Classifier To Predicting Primary Contributory Cause of Car Crashes in Chicago

Final Project Submission

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Student pace:

Part time

Scheduled project review date/time:

Instructor name:

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1. Business problem

1.1. Objective

The goal is to develop a machine learning classifier capable of predicting the primary contributory cause of car accidents in Chicago. By accurately identifying these causes, the City of Chicago and the Vehicle Safety Board can take targeted actions to enhance road safety and reduce the frequency and severity of car accidents.

1.2. Stakeholder

The primary stakeholders for this project are:

City of Chicago: The city's traffic management and road safety departments will utilize the insights to improve traffic safety measures.

Vehicle Safety Board: This board will use the data to formulate policies, launch safety campaigns, and improve vehicular regulations.

1.3. Business Problem

The primary business problem to be addressed is the high rate of car accidents in Chicago. By identifying and understanding the leading causes of these accidents, the city can implement specific interventions. These might include:

- -Enhancing road infrastructure.
- -Introducing stricter traffic regulations.
- -Running educational campaigns targeting high-risk behaviors.

-Improving emergency response protocols.

2. Understand The Data

2.1.Data Source:

Chicago Car Crashes dataset(Traffic Crashes - Crashes 20240516.csv).

2.2.Features:

CRASH_DATE: Useful for extracting temporal features like month and day.

POSTED SPEED LIMIT: Speed limits influence crash dynamics.

TRAFFIC CONTROL DEVICE: Type of traffic control device.

DEVICE_CONDITION: Condition of the traffic control device.

WEATHER_CONDITION: Weather conditions during the crash.

LIGHTING_CONDITION: Lighting conditions during the crash.

FIRST_CRASH_TYPE: Type of the first crash.

TRAFFICWAY TYPE: Type of trafficway.

ALIGNMENT: Road alignment.

ROADWAY SURFACE COND: Roadway surface condition.

ROAD DEFECT: Any road defects present.

REPORT_TYPE: Type of crash report.

CRASH_TYPE: Overall crash type.

DAMAGE: Damage severity.

CRASH_HOUR: Hour of the day when the crash occurred.

CRASH_DAY_OF_WEEK: Day of the week when the crash occurred.

CRASH MONTH: Month when the crash occurred.

NUM UNITS: Number of units (vehicles) involved.

LATITUDE: Latitude of the crash location.

LONGITUDE: Longitude of the crash location.

2.3. Target Variable:

Primary contributory cause of the accident (multi-class classification problem).

Hypothesis

The primary contributory cause of car accidents in Chicago can be accurately predicted using a machine learning classifier that analyzes various factors including:

- -Weather Conditions Hypothesis: Adverse weather conditions (e.g., rain, snow, fog) significantly increase the likelihood of specific contributory causes of car accidents, such as slippery road surfaces and reduced visibility.
- -Road Surface Condition Hypothesis: Poor road surface conditions (e.g., potholes, wet surfaces) are strongly associated with specific types of accidents, such as vehicle skidding and tire blowouts.
- -Time of Day Hypothesis: The time of day (e.g., rush hour, nighttime) significantly influences the primary contributory causes, with factors like reduced visibility at night or higher traffic volumes during rush hour playing a crucial role.

```
In [2]: #loading the dataset.This project uses Chicago car crash dataset.
df = pd.read_csv(r"C:\Users\Caro\Downloads\Traffic_Crashes_-_Crashes_20
```

```
In [3]: #explore the datasets
    df.info()
```

<class 'pandas.core.frame.DataFrame'>
RangeIndex: 455416 entries, 0 to 455415
Data columns (total 48 columns):

Data	columns (total 48 columns):		
#	Column	Non-Null Count	Dtype
0	CRASH_RECORD_ID	455416 non-null	object
1	CRASH_DATE_EST_I	33893 non-null	object
2	CRASH_DATE	455412 non-null	object
3	POSTED_SPEED_LIMIT	455412 non-null	float64
4	TRAFFIC_CONTROL_DEVICE	455412 non-null	object
5	DEVICE_CONDITION	455412 non-null	object
6	WEATHER_CONDITION	455412 non-null	object
7	LIGHTING_CONDITION	455412 non-null	object
8	FIRST_CRASH_TYPE	455412 non-null	object
9	TRAFFICWAY_TYPE	455412 non-null	object
10	LANE_CNT	105503 non-null	float64
11	ALIGNMENT	455412 non-null	object
12	ROADWAY_SURFACE_COND	455412 non-null	object
13	ROAD_DEFECT	455412 non-null	object
14	REPORT_TYPE	440668 non-null	object
15	CRASH_TYPE	455412 non-null	object
16	INTERSECTION_RELATED_I	104186 non-null	object
17	NOT_RIGHT_OF_WAY_I	21117 non-null	object
18	HIT_AND_RUN_I	142486 non-null	object
19	DAMAGE	455412 non-null	object
20	DATE_POLICE_NOTIFIED	455412 non-null	object
21	PRIM_CONTRIBUTORY_CAUSE	455412 non-null	object
22	SEC_CONTRIBUTORY_CAUSE	455412 non-null	object
23	STREET_NO	455412 non-null	float64
24	STREET_DIRECTION	455409 non-null	object
25	STREET_NAME	455411 non-null	object
26	BEAT_OF_OCCURRENCE	455409 non-null	float64
27	PHOTOS_TAKEN_I	6059 non-null	object
28	STATEMENTS_TAKEN_I	10403 non-null	object
29	DOORING_I	1387 non-null	object
30	WORK_ZONE_I	2626 non-null	object
31	WORK_ZONE_TYPE	2014 non-null	object
32	WORKERS_PRESENT_I	699 non-null	object
33	NUM UNITS	455412 non-null	float64
34	MOST_SEVERE_INJURY	454331 non-null	object
35	INJURIES TOTAL	454342 non-null	float64
36	INJURIES_FATAL	454342 non-null	float64
37	INJURIES_INCAPACITATING	454342 non-null	float64
38	INJURIES_NON_INCAPACITATING	454342 non-null	float64
39	INJURIES_REPORTED_NOT_EVIDENT	454342 non-null	float64
40	INJURIES NO INDICATION	454342 non-null	float64
41	INJURIES_UNKNOWN	454342 non-null	float64
42	CRASH HOUR	455412 non-null	float64
43	CRASH_DAY_OF_WEEK	455412 non-null	object
44	CRASH_MONTH	455411 non-null	float64
45	LATITUDE	449632 non-null	float64
46	LONGITUDE	449632 non-null	float64
47	LOCATION	449632 non-null	object
	es: float64(16), object(32))

dtypes: float64(16), object(32)

memory usage: 166.8+ MB

check the first five elements

In [4]:

