Graph Data Structures Minimum Spanning Tree

PROF. NAVRATI SAXENA

Problems Specific with Graphs

Minimum Spanning Tree

- Path Problems
 - 1. Simple Paths
 - 2. Shortest Path Problem
 - Single source shortest paths
 - All-pair shortest paths
 - 3. Find Cycles
 - 4. Euler Path and Circuit Problem
 - 5. Hamiltonian Path and Circuit Problem (or TSP)

Spanning Tree

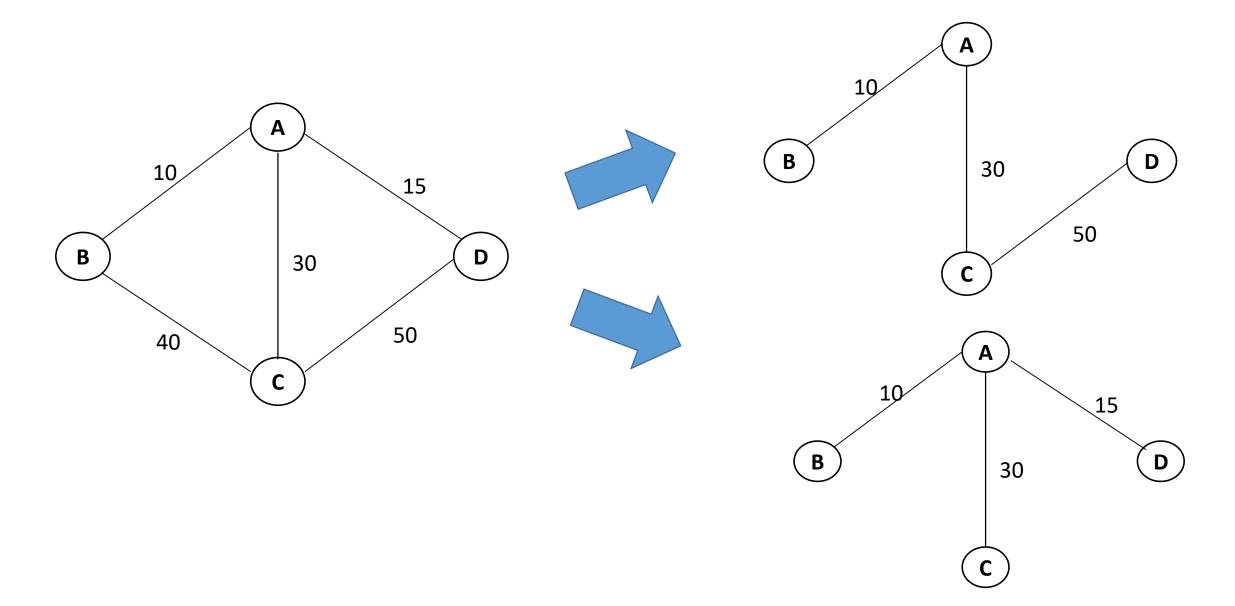
• For a weighted undirected graph, Spanning Tree is a sub-graph that connects all the vertices together using the minimum number of edges required

The graph should be connected: There should be no cycles

• For *n* number of *vertices*, (*n*-1) edges are needed

Hence for four vertices, we need three edges without any cycles

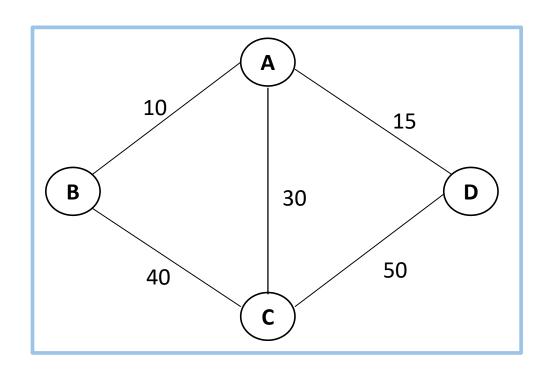
Many Spanning Trees for a Single Graph



Minimum Spanning Tree (MST)

