Georgios Is. Detorakis (GID), PhD

Contact Information

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• https://github.com/gdetor

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Summary of Qualification

- Ten years of research experience in scientific laboratories of various disciplines such as computational neuroscience, machine learning, neuromorphic computing, control theory, and robotics
- Strong abilities in combining and bridging different fields such as machine learning, neuroscience, computer science and mathematics.
- Advanced mathematical skills, especially in linear algebra, dynamical systems, signal processing and control theory.
- Long experience in programming in computational scripting and system languages.

Professional Experience

Data Science Architect with adNomus Inc.

adNomus | San Jose (CA), USA

August 2019-Now

- Developing NLP algorithms with applications on context analysis.
- · Deep learning for time-series forecasting.

Research Experience

Postdoc Researcher in Neuromorphic Computing and Machine Learning

UCI | Irvine (CA), USA

January 2016-July 2019

Neuromorphic Machine Intelligence Lab

- · Binary stochastic deep neural networks.
- Developed a neuromorphic framework and its simulator (https://github.com/nmi-lab/NSAT).
- Developed machine learning algorithms.
- Co-developed algorithms for Brain-Machine Interface using machine learning and neuromorphic devices.
- Integrated neuromorphic sensors (DVS camera) with the NSAT neuromorphic framework.

Postdoc Researcher in Neuroscience and Control Theory

CentraleSupélec | Gif-sur-Yvette, France

December 2013-December 2015

Laboratoire des signaux et systèmes

- Developed a neural model (nonlinear, delayed, neural field) and a closed-loop simulation for Parkinson's disease treatment.
- · Conducted theoretical work on non-linear retarded dynamical systems in a closed-loop setup.
- Co-developed software for spike-sorting (https://github.com/gdetor/SPySort).
- Developed Matlab software for on-line data processing using a Plexon recording device.

Python Instructor | CentraleSupélec | Gif-sur-Yvette, France

March 2014-April 2014

• Instructed the Python Programming Language and the Numpy, Scipy, and Matplotlib packages.

Research Assistant in Computational Neuroscience

INRIA-Nancy Grand Est | Nancy, France CORTEX Team

October 2010-October 2013

- Developed a computational model for self-organizing maps.
- Developed a mathematical model for the development of the somatosensory cortex.
- · Developed an attention mechanism for the self-organizing map.
- Reproduced an *in vivo* experiment *in silico* to study self-organization in the brain.

Research Intern in Robotics

FORTH | Heraklion, Greece

May 2008-October 2008

Computational Vision and Robotics Laboratory

- Configured and calibrated a humanoid robot (HOAP3).
- Applied biped locomotion algorithms on the robotic platform HOAP3.
- Developed demo simulations for the aforementioned robotic platform.

Research Intern in Systems Neuroscience

University of Crete | Heraklion, Greece

October 2007-April 2008

Laboratory of Systems Physiology and Computational Neuroscience

- · Conducting EMG and EEG experiments for studying human tremor.
- · Developed software on Matlab for EMG signal processing and analysis.
- · Analyzing EMG and EEG data.
- · Developed simulations of motor units.

Education

INRIA Nancy Grand-Est/The University of Lorraine, Lorraine, France

Ph.D. in Computer Science,

October 2010-October 2013

- Thesis Topic: Cortical plasticity, dynamic neural fields, and self-organization.
- Area of Study: Computational Neuroscience.

The University of Crete, Heraklion, Greece

M.Sc. in "Brain & Mind Sciences"

January 2007-January 2009

B.Sc. in Applied Mathematics

September 2002-September 2006

Mathematical methods and software development track.

Communication Skills

Languages:

- · Greek-native language,
- · English-full professional proficiency,
- · French-intermediate working proficiency,
- · German-elementary proficiency (dead).

Software Skills

Programming:

- C, C++, Python, Fortran, Java, Pascal, UNIX shell scripting, GNU make, SQL, Matlab/Octave, Maple, HTML, CSS, Bootstrap.
- · Scikit-learn, LAPACK/BLAS, Sundials, OpenMP, Nvidia CUDA, MPI.

Deep Learning Frameworks:

PyTorch, TensorFlow.

Simulators:

Brian, Neuron (Python).

Version Control and Software Configuration Management:

Git and SVN.

Devops:

· Gitlab CI/CD configuration.

Desktop Editing and Productivity Software:

• Vim, TEX (LATEX, BibTEX, Tikz), Microsoft Office, Graphviz, GIMP, Inkscape, Scribus.

Operating Systems:

Linux and BSD, Microsoft Windows family, Apple OS X.

Expertise

Mathematics:

 Linear and Nonlinear Dynamical Systems, Control Theory, Numerical Analysis, Linear Algebra, Probabilities Theory, Theory of Systems and Signals, Information Theory, Optimization, and Empirical Dynamic Modeling.

Computer Science:

Deep Learning, Machine Learning, Neural Networks, Neuromorphic Computing, Software Development, Evolutionary Computing, Theory of Algorithms.

Computational Neuroscience:

• Spiking Neural Networks, Neural Population Models, Mathematical Modeling of Neural Systems.

Software

Major contributor in open source projects in Neuroscience/Machine Learning

 NSAT Is a simulator written in C/Python for the Neural and Synaptic Array Transceiver (NSAT) neuromorphic framework.

Github link: https://github.com/nmi-lab/NSAT

• **NSATcarl** Is a C++ interface of CARLsim (http://www.socsci.uci.edu/~jkrichma/CARLsim/) for the NSAT neuromorphic framework.

Github link: https://github.com/gdetor/CarlNsat

 SPySort Is a Python package for spike sorting. Github link: https://github.com/gdetor/spysort.

