CMP9135M — Computer Vision

1st George Davies

School of Computer Science

University of Lincoln

Lincoln, United Kingdom

27421138@students.lincoln.ac.uk

Abstract— Index Terms—

TASK 1 — IMAGE PROCESSING

Task 1.a — Automated ball objects segmentation

Task 1.b — Segmentation evaluation

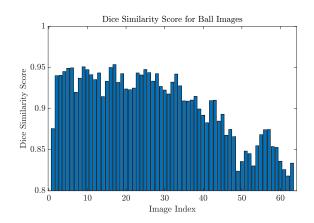


Fig. 1. Dice Similarity score for all 63 images

TASK 2 — FEATURE CALCULATION

Task 2.a — Shape features

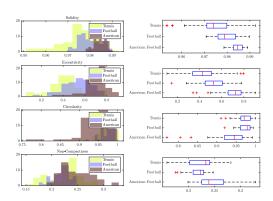


Fig. 2. Shape features

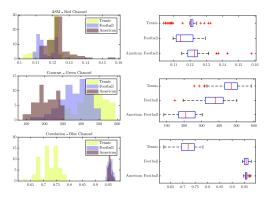


Fig. 3. Texture features Averages

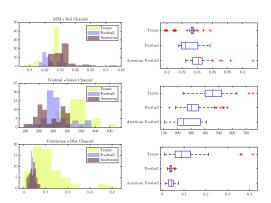


Fig. 4. Texture features Ranges

Task 2.b — Texture features

Task 2.c — Discriminative information

TASK 3 — OBJECT TRACKING

Task 3.a — Kalman filter tracking

Task 3.b — Evaluation

APPENDIX

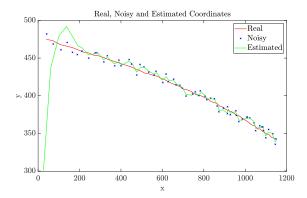
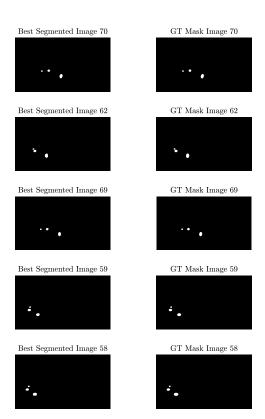


Fig. 5. plot of the estimated trajectory of coordinates [x,y], together with the real [x,y] and the noisy [na,nb] for comparison



Worst Segmented Image 102

Worst Segmented Image 102

GT Mask Image 102

Worst Segmented Image 114

GT Mask Image 114

Worst Segmented Image 106

GT Mask Image 106

GT Mask Image 116

GT Mask Image 116

Fig. 7. Worst 5 segmented ball images compared to the ground truth

Fig. 6. Best 5 segmented ball images compared to the ground truth