df.head() Out[4]: CRASH_RECORD_ID CRASH_DATE_EST_I CRASH DAT 09/05/202 0 23a79931ef555d54118f64dc9be2cf2dbf59636ce253f7... NaN 07:05:00 P 09/22/202 1 2675c13fd0f474d730a5b780968b3cafc7c12d7adb661f... NaN 06:45:00 P 07/29/202 2 5f54a59fcb087b12ae5b1acff96a3caf4f2d37e79f8db4... NaN 02:45:00 P 08/09/202 3 7ebf015016f83d09b321afd671a836d6b148330535d5df... NaN 11:00:00 P 08/18/202 6c1659069e9c6285a650e70d6f9b574ed5f64c12888479... NaN 12:50:00 P 5 rows × 48 columns # check the last five elements In [5]: df.tail() Out[5]: CRASH_RECORD_ID CRASH_DATE_EST_I CRAS 09 **455411** 853eaa096088487ee500121138be38cd31e5b93925ddaf... NaN 06:0 455412 "error": true NaN "message": "Internal error" 455413 NaN 455414 "status" : 500 NaN 455415 } NaN 5 rows × 48 columns df.describe() In [6]: Out[6]: POSTED_SPEED_LIMIT **BEAT_OF_OCCURRENCE** LANE_CNT STREET_NO 455409.000000 count 455412.000000 1.055030e+05 455412.000000 28.396285 1.795405e+01 3682.557390 1244.663990 mean 6.169818 3.903997e+03 2924.608106 704.793876 std 0.000000 0.000000e+00 0.000000 min 111.000000 25% 714.000000 30.000000 2.000000e+00 1238.000000 50% 30.000000 2.000000e+00 3200.000000 1212.000000 75% 30.000000 4.000000e+00 5569.000000 1822.000000 99.000000 1.191625e+06 451100.000000 6100.000000 max

```
In [7]:  # Check unique values for each column
for column in df.columns:
    unique_values = df[column].unique()
    print(f"Column '{column}' has {len(unique_values)} unique values")
    print(unique_values[::]) #all unique values for every column
    print("\n")
```

```
Column 'CRASH RECORD ID' has 455416 unique values
['23a79931ef555d54118f64dc9be2cf2dbf59636ce253f7a1179c4a1c091442a6eeab
8352220c7c56ca1ff7c4b4b0fc345c74e3e85ecb9d43deeb66b5f803d4a0'
 '2675c13fd0f474d730a5b780968b3cafc7c12d7adb661fa8a3093c0658d5a0d51b72
0fc9e031a1ddd83c761a8e2aa7283573557db246f4c9e956aaa58719cacf
 '5f54a59fcb087b12ae5b1acff96a3caf4f2d37e79f8db4106558b34b8a6d2b81af02
cf91b576ecd7ced08ffd10fcfd940a84f7613125b89d33636e6075064e22'
 ... ' "message" : "Internal error" ' "status" : 500' '}']
Column 'CRASH_DATE_EST_I' has 3 unique values
[nan 'Y' 'N']
Column 'CRASH_DATE' has 346504 unique values
['09/05/2023 07:05:00 PM' '09/22/2023 06:45:00 PM'
 '07/29/2023 02:45:00 PM' ... '04/08/2018 05:00:00 AM'
 '09/28/2023 06:05:00 AM' nan]
Column 'POSTED SPEED LIMIT' has 44 unique values
[30. 50. 15. 25. 10. 35. 20. 55. 45. 5. 40. 0. 60. 3. 65. 39. 9. 2
2.
70. 14. 34. 33. 6. 24. 1. 23. 99. 11. 26. 32. 12. 2. 7. 49. 8. 3
6.
63. 29. 38. 16. 44. 62. 4. nan]
Column 'TRAFFIC_CONTROL_DEVICE' has 20 unique values
['TRAFFIC SIGNAL' 'NO CONTROLS' 'OTHER' 'UNKNOWN' 'OTHER WARNING SIGN'
 'STOP SIGN/FLASHER' 'PEDESTRIAN CROSSING SIGN' 'OTHER REG. SIGN' 'YIE
LD'
 'LANE USE MARKING' 'RAILROAD CROSSING GATE' 'FLASHING CONTROL SIGNAL'
 'SCHOOL ZONE' 'POLICE/FLAGMAN' 'DELINEATORS' 'OTHER RAILROAD CROSSIN
G'
 'RR CROSSING SIGN' 'NO PASSING' 'BICYCLE CROSSING SIGN' nan]
Column 'DEVICE CONDITION' has 9 unique values
['FUNCTIONING PROPERLY' 'NO CONTROLS' 'FUNCTIONING IMPROPERLY' 'UNKNOW
N'
 'OTHER' 'NOT FUNCTIONING' 'MISSING' 'WORN REFLECTIVE MATERIAL' nan]
Column 'WEATHER_CONDITION' has 13 unique values
['CLEAR' 'SNOW' 'RAIN' 'UNKNOWN' 'CLOUDY/OVERCAST' 'FOG/SMOKE/HAZE'
 'BLOWING SNOW' 'FREEZING RAIN/DRIZZLE' 'OTHER' 'SEVERE CROSS WIND GAT
E'
 'SLEET/HAIL' 'BLOWING SAND, SOIL, DIRT' nan]
Column 'LIGHTING_CONDITION' has 7 unique values
['DUSK' 'DARKNESS, LIGHTED ROAD' 'DAYLIGHT' 'DARKNESS' 'UNKNOWN' 'DAW
Ν'
nan]
Column 'FIRST_CRASH_TYPE' has 19 unique values
['ANGLE' 'REAR END' 'PARKED MOTOR VEHICLE' 'SIDESWIPE SAME DIRECTION'
 'PEDESTRIAN' 'FIXED OBJECT' 'TURNING' 'SIDESWIPE OPPOSITE DIRECTION'
 'REAR TO FRONT' 'HEAD ON' 'REAR TO SIDE' 'PEDALCYCLIST' 'OTHER OBJEC
```

```
'ANIMAL' 'REAR TO REAR' 'OTHER NONCOLLISION' 'OVERTURNED' 'TRAIN' na
n]
Column 'TRAFFICWAY TYPE' has 21 unique values
['FIVE POINT, OR MORE' 'DIVIDED - W/MEDIAN BARRIER'
 'DIVIDED - W/MEDIAN (NOT RAISED)' 'NOT DIVIDED' 'OTHER' 'ONE-WAY'
 'PARKING LOT' 'T-INTERSECTION' 'RAMP' 'FOUR WAY' 'UNKNOWN' 'ALLEY'
 'UNKNOWN INTERSECTION TYPE' 'DRIVEWAY' 'TRAFFIC ROUTE' 'NOT REPORTED'
 'CENTER TURN LANE' 'L-INTERSECTION' 'Y-INTERSECTION' 'ROUNDABOUT' na
n]
Column 'LANE_CNT' has 33 unique values
          nan 2.000000e+00 4.000000e+00 0.000000e+00 8.000000e+00
 6.000000e+00 3.000000e+00 1.000000e+00 1.100000e+01 2.200000e+01
 1.600000e+01 5.000000e+00 1.000000e+01 9.900000e+01 4.000000e+01
 9.000000e+00 1.300000e+01 1.400000e+01 7.000000e+00 2.000000e+01
 1.200000e+01 1.500000e+01 2.800000e+01 4.100000e+01 4.336340e+05
 2.500000e+01 3.000000e+01 3.500000e+01 1.191625e+06 6.000000e+01
 1.900000e+01 4.000000e+02 2.100000e+01]
Column 'ALIGNMENT' has 7 unique values
['STRAIGHT AND LEVEL' 'CURVE ON GRADE' 'CURVE, LEVEL' 'STRAIGHT ON GRA
DE'
 'STRAIGHT ON HILLCREST' 'CURVE ON HILLCREST' nan]
Column 'ROADWAY_SURFACE_COND' has 8 unique values
['DRY' 'SNOW OR SLUSH' 'WET' 'UNKNOWN' 'OTHER' 'ICE' 'SAND, MUD, DIRT'
nan]
Column 'ROAD_DEFECT' has 8 unique values
['NO DEFECTS' 'UNKNOWN' 'DEBRIS ON ROADWAY' 'OTHER' 'WORN SURFACE'
 'SHOULDER DEFECT' 'RUT, HOLES' nan]
Column 'REPORT_TYPE' has 4 unique values
['ON SCENE' 'NOT ON SCENE (DESK REPORT)' nan 'AMENDED']
Column 'CRASH_TYPE' has 3 unique values
['INJURY AND / OR TOW DUE TO CRASH' 'NO INJURY / DRIVE AWAY' nan]
Column 'INTERSECTION_RELATED_I' has 3 unique values
['Y' nan 'N']
Column 'NOT_RIGHT_OF_WAY_I' has 3 unique values
[nan 'Y' 'N']
Column 'HIT_AND_RUN_I' has 3 unique values
[nan 'Y' 'N']
Column 'DAMAGE' has 4 unique values
```

```
['OVER $1,500' '$501 - $1,500' '$500 OR LESS' nan]
```

```
Column 'DATE POLICE NOTIFIED' has 384044 unique values
['09/05/2023 07:05:00 PM' '09/22/2023 06:50:00 PM'
 '07/29/2023 02:45:00 PM' ... '05/12/2023 04:21:00 PM'
 '09/28/2023 06:08:00 AM' nan]
Column 'PRIM CONTRIBUTORY CAUSE' has 41 unique values
['UNABLE TO DETERMINE' 'FOLLOWING TOO CLOSELY'
 AY'
 'NOT APPLICABLE' 'WEATHER' 'IMPROPER BACKING'
 'IMPROPER TURNING/NO SIGNAL' 'DRIVING SKILLS/KNOWLEDGE/EXPERIENCE'
 'IMPROPER LANE USAGE'
 'VISION OBSCURED (SIGNS, TREE LIMBS, BUILDINGS, ETC.)'
 'ROAD ENGINEERING/SURFACE/MARKING DEFECTS'
 'EQUIPMENT - VEHICLE CONDITION' 'IMPROPER OVERTAKING/PASSING'
 'RELATED TO BUS STOP' 'DISREGARDING TRAFFIC SIGNALS'
 'DRIVING ON WRONG SIDE/WRONG WAY' 'DISREGARDING ROAD MARKINGS'
 'DISTRACTION - FROM INSIDE VEHICLE' 'ANIMAL'
 'ROAD CONSTRUCTION/MAINTENANCE' 'TEXTING'
 'CELL PHONE USE OTHER THAN TEXTING' 'DISREGARDING OTHER TRAFFIC SIGN
S'
 'DISREGARDING STOP SIGN' 'EXCEEDING AUTHORIZED SPEED LIMIT'
 'OPERATING VEHICLE IN ERRATIC, RECKLESS, CARELESS, NEGLIGENT OR AGGRE
SSIVE MANNER'
 'DISTRACTION - FROM OUTSIDE VEHICLE' 'PHYSICAL CONDITION OF DRIVER'
 'EXCEEDING SAFE SPEED FOR CONDITIONS' 'DISREGARDING YIELD SIGN'
 'TURNING RIGHT ON RED'
 'UNDER THE INFLUENCE OF ALCOHOL/DRUGS (USE WHEN ARREST IS EFFECTED)'
 'EVASIVE ACTION DUE TO ANIMAL, OBJECT, NONMOTORIST'
 'HAD BEEN DRINKING (USE WHEN ARREST IS NOT MADE)'
 'DISTRACTION - OTHER ELECTRONIC DEVICE (NAVIGATION DEVICE, DVD PLAYE
R, ETC.)'
 'OBSTRUCTED CROSSWALKS' 'BICYCLE ADVANCING LEGALLY ON RED LIGHT'
 'PASSING STOPPED SCHOOL BUS' 'MOTORCYCLE ADVANCING LEGALLY ON RED LIG
HT'
nan]
Column 'SEC CONTRIBUTORY CAUSE' has 41 unique values
['NOT APPLICABLE' 'FOLLOWING TOO CLOSELY'
 'OPERATING VEHICLE IN ERRATIC, RECKLESS, CARELESS, NEGLIGENT OR AGGRE
SSIVE MANNER'
 'DISTRACTION - FROM INSIDE VEHICLE' 'UNABLE TO DETERMINE' 'WEATHER'
 'FAILING TO YIELD RIGHT-OF-WAY' 'DRIVING SKILLS/KNOWLEDGE/EXPERIENCE'
 'FAILING TO REDUCE SPEED TO AVOID CRASH' 'IMPROPER OVERTAKING/PASSIN
G'
 'IMPROPER TURNING/NO SIGNAL' 'DISREGARDING STOP SIGN'
 'ROAD CONSTRUCTION/MAINTENANCE' 'IMPROPER LANE USAGE'
 'DISTRACTION - FROM OUTSIDE VEHICLE' 'DISREGARDING TRAFFIC SIGNALS'
 'DRIVING ON WRONG SIDE/WRONG WAY'
 'VISION OBSCURED (SIGNS, TREE LIMBS, BUILDINGS, ETC.)'
 'EQUIPMENT - VEHICLE CONDITION' 'IMPROPER BACKING'
 'PHYSICAL CONDITION OF DRIVER' 'EXCEEDING SAFE SPEED FOR CONDITIONS'
 'BICYCLE ADVANCING LEGALLY ON RED LIGHT'
 'EXCEEDING AUTHORIZED SPEED LIMIT'
 'DISTRACTION - OTHER ELECTRONIC DEVICE (NAVIGATION DEVICE, DVD PLAYE
R, ETC.)'
```

```
'UNDER THE INFLUENCE OF ALCOHOL/DRUGS (USE WHEN ARREST IS EFFECTED)'
```

Column 'STREET_NO' has 11074 unique values [5500. 7900. 2101. ... 8473. 3889. nan]

Column 'STREET_DIRECTION' has 5 unique values ['S' 'W' 'E' 'N' nan]

Column 'STREET_NAME' has 1568 unique values ['WENTWORTH AVE' 'CHICAGO SKYWAY OB' 'ASHLAND AVE' ... 'MANILA AVE' 'CARROLL DR' 'KINZUA AVE']

```
Column 'BEAT_OF_OCCURRENCE' has 277 unique values
[ 225. 411. 1235. 1650. 1654. 1655. 1652. 1131. 424. 1814. 2221.
2.
1034. 1651. 222. 1211. 1653. 1712. 731. 1822. 2525. 423.
                                                         533.
                                                                33
1.
 925. 824. 1811. 1121. 434. 412. 1023. 2511. 1433. 1214.
                                                          914. 242
1012. 2222. 1613. 1513. 431. 822. 825. 1031. 924. 833. 2521. 191
 912. 811. 523. 1215. 323. 2512. 1834. 813. 723. 1522. 2032. 101
1.
1622. 913. 1411. 2024. 2213. 2223. 1924. 1925. 834. 221. 2232. 163
1934. 334. 433. 711. 2522. 621. 1414. 622.
                                               932. 122. 2413. 142
1022. 1621. 313. 132. 2523. 324. 111. 1033. 231. 1412. 1531. 163
1623. 1722. 2212. 421. 1112. 524. 1224. 414. 1013. 2234. 735. 143
 921. 114. 1914. 2411. 1631. 224. 815. 1233. 2532. 1823. 2022.
5.
2513. 6100. 1912. 322. 1421. 1922. 2033. 1434. 1231. 1113. 614. 102
2023. 935. 321. 1135. 2432. 915. 1711. 623. 1733. 1123. 1221. 112
 223. 1813. 2012. 1111. 312. 1533. 812. 1212. 311. 631. 2531. 103
1524. 432. 2533. 2524. 1724. 1222. 1234. 1911. 131. 1432. 923. 121
3.
1732. 821. 1611. 1731. 1832. 234. 612. 2013. 611.
                                                    nan 1232. 91
1931. 2515. 1014. 1821. 934. 734. 2535. 511. 1225. 1413. 2514.
                                                               41
                              214. 722. 235. 1713. 712. 1632. 241
 332. 1723. 2534. 1134.
                        215.
2.
```

624. 1133. 832. 1935. 422. 931. 1921. 1624. 2431. 1422. 634.