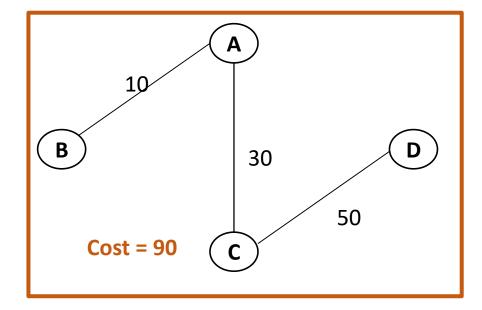
- Cost of any spanning tree: Add weights of all the edges
- Many spanning tress for a single graph
- Calculate cost of all spanning trees and pick the minimum cost spanning tree
 - A tree with minimum weights is MST
- Time complexity: *Exponential*
- Two Algorithms
 - Prim's Algorithm
 - Kruskal's Algorithm

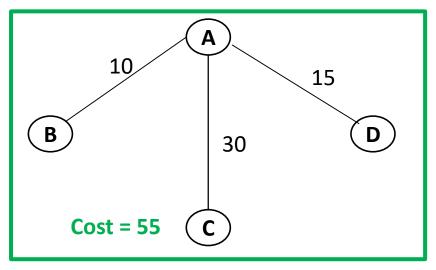
Minimum Spanning Trees











Prim's Algorithm: At a Glance

- Maintains two sets
- MST Set: vertices that are included in the spanning tree
- Set 2: vertices that are not yet included in the spanning tree

Prim's MST Algorithm

- Key Idea: Find the local optimum in the hopes of finding a global optimum.
- Start from one vertex and keep adding edges with the lowest weight until all vertices are reached.

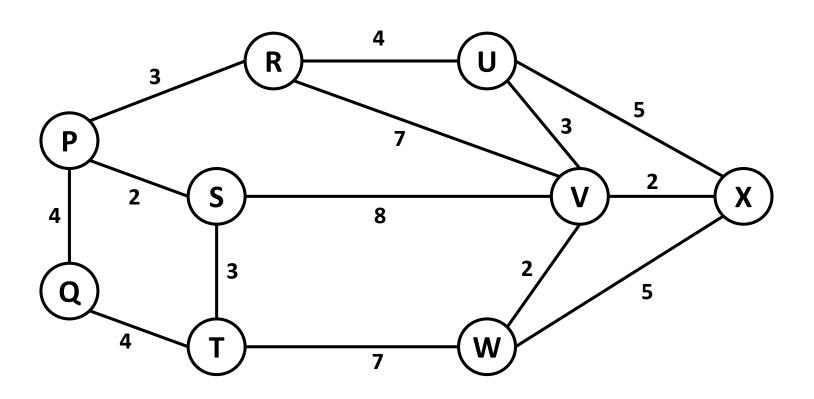
Steps:

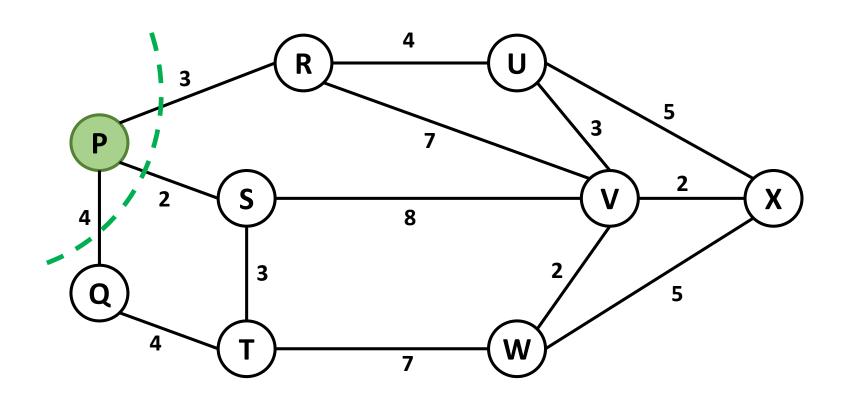
- 1. Initialize the minimum spanning tree with a vertex chosen at random.
- 2. Find all the edges that connect the tree to new vertices, select the minimum and add it to the tree
- 3. Keep repeating step 2 until we get a minimum spanning tree
 - 1. Create an array of size **V** and initialize it with NIL
 - 2. Create a Priority Queue (min Heap) of size *V*. Let the **min Heap be** *Q*
 - 3. Insert all vertices into **Q.** Assign **cost** of starting vertex to **0** and the **cost** of other vertices to infinite.

