P1.

(A)

Solve the initial linear equation and then branch on any variables that have a fractional value. Add the constrains of the fractional variables, solve the linear equation, and repeat until the solution is integral and not fractional.

Branches	Solution	Optimal value
	x = [-5 -5 1.5 5]	2.5
$x_4 \le -1$	$x = \begin{bmatrix} -5 & -5 & 2 & -1 \end{bmatrix}$	2
$x_4 \ge 0$	$x = \begin{bmatrix} -2 & -4 & 0 & 0 \end{bmatrix}$	2

The optimal value of the objective function is 2. One solution that leads to this value is:

$$x_1 = 1$$
 $x_2 = 1$ $x_3 = 1$ $x_4 = 1$

(B)

Branches	Solution	Optimal value
	x = [1.3333 1 1 .6667]	6.3333
$x_4 \ge 1$	$x = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$	6
$x_4 \le 0$	$x = \begin{bmatrix} 0 & 1 & 1 & 0 \end{bmatrix}$	3
$x_1 \leq 1$	$x = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$	6
$x_1 \ge 2$	Infeasible	

The optimal value of the objective function is 6. One solution that leads to this value is:

$$x_1 = 1$$
 $x_2 = 1$ $x_3 = 1$ $x_4 = 1$

P2.

Dictionary # 1

First, we choose x_1 because it is a variable with a fractional solution. We rewrite the equation for x_1 as:

$$0.666667x_5 - 0.333333x_4 + x_1 = 0.6666666666667$$

Next we rewrite the above equation in terms of an integer part and a fractional part.

$$(0x_5 - x_4 + x_1) + (0.666667x_5 + 0.777777x_4) = 0 + 0.6666666666667$$

The fractional part $(0.666667x_5 + 0.777777x_4) \ge 0.6666666666667$. The cutting plane is then given by the equation:

$$(0.666667x_5 + 0.777777x_4) + w_6 = 0.6666666666667$$

Dictionary # 2

Equations for variables with fractional solutions:

$$-0.333333x_8 - 0.666667x_9 + 0.3333333x_3 + x_4 = 4.33333333333$$

$$0.333333x_8 - 0.333333x_9 + 2.666667x_3 + x_5 = 8.66666666667$$

$$0.333333x_8 + 0.666667x_9 - 0.333333x_3 + x_1 = 5.66666666667$$

$$-0.333333x_8 + 0.333333x_9 - 2.666667x_3 + x_2 = 1.3333333333$$

Equations written with integral and fractional parts:

Cutting planes for the above equations:

P3.

(A)

Let x_i be node n_i . If $x_i = 1$ then there is a hospital at that node. If $x_i = 0$ then there is no hospital at that node, but there should be at least one other node $x_j = 1$ and the distance to that node W(i,j) should be between 0 and 1.

This is a 0-1 Integer Linear Program given by the following formulation:

$$\begin{array}{ll} \min & \sum_{j=1}^n (cost_j*node_j) \\ \text{s.t.} & \\ & \sum_{j=1}^n I(W(i,j) \leq 1)*n_j & \geq 1 \text{ for all } i=1...n \\ & n_j & \in \{0,1\} \end{array}$$

For the objective function, we want to minimize the cost of placing hospitals. The constraint

$$\sum_{j=1}^{n} I(W(i,j) \le 1) * n_j \ge 1 \text{ for all } i = 1...n$$

says that for each node i we want to make sure that there is a node j that has a hospital $n_j = 1$ and is within 1 hour of it $I(W(i,j) \le 1) = 1$.

(B)

The code to the solution is at the end of this document. The solution itself is the vector

$$x = [0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 1]$$

This means in order to minimize the cost of building the hospitals within the driving time of 1 hour for each node, hospitals should be placed at node 6 and node 8. The total cost of the hospitals ends up being 2.1 million dollars.

P4.