^{&#}x27;ROAD ENGINEERING/SURFACE/MARKING DEFECTS'

^{&#}x27;EVASIVE ACTION DUE TO ANIMAL, OBJECT, NONMOTORIST' 'ANIMAL'

^{&#}x27;DISREGARDING ROAD MARKINGS' 'DISREGARDING OTHER TRAFFIC SIGNS'

^{&#}x27;CELL PHONE USE OTHER THAN TEXTING'

^{&#}x27;HAD BEEN DRINKING (USE WHEN ARREST IS NOT MADE)' 'TURNING RIGHT ON R

^{&#}x27;PASSING STOPPED SCHOOL BUS' 'RELATED TO BUS STOP'

^{&#}x27;MOTORCYCLE ADVANCING LEGALLY ON RED LIGHT' 'DISREGARDING YIELD SIGN'

^{&#}x27;TEXTING' 'OBSTRUCTED CROSSWALKS' nan]

```
3.
1523. 112. 532. 124. 2233. 133. 2422. 1933. 726. 725. 233. 92
2.
 933. 814. 1532. 1125. 1115. 1824. 333. 733. 2211. 1124. 714. 181
2.
2031. 2011. 513. 1512. 512. 724. 1423. 632. 2424. 1833. 613. 113
1932. 1614. 522. 213. 1915. 212. 314. 1831. 1923. 1511. 1612. 21
2433. 713. 823. 1024. 1114. 531. 633. 715. 121. 1223. 831. 73
2.
 113.]
Column 'PHOTOS_TAKEN_I' has 3 unique values
[nan 'Y' 'N']
Column 'STATEMENTS_TAKEN_I' has 3 unique values
[nan 'Y' 'N']
Column 'DOORING_I' has 3 unique values
[nan 'Y' 'N']
Column 'WORK_ZONE_I' has 3 unique values
[nan 'Y' 'N']
Column 'WORK_ZONE_TYPE' has 5 unique values
[nan 'CONSTRUCTION' 'UTILITY' 'UNKNOWN' 'MAINTENANCE']
Column 'WORKERS_PRESENT_I' has 3 unique values
[nan 'Y' 'N']
Column 'NUM_UNITS' has 16 unique values
[ 2. 4. 1. 3. 5. 6. 7. 8. 12. 16. 9. 11. 10. 14. 18. nan]
Column 'MOST_SEVERE_INJURY' has 6 unique values
['INCAPACITATING INJURY' 'NO INDICATION OF INJURY'
 'NONINCAPACITATING INJURY' 'FATAL' 'REPORTED, NOT EVIDENT' nan]
Column 'INJURIES_TOTAL' has 20 unique values
[ 3. 0. 1. 2. 5. nan 4. 6. 15. 7. 12. 9. 8. 10. 21. 11. 17. 1
4.
19. 13.]
Column 'INJURIES_FATAL' has 5 unique values
[ 0. 1. nan 2. 3.]
Column 'INJURIES_INCAPACITATING' has 8 unique values
[ 1. 0. 5. nan 2. 3. 4. 6.]
```

```
Column 'INJURIES_NON_INCAPACITATING' has 18 unique values
[ 2. 0. 1. 5. nan 3. 4. 6. 7. 8. 11. 10. 21. 14. 12. 19. 9. 1
8.]
Column 'INJURIES_REPORTED_NOT_EVIDENT' has 14 unique values
[ 0. 2. nan 1. 3. 5. 4. 10. 6. 7. 11. 8. 9. 15.]
Column 'INJURIES NO INDICATION' has 45 unique values
[ 2. 1. 5. 3. 0. 4. 8. 7. nan 6. 15. 11. 20. 10. 18. 27. 9. 1
3.
12. 26. 29. 14. 41. 16. 37. 22. 30. 50. 21. 17. 42. 46. 24. 61. 38. 1
9.
48. 34. 31. 43. 45. 40. 36. 23. 28.]
Column 'INJURIES_UNKNOWN' has 2 unique values
[ 0. nan]
Column 'CRASH_HOUR' has 25 unique values
[19. 18. 14. 23. 12. 8. 17. 16. 15. 13. 10. 0. 6. 5. 22. 11. 21.
9.
20. 1. 7. 2. 3. 4. nan]
Column 'CRASH DAY OF WEEK' has 16 unique values
[3 6 7 4 2 1 5 '5' '2' '1' '7' '3' '6' '4' '{ nan ]
Column 'CRASH_MONTH' has 13 unique values
[ 9. 7. 8. 11. 2. 1. 10. 12. 5. 6. 3. 4. nan]
Column 'LATITUDE' has 202996 unique values
        nan 41.85412026 41.80978115 ... 41.89840746 41.75704136
41.93763777]
Column 'LONGITUDE' has 202997 unique values
         nan -87.66590234 -87.59421281 ... -87.72114211 -87.54764299
 -87.75990493]
Column 'LOCATION' has 203097 unique values
[nan 'POINT (-87.665902342962 41.854120262952)'
 'POINT (-87.594212812011 41.809781151018)' ...
 'POINT (-87.721142109818 41.898407459204)'
 'POINT (-87.547642985901 41.757041359914)'
 'POINT (-87.759904933396 41.937637767663)']
```

```
In [8]: M #check for duplicated rows

df[df.duplicated()]

#there are 0 duplicated rows

Out[8]: CRASH_RECORD_ID CRASH_DATE_EST_I CRASH_DATE POSTED_SPEED_LIMIT TRA

0 rows × 48 columns

In [9]: M # check the shape of the data
df.shape

Out[9]: (455416, 48)

In [10]: M #Create a deep copy of the DataFrame
df_copy= df.copy(deep=True)
```

3. Data Preparation

3.1. Data Cleaning

```
In [11]: #create another dataframe for cleaning
df_new = pd.read_csv(r"C:\Users\Caro\Downloads\Traffic_Crashes_-_Crashes
```

3.1.1. Handling missing values

| | = | |
|----------|-----------------------------------|--------|
| Out[12]: | CRASH_RECORD_ID | 0 |
| | CRASH_DATE_EST_I | 421523 |
| | CRASH_DATE | 4 |
| | POSTED_SPEED_LIMIT | 4 |
| | TRAFFIC_CONTROL_DEVICE | 4 |
| | DEVICE_CONDITION | 4 |
| | WEATHER_CONDITION | 4 |
| | LIGHTING_CONDITION | 4 |
| | FIRST_CRASH_TYPE | 4 |
| | TRAFFICWAY_TYPE | 4 |
| | LANE_CNT | 349913 |
| | ALIGNMENT | 4 |
| | ROADWAY_SURFACE_COND | 4 |
| | ROAD_DEFECT | 4 |
| | REPORT_TYPE | 14748 |
| | CRASH_TYPE | 4 |
| | <pre>INTERSECTION_RELATED_I</pre> | 351230 |
| | NOT_RIGHT_OF_WAY_I | 434299 |
| | HIT_AND_RUN_I | 312930 |
| | DAMAGE | 4 |
| | DATE_POLICE_NOTIFIED | 4 |
| | PRIM_CONTRIBUTORY_CAUSE | 4 |
| | SEC_CONTRIBUTORY_CAUSE | 4 |
| | STREET_NO | 4 |
| | STREET_DIRECTION | 7 |
| | STREET_NAME | 5 |
| | BEAT_OF_OCCURRENCE | 7 |
| | PHOTOS_TAKEN_I | 449357 |
| | STATEMENTS_TAKEN_I | 445013 |
| | DOORING_I | 454029 |
| | WORK_ZONE_I | 452790 |
| | WORK_ZONE_TYPE | 453402 |
| | WORKERS_PRESENT_I | 454717 |
| | NUM_UNITS | 4 |
| | MOST_SEVERE_INJURY | 1085 |
| | INJURIES_TOTAL | 1074 |
| | INJURIES_FATAL | 1074 |
| | INJURIES_INCAPACITATING | 1074 |
| | INJURIES_NON_INCAPACITATING | 1074 |
| | INJURIES_REPORTED_NOT_EVIDENT | 1074 |
| | INJURIES_NO_INDICATION | 1074 |
| | INJURIES_UNKNOWN | 1074 |
| | CRASH_HOUR | 4 |
| | CRASH_DAY_OF_WEEK | 4 |
| | CRASH_MONTH | 5 |
| | LATITUDE | 5784 |
| | LONGITUDE | 5784 |
| | LOCATION | 5784 |
| | dtype: int64 | |

```
# List of columns to drop
In [13]:
             columns_to_drop = ['CRASH_RECORD_ID','CRASH_DATE_EST_I','LANE_CNT','INT
                                 'MOST_SEVERE_INJURY', 'INJURIES_TOTAL', 'INJURIES_FATA
                                 'INJURIES_REPORTED_NOT_EVIDENT', 'INJURIES_NO_INDICAT!
                                 'PHOTOS_TAKEN_I', 'STATEMENTS_TAKEN_I', 'DOORING_I', 'WO
                                 'FIRST_CRASH_TYPE', 'TRAFFICWAY_TYPE', 'ALIGNMENT', 'RO
                                 'BEAT_OF_OCCURRENCE', 'SEC_CONTRIBUTORY_CAUSE', 'DATE_
             # Drop the specified columns
             df_new = df_new.drop(columns=columns_to_drop)
                                                                                     \blacktriangleright
          #3. Impute numerical columns with mean
In [14]:
             numerical_cols = ['POSTED_SPEED_LIMIT','NUM_UNITS','CRASH_HOUR','CRASH_I
             for col in numerical_cols:
                 df_new[col].fillna(df_new[col].mean(), inplace=True)
In [15]:
          # Store the original shape of the DataFrame
             original_shape = df_new.shape[0]
             # Convert 'CRASH_DATE' column to datetime format
             df_new['CRASH_DATE'] = pd.to_datetime(df_new['CRASH_DATE'], errors='coe
             # Find unique values in the 'CRASH_DATE' column that are not valid date:
             invalid_dates = df_new['CRASH_DATE'][~df_new['CRASH_DATE'].notnull() &
             # Drop rows with invalid dates
             df_new = df_new[~df_new['CRASH_DATE'].isin(invalid_dates)]
             # Check if any rows were dropped
             dropped_rows = original_shape - df_new.shape[0]
             print(f"Dropped {dropped_rows} rows with invalid dates.")
             Dropped 4 rows with invalid dates.
In [16]:
             #4. Impute categorical columns with mode
             categorical cols = [
                 'TRAFFIC_CONTROL_DEVICE', 'DEVICE_CONDITION', 'WEATHER_CONDITION',
                 'LIGHTING_CONDITION', 'ROADWAY_SURFACE_COND', 'CRASH_DAY_OF_WEEK',
                 'CRASH_TYPE', 'PRIM_CONTRIBUTORY_CAUSE'
             for col in categorical_cols:
                 df new[col].fillna(df new[col].mode()[0], inplace=True)
```

```
▶ #5. Fill Geospatial missing values with the mean of the column
In [17]:
             df_new['LATITUDE'].fillna(df_new['LATITUDE'].mean(), inplace=True)
             df_new['LONGITUDE'].fillna(df_new['LONGITUDE'].mean(), inplace=True)
             # Recreate the LOCATION column
             df_new['LOCATION'] = df_new.apply(
                 lambda row: f"({row['LATITUDE']}, {row['LONGITUDE']})",
                 axis=1
             )
In [18]:
          ▶ #Check for missing values after dropping
             df_new.isna().sum()
   Out[18]: CRASH_DATE
                                         0
             POSTED_SPEED_LIMIT
                                        0
             TRAFFIC_CONTROL_DEVICE
                                        0
             DEVICE_CONDITION
                                         0
             WEATHER_CONDITION
                                        0
             LIGHTING_CONDITION
                                        0
             ROADWAY_SURFACE_COND
             CRASH_TYPE
                                        0
             PRIM CONTRIBUTORY CAUSE
             NUM_UNITS
                                         a
             CRASH HOUR
                                        0
             CRASH_DAY_OF_WEEK
             CRASH MONTH
                                        0
             LATITUDE
                                        0
             LONGITUDE
                                        0
             LOCATION
                                        0
             dtype: int64
In [19]:
          #new shape after cleaning
             df new.shape
   Out[19]: (455412, 16)
In [20]:
          #new columns after cleaning
             df new.columns
   Out[20]: Index(['CRASH_DATE', 'POSTED_SPEED_LIMIT', 'TRAFFIC_CONTROL_DEVICE',
                     'DEVICE_CONDITION', 'WEATHER_CONDITION', 'LIGHTING_CONDITION',
                    'ROADWAY_SURFACE_COND', 'CRASH_TYPE', 'PRIM_CONTRIBUTORY_CAUS
             Ε',
                    'NUM_UNITS', 'CRASH_HOUR', 'CRASH_DAY_OF_WEEK', 'CRASH_MONTH',
                    'LATITUDE', 'LONGITUDE', 'LOCATION'],
                   dtype='object')
```