Recording Techniques

Noninvasive:

• Electroencephalography (EEG) – Operation of portable EEG device consisting in 18 electrodes.

Invasive:

- Extracellular recordings Set up, calibration and development of software for extracellular recordings using a Plexon Recording Device.
- Electromyography (EMG) Conducting muscle force and motor units (MUs) activity recordings.

Talks

- Biologically plausible contrastive divergence: Towards an abstract complementary learning system, Hughes Research Laboratory (HRL), Malibu CA (USA), 2017.
- Closed-loop deep brain stimulation for Parkinson's disease: A computational study, University of California Irvine, Irvine CA (USA), 2016.
- Neural Fields 101, CenraleSupélec, Gif-sur-Yvette (France), 2015.
- The perception of touch: A computational approach, Aix Marseille University, Marseille (France), 2014.

Publications

- [1] **G. Detorakis**, S. Dutta, A. Khanna, B. Grisafe, S. Datta, and E. Neftci, *Inherent Weight Normalization in Stochastic Neural Networks*, accepted for Poster Presentation in NeurIPS (NIPS) Conference, Vancouver, (Canada), 2019.
- [2] B. U. Pedroni, S. Joshi, S. Deiss, S. Sheik, **G. Detorakis**, S. Paul, C. Augustine, E. Neftci, and G. Cauwenberghs, *Memory-efficient Synaptic Connectivity for Spike-Timing-Dependent Plasticity* accepted for publication in Frontiers in Neuroscience (Neuromorphic Section).
- [3] **G. Detorakis**, T. Bartley, E. Neftci, *Contrastive Hebbian Learning with Random Feedback Weights*, Neural Networks, 114, 2019.
- [4] G. Detorakis, S. Sheik, C. Augustine, S. Paul, B.U. Pedroni, N. Dutt, J. Krichmar, G. Cauwenberghs, E. Neftci, Neural and Synaptic Array Transceiver: A Brain-Inspired Computing Framework for Embedded Learning, Frontiers in Neuroscience (Neuromorphic section) 12, 2018.
- [5] H. Kashyap, G. Detorakis, N. Dutt, J. Krichmar, and E. Neftci, A Recurrent Neural Network Based Model of Predictive Smooth Pursuit Eye Movement in Primates, IJCNN, Rio de Janeiro (Brazil), 2018.
- [6] N.P. Rougier, K. Hinsen, [et al., including **Georgios Detorakis**] *Sustainable computational science: the ReScience initiative*, PeerJ Computer Science 3, 2017.
- [7] E. Neftci, S. Paul, C. Augustine, **G. Detorakis** *Event-Driven Random Back-Propagation: Enabling Neuromorphic Deep Learning Machines*, Frontiers in Neuroscience 11, 2017.
- [8] **G. Detorakis** and A. Chaillet, *Incremental stability of spatiotemporal delayed dynamics and application to neural fields*, CDC, Melbourne (Australia), 2017.
- [9] E. Neftci, C. Augustine, S. Paul, **G. Detorakis**, *Event-Driven Random Backpropagation: Enabling Neuromorphic Deep Learning Machines*, IEEE ISCAS, Baltimore (MD, USA), 2017.
- [10] **G. Detorakis**, [Re] A generalized linear Integrate-and-Fire neural model produces diverse spiking behaviors, The ReScience Journal, 3:1, 2017.

- [11] A. Chaillet, **G. Is. Detorakis**, S. Palfi and S. Senova *Robust stabilization of delayed neural fields with partial measurement and actuation*, Automatica 83, 2017.
- [12] **G.Is. Detorakis**, [Re] Multiple dynamical modes of thalamic relay neurons: rhythmic bursting and intermittent phase-locking, The ReScience Journal, 2:1, 2016.
- [13] B. U. Pedroni, S. Sheik, S. Joshi, G. Detorakis, S. Paul, C. Augustine, E. Neftci, G. Cauwen-berghs, Forward Table-Based Presynaptic Event-Triggered Spike-Timing-Dependent Plasticity, IEEE BioCAS 2016, Shanghai (China), 2016.
- [14] **G.Is. Detorakis**, A. Chaillet, S. Palfi, and S. Senova, *Closed-loop stimulation of a delayed neural fields model of parkinsonian STN-GPe network: a theoretical and computational study*, Frontiers in Neuroscience, 9:237, 2015.
- [15] C. Pouzat and **G.Is. Detorakis**, *SPySort: Neural spike sorting with Python*, Proc. of the 7th Eur. Conf. on Python in Science (Euroscipy 2014), Cambridge (UK), 2014.
- [16] **G.Is. Detorakis** and N.P. Rougier, *Structure of Receptive Fields in a Computational Model of Area 3b of Primary Sensory Cortex*, Frontiers in Computational Neuroscience, 8(76), 2014.
- [17] G. Is. Detorakis Cortical plasticity, dynamic neural fields, and self-organization, University of Lorraine, 2013.
- [18] **G.Is. Detorakis** and N.P. Rougier, *A Neural Field Model of the Somatosensory Cortex: Formation, Maintenance and Reorganization of Ordered Topographic Maps*, PLoS ONE 7(7): e40257, 2012.
- [19] N.P. Rougier and **G.Is. Detorakis**, Self-Organizing Dynamic Neural Fields, Advances in Cognitive Neurodynamics III, Hokaido (Japan), 2012.
- [20] A. Chaillet, **G. Is. Detorakis**, S. Palfi, and S. Senova, *ISS-stabilization of delayed neural fields by small-gain arguments*, to be published in Advances on Delays and Dynamics at Springer.

Book Chapters