cdot p_f (p_{i\alpha} p_{f\mu} + p_{f\alpha} p_{i\mu} - p_i \cdot p_f \delta_{\alpha\mu}) \right)$$

## 4.2 The $M_{\sigma\mu}^{(n)}$ for $T = T_j$

In these expressions, Greek indices run from 1 to 4 and Roman indices run from 1 to 3.

$$\begin{aligned}
M_{\sigma\mu}^{(1)} = & \frac{-(m_N + m_\Delta)p_{i\alpha}p_{f\beta}}{m_N((m_N + m_\Delta)^2 + q^2)} \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right) \\
& \left[ (E_\Delta + m_\Delta)(E_N + m_N)\epsilon_{\tau\mu\alpha\beta}\epsilon_{j\sigma\tau}(1 - \delta_{4\tau}) \right. \\
& + \left( (E_N + m_N)p_{fk} - (E_\Delta + m_\Delta)p_{ik} \right) \frac{p_{f\sigma}}{m_\Delta}(1 - \delta_{4\tau})\epsilon_{\tau\mu\alpha\beta}\epsilon_{jk\tau} \\
& + i \left( (E_N + m_N)p_{fk} - (E_\Delta + m_\Delta)p_{ik} \right) \epsilon_{\tau\mu\alpha\beta}(\delta_{4\tau}(1 - \delta_{4\sigma})\epsilon_{jk\sigma} - \delta_{4\sigma}(1 - \delta_{4\tau})\epsilon_{jk\tau}) \\
& + p_{fk}p_{il}\epsilon_{jkl} \left( 3\epsilon_{\sigma\mu\alpha\beta} + i\frac{p_{f\sigma}}{m_\Delta}\epsilon_{4\mu\alpha\beta} - \epsilon_{4\mu\alpha\beta}\delta_{4\sigma} \right) \\
& \left. - p_{fk}p_{il}\epsilon_{\tau\mu\alpha\beta}(1 - \delta_{4\sigma})(1 - \delta_{4\tau})(\delta_{jk}\epsilon_{\sigma\tau l} + \delta_{\sigma\tau}\epsilon_{jkl} + \delta_{\tau l}\epsilon_{jk\sigma} - \delta_{\sigma l}\epsilon_{jk\tau}) \right] \quad (25)
\end{aligned}$$

$$\begin{aligned}
M_{\sigma\mu}^{(2)} = & -M_{\sigma\mu}^{(1)} + \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right) \left[ \right. \\
& - 2i\mathcal{K}_{\sigma\mu} \left( (E_N + m_N)p_{fj} - (E_\Delta + m_\Delta)p_{ij} \right) \\
& + \mathcal{K}_{4\mu} \left( -\delta_{\sigma j}(E_N + m_N)(E_\Delta + m_\Delta) - \frac{p_{fj}p_{f\sigma}}{m_\Delta}(E_N + m_N) \right. \\
& \left. - \frac{p_{ij}p_{f\sigma}}{m_\Delta}(E_\Delta + m_\Delta) + p_{fj}p_{i\sigma} - \delta_{j\sigma}\vec{p}_i \cdot \vec{p}_f + p_{ij}p_{f\sigma} \right) \\
& + \mathcal{K}_{j\mu} \left( \left( \delta_{4\sigma} - \frac{ip_{f\sigma}}{m_\Delta} \right) (E_N + m_N)(E_\Delta + m_\Delta) + ip_{f\sigma}(E_N + m_N)(1 - \delta_{4\sigma}) \right. \\
& \left. + ip_{i\sigma}(E_\Delta + m_\Delta)(1 - \delta_{4\sigma}) + \frac{ip_{f\sigma}}{m_\Delta}\vec{p}_i \cdot \vec{p}_f + \delta_{4\sigma}\vec{p}_i \cdot \vec{p}_f \right) \left. \right] \quad (26)
\end{aligned}$$