3.1.2. Data Type conversions

```
In [21]:
             # Convert object columns to category to optimize memory and improve per
             category_columns = [
                 'TRAFFIC_CONTROL_DEVICE', 'DEVICE_CONDITION', 'WEATHER_CONDITION',
                 'LIGHTING_CONDITION', 'ROADWAY_SURFACE_COND', 'CRASH_TYPE',
                 'PRIM_CONTRIBUTORY_CAUSE', 'CRASH_DAY_OF_WEEK', 'LOCATION'
             for col in category_columns:
                 df_new[col] = df_new[col].astype('category')
             #Crash-records will not be converted since its a unique identifier
In [22]:
          # Convert numerical columns with integer values to reduce memory usage
             integer_columns = [
                 'POSTED_SPEED_LIMIT', 'NUM_UNITS',
                 'CRASH_HOUR', 'CRASH_MONTH'
             for col in integer columns:
                 df_new[col] = pd.to_numeric(df_new[col], downcast='integer', errors
In [23]:
          # Select integer columns
             integer_columns = df_new.select_dtypes(include='int64').columns
             # Convert integer columns to int32
             df_new[integer_columns] = df_new[integer_columns].astype('int32')
             # Convert float columns to integer
             float_columns = df_new.select_dtypes(include=['float']).columns
             df_new[float_columns] = df_new[float_columns].astype(int)
```

```
In [24]: # checking if the conversions were effective
df_new.info()

<class 'pandas.core.frame.DataFrame'>
```

```
Index: 455412 entries, 0 to 455411
Data columns (total 16 columns):
    Column
                            Non-Null Count
                                            Dtype
    ----
0
    CRASH_DATE
                            455412 non-null datetime64[ns]
    POSTED SPEED LIMIT
                            455412 non-null int8
1
    TRAFFIC_CONTROL_DEVICE 455412 non-null category
                            455412 non-null category
3
    DEVICE_CONDITION
4
    WEATHER_CONDITION
                          455412 non-null category
5
    LIGHTING_CONDITION
                           455412 non-null category
    ROADWAY_SURFACE_COND
                            455412 non-null category
6
7
    CRASH TYPE
                            455412 non-null category
    PRIM_CONTRIBUTORY_CAUSE 455412 non-null category
                            455412 non-null int8
9
    NUM UNITS
                            455412 non-null int8
10 CRASH HOUR
                          455412 non-null category
11 CRASH_DAY_OF_WEEK
                           455412 non-null int32
12 CRASH MONTH
                            455412 non-null int32
13 LATITUDE
                            455412 non-null int32
14 LONGITUDE
                            455412 non-null category
15 LOCATION
dtypes: category(9), datetime64[ns](1), int32(3), int8(3)
memory usage: 28.3 MB
```

3.1.3. Feauture Engineering

```
In [25]: # Convert 'CRASH_DATE' column to datetime format
df_new['CRASH_DATE'] = pd.to_datetime(df_new['CRASH_DATE'], errors='coe

# Check if 'CRASH_DATE' column is properly converted
print(df_new['CRASH_DATE'].dtype)

# Now, you can perform the feature engineering
# Feature engineering: Date and Time Features
df_new['CRASH_YEAR'] = df_new['CRASH_DATE'].dt.year
df_new['CRASH_MONTH'] = df_new['CRASH_DATE'].dt.month
df_new['CRASH_DAY'] = df_new['CRASH_DATE'].dt.day
df_new['CRASH_DAY_OF_WEEK'] = df_new['CRASH_DATE'].dt.dayofweek
df_new['CRASH_HOUR'] = df_new['CRASH_DATE'].dt.hour
```

datetime64[ns]

In [26]: # Print the first few rows to verify the result
df_new[['CRASH_DATE', 'CRASH_YEAR', 'CRASH_MONTH', 'CRASH_DAY', 'CRASH_I

| Out[26]: | | CRASH_DATE | CRASH_YEAR | CRASH_MONTH | CRASH_DAY | CRASH_DAY_OF_WEEK |
|----------|---|------------------------|------------|-------------|-----------|-------------------|
| | 0 | 2023-09-05
19:05:00 | 2023 | 9 | 5 | 1 |
| | 1 | 2023-09-22
18:45:00 | 2023 | 9 | 22 | 4 |
| | 2 | 2023-07-29
14:45:00 | 2023 | 7 | 29 | 5 |
| | 3 | 2023-08-09
23:00:00 | 2023 | 8 | 9 | 2 |
| | 4 | 2023-08-18
12:50:00 | 2023 | 8 | 18 | 4 |
| | 4 | | | | | • |

```
In [27]: # Interaction Features to capture relationships between different varial
# Create interaction feature: POSTED_SPEED_LIMIT * DEVICE_CONDITION

df_new['SPEED_DEVICE_CONDITION'] = df_new['POSTED_SPEED_LIMIT'] * df_new

# Create interaction feature: WEATHER_CONDITION * LIGHTING_CONDITION

df_new['WEATHER_LIGHTING_CONDITION'] = df_new['WEATHER_CONDITION'].cat.org

df_new
```

| ıt[27]: | | CRASH_DATE | POSTED_SPEED_LIMIT | TRAFFIC_CONTROL_DEVICE | DEVICE_CO | |
|---------|--------------------------|------------------------|--------------------|------------------------|-------------------------|--|
| | 0 | 2023-09-05
19:05:00 | 30 | TRAFFIC SIGNAL | FUNC [.]
PR | |
| | 1 | 2023-09-22
18:45:00 | 50 | NO CONTROLS | NO CO | |
| | 2 | 2023-07-29
14:45:00 | 30 | TRAFFIC SIGNAL | FUNC [·]
PR | |
| | 3 | 2023-08-09
23:00:00 | 30 | NO CONTROLS | NO CO | |
| | 4 | 2023-08-18
12:50:00 | 15 | OTHER | FUNC [.]
PR | |
| | | | | | | |
| | 455407 | 2018-04-13
18:08:00 | 30 | NO CONTROLS | NO CO | |
| | 455408 | 2022-08-12
19:31:00 | 15 | NO CONTROLS | NO CO | |
| | 455409 | 2018-04-08
05:00:00 | 20 | NO CONTROLS | NOT FUNC | |
| | 455410 | 2023-05-12
14:30:00 | 35 | STOP SIGN/FLASHER | NO CO | |
| | 455411 | 2023-09-28
06:05:00 | 30 | TRAFFIC SIGNAL | FUNC [*]
PR | |
| | 455412 rows × 20 columns | | | | | |
| | 4 | | | | • | |

4. Exploratory Data Analysis

In [28]:

1. Summary Statistics

summary_stats = df_new.describe()
summary_stats

Out[28]:

| | CRASH_DATE | POSTED_SPEED_LIMIT | NUM_UNITS | CRASH_HOUR | CRASI |
|-------|----------------------------------|--------------------|---------------|---------------|-------|
| count | 455412 | 455412.000000 | 455412.000000 | 455412.000000 | |
| mean | 2020-08-01
19:04:37.228926464 | 28.396285 | 2.034367 | 13.201036 | |
| min | 2013-06-01
20:29:00 | 0.000000 | 1.000000 | 0.000000 | |
| 25% | 2018-08-25
18:52:30 | 30.000000 | 2.000000 | 9.000000 | |
| 50% | 2020-08-05
06:00:00 | 30.000000 | 2.000000 | 14.000000 | |
| 75% | 2022-08-16
17:15:45 | 30.000000 | 2.000000 | 17.000000 | |
| max | 2024-05-15
23:42:00 | 99.000000 | 18.000000 | 23.000000 | |
| std | NaN | 6.169818 | 0.454028 | 5.571367 | |
| 4 | | | | | • |