(A) We add the indicator variable $z_1...z_n$ to the problem. If $x_i == 0$ then $z_i = 0$ else $z_i = 1$. In this problem we want to minimize the sum of z_i and this occurs best when x_i is 0.

$$\begin{array}{ll} \min & \sum z \\ \text{s.t.} & \\ & Ax & \leq b \\ & x & \leq u*z \\ & x & \geq \ell*z \\ & x & \leq u \\ & x & \geq \ell \\ & z & \in \{0,1\} \end{array}$$

The additional constraints

$$x \le u * z$$
$$x \ge \ell * z$$

say that if x_i is negative then z_i must equal 1, referring to $x \ge \ell * z$. If x_i is positive then z_i must be equal to 1, referring to $x \le u * z$. But if x is 0 then z should be equal to 0 because this is a minimization problem.

(B)

We can use the same problem formulation from above except we make it a maximization problem instead of a minimization.

$$\begin{array}{ll} \max & \sum z \\ \text{s.t.} & \\ & Ax & \leq b \\ & x & \leq u*z \\ & x & \geq \ell*z \\ & x & \leq u \\ & x & \geq \ell \\ & z & \in \{0,1\} \end{array}$$

The additional constraints

$$x \le u * z$$
$$x \ge \ell * z$$

say that if x is negative then z must equal 1, referring to $x \ge \ell * z$. If x is positive then z must be equal to 1, referring to $x \le u * z$. But if x is 0 then z should be equal to 1 because this is a maximization problem.

(C)

In order to not satisfy the inequality $a \le x \le b$, x needs to be either $\ell \le x \le a$ or $b \le x \le u$. The

mixed integer program would look like:

$$\begin{array}{ll} \max & c^t x \\ \text{s.t.} & \leq b \\ & x \geq \ell * w + (1-w) * b \\ & x \leq a * w + (1-w) * u \\ & w & \in \{1,0\} \end{array}$$

The additional constraints

$$x \ge \ell * w + (1 - w) * b$$

 $x \le a * w + (1 - w) * u$

say that if $w_i = 1$ then $\ell \le x \le a$. If $w_i = 0$ then $b \le x \le u$.

P5.

We have to find a subset S that contains at least one element in the set S_i for i = 1, ..., k and the sum of the elements in S is minimized.

$$\begin{array}{ll} \min & \sum_{i=1}^n (i*x_i) \\ \text{s.t.} & \sum_{i=1}^n (i*x_{ij}) & \geq 1 \text{ for all } j=1...k \\ & x_i & \in \{0,1\} \end{array}$$

 $x_i = 1$ if the element i is in the subset S otherwise $x_i = 0$. The constraint

$$\sum_{j=1}^{n} (j * x_{ji}) \ge 1 \text{ for all } i = 1...k$$

says that for each set S_i , the subset S must contain at least one element from S_i . Solving the above example in the 0-1 ILP we get the solution vector