$$\begin{aligned}
M_{\sigma\mu}^{(3)} = & \frac{i(m_N + m_\Delta)}{m_N\Omega(q^2)} \left( q^2(p_i + p_f)_\mu - q \cdot (p_i + p_f)q_\mu \right) \\
& \left( Z_B^{(1)}(|\vec{p}_f|) + Z_B^{(2)}(|\vec{p}_f|) \right) \left( Z_A^{(1)*}(|\vec{p}_i|) + Z_A^{(2)*}(|\vec{p}_i|) \right) \left[ \right. \\
& (m_N + E_N)p_{fj} \left( -3p_{i\sigma} + \frac{p_{f\sigma}}{m_\Delta} \left( m_N - \frac{2p_i \cdot p_f}{m_\Delta} \right) - i\delta_{4\sigma} \left( m_N + \frac{p_i \cdot p_f}{m_\Delta} \right) \right) \\
& - (m_\Delta + E_\Delta)p_{ij} \left( -3p_{i\sigma} + \frac{p_{f\sigma}}{m_\Delta} \left( m_N - \frac{2p_i \cdot p_f}{m_\Delta} \right) + i\delta_{4\sigma} \left( m_N + \frac{p_i \cdot p_f}{m_\Delta} \right) \right) \\
& + \delta_{j\sigma}(m_N + E_N)(m_\Delta + E_\Delta) \left( m_N + \frac{p_i \cdot p_f}{m_\Delta} \right) \\
& \left. + (1 - \delta_{4\sigma}) \left( m_N + \frac{p_i \cdot p_f}{m_\Delta} \right) \left( p_{i\sigma}p_{fj} - \vec{p}_i \cdot \vec{p}_f\delta_{j\sigma} + p_{ij}p_{f\sigma} \right) \right] \quad (27)
\end{aligned}$$

where  $\mathcal{K}_{\alpha\mu}$  was defined in the previous subsection.

### 4.3 Special case: $T = T_j$ , $\mu = 4$ , $\sigma \neq 4$ , $\vec{p}_i = \vec{0}$

$$M_{\sigma\mu}^{(1)} = 0$$

$$M_{\sigma\mu}^{(2)} = 0$$

$$M_{\sigma\mu}^{(3)} = \left( Z_B^{(1)}(|\vec{q}|) + Z_B^{(2)}(|\vec{q}|) \right) \left( Z_A^{(1)*}(0) + Z_A^{(2)*}(0) \right) \frac{m_N + m_\Delta}{m_\Delta} \left[ q_j q_\sigma \left( 1 + \frac{2E_\Delta}{m_\Delta} \right) - \vec{q}^2 \delta_{\sigma j} \right]$$

Eq. (21) simplifies to

$$G_{C2}(q^2) = \pm \frac{4\sqrt{6}m_\Delta E_\Delta m_N}{(m_N + m_\Delta)} \sqrt{1 + \frac{m_\Delta}{E_\Delta}} \sqrt{1 + \frac{\vec{q}^2}{3m_\Delta^2}} \left( \frac{\sqrt{R_{\sigma\mu j}}}{q_j q_\sigma (1 + 2E_\Delta/m_\Delta) - \vec{q}^2 \delta_{\sigma j}} \right)$$

in agreement with Alexandrou et al, PRD69,114506 (2004), eq 19.

### 4.4 Special case: $T = T_4$ , $\mu \neq 4$ , $\sigma \neq 4$ , $\vec{p}_i = \vec{0}$

$$M_{\sigma\mu}^{(1)} = 2 \left( Z_B^{(1)}(|\vec{q}|) + Z_B^{(2)}(|\vec{q}|) \right) \left( Z_A^{(1)*}(0) + Z_A^{(2)*}(0) \right) (m_N + m_\Delta) \epsilon_{\sigma\mu k} q_k$$

$$M_{\sigma\mu}^{(2)} = 0$$

$$M_{\sigma\mu}^{(3)} = 0$$

Eq. (21) simplifies to

$$G_{M1}(q^2) = \pm \frac{2\sqrt{6}E_\Delta m_N}{(m_N + m_\Delta)q_k} \sqrt{1 + \frac{m_\Delta}{E_\Delta}} \sqrt{1 + \frac{\vec{q}^2}{3m_\Delta^2}} \sqrt{R_{\sigma\mu j}}$$

where  $\mu$ ,  $\sigma$  and  $k$  are three distinct spatial directions. This equation is in agreement with Alexandrou et al, PRD69,114506 (2004), eq 20(a).