4.1. Univarate Analysis

4.1.1 Primary Contributory Cause(Target Variable)

```
PRIM CONTRIBUTORY CAUSE
UNABLE TO DETERMINE
178000
FAILING TO YIELD RIGHT-OF-WAY
50060
FOLLOWING TOO CLOSELY
44170
NOT APPLICABLE
24382
IMPROPER OVERTAKING/PASSING
FAILING TO REDUCE SPEED TO AVOID CRASH
19062
IMPROPER BACKING
17763
IMPROPER LANE USAGE
16400
DRIVING SKILLS/KNOWLEDGE/EXPERIENCE
IMPROPER TURNING/NO SIGNAL
DISREGARDING TRAFFIC SIGNALS
8883
WEATHER
6841
OPERATING VEHICLE IN ERRATIC, RECKLESS, CARELESS, NEGLIGENT OR AGGRESS
IVE MANNER
                5912
DISREGARDING STOP SIGN
4810
DISTRACTION - FROM INSIDE VEHICLE
3101
EQUIPMENT - VEHICLE CONDITION
2897
PHYSICAL CONDITION OF DRIVER
VISION OBSCURED (SIGNS, TREE LIMBS, BUILDINGS, ETC.)
DRIVING ON WRONG SIDE/WRONG WAY
2433
UNDER THE INFLUENCE OF ALCOHOL/DRUGS (USE WHEN ARREST IS EFFECTED)
DISTRACTION - FROM OUTSIDE VEHICLE
ROAD ENGINEERING/SURFACE/MARKING DEFECTS
1139
EXCEEDING AUTHORIZED SPEED LIMIT
DISREGARDING OTHER TRAFFIC SIGNS
973
ROAD CONSTRUCTION/MAINTENANCE
923
EXCEEDING SAFE SPEED FOR CONDITIONS
860
EVASIVE ACTION DUE TO ANIMAL, OBJECT, NONMOTORIST
CELL PHONE USE OTHER THAN TEXTING
566
DISREGARDING ROAD MARKINGS
HAD BEEN DRINKING (USE WHEN ARREST IS NOT MADE)
502
```

```
ANIMAL
418
TURNING RIGHT ON RED
393
RELATED TO BUS STOP
242
DISTRACTION - OTHER ELECTRONIC DEVICE (NAVIGATION DEVICE, DVD PLAYER, ETC.) 223
TEXTING
174
DISREGARDING YIELD SIGN
148
PASSING STOPPED SCHOOL BUS
60
OBSTRUCTED CROSSWALKS
45
BICYCLE ADVANCING LEGALLY ON RED LIGHT
42
MOTORCYCLE ADVANCING LEGALLY ON RED LIGHT
11
```


15097

15034

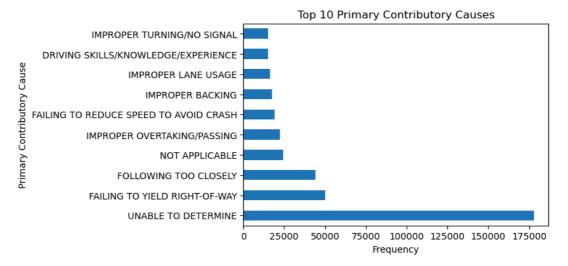
Out[56]: PRIM_CONTRIBUTORY_CAUSE UNABLE TO DETERMINE 178000 FAILING TO YIELD RIGHT-OF-WAY 50060 FOLLOWING TOO CLOSELY 44170 NOT APPLICABLE 24382 IMPROPER OVERTAKING/PASSING 22357 FAILING TO REDUCE SPEED TO AVOID CRASH 19062 IMPROPER BACKING 17763 IMPROPER LANE USAGE 16400

DRIVING SKILLS/KNOWLEDGE/EXPERIENCE

IMPROPER TURNING/NO SIGNAL
Name: count, dtype: int64

Name: count, dtype: int64

```
In [55]:  #Frequency of 10 contributory cause
# Get the top ten contributory causes
top_10_causes = df_new['PRIM_CONTRIBUTORY_CAUSE'].value_counts().nlarge
# Plot the top ten contributory causes
plt.figure(figsize=(6, 4))
top_10_causes.plot(kind='barh')
plt.title('Top 10 Primary Contributory Causes')
plt.ylabel('Primary Contributory Cause')
plt.xlabel('Frequency')
plt.show()
```



4.1.2. Numeric Variables

```
In [40]:
                   # distribution of numerical columns
                   fig, axs = plt.subplots(ncols=4, nrows=3, figsize=(10, 10))
                   for ax, col in zip(axs.ravel(), df_new.select_dtypes(include='number').
                         sns.histplot(df_new[col], kde=True, ax=ax)
                         ax.set_xlabel('Value')
                         ax.set_ylabel('Frequency')
                         ax.set_title(f'Dist of {col}')
                   plt.tight_layout()
                   plt.show()
                       Dist of POSTED_SPEED_LIMIT
                                                    Dist of NUM_UNITS
                                                                           Dist of CRASH_HOUR
                                                                                                Dist of CRASH DAY OF WEEK
                                                 3.0
                                                                       35000
                                                                                                70000
                        1.2
                                                                        30000
                                                 2.5
                                                                                                60000
                        1.0
                                                                       25000
                                               Lednency
1.5
                                                                                                50000
                        0.8
                                                                       20000
                                                                                                40000
                                                                     Ē 15000
                        0.6
                                                                                                30000
                                                 1.0
                        0.4
                                                                       10000
                                                                                                20000
                                                 0.5
                                                                                                10000
                        0.2
                                                                        5000
                                                 0.0
                                                           10
                                                               15
                                                                                   10
                                                                                        20
                                                                                                     0.0
                                                                                                                5.0
                                                    Dist of LATITUDE
                                                                            Dist of LONGITUDE
                         Dist of CRASH MONTH
                                                                                                    Dist of CRASH YEAR
                                                                          1.2
                      40000
                                                                                                60000
                                                 2.5
                                                                                                50000
                      30000
                                                 2.0
                                                                         0.8
                                                                                                40000
                    Frequency
                                                 1.5
                      20000
                                                                          0.6
                                                                                                30000
                                                 1.0
                                                                          0.4
                                                                                                20000
                      10000
                                                 0.5
                                                                          0.2
                                                                                                10000
                                                 0.0
                                                                          0.0
                                      10
                                                          20
                                                                                  -50
                                                                                                       2015
                                                                                                             2020
                                                                                                           Value
                                                          Value
                                                                                  Value
                                             Dist of SPEED_DEVICE_CONDITIONWEATHER_LIGHTING_CONDITION 1.0
                           Dist of CRASH DAY
                                                                       350000
                                              175000
                      15000
                                                                       300000
                                              150000
                                                                                                  0.8
                      12500
                                                                      250000
                                              125000
                      10000
                                                                                                  0.6
                                                                      200000
                                              100000
                       7500
                                                                      150000
                                               75000
                                                                                                  0.4
                                                                       100000
                                               50000
                                                                                                  0.2
                                                                       50000
                                               25000
```

20

Value

-100

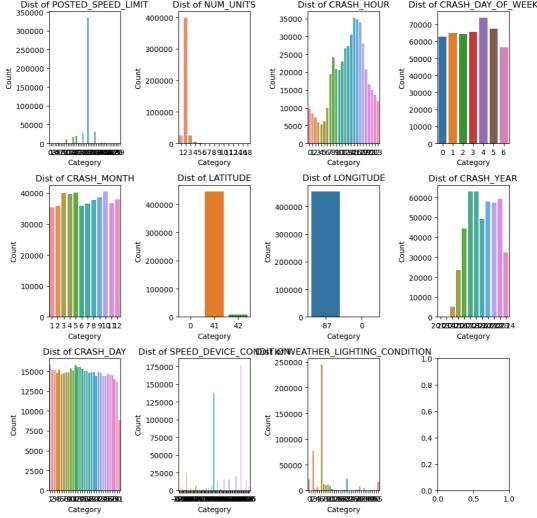
Value

100

Value

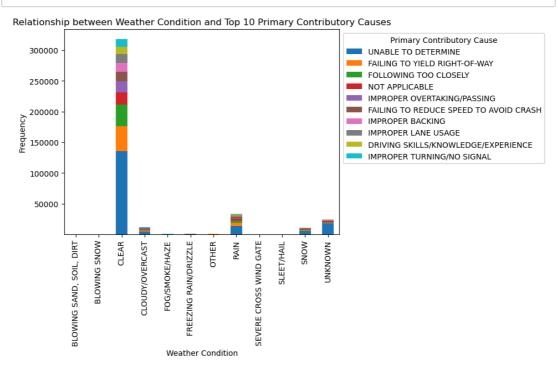
4.1.3. Categorical Variables

```
In [41]:
              # distribution of numerical columns
               fig, axs = plt.subplots(ncols=4, nrows=3, figsize=(10, 10))
               for ax, col in zip(axs.ravel(), df_new.select_dtypes(include='number').
                   sns.countplot(data=df_new, x=col, ax=ax,)
                   ax.set_xlabel('Category')
                   ax.set_ylabel('Count')
                   ax.set_title(f'Dist of {col}')
              plt.tight_layout()
              plt.show()
                 Dist of POSTED_SPEED_LIMIT
                                        Dist of NUM_UNITS
                                                          Dist of CRASH_HOUR
                                                                           Dist of CRASH_DAY_OF_WEEK
                                    400000
                                                        35000
                                                                           70000
                                                        30000
                                                                           60000
```



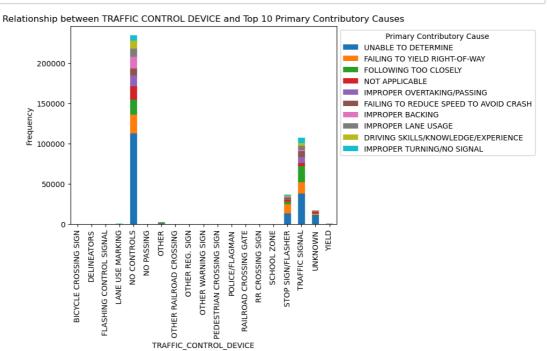
4.2 Bivaret Analysis

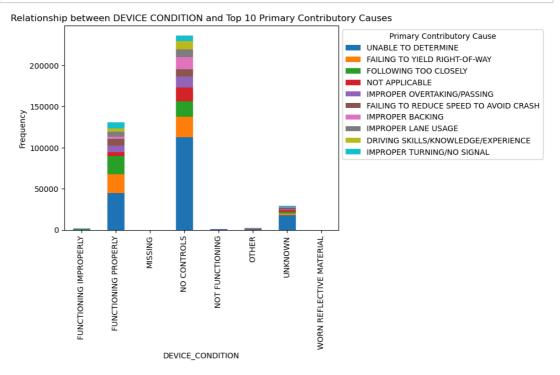
4.2.1. Categorical vs Categorical

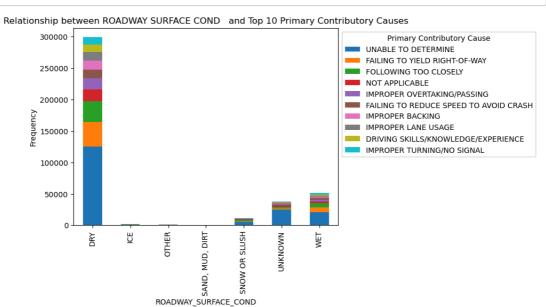


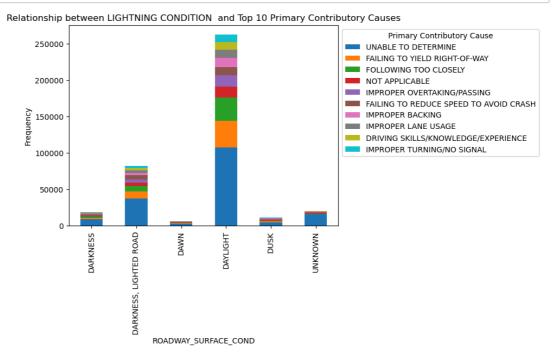
```
In [43]:  #Relationship between Weather Condition and Top 10 Primary Contributory
# Create a cross-tabulation table
cross_tab = pd.crosstab(df_new['TRAFFIC_CONTROL_DEVICE'], df_new['PRIM_c
# Calculate the top 10 primary contributory causes
top_10_causes = df_new['PRIM_CONTRIBUTORY_CAUSE'].value_counts().nlarge:
# Filter the cross-tabulation table to include only the top 10 causes
cross_tab_top_10 = cross_tab[top_10_causes]

# Plot the clustered bar chart
cross_tab_top_10.plot(kind='bar', stacked=True)
plt.title('Relationship between TRAFFIC CONTROL DEVICE and Top 10 Primar
plt.xlabel('TRAFFIC_CONTROL_DEVICE')
plt.ylabel('Frequency')
plt.legend(title='Primary Contributory Cause', loc='upper left', bbox_toplt.show()
```



