

Parallel Two-Phase Construction

Parallel Programming in Scala

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- ▶ has an efficient += method

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The *intermediate data structure* is a data structure that:

- ▶ has an efficient combine method $-O(\log n + \log m)$ or better
- has an efficient += method
- ightharpoonup can be converted to the resulting data structure in O(n/P) time

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```
class ArrayCombiner[T <: AnyRef: ClassTag](val parallelism: Int) {
  private var numElems = 0
  private val buffers = new ArrayBuffer[ArrayBuffer[T]]
  buffers += new ArrayBuffer[T]</pre>
```

First, we implement the += method:

```
def +=(x: T) = {
  buffers.last += x
  numElems += 1
  this
}
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Amortized O(1), low constant factors – as efficient as an array buffer.

Next, we implement the combine method:

```
def combine(that: ArrayCombiner[T]) = {
  buffers ++= that.buffers
  numElems += that.numElems
  this
}
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O(P), assuming that buffers contains no more than O(P) nested array buffers.

Finally, we implement the result method:

```
def result: Array[T] = {
  val array = new Array[T](numElems)
  val step = math.max(1, numElems / parallelism)
  val starts = (0 until numElems by step) :+ numElems
  val chunks = starts.zip(starts.tail)
  val tasks = for ((from. end) <- chunks) vield task {</pre>
    copyTo(array, from, end)
  tasks.foreach(_.join())
  arrav
```

Benchmark

Demo – we will test the performance of the aggregate method:

```
xs.par.aggregate(newCombiner)(_ += _, _ combine _).result
```

Two-Phase Construction for Arrays

Two-phase construction works for in a similar way for other data structures. First, partition the elements, then construct parts of the final data structure in parallel:

- 1. partition the indices into subintervals
- 2. initialize the array in parallel

Two-Phase Construction for Hash Tables

- 1. partition the hash codes into buckets
- 2. allocate the table, and map hash codes from different buckets into different regions

Two-Phase Construction for Search Trees

- 1. partition the elements into non-overlapping intervals according to their ordering
- 2. construct search trees in parallel, and link non-overlapping trees

Two-Phase Construction for Spatial Data Structures

- 1. spatially partition the elements
- 2. construct non-overlapping subsets and link them

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 Two-phase construction – the combiner uses an intermediate data structure with an efficient combine method to partition the elements. When result is called, the final data structure is constructed in parallel from the intermediate data structure.

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How can we implement combiners?

- Two-phase construction the combiner uses an intermediate data structure with an efficient combine method to partition the elements. When result is called, the final data structure is constructed in parallel from the intermediate data structure.
- 2. An efficient concatenation or union operation a preferred way when the resulting data structure allows this.
- 3. Concurrent data structure different combiners share the same underlying data structure, and rely on *synchronization* to correctly update the data structure when += is called.