

# Weekly Status Report

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Mode of Preparation : Single

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Week Summary	Installation of Minibloq version 0.82 Understanding new features Added Electric Ray Robot as a new hardware in the existing Minibloq. Installed FTDI Drivers for Electric Ray Robot. Uploaded program to Electric Ray Robot to run the motors from Arduino IDE. Coded program to run motors in Minibloq. Uploaded the program to Electric Ray Robot from Minibloq successfully.
Time Spent (hrs)	5
Plan for next week	Blocks for Forward and Backword
Estimated total remaining time	62
Status	On Track
Problems faced	Error avrdude: stk500_getsync(): not in sync: resp=0x00
Solution	This error is what happens when your computer isn't communicating with the Arduino. Disconnect the cables and connect again. Turn the power switch on and upload the code. Program was uploaded successfully.