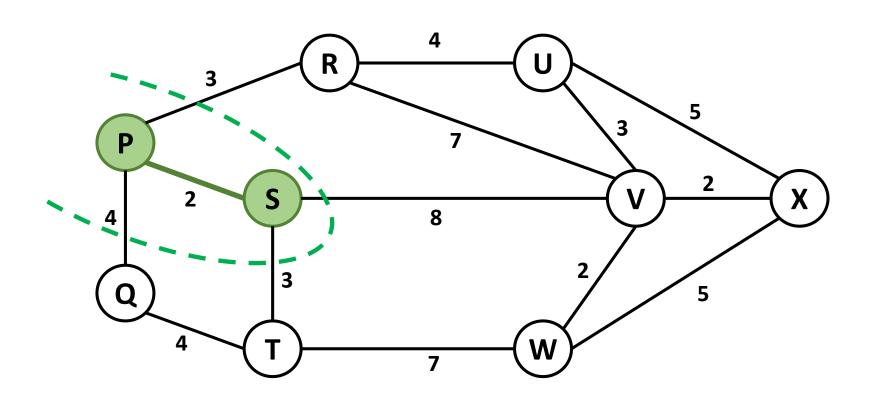
Prim's Algorithm: Pseudo-code

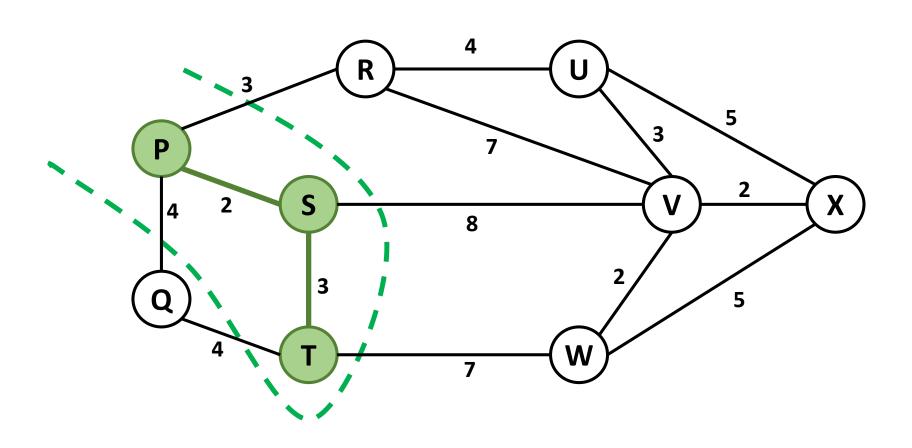
```
MST-PRIM(G, w, source)
1. for each u \in V[G] do // for all vertices
2. cost[u] \leftarrow \infty
3. \pi[u] \leftarrow NULL
4. cost[source] \leftarrow 0
5. Q \leftarrow V[G] // set 2
6. while Q \neq \emptyset do
    u \leftarrow EXTRACT-MIN(Q)
8. for each v \in Adj[u] do
              if v \in Q and w(u, v) < cost[v]
10.
                       \pi[v] \leftarrow u
                       cost[v] \leftarrow w(u, v)
11.
```