## 4.5 Special case: $T = T_j$ , $\mu \neq 4$ , $\sigma \neq 4$ , $\vec{p}_i = \vec{0}$

$$\begin{aligned}
M_{\sigma\mu}^{(1)} &= -i \left( Z_B^{(1)}(|\vec{q}|) + Z_B^{(2)}(|\vec{q}|) \right) \left( Z_A^{(1)*}(0) + Z_A^{(2)*}(0) \right) \left( \frac{m_N + m_\Delta}{m_\Delta + E_\Delta} \right) q_k \epsilon_{l\mu k} \\
&\quad \left( (E_\Delta + m_\Delta) \epsilon_{j\sigma l} + \frac{q_\sigma q_m}{m_\Delta} \epsilon_{jml} \right) \\
M_{\sigma\mu}^{(2)} &= -M_{\sigma\mu}^{(1)} + i \left( Z_B^{(1)}(|\vec{q}|) + Z_B^{(2)}(|\vec{q}|) \right) \left( Z_A^{(1)*}(0) + Z_A^{(2)*}(0) \right) (m_N + m_\Delta) \left[ 4q_j \left( \delta_{\sigma\mu} - \frac{q_\sigma q_\mu}{\vec{q}^2} \right) \right. \\
&\quad \left. + 3 \frac{E_\Delta}{m_\Delta} q_\sigma \left( \delta_{j\mu} - \frac{q_j q_\mu}{\vec{q}^2} \right) \right] \\
M_{\sigma\mu}^{(3)} &= -i \left( Z_B^{(1)}(|\vec{q}|) + Z_B^{(2)}(|\vec{q}|) \right) \left( Z_A^{(1)*}(0) + Z_A^{(2)*}(0) \right) (m_N + m_\Delta) \frac{q_\mu}{m_\Delta} (E_\Delta - m_N) \\
&\quad \left[ \delta_{\sigma j} - \frac{q_j q_\sigma}{\vec{q}^2} \left( 1 + \frac{2E_\Delta}{m_\Delta} \right) \right]
\end{aligned}$$

Eq. (21) simplifies to

$$\begin{aligned}
G_{M1}(q^2) &= \pm \frac{2\sqrt{6}E_\Delta m_N}{(m_N + m_\Delta)(q_j^2 - q_k^2)} \sqrt{1 + \frac{m_\Delta}{E_\Delta}} \sqrt{1 + \frac{\vec{q}^2}{3m_\Delta^2}} \\
&\quad \left[ \left( q_j \sqrt{R_{kkj}} - q_k \sqrt{R_{jjk}} \right) - \frac{m_\Delta}{E_\Delta} \left( q_j \sqrt{R_{jkk}} - q_k \sqrt{R_{kjj}} \right) \right] \\
G_{E2}(q^2) &= \pm \frac{2\sqrt{6}E_\Delta m_N}{3(m_N + m_\Delta)(q_j^2 - q_k^2)} \sqrt{1 + \frac{m_\Delta}{E_\Delta}} \sqrt{1 + \frac{\vec{q}^2}{3m_\Delta^2}} \\
&\quad \left[ \left( q_j \sqrt{R_{kkj}} - q_k \sqrt{R_{jjk}} \right) + \frac{m_\Delta}{E_\Delta} \left( q_j \sqrt{R_{jkk}} - q_k \sqrt{R_{kjj}} \right) \right]
\end{aligned}$$

where  $\mu$ ,  $\sigma$  and  $k$  are three distinct spatial directions. These equations are in agreement with Alexandrou et al, PRD69,114506 (2004), eqs 20(b) and 21.

## 5 The $\Delta \rightarrow \Delta$ electromagnetic form factors

In conventional (but Euclidean) notation, the matrix element of interest is

$$\begin{aligned} \langle \Delta(\vec{p}_f, s') | V_\mu(0) | \Delta(\vec{p}_i, s) \rangle_{\text{continuum}} \\ = Z_V \langle \Delta(\vec{p}_f, s') | V_\mu(0) | \Delta(\vec{p}_i, s) \rangle \\ = -\bar{u}_\alpha(\vec{p}_f, s') \mathcal{O}^{\alpha\mu\beta} u_\beta(\vec{p}_i, s) \end{aligned}$$

where  $Z_V$  is the renormalization factor ( $Z_V = 1$  for a conserved current),  $q = p_f - p_i$ ,  $u_\alpha(\vec{p}, s)$  is a spin-vector in the Rarita-Schwinger formalism, The operator  $\mathcal{O}^{\alpha\mu\beta}$  can be decomposed into

$$\mathcal{O}^{\alpha\mu\beta} = -\delta^{\alpha\beta} \left( a_1 \gamma_\mu + \frac{a_2}{2m_\Delta} P^\mu \right) + \frac{q^\alpha q^\beta}{(2m_\Delta)^2} \left( c_1 \gamma_\mu + \frac{c_2}{2m_\Delta} P^\mu \right)$$

where  $P^\mu = (p_f + p_i)/2$ . The parameters  $a_1$ ,  $a_2$ ,  $c_1$ ,  $c_2$  are independent covariant vertex function coefficients related to the multipole form factors (Leinweber PRD46).