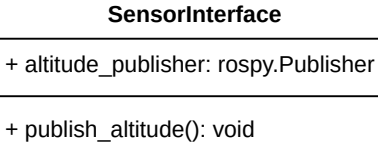


sensor\_interface



**SensorDriver**

+ altitude: float

+ update\_altitude(): void