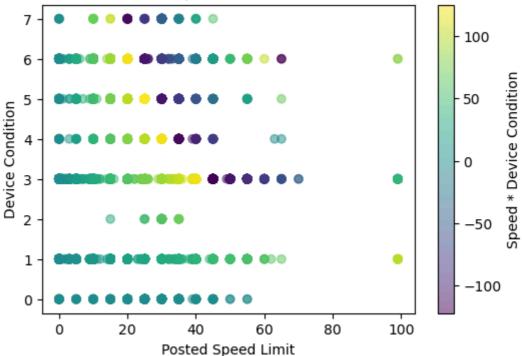






4.2.2. Numerical vs Categorical

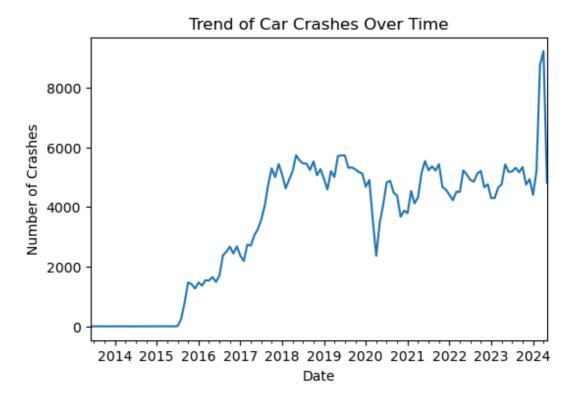
Interaction between Speed Limit and Device Condition



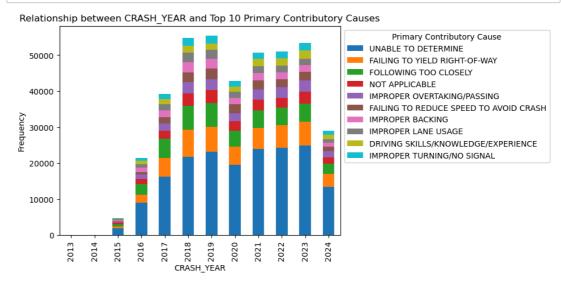
4.2.3. Categorical vs Date/Time

In [49]: # Trend of car crash over time
 df_new.assign(CRASH_DATE=pd.to_datetime(df_new['CRASH_DATE'])).resample
 title='Trend of Car Crashes Over Time', xlabel='Date', ylabel='Number or

Out[49]: <Axes: title={'center': 'Trend of Car Crashes Over Time'}, xlabel='Dat
 e', ylabel='Number of Crashes'>

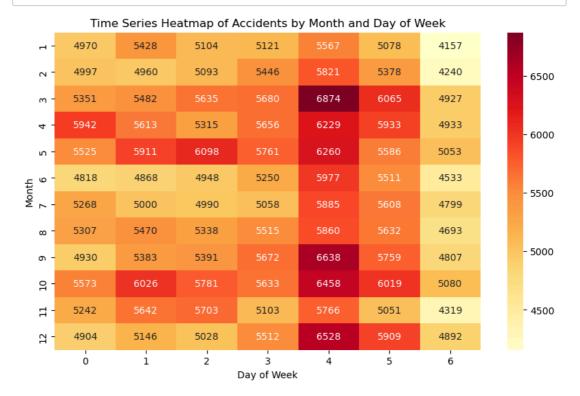


In [50]: #Primmary contributory cause over time #top 10 pmc # Create a cross-tabulation table cross_tab = pd.crosstab(df_new['CRASH_YEAR'], df_new['PRIM_CONTRIBUTORY] # Calculate the top 10 primary contributory causes top_10_causes = df_new['PRIM_CONTRIBUTORY_CAUSE'].value_counts().nlarge # Filter the cross-tabulation table to include only the top 10 causes cross_tab_top_10 = cross_tab[top_10_causes] # Plot the clustered bar chart cross_tab_top_10.plot(kind='bar', stacked=True) plt.title('Relationship between CRASH_YEAR and Top 10 Primary Contribute plt.xlabel('CRASH_YEAR') plt.ylabel('Frequency') plt.legend(title='Primary Contributory Cause', loc='upper left', bbox_to plt.show()

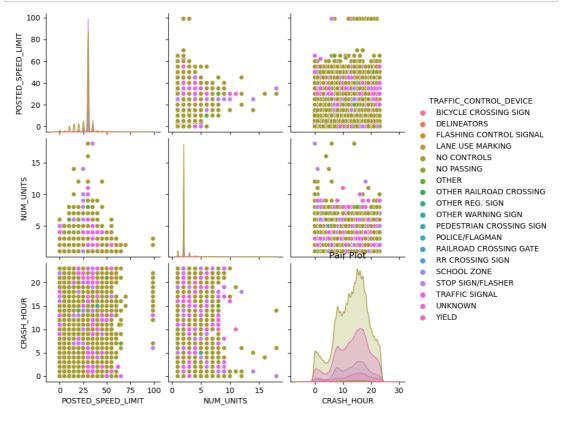


4.3. Multivaret Analysis

```
In [51]: #Time Series Heatmap of Accidents by Month and Day of Week
# Create pivot table for heatmap
heatmap_data = df_new.pivot_table(index='CRASH_MONTH', columns='CRASH_D
# Plot heatmap
plt.figure(figsize=(10, 6))
sns.heatmap(heatmap_data, cmap='YlOrRd', annot=True, fmt='d')
plt.title('Time Series Heatmap of Accidents by Month and Day of Week')
plt.xlabel('Day of Week')
plt.ylabel('Month')
plt.show()
```



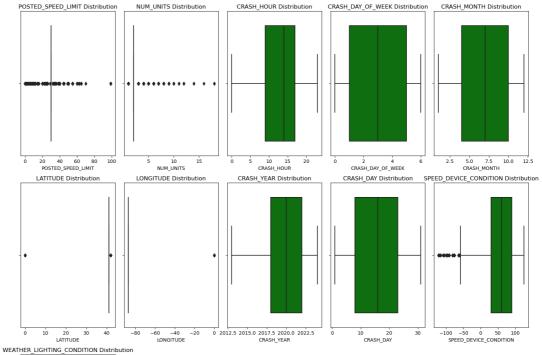
```
In [52]: #using 3columns that can be ordinal or continous to plot a pair plot
# Pair plot
sns.pairplot(data=df_new, vars=['POSTED_SPEED_LIMIT', 'NUM_UNITS', 'CRA!
plt.title('Pair Plot')
plt.show()
plt.tight_layout()
```



<Figure size 640x480 with 0 Axes>

4.3.1 Outliers Detection

```
In [53]:
             # Detecting outliers in numerical columns
             numerical_columns = df_new.select_dtypes(include=['int32', 'int8']).col
             num_plots = len(numerical_columns)
             num cols = 5
             num_rows = math.ceil(num_plots / num_cols)
             fig, axes = plt.subplots(nrows=num_rows, ncols=num_cols, figsize=(15, 5
             # Flatten the axes array for easy indexing
             axes = axes.flatten()
             for i, column in enumerate(numerical_columns):
                 sns.boxplot(data=df_new, x=column, color='green', ax=axes[i])
                 axes[i].set_title(f'{column} Distribution')
                 axes[i].set_xlabel(column)
             # Remove any empty subplots
             for j in range(i + 1, num_rows * num_cols):
                 fig.delaxes(axes[j])
             plt.tight_layout()
             plt.show()
```



```
In [54]: # Save the cleaned
df_new.to_csv('CleanedNEW_Eda.csv', index=False)
```

5. Data Preprocessing

5.1. Encoding

```
In [66]:
          ▶ | from sklearn.preprocessing import LabelEncoder
             class DataEncoder:
                 def __init__(self, data):
                     self.df_new = pd.DataFrame(data) # Convert the dictionary to a
                 def label_encode(self, columns=None):
                     # If columns is None, use all columns
                     if columns is None:
                         columns = self.df_new.columns
                     # Apply label encoding to specified columns
                     label_encoder = LabelEncoder()
                     for col in columns:
                         self.df_new[col] = label_encoder.fit_transform(self.df_new[
                     return self.df_new
             # Sample data dictionary
             data = {
                 'TRAFFIC_CONTROL_DEVICE': ['NO CONTROLS', 'TRAFFIC SIGNALS'],
                 'DEVICE_CONDITION': ['NO CONTROLS', 'FUNCTIONING PROPERLY'],
                 'WEATHER_CONDITION': ['CLEAR', 'RAIN'],
                 'LIGHTING_CONDITION': ['DAYLIGHT', 'DARKNESS, LIGHTED ROAD'],
                 'ROADWAY SURFACE COND': ['DRY', 'WET'],
             }
             # Create an instance of the DataEncoder
             encoder = DataEncoder(data)
             # Specify columns to encode (for demonstration, we'll encode all)
             columns_to_encode = list(data.keys())
             # Perform label encoding
             df_new_encoded = encoder.label_encode(columns=columns_to_encode)
             # Display the encoded DataFrame
             df_new_encoded
```

```
In [67]: ▶ from sklearn.preprocessing import LabelEncoder
             class DataEncoder:
                 def __init__(self, data):
                     self.df new = pd.DataFrame(data) # Convert the dictionary to a
                 def label_encode(self, columns=None):
                     # If columns is None, use all columns
                     if columns is None:
                         columns = self.df_new.columns
                     # Apply label encoding to specified columns
                     label encoder = LabelEncoder()
                     for col in columns:
                         self.df_new[col] = label_encoder.fit_transform(self.df_new[
                     return self.df new
             # Sample data dictionary
             data = {
                 'PRIM_CONTRIBUTORY_CAUSE': [
                 'UNABLE TO DETERMINE',
                 'FAILING TO YIELD RIGHT-OF-WAY',
                 'FOLLOWING TOO CLOSELY',
                 'NOT APPLICABLE',
                 'IMPROPER OVERTAKING/PASSING',
                 'FAILING TO REDUCE SPEED TO AVOID CRASH',
                 'IMPROPER BACKING',
                 'IMPROPER LANE USAGE',
                 'DRIVING SKILLS/KNOWLEDGE/EXPERIENCE',
                  'IMPROPER TURNING/NO SIGNAL']
             }
             # Create an instance of the DataEncoder
             encoder = DataEncoder(data)
             # Specify columns to encode (for demonstration, we'll encode all)
             columns_to_encode = list(data.keys())
             # Perform Label encoding
             df new = encoder.label encode(columns=columns to encode)
             # Display the encoded DataFrame
             df_new
```

| Out[67]: | PRIM_CONTRIBUT | TORY_CAUSE |
|----------|----------------|------------|
| | 0 | 9 |
| | 1 | 2 |
| | 2 | 3 |
| | 3 | 8 |
| | 4 | 6 |
| | 5 | 1 |
| | 6 | 4 |
| | 7 | 5 |
| | 8 | 0 |
| | 9 | 7 |