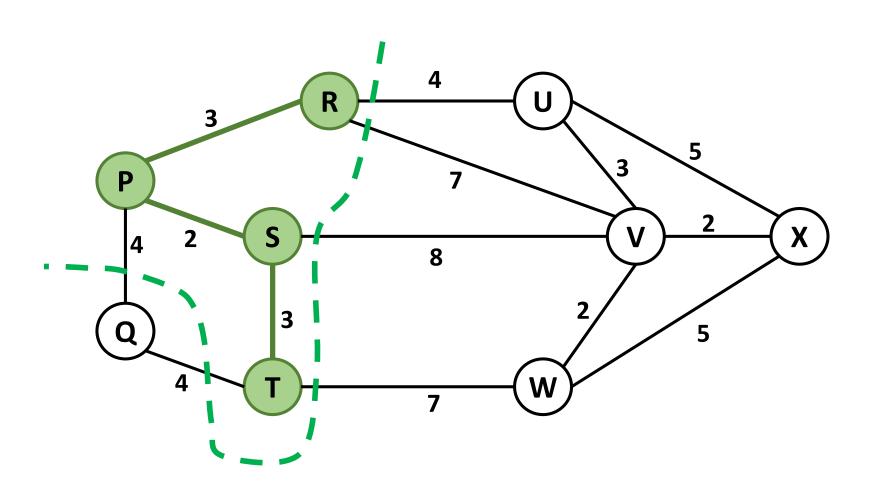
Prim's Algorithm: An Example

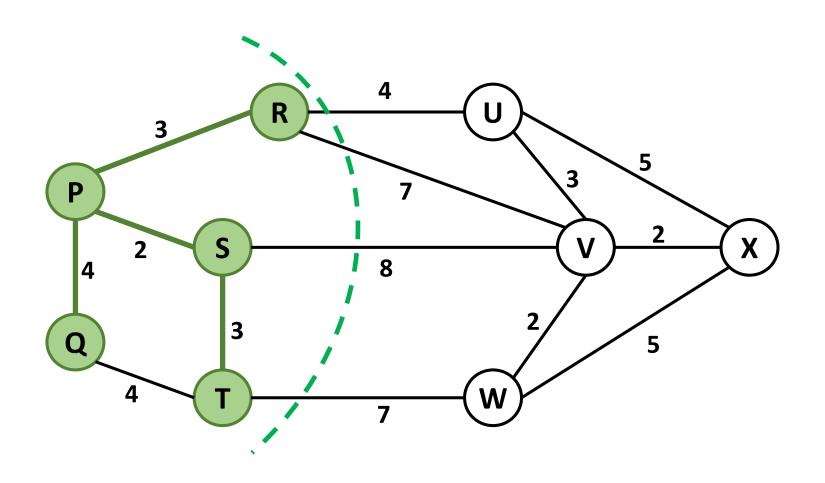


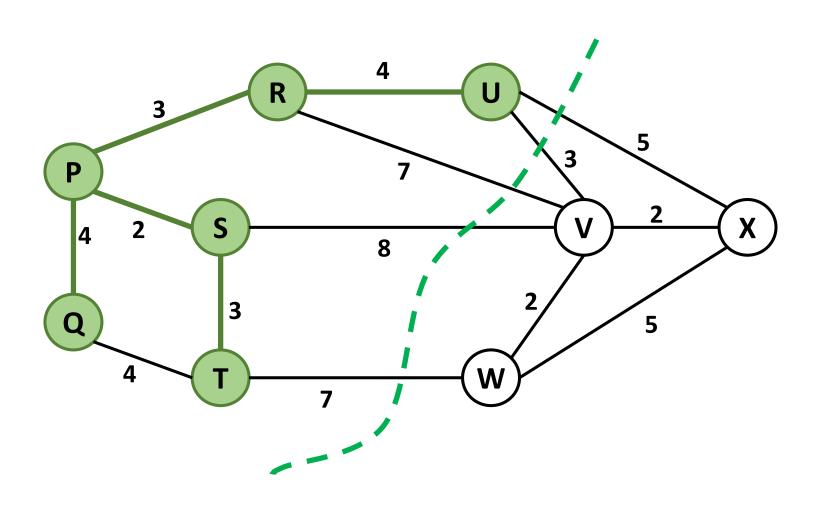


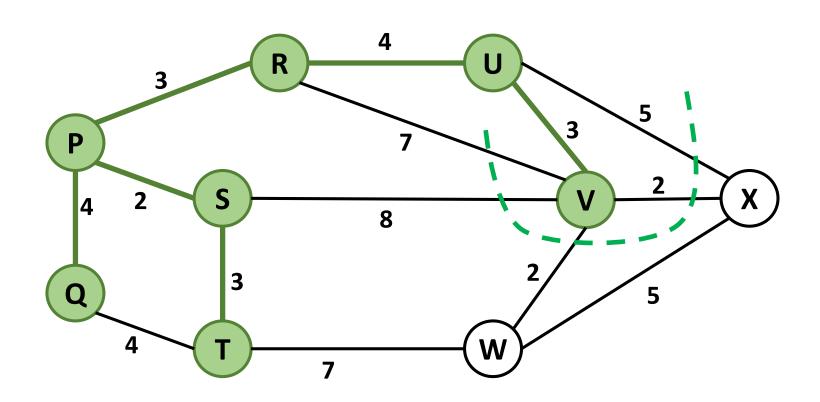


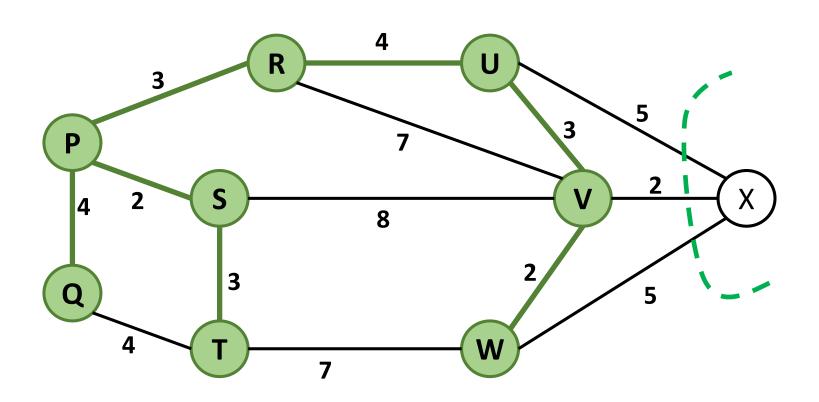


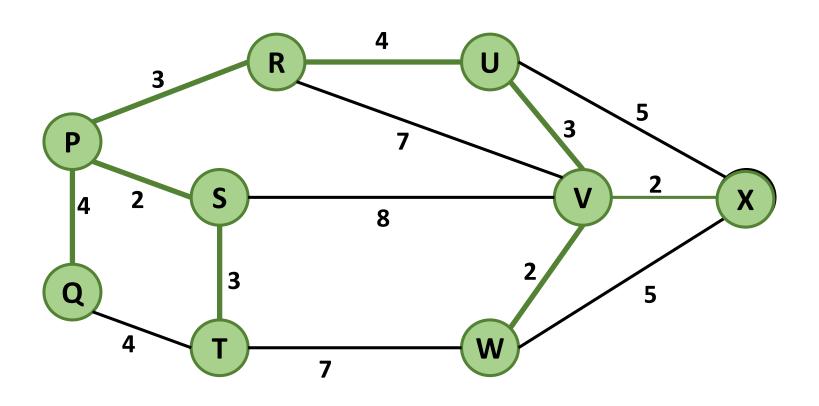












Prim's Algorithm

- The algorithm was developed in 1930 by Czech mathematician Vojtěch Jarník
- Later rediscovered and republished by computer scientists Robert C. Prim in 1957 and Edsger W. Dijkstra in 1959.
- Therefore, it is also sometimes called the Jarník's algorithm, Prim-Jarník algorithm, Prim-Dijkstra algorithm or the DJP algorithm.

Minimum Spanning Trees

- A tree of the nodes of the graph with minimum total edge weight.
- Both Prim's and Kruskal's algorithms are examples of greedy algorithms

Applications

- Reducing copper to connect multiple nodes in a electrical/electronic circuit
- Minimizing network length (cable cost) to connect multiple routers / computers etc.

Thank you!