



# Test Drive

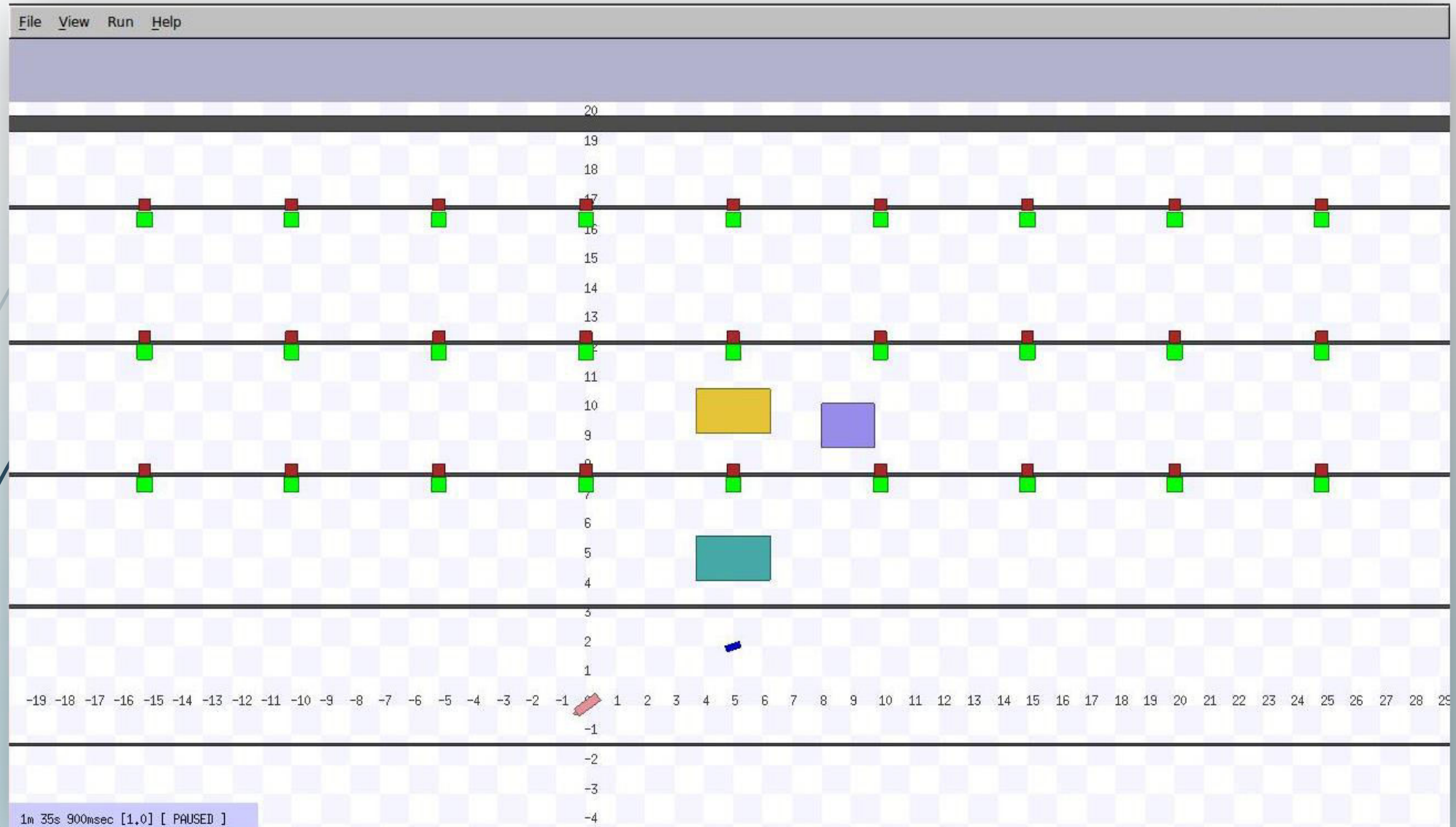
306 Project One Presentation



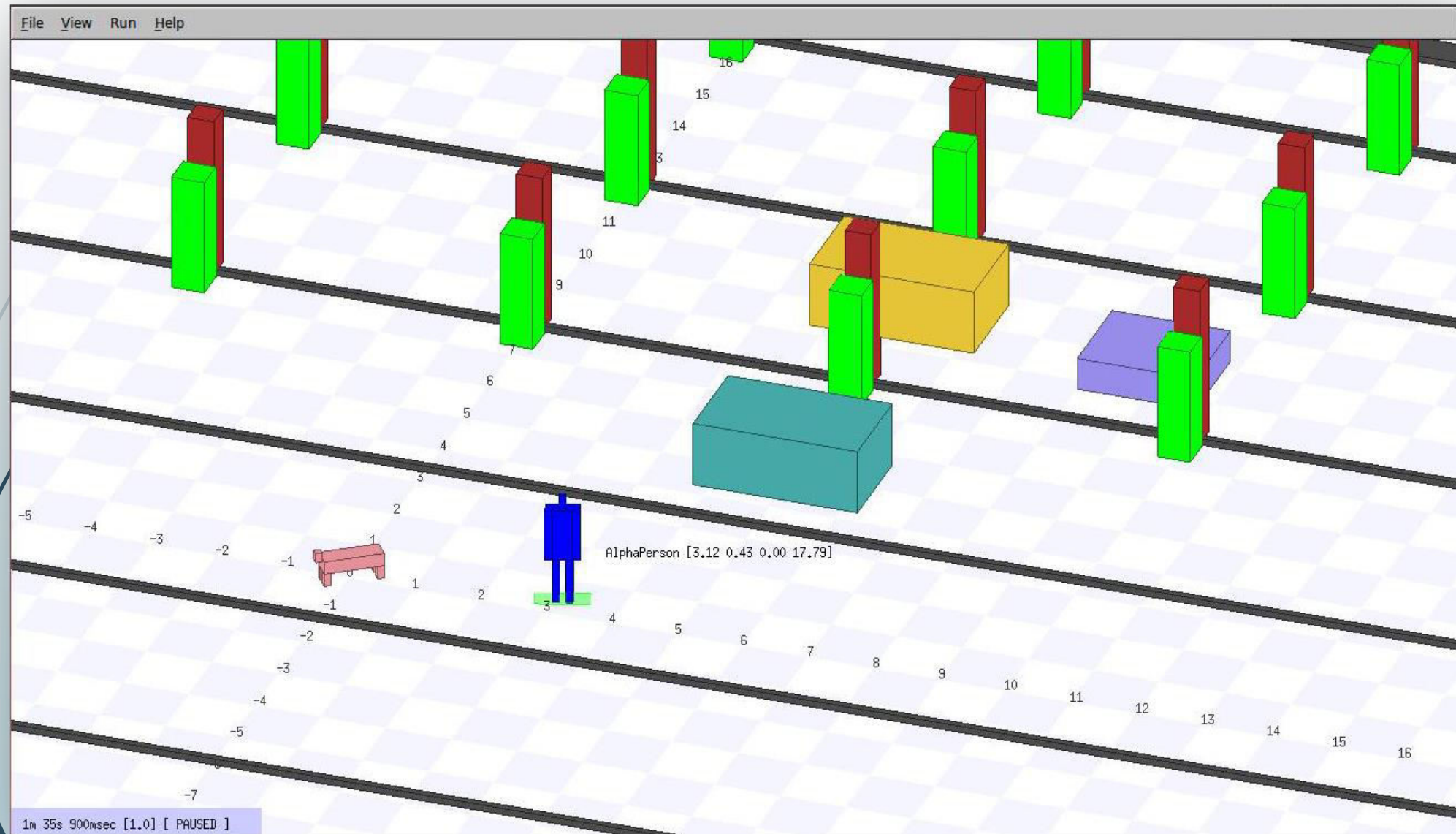
# Delegation of Tasks

- Implementation of agreed Software Design
    - John Law, Nikhil Prasad, Guyver Fu
  - Implementation of Picker & Carrier Robot functions
    - Nikhil Prasad, Guyver Fu
  - Detection of obstacles in the environment
    - Chang Kon Han, Lennon Chan
  - Visualisation of Success & Errors for Debugging & Project Plan
    - Elliot Whiley, Paul Joo
  - Implementation of the behaviour of Environment Objects
    - John Law
  - Gui Design and Model Design of World File
    - Wesley Yep
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# Results Thus Far



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# GUI