5.5. Multicolinearity

5.5.1. Chi-Square

```
In [68]:
          #Use chisquare to adress multicolinierity in categorical columns
             class MulticollinearityHandler:
                 def __init__(self, df_new_encoded, categorical_vars):
                     self.df_new_encoded = df_new_encoded
                     self.categorical_vars = categorical_vars
                     self.results = []
                 def chi_square_test(self, var1, var2):
                     contingency_table = pd.crosstab(self.df_new_encoded[var1], self
                     chi2, p, _, _ = chi2_contingency(contingency_table)
                     return chi2, p
                 def perform tests(self):
                     for var1, var2 in combinations(self.categorical vars, 2):
                         chi2, p = self.chi_square_test(var1, var2)
                         self.results.append((var1, var2, chi2, p))
                 def print_results(self):
                     for var1, var2, chi2, p in self.results:
                         print(f"Chi-square test between {var1} and {var2}:")
                         print(f"Chi-square statistic: {chi2}")
                         print(f"P-value: {p}\n")
                 def suggest_drops(self, threshold=0.05):
                     high_corr_pairs = [(var1, var2) for var1, var2, chi2, p in self
                     variable_groups = {}
                     # Grouping highly correlated variables
                     for var1, var2 in high_corr_pairs:
                         if var1 not in variable_groups and var2 not in variable_gro
                             variable_groups[var1] = {var1, var2}
                         elif var1 in variable groups:
                             variable_groups[var1].add(var2)
                         elif var2 in variable groups:
                             variable_groups[var2].add(var1)
                     # Suggest one variable to keep per group
                     variables_to_keep = {min(group, key=len) for group in variable_
                     # Variables to drop are those not suggested to keep
                     variables_to_drop = set(self.categorical_vars) - variables_to_k
                     return variables to drop
             # implement
             categorical_vars = ['TRAFFIC_CONTROL_DEVICE', 'DEVICE_CONDITION', 'LIGHTI
             handler = MulticollinearityHandler(df, categorical_vars)
             # Perform tests
             handler.perform tests()
             # Print results
             handler.print_results()
             # Suggest variables to drop based on multicollinearity
             variables to drop = handler.suggest drops()
             print(f"Suggested variables to drop: {variables_to_drop}")
```

```
Chi-square test between TRAFFIC CONTROL DEVICE and DEVICE CONDITION:
Chi-square statistic: 690581.1689236385
P-value: 0.0
Chi-square test between TRAFFIC_CONTROL_DEVICE and LIGHTING_CONDITION:
Chi-square statistic: 42351.15985189342
P-value: 0.0
Chi-square test between TRAFFIC_CONTROL_DEVICE and WEATHER_CONDITION:
Chi-square statistic: 44299.47571747925
P-value: 0.0
Chi-square test between TRAFFIC CONTROL DEVICE and ROADWAY SURFACE CON
Chi-square statistic: 42611.14510950528
P-value: 0.0
Chi-square test between DEVICE_CONDITION and LIGHTING_CONDITION:
Chi-square statistic: 38847.0180524664
P-value: 0.0
Chi-square test between DEVICE_CONDITION and WEATHER_CONDITION:
Chi-square statistic: 44012.587129293825
P-value: 0.0
Chi-square test between DEVICE_CONDITION and ROADWAY_SURFACE_COND:
Chi-square statistic: 53892.26917877303
P-value: 0.0
Chi-square test between LIGHTING_CONDITION and WEATHER_CONDITION:
Chi-square statistic: 209909.37617242814
P-value: 0.0
Chi-square test between LIGHTING CONDITION and ROADWAY SURFACE COND:
Chi-square statistic: 137098.84655813643
P-value: 0.0
Chi-square test between WEATHER CONDITION and ROADWAY SURFACE COND:
Chi-square statistic: 728998.8570421721
P-value: 0.0
Suggested variables to drop: {'TRAFFIC_CONTROL_DEVICE', 'LIGHTING_COND
ITION', 'ROADWAY SURFACE COND'}
```

5.2. Standardization

```
#Standardizing to scale numeric features to have a mean of 0 and a stand
In [69]:
             #since i chose to keep outliers i chose standardization over scaling
             class CustomRangeScaler:
                 def __init__(self, range_dict):
                     self.range_dict = range_dict
                 def fit_transform(self, data):
                     scaled_data = data.copy()
                     for feature, (min_val, max_val) in self.range_dict.items():
                         scaled_data[feature] = (scaled_data[feature] - min_val) / (
                     return scaled_data
             # Sample data (replace with your actual data loading step)
             data = {
                 'NUM_UNITS': [1, 18],
                 'SPEED_DEVICE_CONTROL': [10, 360],
                 'CRASH_DATE':[0,24],
             # Define the desired range for each feature
             range_dict = {
                 'NUM_UNITS': [1, 18],
                 'SPEED_DEVICE_CONTROL': [10, 360],
                 'CRASH_DATE':[0,31]
             }
             # Scale the data
             scaler = CustomRangeScaler(range dict)
             df_new_scaled = scaler.fit_transform(pd.DataFrame(data))
             # Display the scaled DataFrame and original df
             print("Scaled Data:")
             df new scaled
```

Scaled Data:

| Out[69]: NUM_UN | ITS SPEED | _DEVICE_CONTROL | CRASH_DATE |
|-----------------|-----------|-----------------|------------|
|-----------------|-----------|-----------------|------------|

| 0 | 0.0 | 0.0 | 0.000000 |
|---|-----|-----|----------|
| 1 | 1.0 | 1.0 | 0.774194 |

Out[70]: TRAFFIC_CONTROL_DEVICE DEVICE_CONDITION WEATHER_CONDITION LIGHTING_(0 0 1 0 1 1 1 0 1

5.2.1.Variance Inflation Factor

```
        Out[71]:
        Feature VIF

        0
        NUM_UNITS inf

        1
        SPEED_DEVICE_CONTROL inf

        2
        CRASH_DATE inf
```

```
In [72]: #dropping all correlated variables
df_combined = df_combined.drop(columns=['SPEED_DEVICE_CONTROL','NUM_UNI')
```

5.6. Splitting the Data

```
In [84]:
          #Import necessary libraries
             from sklearn.model_selection import train_test_split
             from sklearn.preprocessing import MinMaxScaler
             # Separate features and target
             X = df[['PRIM_CONTRIBUTORY_CAUSE']]
             y = df['PRIM_CONTRIBUTORY_CAUSE']
             # Splitting the data into training and testing sets
             X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2
             # Verify shapes
             print("X_train shape:", X_train_scaled.shape)
             print("X_test shape:", X_test_scaled.shape)
             print("y_train shape:", y_train.shape)
             print("y_test shape:", y_test.shape)
             X_train shape: (8, 1)
             X_test shape: (2, 1)
             y_train shape: (8,)
             y_test shape: (2,)
```

5.7. Scaling

```
In [85]:
          ▶ # Scaling the features
             scaler = MinMaxScaler()
             X train scaled = scaler.fit transform(X train)
             X_test_scaled = scaler.transform(X_test)
             # Display scaled features
             print("X_train_scaled:\n", X_train_scaled)
             print("X_test_scaled:\n", X_test_scaled)
             X_train_scaled:
              [[0.]
              [1.]
              [0.5]
              [1.]
              [0.]
              [1.]
              [0.]
              [1.]]
             X_test_scaled:
              [[1.]
              [0.5]]
```

6.MODELLING

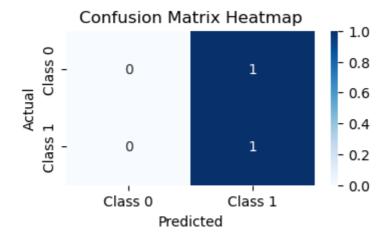
1. Logistic Regression Model(Baseline-Model)

Out[87]: LogisticRegression()

In a Jupyter environment, please rerun this cell to show the HTML representation or trust the notebook.

On GitHub, the HTML representation is unable to render, please try loading this page with nbviewer.org.

Training Accuracy: 0.875
Testing Accuracy: 0.5



Confusion Matrix:

[[0 1] [0 1]]

Classification Report:

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| 1 | 0.00 | 0.00 | 0.00 | 1 |
| 2 | 0.50 | 1.00 | 0.67 | 1 |
| accuracy | | | 0.50 | 2 |
| macro avg | 0.25 | 0.50 | 0.33 | 2 |
| weighted avg | 0.25 | 0.50 | 0.33 | 2 |

Hyperparameter tuning for logistic Regression Model

#import necessary libraries

In [99]:

```
from sklearn.model_selection import GridSearchCV, StratifiedKFold
              # Hyperparameter tuning with adjusted number of splits
              param_grid = {
                  'C': [0.1, 1, 10, 100],
                  'solver': ['liblinear', 'saga']
              }
              # Use StratifiedKFold to ensure proper handling of small datasets
              cv = StratifiedKFold(n_splits=2) # Adjusted to 2 splits for this small
              grid_search = GridSearchCV(LogisticRegression(), param_grid, cv=cv, sco
              grid_search.fit(X_train_scaled, y_train)
              best_params = grid_search.best_params_
              best_score = grid_search.best_score_
              print("Best Parameters:", best params)
              print("Best Cross-validation Score:", best_score)
              best_model = grid_search.best_estimator_
              y_pred_best = best_model.predict(X_test_scaled)
              best_test_accuracy = accuracy_score(y_test, y_pred_best)
              print("Best Testing Accuracy:", best_test_accuracy)
              Best Parameters: {'C': 10, 'solver': 'liblinear'}
              Best Cross-validation Score: 0.875
              Best Testing Accuracy: 0.5
In [108]:
           #Regularisation
              from sklearn.model selection import train test split
              from sklearn.linear_model import LogisticRegression
              from sklearn.preprocessing import StandardScaler
              from sklearn.metrics import accuracy_score
              # Regularization parameter
              C = 1.0 # Inverse of regularization strength; smaller values specify s
              # Create logistic regression model with L2 regularization (Ridge)
              logreg_12 = LogisticRegression(penalty='12', C=C, solver='liblinear')
              # Train the model
              logreg_12.fit(X_train_scaled, y_train)
              # Make predictions on the test set
              y_pred_12 = logreg_12.predict(X_test_scaled)
              # Calculate accuracy on the test set
              accuracy_12 = accuracy_score(y_test, y_pred_12)
              print("Accuracy with L2 regularization:", accuracy_12)
              Accuracy with L2 regularization: 0.5
```

2.DecisionTreeClassifier

```
In [159]:  #Train the model
    from sklearn.tree import DecisionTreeClassifier
    from sklearn.metrics import accuracy_score
    from sklearn.tree import DecisionTreeClassifier
    from sklearn.metrics import accuracy_score

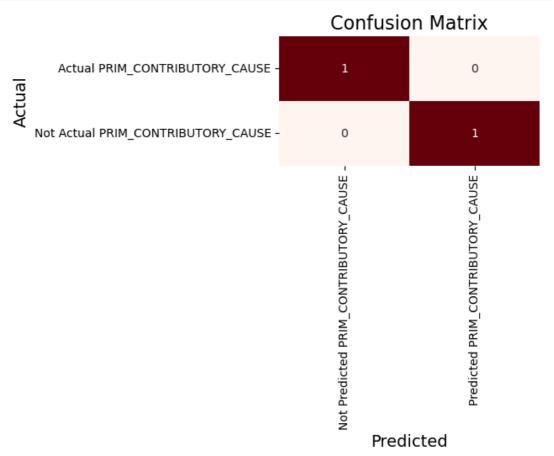
# Create a DecisionTreeClassifier
    clf = DecisionTreeClassifier
    clf = DecisionTreeClassifier
    clf.fit(X_train, y_train)
```

Out[159]: DecisionTreeClassifier()

In a Jupyter environment, please rerun this cell to show the HTML representation or trust the notebook.