$$x = [1 \quad 1 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0]$$

This means the subset $S = \{1, 2\}$ which sums to 3.

```
% Problem 1 Part a
    options = optimoptions('linprog', 'Algorithm', 'dual-simplex');
   % p1 a
   f = [2 -3 -2 -1];
   A = \begin{bmatrix} 1 & -1 & 1 & 0 \end{bmatrix}
         1 -2 -1 1
         1 -1 -1 -1];
   b = [5 \ 3 \ -1];
1b = [-5 \ -5 \ -5];
    ub = [5 \ 5 \ 5 \ 5];
10
    [x, fval] = linprog(-f, A, b, [], [], lb, ub, options)
12
13
   \% p1 a x<sub>-</sub>4 <= -1
    1b = [-5 \ -5 \ -5 \ -5];
    ub = [5 \ 5 \ 5 \ -1];
    [x, fval] = linprog(-f, A, b, [], [], lb, ub, options)
17
   \% p1 a x<sub>-</sub>4 >= 0
18
    lb = [-5 -5 -5 0];
19
    ub = [5 \ 5 \ 5 \ 5];
20
    [x, fval] = linprog(-f, A, b, [], [], lb, ub, options)
1 % Problem 1 Part b
    options = optimoptions('linprog', 'Algorithm', 'dual-simplex');
    f = [2 \ 0 \ 3 \ 1];
   A = [1 -1 0 1]
4
         0 \ 2 \ 0 \ -1
         1 \ 0 \ -1 \ -2
         -1 \ 0 \ 0 \ 1];
    b = [1 \ 2 \ -1 \ 1];
    ub = [2 \ 1 \ 1 \ 1];
    1b = \begin{bmatrix} -2 & -1 & 0 & -1 \end{bmatrix};
10
11
    [x, fval] = linprog(-f, A, b, [], [], lb, ub, options)
12
13
14 \% x_4 <= 0
ub = [2 \ 1 \ 1 \ 0];
16 lb = [-2 -1 0 -1];
```

```
17
      [x, fval] = linprog(-f, A, b, [], [], lb, ub, options)
18
19
     \% x_4 >= 1
20
     ub = [2 \ 1 \ 1 \ 1];
     lb = [-2 \ -1 \ 0 \ 1];
22
23
     [x, fval] = linprog(-f, A, b, [], [], lb, ub, options)
^{24}
25
     \% x_1 <= 1
     ub = [1 \ 1 \ 1 \ 1];

lb = [-2 \ -1 \ 0 \ -1];
27
28
     [x, fval] = linprog(-f,A,b,[],[],lb,ub,options)
29
30
31 \% x_1 >= 2
\begin{array}{lll} 32 & ub \ = \ [2 & 1 & 1 & 1]\,; \\ 33 & lb \ = \ [2 & -1 & 0 & -1]; \end{array}
     [x, fval] = linprog(-f,A,b,[],[],lb,ub,options)
 1 % Problem 3 Part b
 2 \quad f \ = \ [3 \ 3 \ 1.5 \ 1 \ 1.2 \ 1.3 \ .9 \ .8];
 3 A = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}
            \dot{1} 1 1 1 0 1 0 0
 4
 5
            1 1 1 0 1 1 1 1
            0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 0
 6
            0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1 \ 1
            1 1 1 1 0 1 1 1
            0 \ 0 \ 1 \ 0 \ 1 \ 1 \ 1 \ 1
 9
            0 0 1 0 1 1 1 1];
10
11 A = A.*(-1);
12 b = \begin{bmatrix} -1 & -1 & -1 & -1 & -1 & -1 & -1 \end{bmatrix};
intcon = 8;
14 \quad ub \, = \, \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix};
15
     1b = [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0];
16
     [x, fval] = intlinprog(f, intcon, A, b, [], [], lb, ub)
 1 % Problem 5
 2 	ext{ f} = [1 	ext{ 2} 	ext{ 3} 	ext{ 4} 	ext{ 5} 	ext{ 6} 	ext{ 7} 	ext{ 8} 	ext{ 9} 	ext{ 10}];
 3 \quad A = \begin{bmatrix} -1 & 0 & -1 & 0 & 0 & -1 & 0 & 0 & 0 \end{bmatrix}
            0 \ -1 \ 0 \ 0 \ 0 \ -1 \ -1 \ 0 \ 0
            -1 \ 0 \ 0 \ 0 \ 0 \ 0 \ -1 \ -1 \ 0
 5
            -1 \ 0 \ -1 \ 0 \ -1 \ -1 \ 0 \ 0 \ 0 \ 0];
 7 \quad b = \begin{bmatrix} -1 & -1 & -1 \end{bmatrix};
      \begin{array}{l} ub = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1b = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}; \\ \end{array} 
 9
intcon = 10;
11
12 [x, fval] = intlinprog(f, intcon, A, b, [], [], lb, ub)
```