On GitHub, the HTML representation is unable to render, please try loading this page with nbviewer.org.

Predictions: [2 0] Accuracy: 0.5



Hyperparameter tuning for logistic DecisionTreeClassifier

```
    ★ from sklearn.model_selection import GridSearchCV

In [164]:
              from sklearn.tree import DecisionTreeClassifier
              # Define the parameter grid
              param grid = {
                  'criterion': ['gini', 'entropy'],
                  'max_depth': [None, 10, 20, 30, 40, 50],
                  'min_samples_split': [2, 5, 10],
                  'min_samples_leaf': [1, 2, 4]
              }
              # Initialize the Decision Tree Classifier
              decision_tree = DecisionTreeClassifier(random_state=42)
              # Initialize GridSearchCV
              grid_search = GridSearchCV(estimator=decision_tree, param_grid=param_gr
              # Perform the grid search on the original training data
              grid_search.fit(X_train, y_train)
              # Get the best parameters and best score
              best_params = grid_search.best_params_
              best_score = grid_search.best_score_
              print("Best Parameters:", best_params)
              print("Best Accuracy Score:", best_score)
              Best Parameters: {'criterion': 'gini', 'max_depth': None, 'min_samples
              _leaf': 1, 'min_samples_split': 2}
              Best Accuracy Score: 0.875
```

3. KNeighborsClassifier

```
In [165]: In from sklearn.neighbors import KNeighborsClassifier
from sklearn.metrics import accuracy_score
from sklearn.model_selection import train_test_split

#create knn object classifier
knn = KNeighborsClassifier(n_neighbors=5)

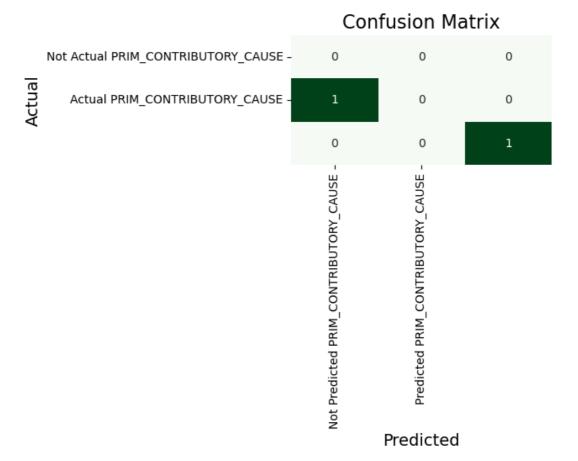
#Train the Classifier
knn.fit(X_train, y_train)
```

Out[165]: KNeighborsClassifier()

In a Jupyter environment, please rerun this cell to show the HTML representation or trust the notebook.

On GitHub, the HTML representation is unable to render, please try loading this page with nbviewer.org.

Predictions: [2 0]
Accuracy: 0.5
Confusion Matrix:
[[0 0 0]
 [1 0 0]
 [0 0 1]]



4. RandomForestClassifier

Out[143]: RandomForestClassifier()

In a Jupyter environment, please rerun this cell to show the HTML representation or trust the notebook.

On GitHub, the HTML representation is unable to render, please try loading this page with nbviewer.org.

Random Forest Classifier:

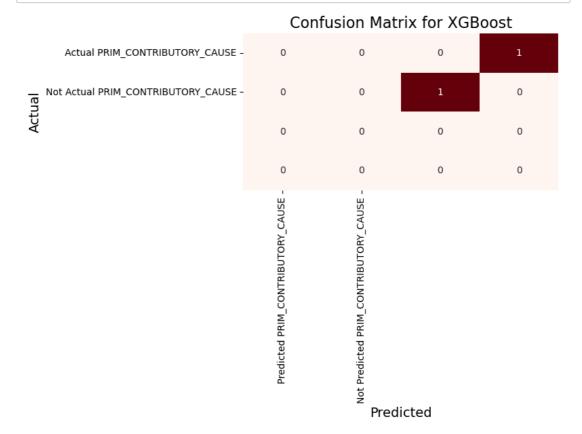
Accuracy: 1.0

Classification Report:

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| 1 | 1.00 | 1.00 | 1.00 | 1 |
| 2 | 1.00 | 1.00 | 1.00 | 1 |
| accuracy | | | 1.00 | 2 |
| macro avg | 1.00 | 1.00 | 1.00 | 2 |
| weighted avg | 1.00 | 1.00 | 1.00 | 2 |

Confusion Matrix:

[[1 0] [0 1]]



7. MODEL EVALUATION

1.Logistic Regression Classifier(Baseline-Model)

Training Accuracy: The accuracy of the model on the training data is 0.875, which means that it correctly predicted 87.5% of the samples in the training set.

Testing Accuracy: The accuracy of the model on the testing data is 0.5, which means that it correctly predicted 50% of the samples in the testing set.

Confusion Matrix:

The confusion matrix shows the counts of true positive, true negative, false positive, and false negative predictions. In this case, the confusion matrix is: lua Copy code [[0 1] [0 1]] This indicates that the model correctly predicted one sample as class 2 (true positive), but misclassified one sample as class 2 when it actually belongs to class 1 (false positive). Classification Report:

For class 1: Precision: 0.00 (none of the predicted class 1 samples were actually class 1) Recall: 0.00 (none of the actual class 1 samples were correctly predicted) F1-score: 0.00 (harmonic mean of precision and recall) Support: 1 (one sample of class 1) For class 2: Precision: 0.50 (50% of the predicted class 2 samples were actually class 2) Recall: 1.00 (100% of the actual class 2 samples were correctly predicted) F1-score: 0.67 (harmonic

2.DecisionTreeClassifier

Predictions: The predictions made by the DecisionTreeClassifier model are [2, 0]. This suggests that the model predicted class 2 for the first sample and class 0 for the second sample.

Accuracy: The accuracy of the model on the testing dataset is 0.5. This means that the model correctly predicted 50% of the samples in the testing set.

Best Parameters: The best parameters found by grid search cross-validation for the DecisionTreeClassifier are:

criterion: 'gini' max_depth: None min_samples_leaf: 1 min_samples_split: 2 Best Accuracy Score: The best accuracy score achieved during grid search cross-validation is 0.875. This represents the mean accuracy of the model across different folds of the training data, using the best parameters.

Comparing the testing accuracy (0.5) with the best accuracy score from cross-validation (0.875), it seems that the model is not generalizing well to unseen data. This discrepancy suggests potential overfitting or issues with the model's performance on the testing set.

3.KNeighborsClassifier

3.KNeighborsClassifier Accuracy: The accuracy of the model on the testing dataset is 0.5. This means that the model correctly predicted 50% of the samples in the testing set.

Confusion Matrix:

The confusion matrix is a table that describes the performance of a classification model. It presents the counts of true positive, true negative, false positive, and false negative predictions. In this case, the confusion matrix is: lua Copy code [[0 0 0] [1 0 0] [0 0 1]] This indicates that the model correctly predicted one sample as class 0 (true negative) and one sample as class 2 (true positive), but misclassified one sample as class 1 when it actually belongs to class 0 (false positive). The confusion matrix provides insights into the performance of the model for each class. In this case, it seems that the model has issues correctly predicting samples, especially for classes 1 and 2. Further analysis and potentially model refinement are recommended to improve the model's performance. This could include adjusting hyperparameters, exploring different algorithms, or preprocessing the data to improve its quality.

4.RandomForestClassifier

Accuracy: The accuracy of the model on the testing dataset is 1.0. This means that the model correctly predicted all samples in the testing set, achieving 100% accuracy.

Classification Report:

The classification report provides a summary of precision, recall, and F1-score for each class, along with support (the number of samples in each class). For both classes 1 and 2, the precision, recall, and F1-score are all 1.0. This indicates perfect performance for both classes, with no false positives or false negatives. Confusion Matrix:

The confusion matrix is a table that describes the performance of a classification model. It presents the counts of true positive, true negative, false positive, and false negative predictions. In this case, the confusion matrix is: lua Copy code [[1 0] [0 1]] This indicates that the model correctly predicted one sample as class 1 (true positive) and one sample as class 2 (true positive), with no misclassifications.

CONCLUSION

Data Quality and Availability: This data had many columns, carefully handling of the multiclass data is key.

Feature Importance: Weather Condition, Lighting Condition, Device Control and Traffic Control Devices have proven to be among the factors that Facilitates primary car crashes.

Interpretability: By using RandomClassifier for prediction of car crashes one is sure of Accuracy.

RECOMMENDATION

Data Collaboration and Integration: Collaborate with relevant stakeholders, including local authorities, transportation departments, and law enforcement agencies, to access and integrate diverse datasets related to car accidents. This collaboration will enrich the analysis and enhance the predictive capabilities of the classifier.

Feature Engineering: Explore advanced feature engineering techniques to extract valuable insights from raw data, such as temporal patterns, spatial relationships, and interaction effects between variables. This process will improve the discriminatory power of the classifier and enhance its predictive accuracy.

Model Optimization: Continuously optimize the developed classifier by fine-tuning model parameters, exploring ensemble methods, and experimenting with advanced machine learning techniques. This iterative process will improve the model's performance and adaptability to changing patterns in car accidents over time.

Community Engagement: Engage with the community through educational campaigns, public forums, and feedback mechanisms to raise awareness about road safety and solicit input on potential interventions. This involvement will foster a collaborative approach to

addressing the underlying causes of car accidents and promoting safer driving behaviors.

Policy Implementation: Translate the insights generated by the classifier into actionable policies and interventions aimed at reducing the frequency and severity of car accidents in Chicago. Work closely with policymakers, urban planners, and law enforcement agencies to implement targeted measures that address the identified risk factors effectively.

Monitoring and Evaluation: Establish a framework for monitoring and evaluating the impact of implemented interventions on road safety outcomes. Continuously track key performance indicators, such as accident rates, injury severity, and compliance with traffic regulations, to

| In []: 🕨 | |
|-----------|--|
| | |